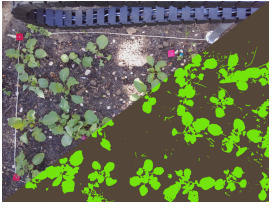Small set of noisy labels → Active contours → Small set of clean data → Classifier (*e.g.,SVM*) → Large set of (almost) clean data