

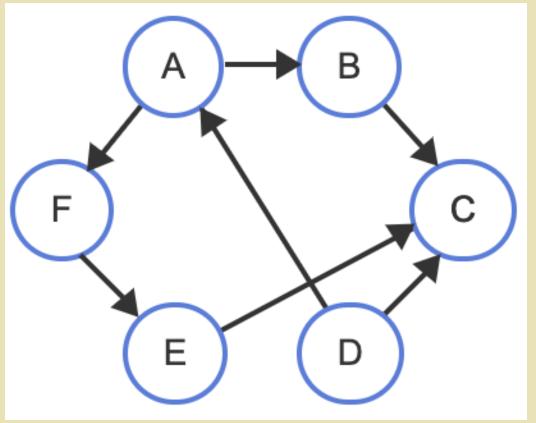


Topological Sort

- Topological ordering is an operation on directed acyclic graphs (DAGs).
- A **topological ordering** is a list of the DAG's vertices such that for every edge from a vertex X to a vertex Y, X comes before Y in the list.
 - May not be unique
- A topological sort produces a list of topological ordering
- Applications: scheduling of tasks from the given dependencies among tasks.
- 2 a student can have an ordered list of courses to take.

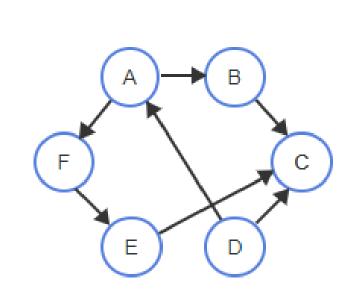


- Is it a topological sort?
- C, D, A, F, B, E





 Analysis of each edge in the graph determines if an ordering of vertices is a valid topological sort.

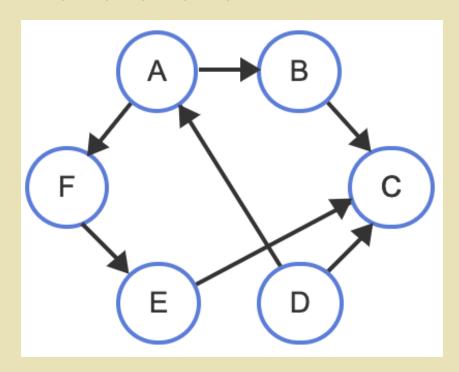


Proposed ordering: C, D, A, F, B, E

Edge (X to Y)	X before Y in ordering?
A to B	Yes
A to F	Yes
B to C	No
D to A	Yes
D to C	No
E to C	No
F to E	Yes



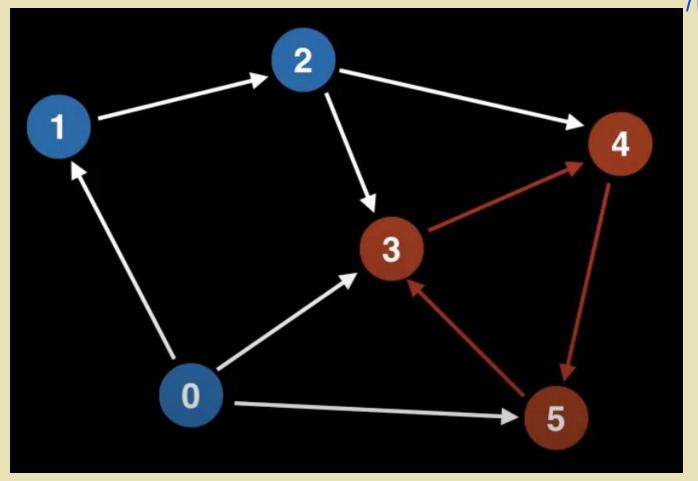
- Is it a topological sort?
- D, A, F, E, B, C



If you check the edges of D and C, what can you find?

