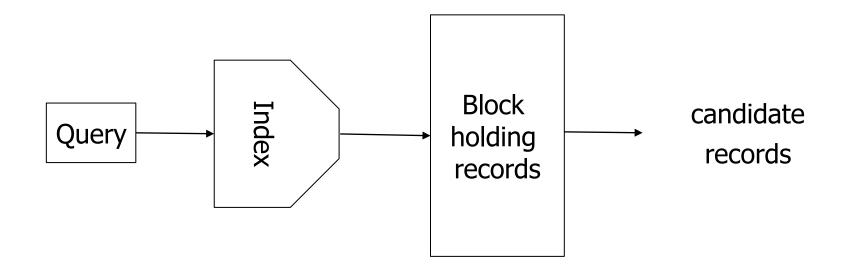
Indexing

Hector Garcia-Molina Mahmoud Sakr

Indexing



Topics

- Conventional indexes
- B-trees
- Hashing schemes

Sequential File

10	
20	

30	
40	

50	
60	

70	
80	

90	
100	

Dense Index

Sequential File

Dense Index = a pointer per key

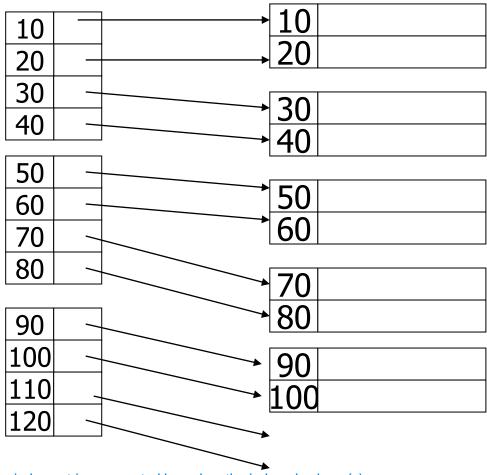
How to search for a key= 30?

How to search for a key= 25?

Can we use a dense index on a non-sequential file? yes

Why querying a dense index is more efficient than querying the sequential file?

memory / disk



In a dense index, an entry exists in the index for every record in the table, and the index entries are sorted based on the indexed column(s). helps the database system quickly navigate to the desired record when a search operation is performed based on the indexed column(s). The dense index is particularly useful for range queries or queries involving comparison operators (e.g., greater than, less than) on the indexed column(s). However, because it requires additional storage space for the index entries and may need maintenance during data modifications (inserts, updates, deletes)

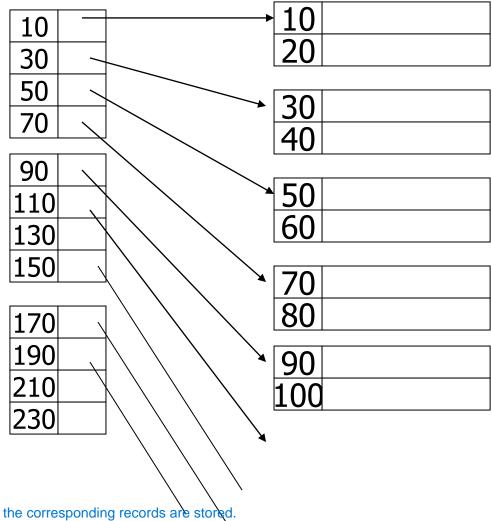
Sparse Index

Sequential File

Sparse index = a pointer per block

How to search for a key= 30? How to search for a key= 25?

Can we use a sparse index on a non-sequential file?



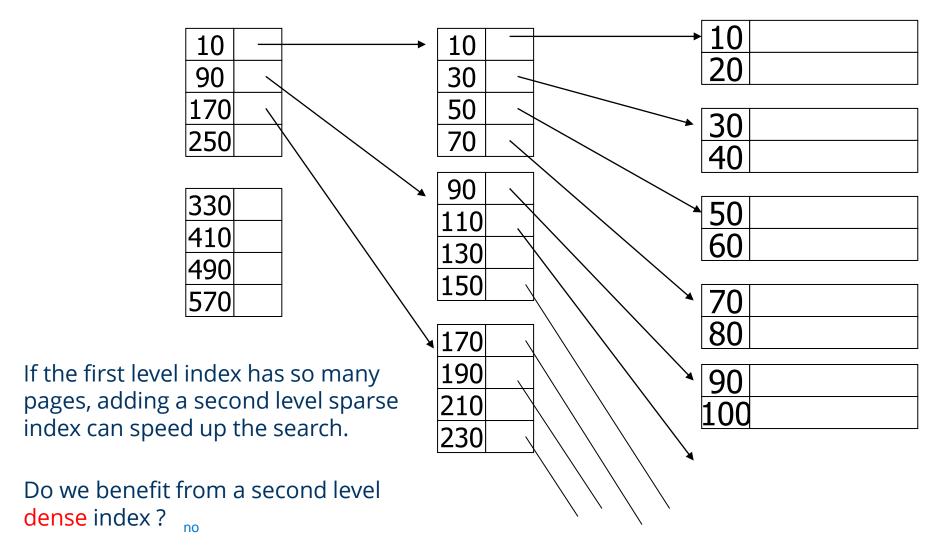
In a sparse index, the index entries point to specific locations in the table where the corresponding records are stored. This makes sparse indexes more compact than dense indexes because they do not require an entry for every record. However, it may take more time to locate a specific record if it does not have an entry in the index.

6

Sparse indexes are often used when the indexed column has a large number of distinct values, and creating an entry for every record would be impractical in terms of storage and maintenance.

