

A collection of objects is arranged on a light-colored, textured surface. In the top left, a portion of a chessboard with a checkered pattern and several chess pieces is visible. Below the chessboard, there are two medals: one with a red ribbon and a star-shaped center, and another with a blue ribbon and a star-shaped center. A pair of thin-framed glasses lies diagonally across the middle. In the bottom left corner, a small, round, silver-colored compass is visible. The text 'Graph Topological sort' is written in a serif font on the right side of the image.

# Graph Topological sort

Notes by Yan Yan



# Topological Sort

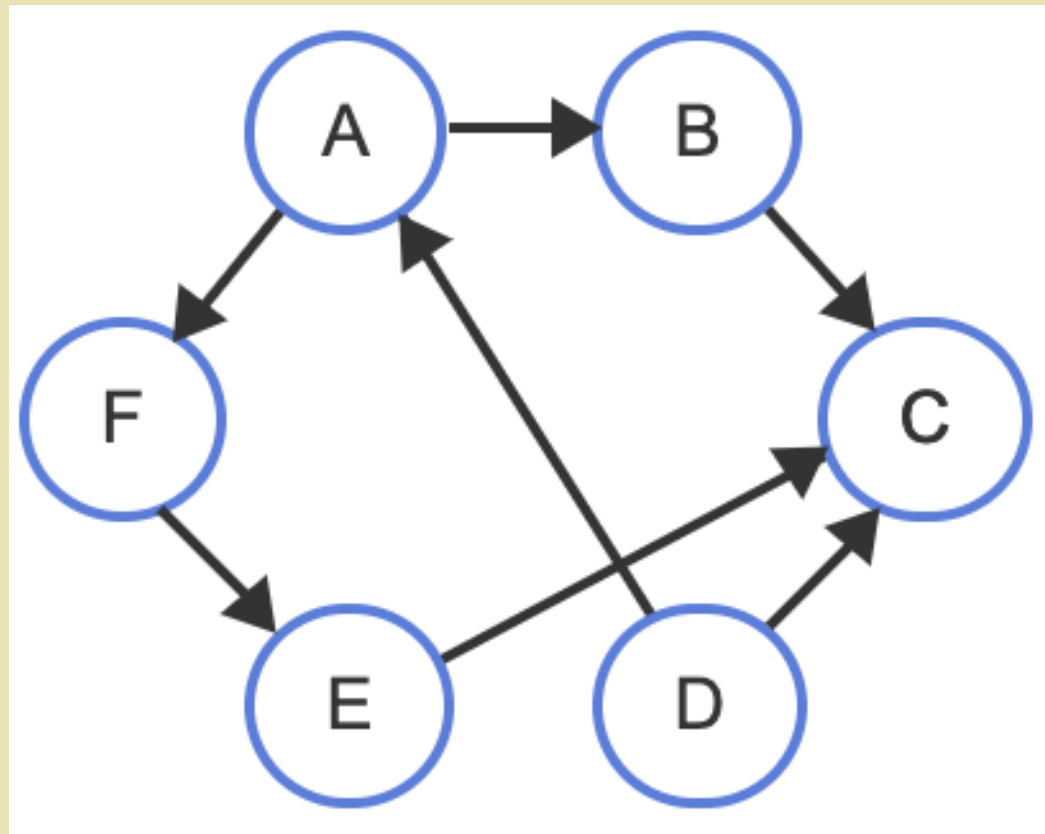
- ◆ Topological ordering is an operation on **directed acyclic graphs (DAGs)**.
- ◆ A **topological ordering** is a list of the DAG's vertices such that for every edge from a vertex  $X$  to a vertex  $Y$ ,  $X$  comes before  $Y$  in the list.
  - May not be unique
- ◆ A **topological sort** produces a list of topological ordering
- ◆ Applications: scheduling of tasks from the given dependencies among tasks.

2     – a student can have an ordered list of courses to take.



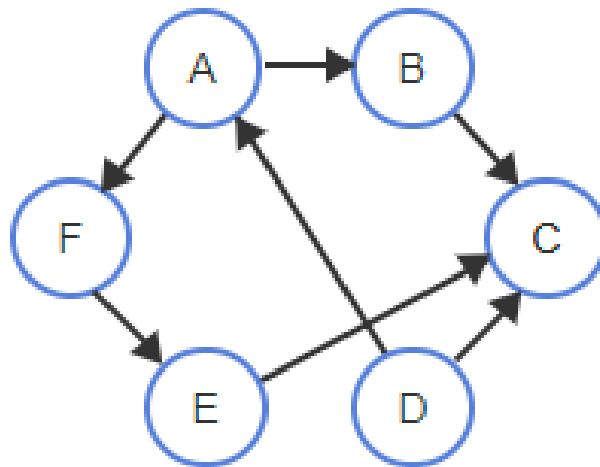
# Topological Sort -- Example

- ◆ Is it a topological sort?
- ◆ C, D, A, F, B, E



# Topological Sort -- Example

- ◆ Analysis of each edge in the graph determines if an ordering of vertices is a valid topological sort.



