

D3-2. KB. MEX.

Wheeler
5/23-19-1

Zagame w1

$$A = \begin{pmatrix} \cos \theta & -i \sin \theta \\ i \sin \theta & -\cos \theta \end{pmatrix}$$

$$1. \det(A - \lambda E) = \begin{vmatrix} (\cos \theta - \lambda) & -i \sin \theta \\ i \sin \theta & -\cos \theta - \lambda \end{vmatrix} = -(\cos^2 \theta - \lambda^2) + i^2 \sin^2 \theta =$$

$$= \lambda^2 - 1 = 0$$

$$\begin{cases} \lambda_1 = 1 \\ \lambda_2 = -1 \end{cases}$$

$$\lambda = 1$$

$$\begin{pmatrix} \cos \theta - 1 & -i \sin \theta \\ i \sin \theta & -\cos \theta - 1 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} \psi_1 (\cos \theta - 1) - i \sin \theta \psi_2 = 0 \\ i \psi_1 \sin \theta + \psi_2 (\cos \theta + 1) = 0 \end{cases}$$

$$\psi_1 = \frac{i \sin \theta}{\cos \theta - 1} \psi_2$$

$$\vec{f}_1 = \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} \frac{i \sin \theta}{\cos \theta - 1} \psi_2 \\ \psi_2 \end{pmatrix} = \psi_2 \begin{pmatrix} \frac{i \sin \theta}{\cos \theta - 1} \\ 1 \end{pmatrix}$$

$$\lambda = -1$$

$$\begin{pmatrix} \cos \theta + 1 & -i \sin \theta \\ i \sin \theta & 1 - \cos \theta \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} \psi_1 (\cos \theta + 1) - i \sin \theta \psi_2 = 0 \\ i \psi_1 \sin \theta + \psi_2 (1 - \cos \theta) = 0 \end{cases}$$

$$\psi_1 = \frac{i \sin \theta}{\cos \theta + 1} \psi_2$$

$$\vec{f}_2 = \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \psi_2 \begin{pmatrix} \frac{i \sin \theta}{\cos \theta + 1} \\ 1 \end{pmatrix}$$

Пусть $\bar{g}_1 = \bar{f}_1$

$$\bar{g}_2 = \bar{f}_2 - \lambda_{21} \bar{g}_1, \text{ где } \lambda_{21} = \frac{(\bar{f}_2, \bar{g}_1)}{(\bar{g}_1, \bar{g}_1)}$$

$$\lambda_{21} = 1 + \frac{1}{\cos \theta}$$

$$\bar{g}_2 = \bar{f}_2 - \left(1 + \frac{1}{\cos \theta}\right) \bar{g}_1 = \bar{f}_2 - \left(1 + \frac{1}{\cos \theta}\right) \bar{f}_1$$

Заметим, что

$$\hat{A} \bar{g}_2 = \hat{A} \bar{f}_2 - \hat{A} \left(1 + \frac{1}{\cos \theta}\right) \bar{f}_1 = 0 \bar{f}_2 - \left(1 + \frac{1}{\cos \theta}\right) 0 \bar{f}_1 = 0 \cdot \bar{g}_2$$

т.е. $g_2 \perp g_1$,

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2. $e^{i\alpha A}$?

$$e^{i\alpha A} = \sum_{k=1}^{\infty} \frac{(i\alpha A)^k}{k!} = 1 + \frac{i\alpha A}{1} - \frac{\alpha^2 A^2}{2} + \frac{i\alpha^3 A^3}{6} + \dots = 1 + i \sum_{j=1}^{\infty} \frac{(-1)^{j+1} \alpha^{2j-1} A^{2j-1}}{(2j-1)!} + \sum_{k=1}^{\infty} \frac{(-1)^k (\alpha^{2k}) A^{2k}}{(2k)!}$$

$$A^2 |f\rangle = A |A|f\rangle = A \begin{pmatrix} \cos \theta & -i \sin \theta \\ i \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} = A \begin{pmatrix} f_1 \cos \theta - f_2 i \sin \theta \\ f_1 i \sin \theta - f_2 \cos \theta \end{pmatrix} =$$

$$= \begin{pmatrix} f_1 \cos^2 \theta - i f_2 \sin \theta \cos \theta + f_1 \sin^2 \theta + i f_2 \sin \theta \cos \theta \\ i f_1 \sin \theta \cos \theta + f_2 \sin^2 \theta - i f_1 \cos \theta \sin \theta + f_2 \cos^2 \theta \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} = |f\rangle$$

$$A^{2k} = 1, \quad A^{2j-1} = A$$

$$e^{i\alpha A} = 1 + iA \sum_{j=1}^{\infty} \frac{(-1)^{j+1} \alpha^{2j-1}}{(2j-1)!} + \sum_{k=1}^{\infty} \frac{(-1)^k \alpha^{2k}}{(2k)!} = \underline{iA \sinh \alpha + \cosh \alpha}$$