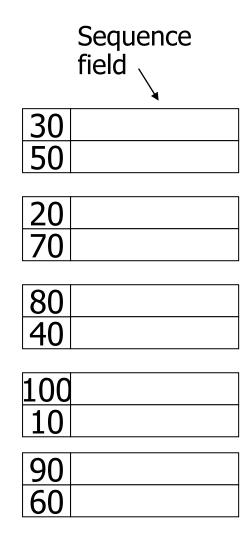
Sparse 2nd level

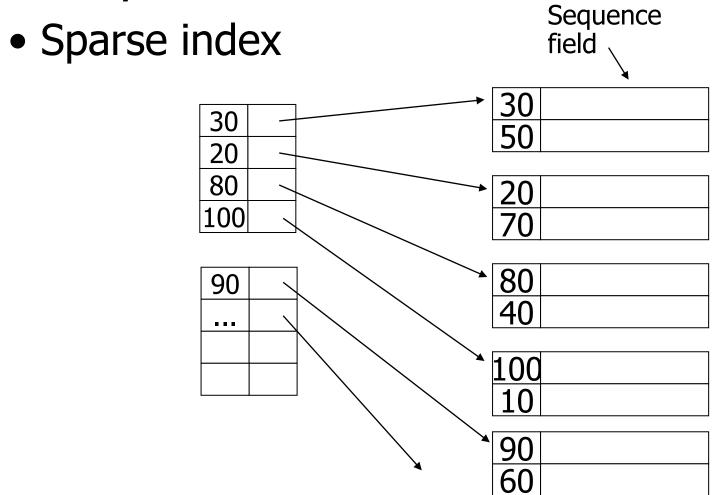
Sequential File

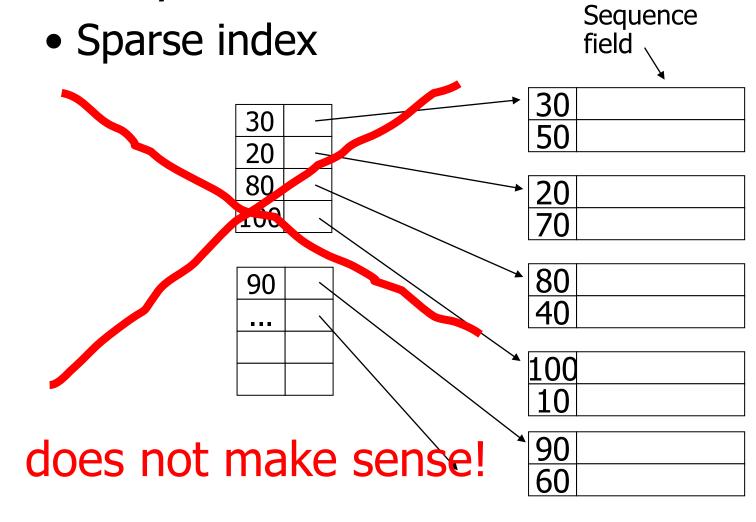


Sparse vs. Dense Tradeoff

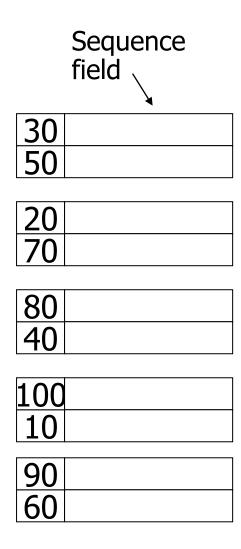
- Sparse: Less index space per record can keep more of index in memory
- Dense: Can tell if any record exists without accessing file



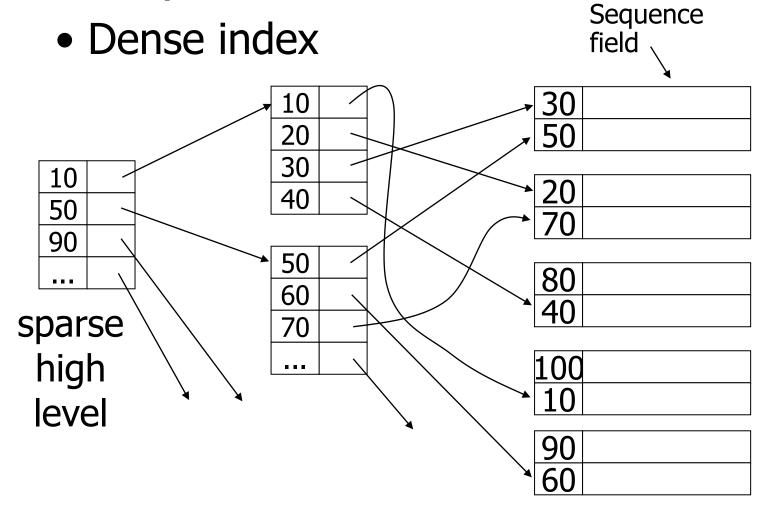




• Dense index



Sequence Dense index field



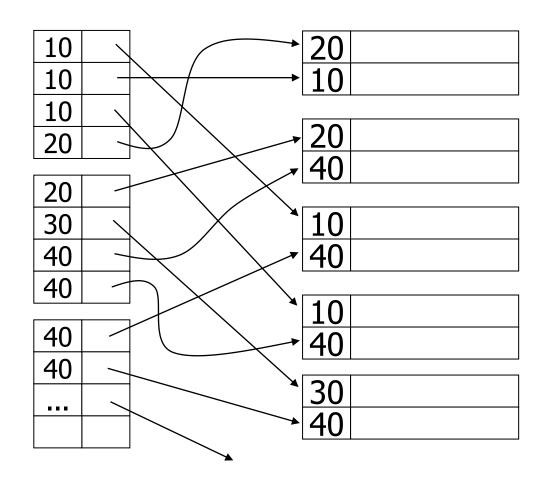
With secondary indexes:

- Lowest level is dense
- Other levels are sparse

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20	
20 10	
<u>20</u> 40	
40	
10	
10 40	
10	
10 40	
30 40	
40	

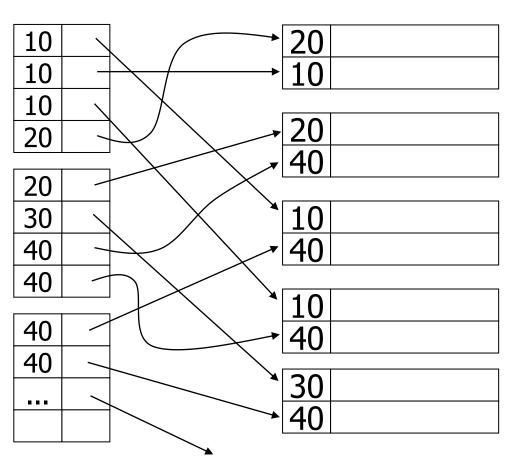
one option...