Proposed ordering: C, D, A, F, B, E

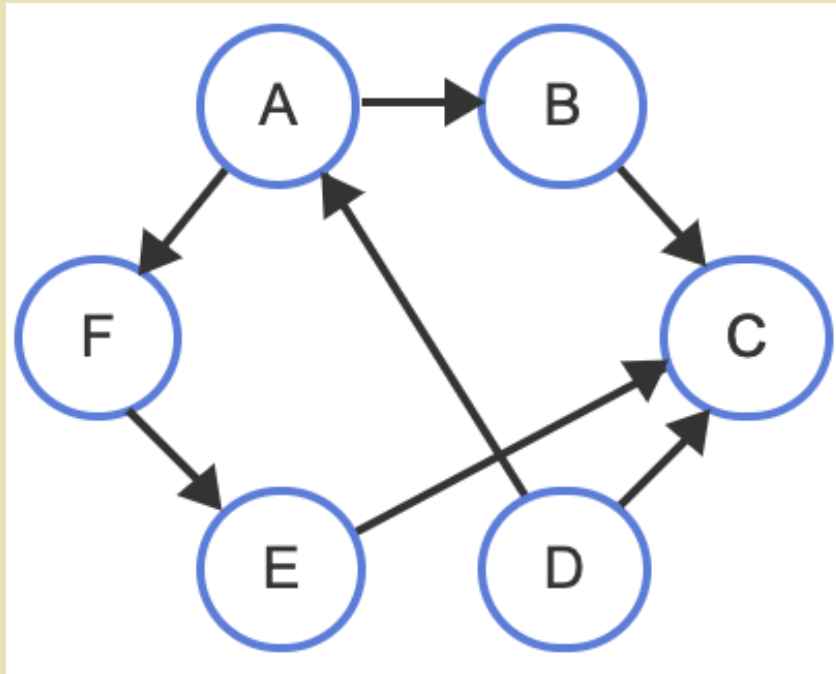
1 2  
▼ ▼

Edge (X to Y)	X before Y in ordering?
A to B	Yes
A to F	Yes
B to C	No
D to A	Yes
D to C	No
E to C	No
F to E	Yes

# Topological Sort -- Example

- ◆ Is it a topological sort?
- ◆ D, A, F, E, B, C

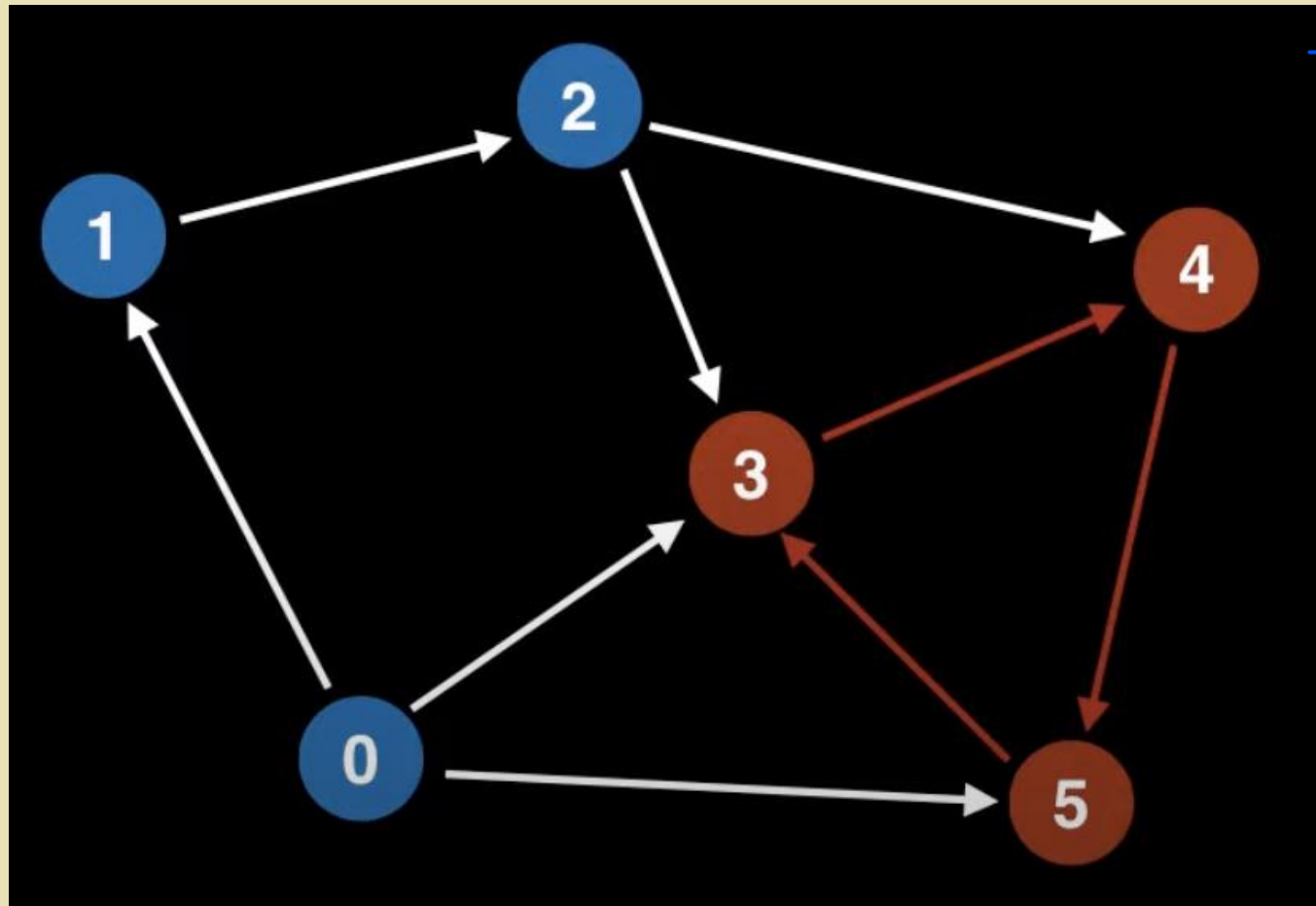
Yes



- ◆ If you check the edges of D and C, what can you find?