Задача №2

$$A = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

$$1. \det(A - \lambda E) = \frac{1}{\sqrt{2}} \begin{vmatrix} -\lambda & -i & 0 \\ i & -\lambda & -i \\ 0 & i & -\lambda \end{vmatrix} = \frac{1}{\sqrt{2}} (-\lambda(\lambda^2 + i^2) + i(-i\lambda)) =$$

$$= \frac{1}{\sqrt{2}} (-\lambda^3 + 2\lambda) = 0$$

$$\begin{cases} \lambda_1 = 0 \\ \lambda_2 = \sqrt{2} \\ \lambda_3 = -\sqrt{2} \end{cases}$$

• $\lambda_1 = 0$

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} -i\psi_2 = 0 \\ \psi_1 i - i\psi_3 = 0 \\ i\psi_3 = 0 \end{cases} \Rightarrow \begin{cases} \psi_1 = \psi_3 \\ \psi_2 = 0 \end{cases} \Rightarrow f = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} = \psi_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

• $\lambda_2 = \sqrt{2}$

$$\frac{1}{\sqrt{2}} \begin{pmatrix} -\sqrt{2} & -i & 0 \\ i & -\sqrt{2} & -i \\ 0 & i & -\sqrt{2} \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} -\psi_1 \sqrt{2} - i\psi_2 = 0 \\ i\psi_1 - \sqrt{2}\psi_2 - i\psi_3 = 0 \\ i\psi_2 - \sqrt{2}\psi_3 = 0 \end{cases} \Rightarrow \begin{cases} \psi_1 = \frac{-i}{\sqrt{2}} \psi_2 \\ \psi_3 = \frac{1}{\sqrt{2}} \psi_2 \end{cases} \Rightarrow f = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} = \frac{1}{\sqrt{2}} \frac{\sqrt{2}}{2} \psi_2 \begin{pmatrix} -i \\ \sqrt{2} \\ i \end{pmatrix} = \frac{1}{2} \psi_2 \begin{pmatrix} -i \\ \sqrt{2} \\ i \end{pmatrix}$$

• $\lambda_3 = -\sqrt{2}$

$$\frac{1}{\sqrt{2}} \begin{pmatrix} \sqrt{2} & -i & 0 \\ i & \sqrt{2} & -i \\ 0 & i & \sqrt{2} \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} \sqrt{2} \psi_1 - i \psi_2 = 0 \\ i(\psi_1 - \psi_3) + \sqrt{2} \psi_2 = 0 \\ i \psi_2 + \sqrt{2} \psi_3 = 0 \end{cases} \Rightarrow \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} = \frac{1}{\sqrt{2}} \psi_2 \begin{pmatrix} i \\ \sqrt{2} \\ -i \end{pmatrix} = \frac{1}{2} \psi_2 \begin{pmatrix} i \\ \sqrt{2} \\ -i \end{pmatrix}$$

$$f_1 \cdot f_2 = 1 \cdot (-i) + 0 + 1 \cdot i = 0 \Rightarrow \bar{f}_1 \perp \bar{f}_2$$

$$f_1 \cdot f_3 = 1 \cdot i + 0 + 1 \cdot (-i) = 0 \Rightarrow \bar{f}_1 \perp \bar{f}_3$$

$$\text{Then } \bar{g}_1 = \bar{f}_1, \bar{g}_2 = \bar{f}_2$$

$$\bar{g}_3 = \bar{f}_3 - \lambda_{31} \bar{g}_1 - \lambda_{32} \bar{g}_2$$

$$\lambda_{31} = \frac{(\bar{f}_3, \bar{g}_1)}{(\bar{g}_1, \bar{g}_1)} = 0; \quad \lambda_{32} = \frac{(\bar{f}_3, \bar{g}_2)}{(\bar{g}_2, \bar{g}_2)} = 1$$

$$\bar{g}_3 = \bar{f}_3 - \bar{g}_2 = \bar{f}_3 - \bar{f}_2$$

$$\text{Then } \bar{g}_3 \hat{A} = \hat{A} \bar{f}_3 - \hat{A} \bar{f}_2 = 0 f_3 - 0 f_2 = 0 \cdot \bar{g}_3$$

$$\text{no } \bar{g}_3 \perp \bar{g}_2$$

$$3. |\psi\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = C_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + C_2 \begin{pmatrix} -i \\ \sqrt{2} \\ i \end{pmatrix} + C_3 \begin{pmatrix} i \\ \sqrt{2} \\ -i \end{pmatrix}$$