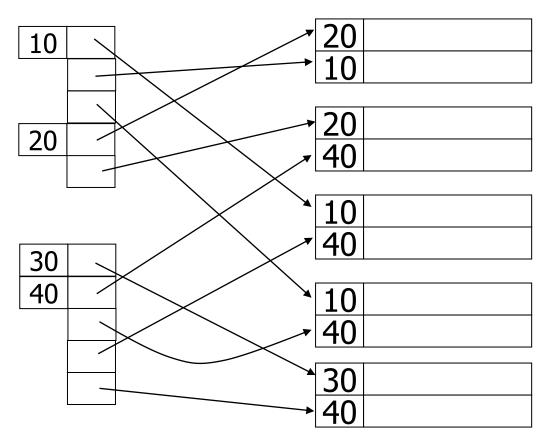
one option...

Problem: excess overhead!

- disk space
- search time

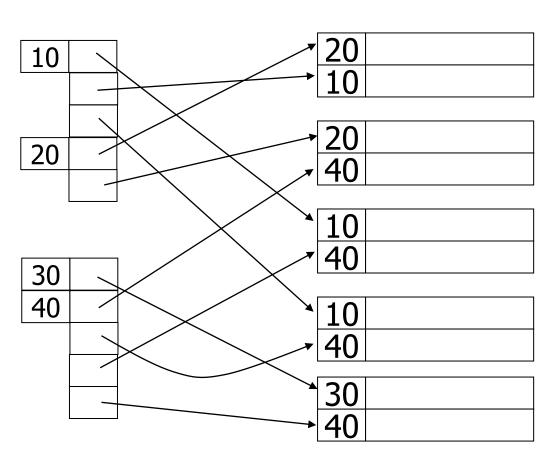


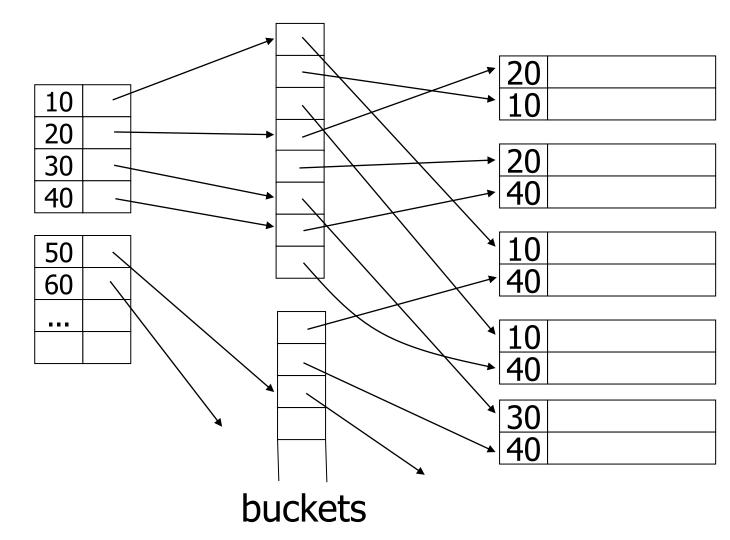
another option...



another option...

Problem:
variable size
records in
index!





Index is fixed size

Why "bucket" idea is useful

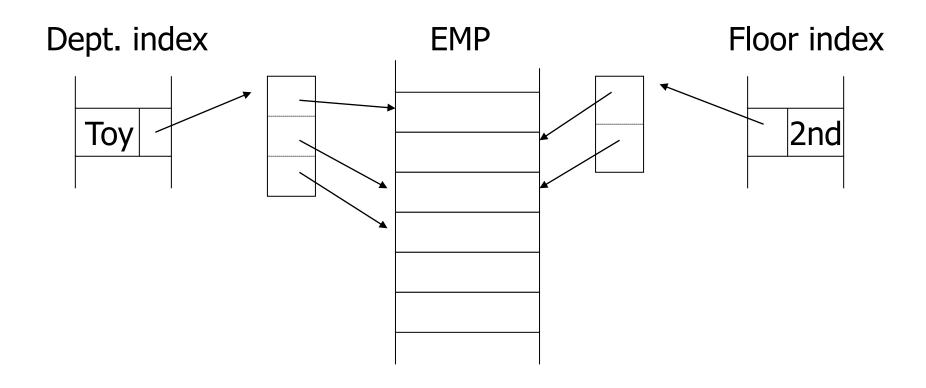
<u>Indexes</u> Records

Name: primary EMP (name,dept,floor,...)

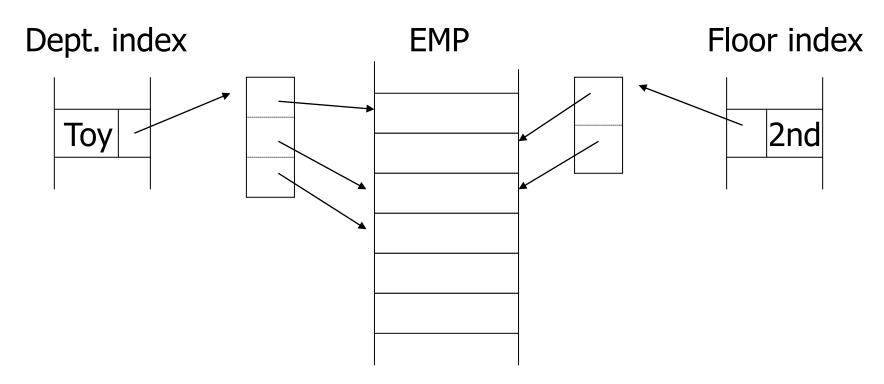
Dept: secondary

Floor: secondary

Query: Get employees in (Toy Dept) \(\lambda \) (2nd floor)



Query: Get employees in (Toy Dept) \(\cap \) (2nd floor)



→ Intersect toy bucket and 2nd Floor bucket to get set of matching EMP's

Conventional indexes

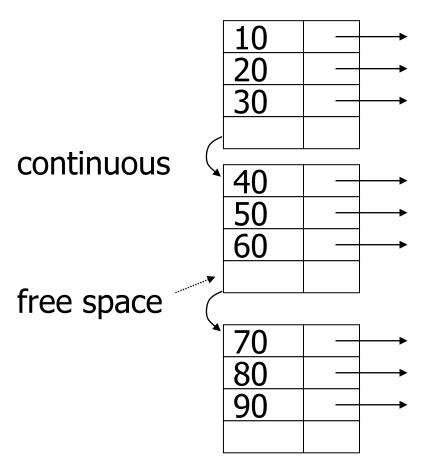
Advantage:

- Simple
- Index is sequential file good for scans

Disadvantage:

- Inserts expensive, or
- Lose sequentiality & balance

Example Index (sequential)



Example Index (sequential) continuous free space <u>70</u> overflow area (not sequential)

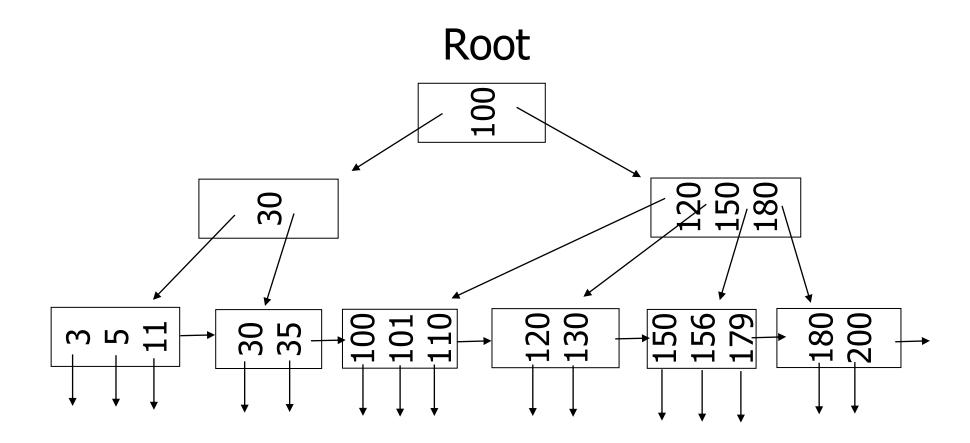
Outline:

- Conventional indexes
- B-Trees ⇒ NEXT
- Hashing schemes

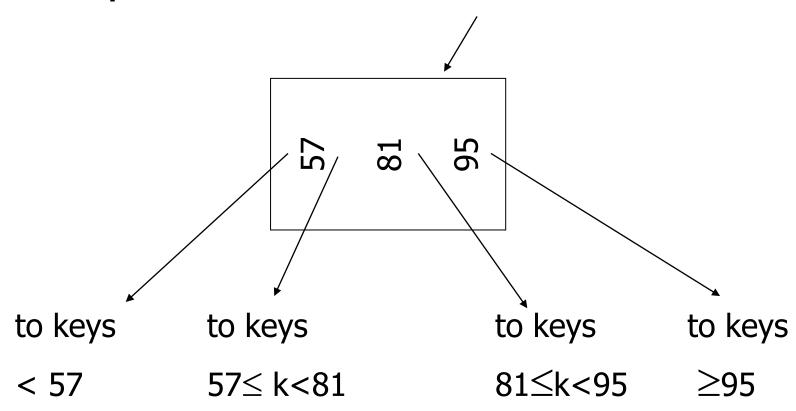
- NEXT: Another type of index
 - Give up on sequentiality of index
 - Try to get "balance"

B+Tree Example

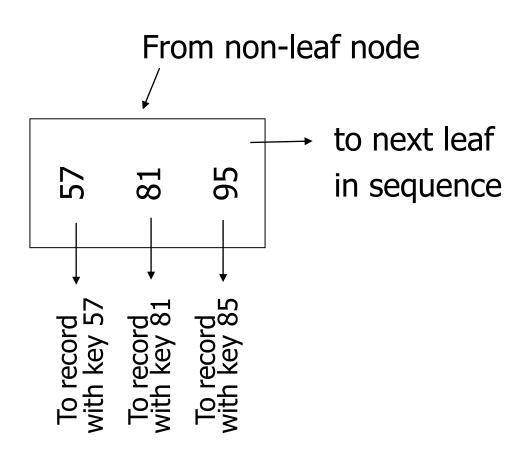
n=3



Sample non-leaf



Sample leaf node:



```
Size of nodes: n+1 pointers
n keys
```

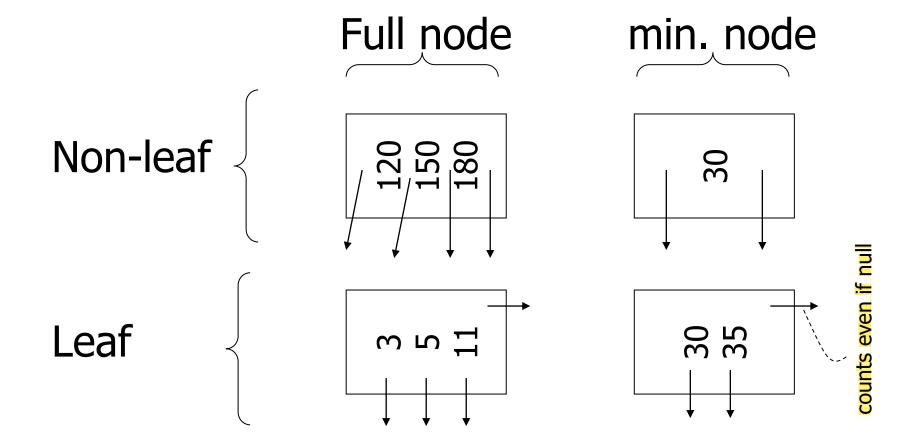
Don't want nodes to be too empty

Use at least

Non-leaf: $\lceil (n+1)/2 \rceil$ pointers

Leaf: $\lfloor (n+1)/2 \rfloor$ pointers to data

n=3



B+tree rules tree of order n

- (1) All leaves at same lowest level (balanced tree)
- (2) Pointers in leaves point to records except for "sequence pointer"