# Topological Sort -- Example

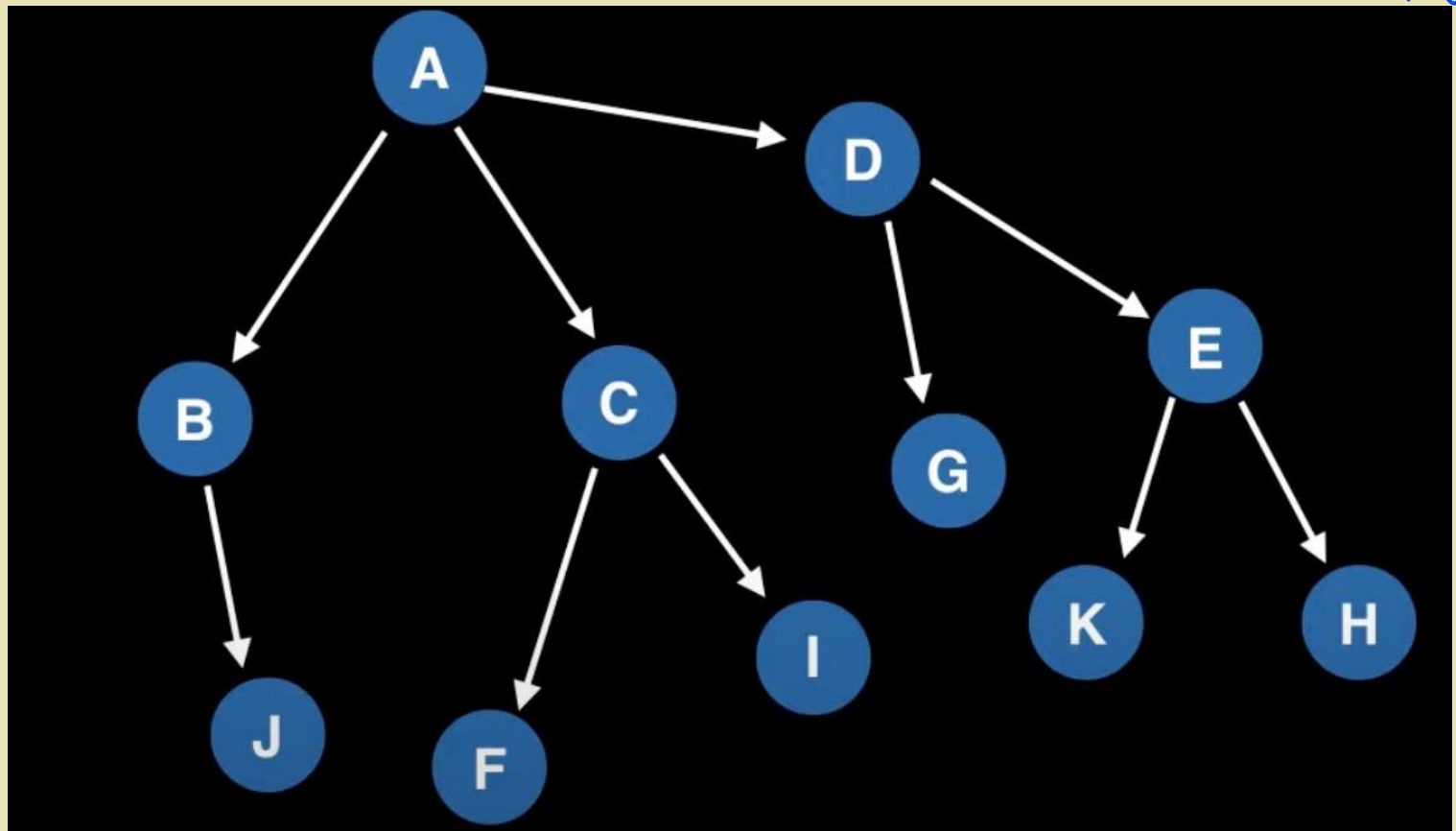
- ◆ Will cyclic graph have topological ordering? *NO*





# Topological Sort -- Example

- ◆ Will a (directed) tree have topological ordering? *Yes*

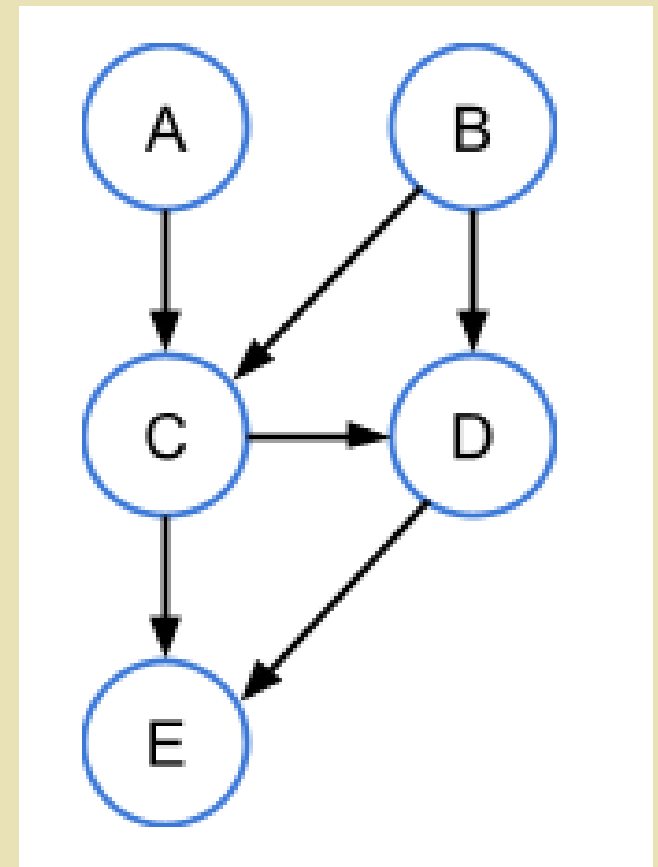


# Topological Sort -- Exercise

- ◆ Determine if each of the following is a topological sort for the given graph

1. A, B, C, D, E *Y*
2. E, D, C, B, A *N*
3. D, E, A, B, C *N*
4. B, A, C, D, E *X*

- ◆ Check each edge!