$$\begin{cases} C_1 - i C_2 + i C_3 = 1 \\ \sqrt{2} C_2 + \sqrt{2} C_3 = 0 \\ C_1 + i C_2 - i C_3 = 0 \end{cases} \Rightarrow \begin{cases} C_1 = \frac{1}{2} \\ C_2 = i \frac{1}{4} \\ C_3 = -i \frac{1}{4} \end{cases}$$

$$|\psi\rangle = \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \frac{i}{4} \begin{pmatrix} -i \\ \sqrt{2} \\ i \end{pmatrix} - \frac{i}{4} \begin{pmatrix} i \\ \sqrt{2} \\ -i \end{pmatrix}$$

$$2. e^{i\theta A} = 1 + \frac{i\theta A}{1} - \frac{\theta^2 A^2}{2} - \frac{i\theta^3 A^3}{6} + \dots = \sum_{j=0}^{\infty} \frac{(i\theta A)^j (-1)^j}{(2j)!} + i \sum_{k=1}^{\infty} \frac{(-1)^{k+1} \theta^{2k+1} A^{2k+1}}{(2k+1)!}$$

$$A|f\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} \begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} -if_2 \\ f_1 i - if_3 \\ if_2 \end{pmatrix} = \frac{i}{\sqrt{2}} \begin{pmatrix} -f_2 \\ f_1 - f_3 \\ f_2 \end{pmatrix}$$

$$A^2|f\rangle = A|A|f\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} \frac{i}{\sqrt{2}} \begin{pmatrix} -f_2 \\ f_1 - f_3 \\ f_2 \end{pmatrix} = \frac{i}{2} \begin{pmatrix} i(f_3 - f_1) \\ -if_2 - if_2 \\ i(f_1 - f_3) \end{pmatrix} = \frac{-1}{2} \begin{pmatrix} f_3 - f_1 \\ 2f_2 \\ f_1 - f_3 \end{pmatrix}$$

$$A^3|f\rangle = \frac{-1}{2\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} \begin{pmatrix} f_3 - f_1 \\ -2f_2 \\ f_1 - f_3 \end{pmatrix} = \frac{-1}{2\sqrt{2}} \begin{pmatrix} 2if_2 \\ (f_3 - f_1)i - i(f_1 - f_3) \\ -2if_2 \end{pmatrix} = \frac{i}{\sqrt{2}} \begin{pmatrix} -f_2 \\ f_3 - f_1 \\ f_2 \end{pmatrix}$$

$$A^{2n+1} = A, \quad A^{2n} = A^2$$

$$e^{i\theta A} = A \sum_{j=0}^{\infty} \frac{(-1)^j \theta^{2j}}{(2j)!} + iA \sum_{k=1}^{\infty} \frac{(-1)^{k+1} \theta^{2k+1}}{(2k+1)!} = A^2 \cos \theta + iA \sin \theta$$

Задача №3

$$\hat{T}_a \psi(x) = \psi(x+a)$$

$$1. \langle \psi | \hat{T}_a \psi \rangle = \int_{-\infty}^{+\infty} \psi^*(x) \psi(x+a) dx = \int_{-\infty}^{+\infty} \psi^*(x'-a) \psi(x') dx' =$$

$$x' = x+a$$

$$= \langle \hat{T}_{-a} \psi | \psi \rangle \Rightarrow \hat{T}_a^\dagger = \hat{T}_{-a} \Rightarrow \text{не эрмитов}$$

$$3. \hat{T}_a^\dagger = \hat{T}_{-a}$$

$$\hat{T}_a^\dagger \hat{T}_a |\psi\rangle = \hat{T}_{-a} \psi(x+a) = \psi(x) \Rightarrow \hat{T}_a^\dagger \hat{T}_a = 1$$

$$4. \hat{T}_a \psi(x) = \int_{-\infty}^{+\infty} T_a(x, x') \psi(x') dx' = \psi(x+a)$$

$$\hat{T}_a(x, x') = \delta(x' - (x+a))$$

Задача №4

$$\hat{J} = \mathcal{L} \left(x^2 \frac{d}{dx} - \frac{d}{dx} x^2 \right)$$

$$1. \hat{J}|\psi\rangle = \mathcal{L} \left(x^2 \frac{d\psi}{dx} - 2x\psi - x^2 \frac{d\psi}{dx} \right) = -2x\mathcal{L}\psi$$

$$\langle \psi | \hat{J} | \psi \rangle = \int_{-\infty}^{+\infty} \psi^*(x) \cdot (-2x\psi(x)) dx = \langle \hat{J}^\dagger \psi | \psi \rangle = \int_{-\infty}^{+\infty} (\hat{J}^\dagger \psi)^* \psi(x) dx =$$

$$= \int_{-\infty}^{+\infty} (-2x\psi(x))^* \cdot \psi dx \quad (\text{это можно же } \mathcal{L} \in \mathbb{R})$$