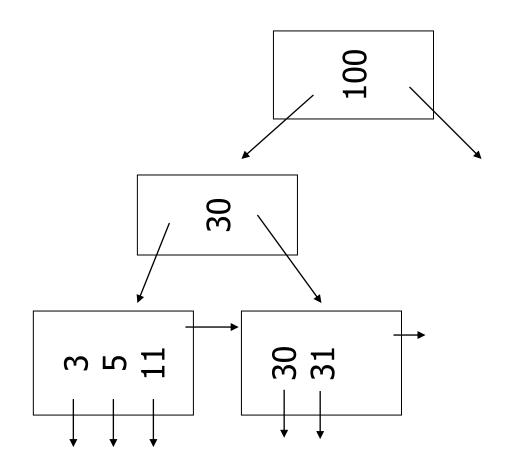
(3) Number of pointers/keys for B+tree

	Max ptrs	Max keys	Min ptrs→data	Min keys
Non-leaf (non-root)	n+1	n	「(n+1)/2	「(n+1)/2 - 1
Leaf (non-root)	n+1	n	[(n+1)/2]	[(n+1)/2]
Root	n+1	n	1	1

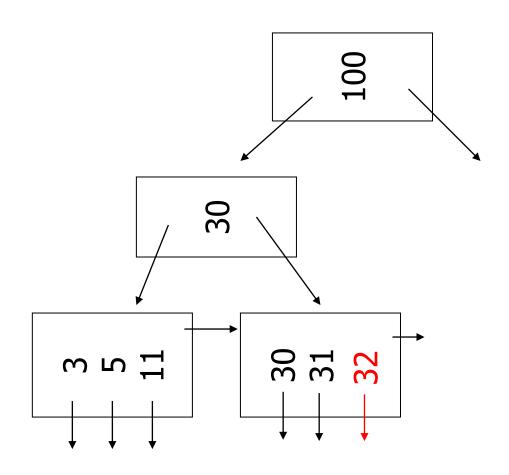
Insert into B+tree

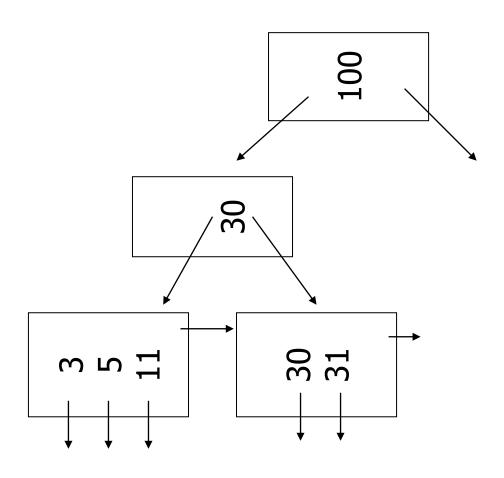
- (a) simple case
 - space available in leaf
- (b) leaf overflow
- (c) non-leaf overflow
- (d) new root

