

# YGH

## HX Camera 4X:P5,P14 (355°)

Function	Call	Submit
Patrol Route 1 (1-16 preset points)	Call 41	Submit 41 to clear patrol route 1
Patrol Route 2 (17-32 preset points)	Call 42	Submit 42 to clear patrol route 2
Patrol Route 3 (65-80 preset points)	Call 43	Submit 43 to clear patrol route 3
Patrol Route 4 (113-128 preset points)	Call 44	Submit 44 to clear patrol route 4
Patrol Route 5 (129-144 preset points)	Call 45	Submit 45 to clear patrol route 5
Patrol Route 6 (145-160 preset points)	Call 46	Submit 46 to clear patrol route 6
Patrol Route 7 (161-176 preset points)	Call 47	Submit 47 to clear patrol route 7
Patrol Route 8 (177-192 preset points)	Call 48	Submit 48 to clear patrol route 8
Preset Position: Enter "1" in "presetting" area→ click "Submit"; Turn the camera to other position→ enter "2" in "presetting" area→ click "Submit"; Turn the camera to other position→ enter "3" in "presetting" area→ click "Submit"; Until 16 points. Finally, enter "41" in "presetting" area, then click "Call".		
Sensor position (reset) PTZ calibration	Call 34	

Left limit	Turn to the leftmost position to be set	Submit 35
Right limit	Turn to the rightmost position to be set	Submit 36
Left and right limit scanning (on-off)	Call 38 to turn on	Submit 38 to clear limited position
	<b>Submit 38    clear + stop, then Call 38 to start horizontal scanning, and then Submit 38 to stop</b>	
PTZ initialization	Call 115 (not restore video and wireless functions)	Submit 40
Cruise stay time	Stay for 4 seconds at the cruise preset point	Submit 51
	Stay at the cruise preset point for 6 seconds	Submit 52
	Stay at the cruise preset point for 8 seconds	Submit 53
	Stay at the cruise preset point for 10 seconds	Submit 54
	Stay at the cruise preset point for 12 seconds	Submit 55
IR - Auto	Call 81	

IR - on	Call 82	
IR - off	Call 83	
355 ° horizontal scan	Call 99 to turn on	Submit 99 to stop
Enable horizontal 355 ° continuous scanning		
	Call 97	6 degrees / second
	Call 99	15 degrees / second
Idle action	Call 101: Preset position 1	
	Call 102: 355 degree scan (15 degrees / second)	
	Call 103: Limit Scan	The limited position needs to be set for operation
	Call 104: Patrol Route 1	
Clear all preset points		Submit 104
Guard position	Call 1, 105, 101	Submit 105 (close guard position)
Idle action	Call 105	Submit 105 to turn off
Clear preset point		Submit 104

IR sensitivity adjustment	Call 110, then call the preset parameter between 37-100	The smaller value of 37-100, the earlier it switch
Infrared light switch multiple setting of far and near light	Call 110, then call 123;	
	Call 246, then call 123.	
Ball machine rotation mode	Call 246 and then call 119	Forward
	Call 246 and then call 120	reverse
Automatic tracking (4x)		
automatic tracking	Open on APP or web interface	
Guard position setting	Call 1, 105, 101	Submit preset position 1