# Topological Sort Algorithm

- ◆ Can be done using **source removal**.
- ◆ A source is **a vertex with no incoming edges**.
- ◆ Each step, a source is identified. The source is removed from the graph along with all its outgoing edges. The vertex is then added at the end of the list.
- ◆ The process continues until all vertices are removed from the graph.



# Topological Sort Algorithm

- ◆ The topological sort algorithm uses three lists:
  - a **results** list that will contain a topological sort of vertices: start as empty
  - a **no-incoming-edges** list of vertices with no incoming edges (source)
  - a remaining-edges list: start as all edges



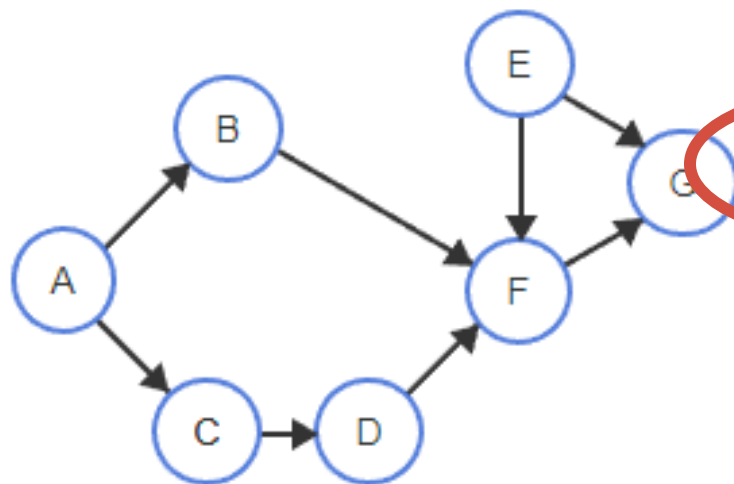
# Topological Sort Algorithm

- ◆ while the no-incoming-edges vertex list is not empty
  - a vertex is removed from the no-incoming-edges list and added to the result list.
  - a temporary list is built by removing all edges in the remaining-edges list that are outgoing from the removed vertex.
  - For each edge  $currentE$  in the temporary list, the number of edges in the remaining-edges list that are incoming to  $currentE$ 's terminating vertex are counted.
  - If the incoming edge count is 0, then  $currentE$ 's terminating vertex is added to the no-incoming-edges vertex list.



# Topological Sort Algorithm

```
GraphTopologicalSort(graph) {  
    resultList = empty list of vertices  
    noIncoming = list of all vertices with no incoming edges  
    remainingEdges = list of all edges in the graph  
  
    while (noIncoming is not empty) {  
        currentV = remove any vertex from noIncoming  
        Add currentV to resultList  
        outgoingEdges = remove currentV's outgoing edges from remainingEdges  
        for each edge currentE in outgoingEdges {  
            inCount = GraphGetIncomingEdgeCount(remainingEdges, currentE→toVertex)  
            if (inCount == 0)  
                Add currentE→toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

noIncoming:

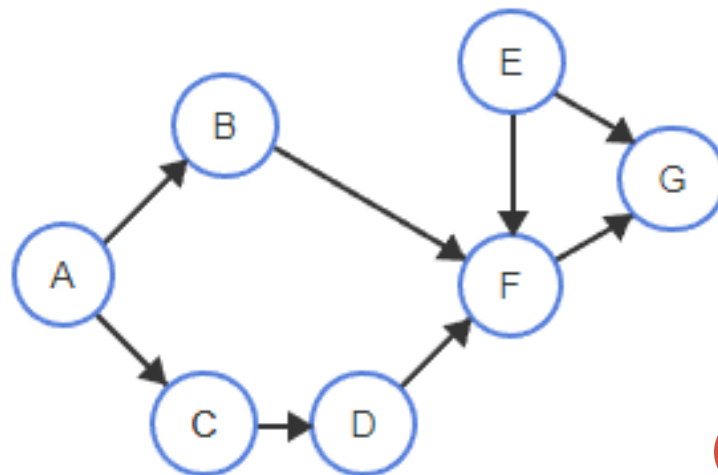
A E

remainingEdges:

AB AC BF CD DF EF EG FG

# Topological Sort Algorithm

```
GraphTopologicalSort(graph) {  
    resultList = empty list of vertices  
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            if (inCount == 0)  
                Add currentE→toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E

noIncoming:

A

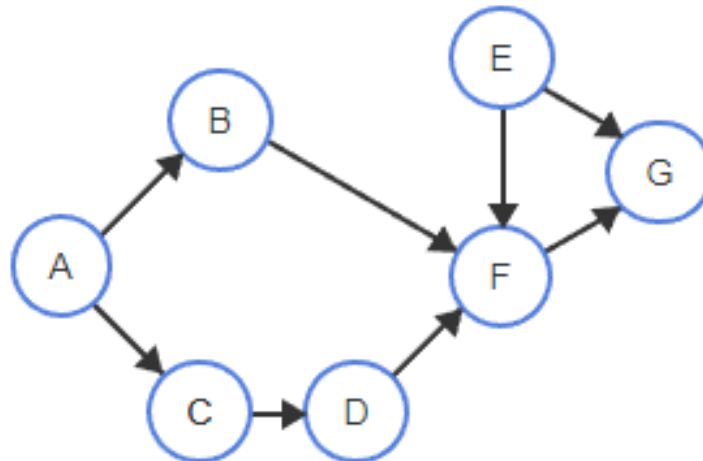
remainingEdges:

AB AC BF CD DF EF EG FG

currentV: E

# Topological Sort Algorithm

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            if (inCount == 0)  
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        }  
    }  
    return resultList  
}
```



resultList:

E

noIncoming:

A

remainingEdges:

AB AC BF CD DF FG

currentV: E

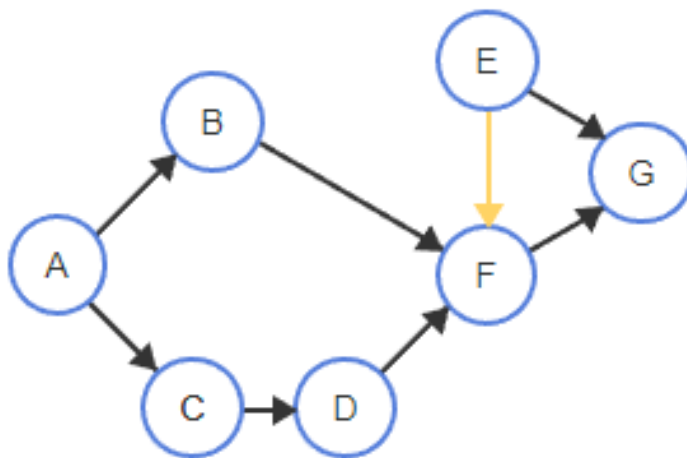
outgoingEdges:

EF EG



# Topological Sort Algorithm

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GraphTopologicalSort(graph) {  
    resultList = empty list of vertices  
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            if (inCount == 0)  
                Add currentE→toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E

noIncoming:

A

remainingEdges:

AB AC BF CD DF FG

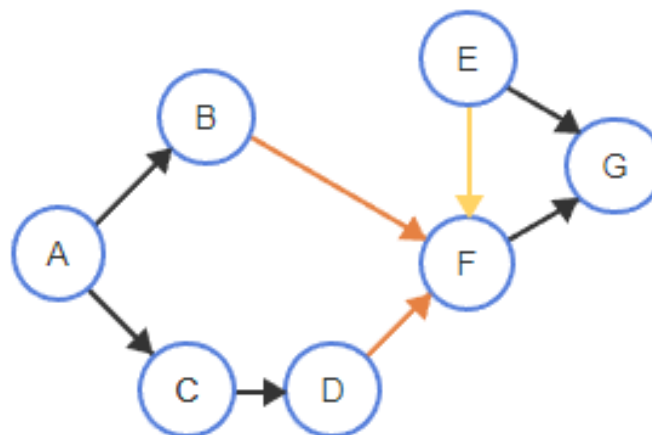
currentV: E

outgoingEdges:

EF EG

# Topological Sort Algorithm

```
GraphTopologicalSort(graph) {  
    resultList = empty list of vertices  
    noIncoming = list of all vertices with no incoming edges  
    remainingEdges = list of all edges in the graph  
  
    while (noIncoming is not empty) {  
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        for each edge currentE in outgoingEdges {  
            inCount = GraphGetIncomingEdgeCount(remainingEdges, currentE→toVertex)  
            if (inCount == 0)  
                Add currentE→toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E

noIncoming:

A

remainingEdges:

AB AC BF CD DF FG

currentV: E

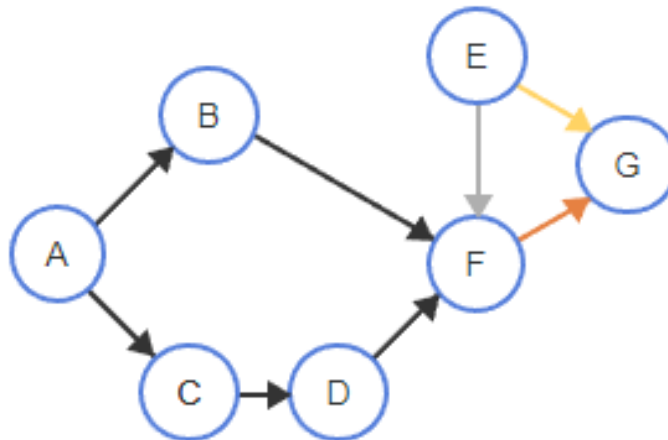
inCount: 2

outgoingEdges:

EF EG

# Topological Sort Algorithm

```
GraphTopologicalSort(graph) {  
    resultList = empty list of vertices  
    noIncoming = list of all vertices with no incoming edges  
    remainingEdges = list of all edges in the graph  
  
    while (noIncoming is not empty) {  
        currentV = remove any vertex from noIncoming  
        Add currentV to resultList  
        outgoingEdges = remove currentV's outgoing edges from remainingEdges  
        for each edge currentE in outgoingEdges {  
            inCount = GraphGetIncomingEdgeCount(remainingEdges, currentE-->toVertex)  
            if (inCount == 0)  
                Add currentE-->toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E

noIncoming:

A

remainingEdges:

AB AC BF CD DF FG

currentV: E

inCount: 1

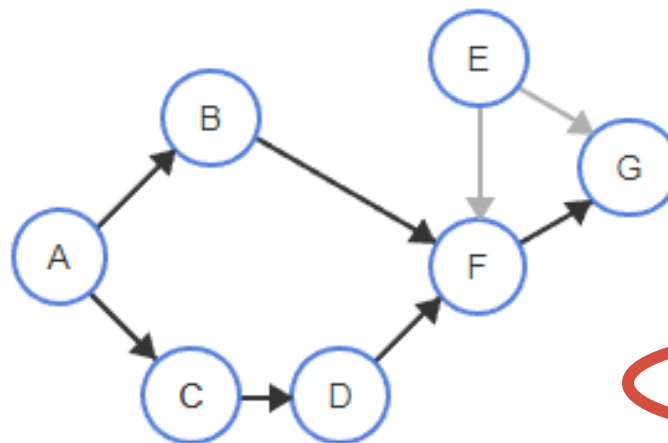
outgoingEdges:

EF EG



# Topological Sort Algorithm

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GraphTopologicalSort(graph) {  
    resultList = empty list of vertices  
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            if (inCount == 0)  
                Add currentE.toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E A

noIncoming:

remainingEdges:

BF CD DF FG

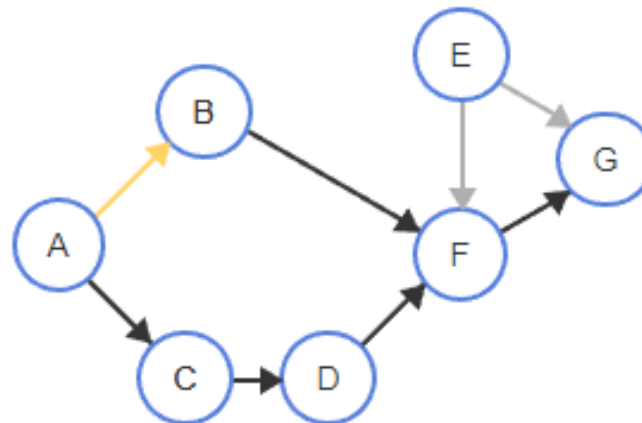
currentV: A

outgoingEdges:

AB AC

# Topological Sort Algorithm

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GraphTopologicalSort(graph) {  
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            inCount = GraphGetIncomingEdgeCount(remainingEdges, currentE->toVertex)  
            if (inCount == 0)  
                Add currentE->toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E A

noIncoming:

remainingEdges:

BF CD DF FG

currentV: A

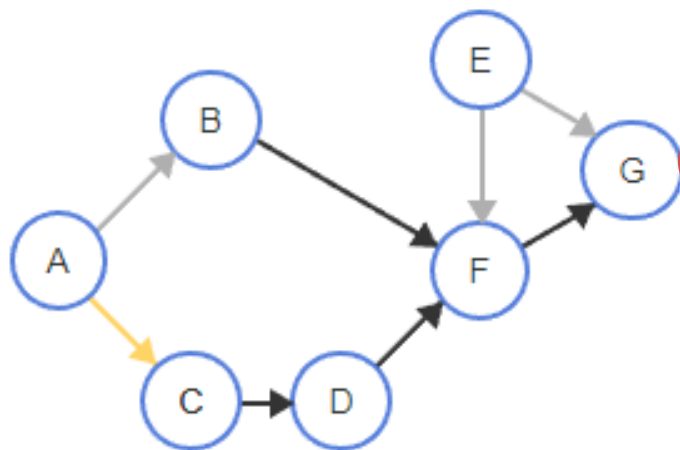
inCount: 0 == 0

outgoingEdges:

AB AC

# Topological Sort Algorithm

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            if (inCount == 0)  
                Add currentE->toVertex to noIncoming  
        }  
    }  
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}
```



resultList:

E A

noIncoming:

B

remainingEdges:

BF CD DF FG

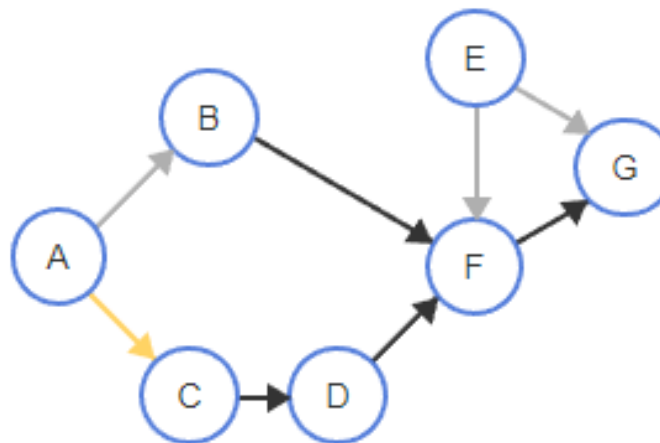
currentV: A      inCount: 0 == 0

outgoingEdges:

AB AC

# Topological Sort Algorithm

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        }  
    }  
    return resultList  
}
```



resultList:

E A

noIncoming:

B C

remainingEdges:

BF CD DF FG

currentV: A

inCount: 0

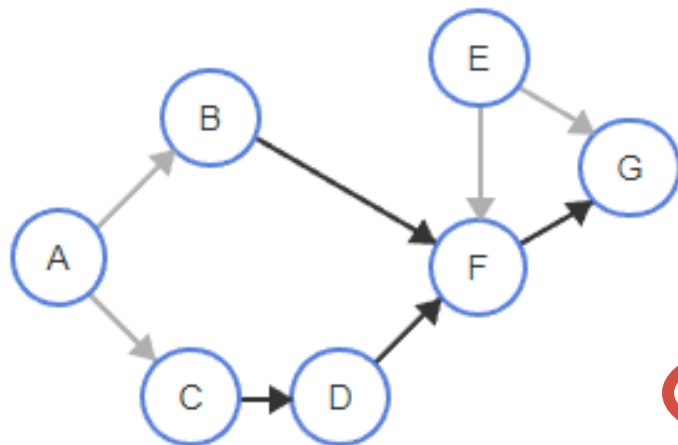
outgoingEdges:

AB AC



# Topological Sort Algorithm

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        }  
    }  
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}
```



resultList:

E A C

noIncoming:

B

remainingEdges:

BF DF FG

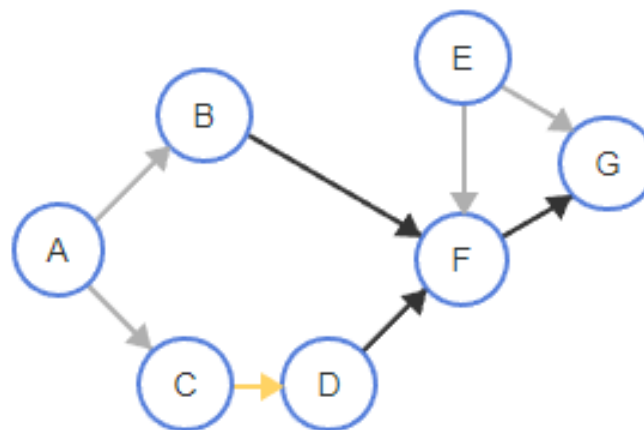
currentV: C

outgoingEdges:

CD

# Topological Sort Algorithm

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}
```



resultList:

E A C

noIncoming:

B D

remainingEdges:

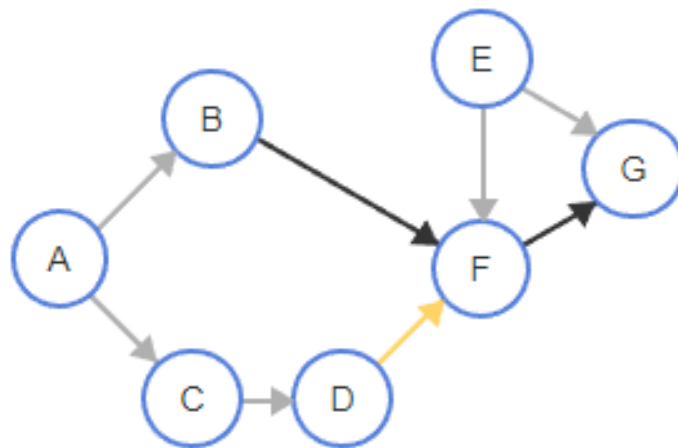
BF DF FG

currentV:

outgoingEdges:

# Topological Sort Algorithm

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resultList:

E A C D

noIncoming:

B

remainingEdges:

BF FG

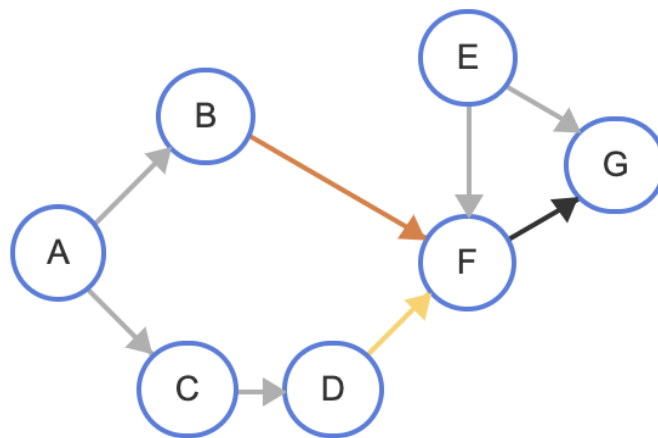
currentV: D

outgoingEdges:

DF

# Topological Sort Algorithm

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    }  
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}
```



resultList:

E A C D

noIncoming:

B

remainingEdges:

BF FG

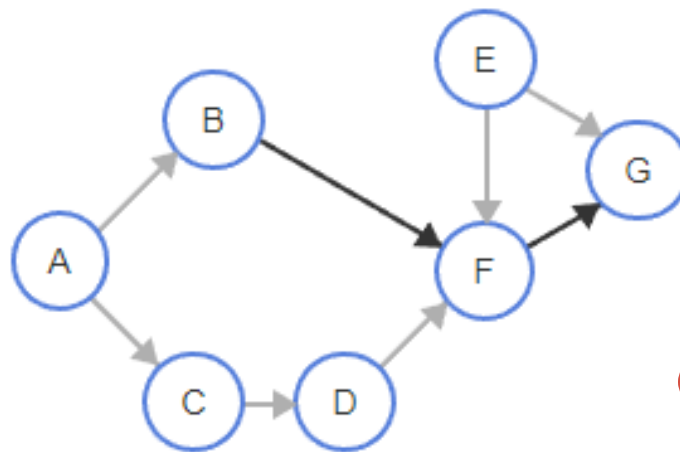
currentV: D      inCount: 1 != 0

outgoingEdges:

DF

# Topological Sort Algorithm

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    }  
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}
```



resultList:

E A C D B

noIncoming:

remainingEdges:

BF FG

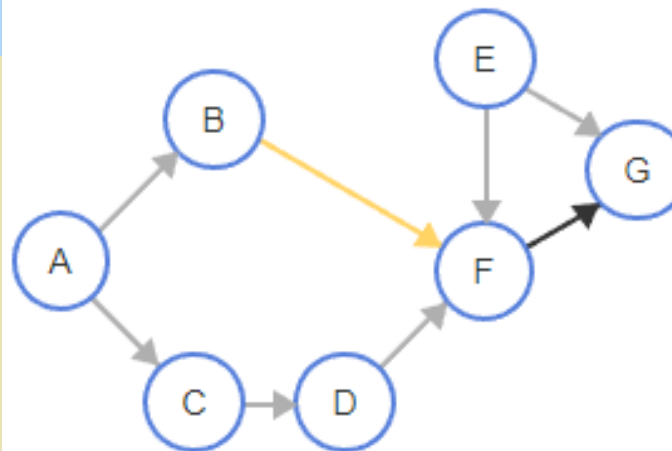
currentV: B

outgoingEdges:



# Topological Sort Algorithm

```
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            if (inCount == 0)  
                Add currentE->toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E A C D B

noIncoming:

F

remainingEdges:

FG

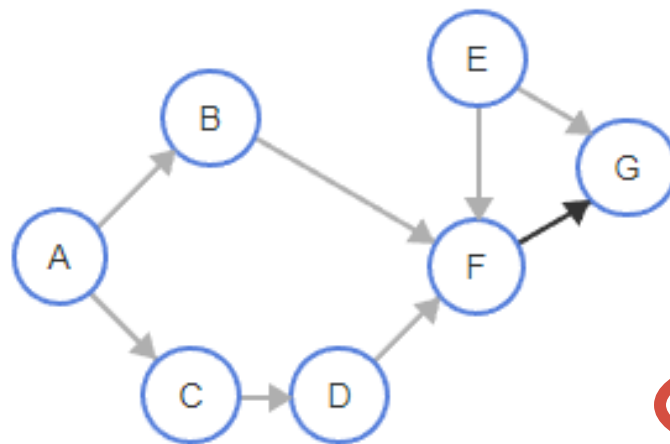
currentV: B      inCount: 0

outgoingEdges:

BF

# Topological Sort Algorithm

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            if (inCount == 0)  
                Add currentE→toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E A C D B F

noIncoming:

remainingEdges:

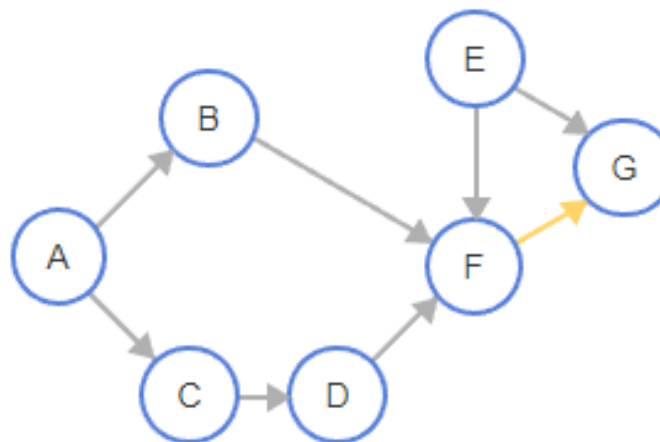
currentV: F

outgoingEdges:

FG

# Topological Sort Algorithm

```
GraphTopologicalSort(graph) {  
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            if (inCount == 0)  
                Add currentE->toVertex to noIncoming  
        }  
    }  
    return resultList  
}
```



resultList:

E A C D B F

noIncoming:

G

remainingEdges:

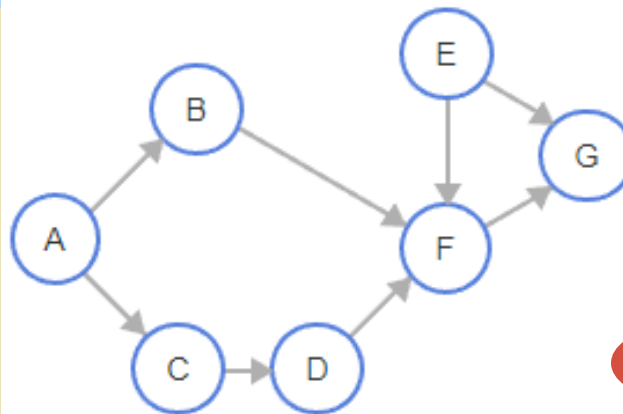
currentV: F      inCount: 0

outgoingEdges:

FG

# Topological Sort Algorithm

```
GraphTopologicalSort(graph) {  
    resultList = empty list of vertices  
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        }  
    }  
    return resultList  
}
```



resultList:

E A C D B F G

noIncoming:

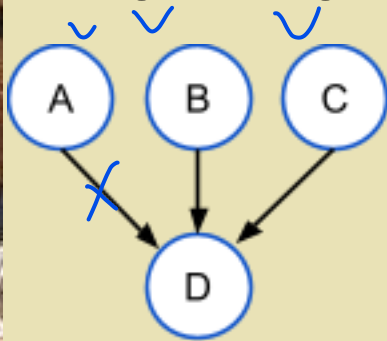
remainingEdges:

currentV: G

outgoingEdges:

# Topological Sort -- Example

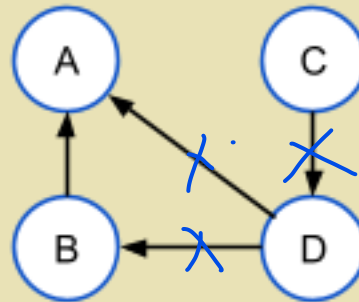
- ◆ Write down a valid topological sort for each of the given graph.



C B A D

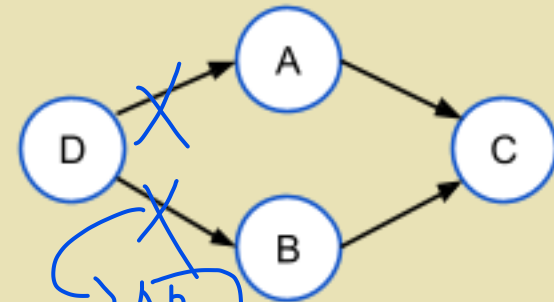
1

A B C



C D B A

2



~~D A B C~~

3

D B A C





# Algorithm efficiency

- ◆ The two vertex lists used in the topological sort algorithm will at most contain all the vertices in the graph. The remaining-edge list will at most contain all edges in the graph.
- ◆ For a graph with a set of vertices  $V$  and a set of edges  $E$ , the space complexity of topological sorting is  $O(|V|+|E|)$ .
- ◆ If a graph implementation allows for retrieval of a vertex's incoming and outgoing edges in constant time, then the time complexity of topological sorting is also  $O(|V|+|E|)$ .

That's  
about this  
lecture!