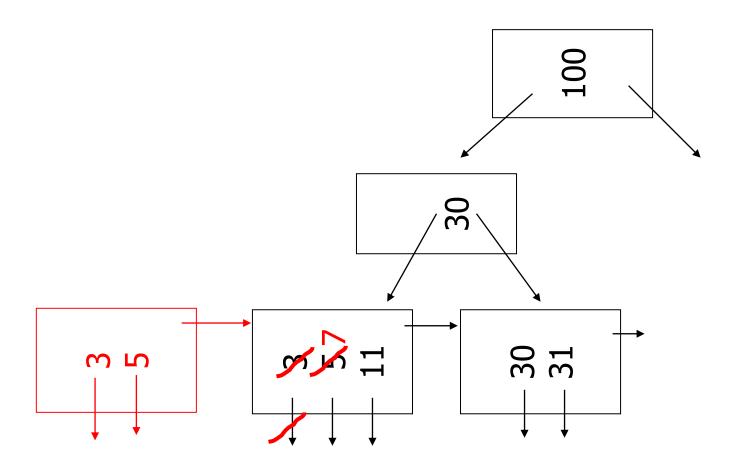




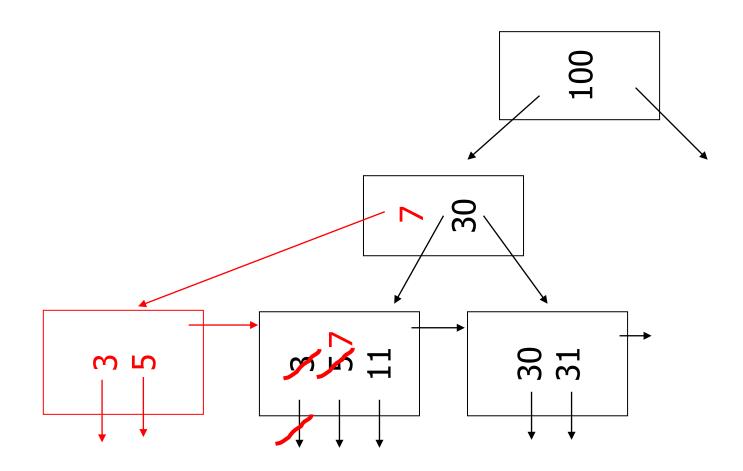


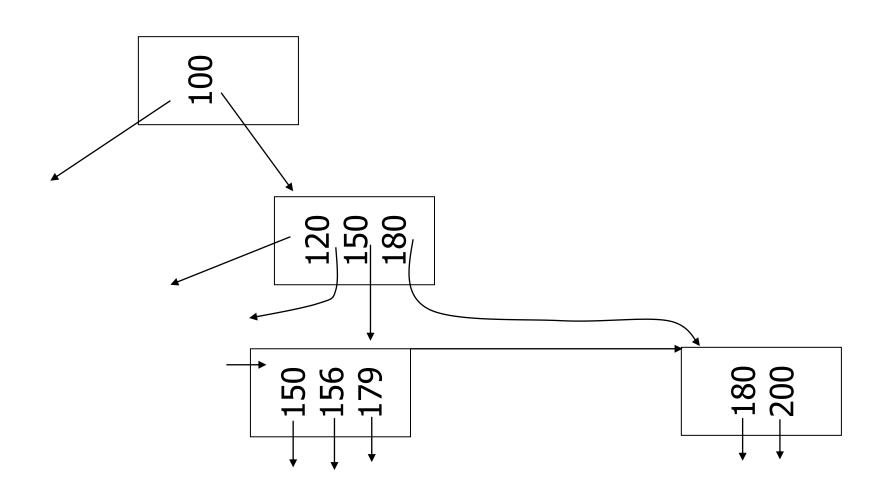


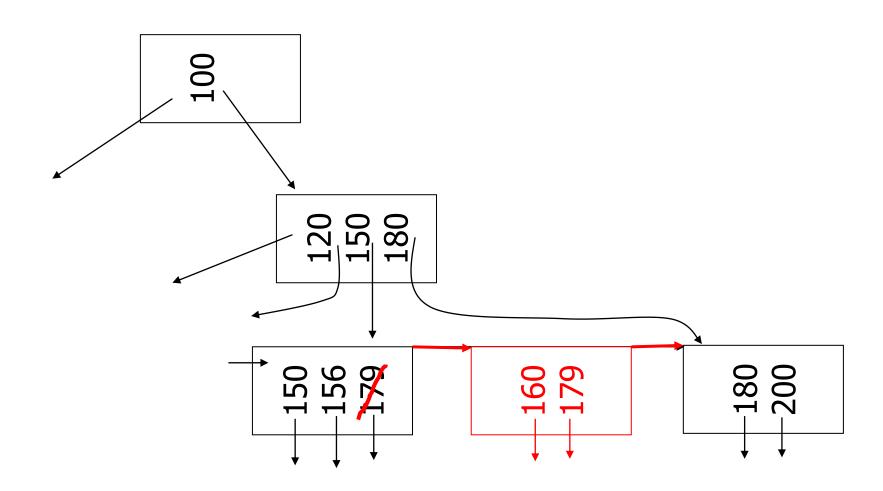




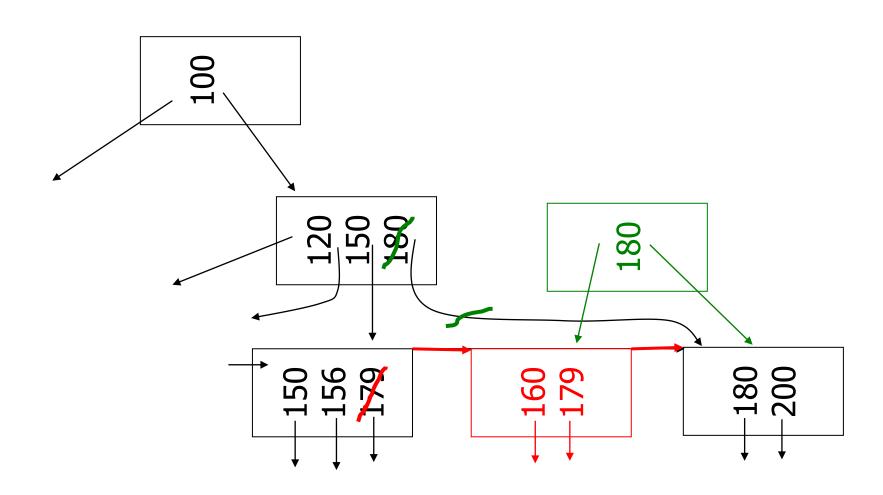




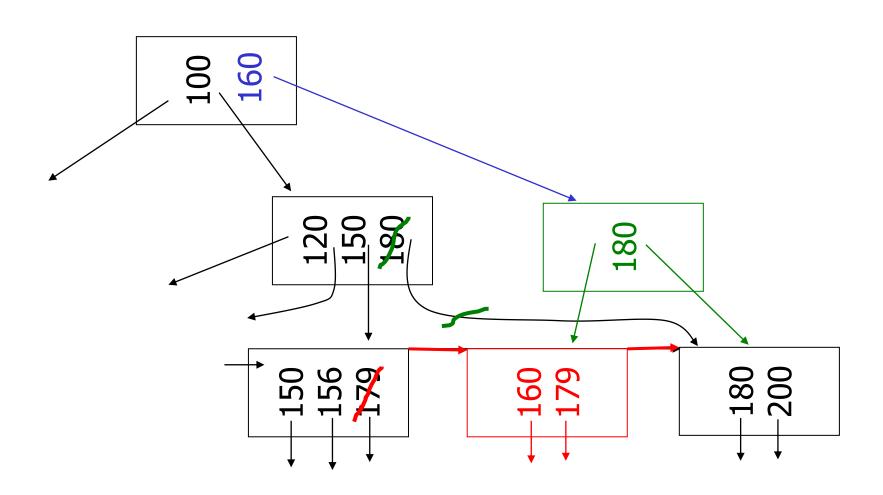


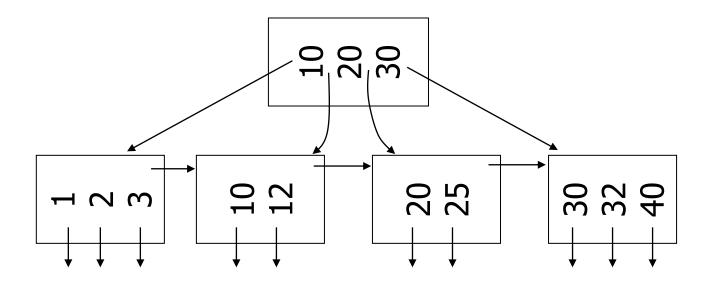