2. Для $\mathcal{L} \in \mathbb{R}$ оператор \hat{J} эрмитов

$$1) \mathcal{L} \in \mathbb{R}: \hat{J}^\dagger = \hat{J}$$

$$2) \mathcal{L} \notin \mathbb{R}: (\hat{J}^\dagger \psi)^* = -2\mathcal{L}^* x \psi^* = -2\underbrace{\mathcal{L} e^{i\pi}}_{\mathcal{L}} x \psi^*$$

$$\hat{J}^\dagger = -2\mathcal{L}^* x$$

$$3. \hat{J}|\psi\rangle = \int_{-\infty}^{+\infty} S(x, x') \psi(x') dx' = -2\mathcal{L} x \psi(x)$$

$$S(x, x') = -2\mathcal{L} x \delta(x' - x)$$

Задача №5

$$B = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad D\text{-мб: } B^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$1. BX = X'$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} ax_1 + bx_2 \\ cx_1 + dx_2 \end{pmatrix} = \begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix}$$

$$B^{-1} X' = X$$

$$\begin{pmatrix} a^{-1} & b^{-1} \\ c^{-1} & d^{-1} \end{pmatrix} \begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\begin{pmatrix} a^{-1}(ax_1 + bx_2) + b^{-1}(cx_1 + dx_2) \\ c^{-1}(ax_1 + bx_2) + d^{-1}(cx_1 + dx_2) \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} a^{-1} & b^{-1} & 1 \\ a & c & 0 \\ b & d & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} ad & cd & d \\ bc & cd & 0 \end{array} \right) \rightarrow (ad-bc)a^{-1} = d \Rightarrow a^{-1} = \frac{d}{ad-bc}$$

$$\rightarrow \left(\begin{array}{cc|c} ab & cb & b \\ ab & ad & 0 \end{array} \right) \rightarrow (bc-ad)b^{-1} = b \Rightarrow b^{-1} = \frac{-b}{ad-bc}$$

$$\left(\begin{array}{cc|c} a & c & 0 \\ b & d & 1 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} ad & cd & 0 \\ bc & cd & c \end{array} \right) \Rightarrow (bc - ad)C^{-1} = c \Rightarrow C^{-1} = \frac{-c}{ad - bc}$$

$$\rightarrow \left(\begin{array}{cc|c} ab & cb & 0 \\ ab & ad & a \end{array} \right) \Rightarrow (ad - bc)d^{-1} = a \Rightarrow d^{-1} = \frac{a}{ad - bc}$$

$$\begin{pmatrix} a^{-1} & b^{-1} \\ c^{-1} & d^{-1} \end{pmatrix} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

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$$2. \quad O = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\langle \varphi | O \psi \rangle = \langle O^+ \varphi | \psi \rangle$$

$$|O \psi\rangle = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} \psi_1 \cos \theta - \psi_2 \sin \theta \\ \psi_1 \sin \theta + \psi_2 \cos \theta \end{pmatrix}$$

$$\langle \varphi | O \psi \rangle = \varphi_1^* (\psi_1 \cos \theta - \psi_2 \sin \theta) + \varphi_2^* (\psi_1 \sin \theta + \psi_2 \cos \theta)$$

$$\langle \varphi | O \psi \rangle = \varphi_1^* (\psi_1 \cos \theta - \psi_2 \sin \theta) + \varphi_2^* (\psi_1 \sin \theta + \psi_2 \cos \theta) = \langle O^+ \varphi | \psi \rangle$$

$$\langle O^+ \varphi | = \begin{pmatrix} \varphi_1^* \cos \theta + \varphi_2^* \sin \theta \\ \varphi_2^* \cos \theta - \varphi_1^* \sin \theta \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \varphi_1^* \\ \varphi_2^* \end{pmatrix}$$

$$O^+ = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

$$3. \quad O^{-1} = \frac{1}{\det O} \cdot O^+ = \frac{1}{\cos^2 \theta + \sin^2 \theta} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

Задача 18

$$\langle (\hat{A}\hat{B})^+ \varphi | \psi \rangle = \langle \varphi | \hat{A}\hat{B} \psi \rangle = \langle \hat{A}^+ \varphi | \hat{B} \psi \rangle = \langle \hat{A}^+ \hat{B}^+ \varphi | \psi \rangle$$

$$(\hat{A}\hat{B})^+ = \hat{A}^+ \hat{B}^+$$

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Задача 19

$$\langle \varphi | \hat{C}^+ \hat{C} | \psi \rangle = \langle \hat{C} \varphi | \hat{C} \psi \rangle = \int_{-\infty}^{+\infty} |\hat{C} \psi|^2 dx \geq 0$$

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