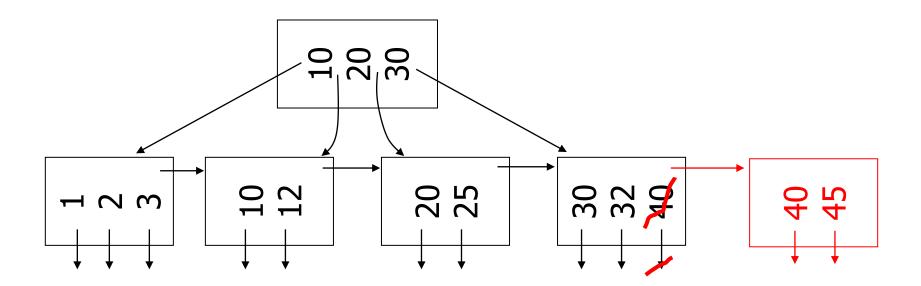


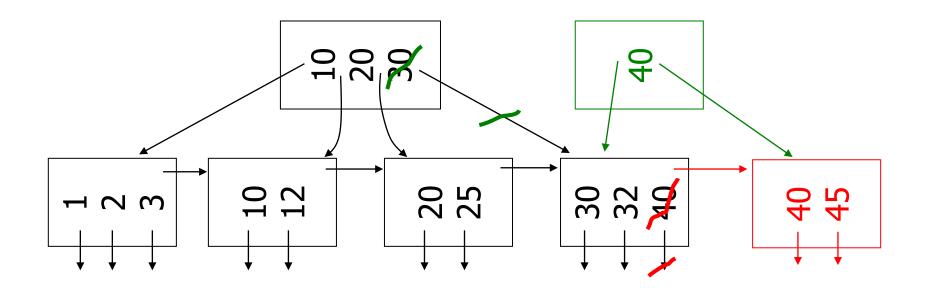


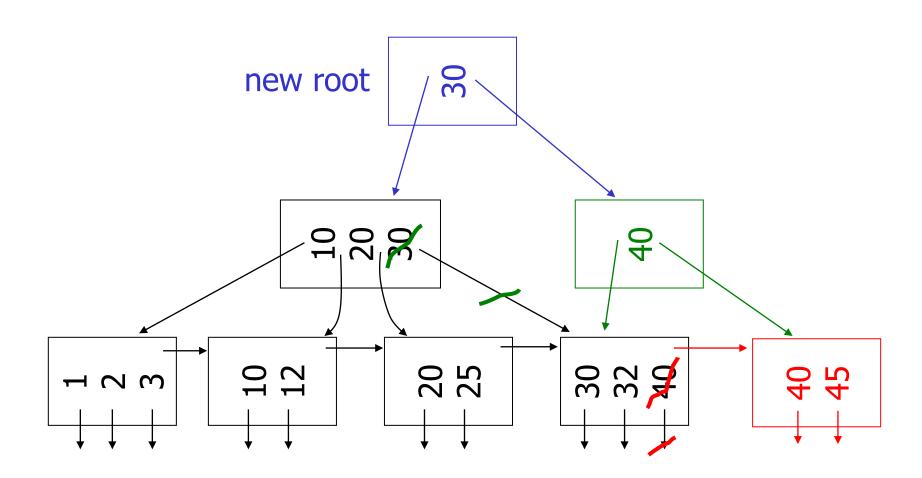










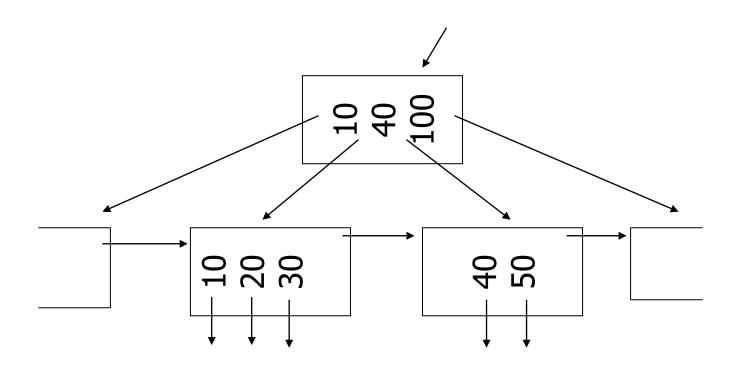


<u>Deletion from B+tree</u>

- (a) Simple case no example
- (b) Coalesce with neighbor (sibling)
- (c) Re-distribute keys
- (d) Cases (b) or (c) at non-leaf

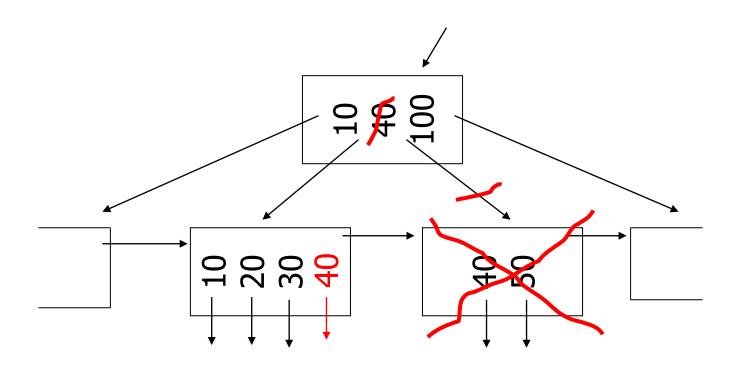
(b) Coalesce with sibling

- Delete 50



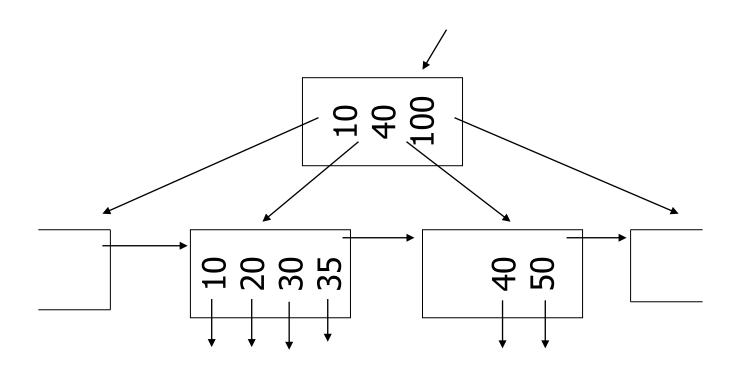
(b) Coalesce with sibling

- Delete 50



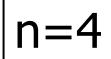
(c) Redistribute keys

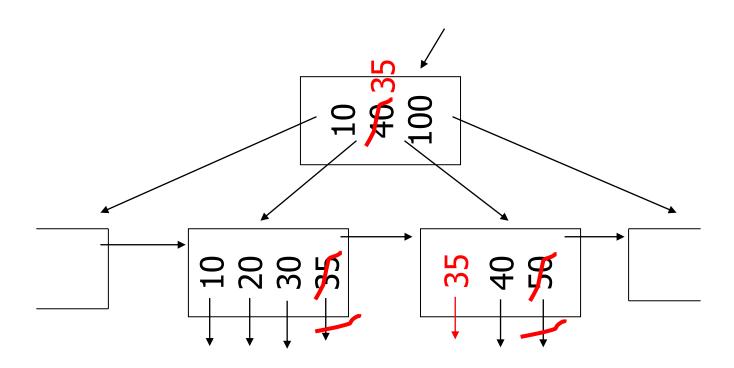
- Delete 50



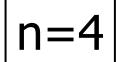
(c) Redistribute keys

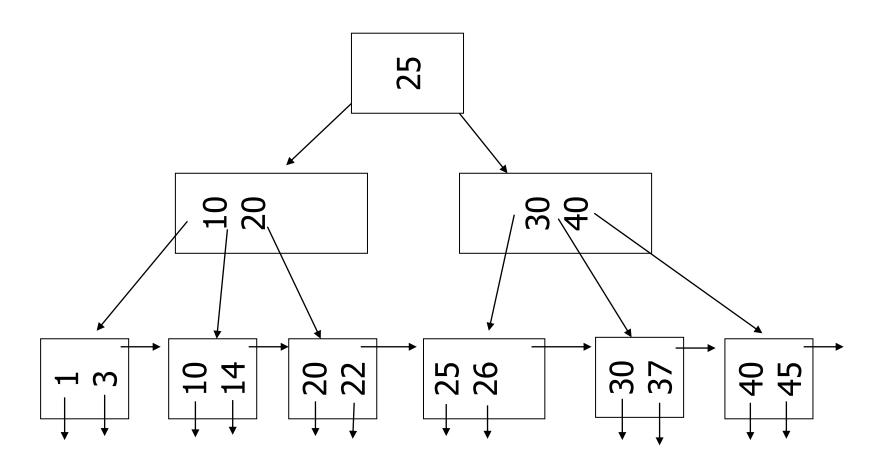
- Delete 50



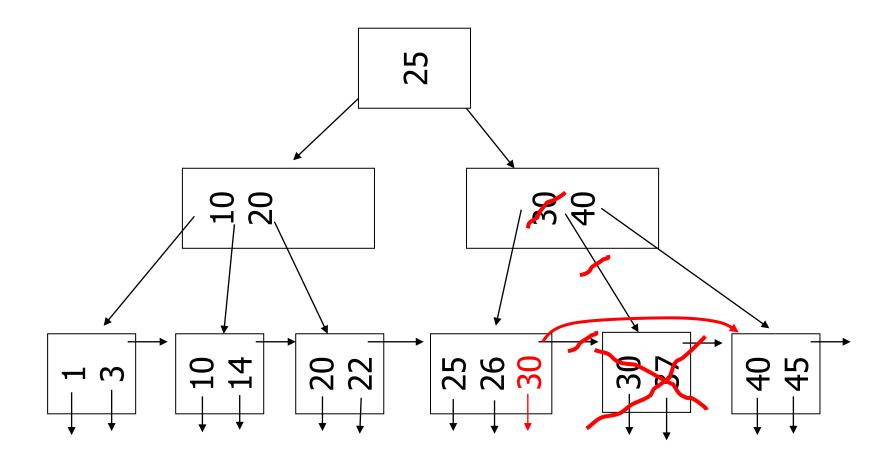


- Delete 37

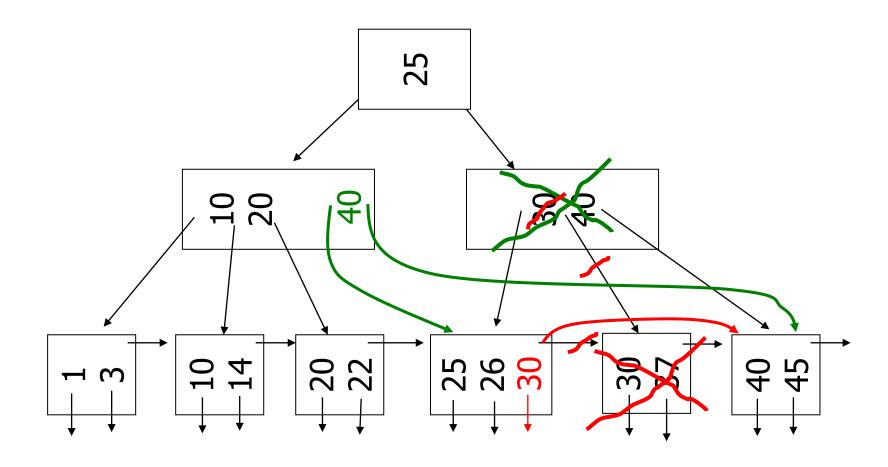




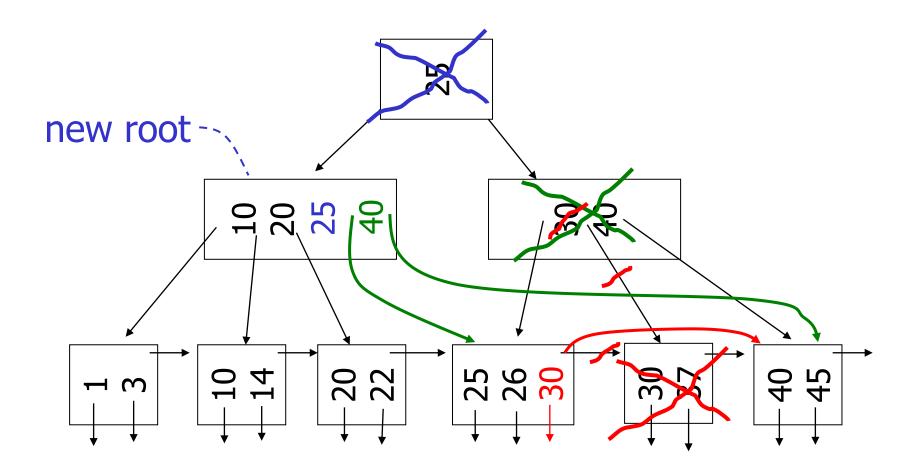
- Delete 37



- Delete 37



- Delete 37



B+tree deletions in practice

- Often, coalescing is <u>not</u> implemented
 - Too hard and not worth it!

Outline/summary

- Conventional Indexes
 - Sparse vs. dense
 - Primary vs. secondary
- B trees
- Hashing schemes (recommended reading, not mandatory)

The slides in this lecture are taken from:

 Hector Garcia-Molina, CS 245: Database System Principles, Notes 4: Indexing.

Reading

 Héctor García-Molina, Jeffrey Ullman, and Jennifer Widom. Database Systems: The Complete Book