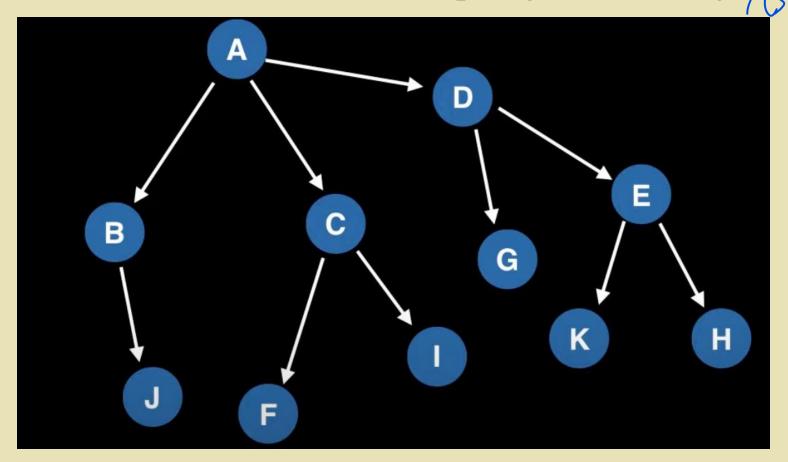


Will cyclic graph have topological ordering?





Will a (directed) tree have topological ordering?





Topological Sort -- Exercise

Determine if each of the following is a topological

sort for the given graph

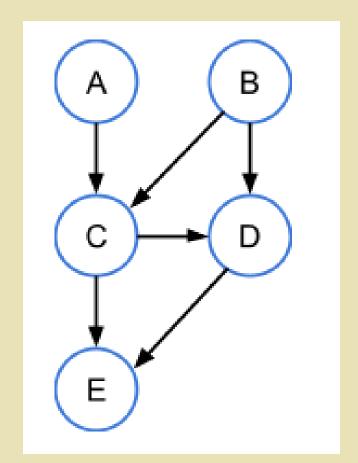
1. A, B, C, D, E

2. E, D, C, B, A ✓

3. D, E, A, B, C $\stackrel{\text{$\vee}}{\sim}$

4. B, A, C, D, E

Check each edge!





- Can be done using **source removal**.
- A source is a vertex with no incoming edges.
- Each step, a source is identified. The source is removed from the graph along with all its outgoing edges. The vertex is then added at the end of the list.
- The process continues until all vertices are removed from the graph.



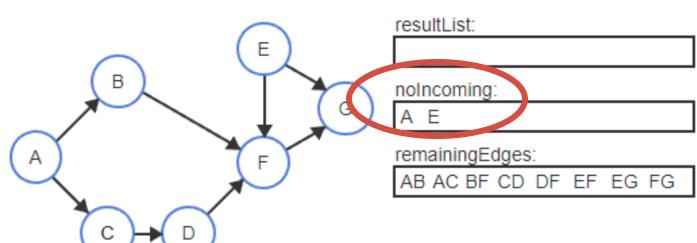
- The topological sort algorithm uses three lists:
 - a results list that will contain a topological sort of vertices: start as empty
 - a no-incoming-edges list of vertices with no incoming edges (source)
 - a remaining-edges list: start as all edges

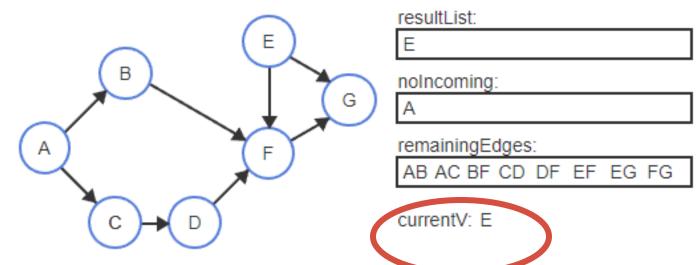


- while the no-incoming-edges vertex list is not empty
 - a vertex is removed from the no-incoming-edges list and added to the result list.
 - a temporary list is built by removing all edges in the remaining-edges list that are outgoing from the removed vertex.
 - For each edge currentE in the temporary list, the number of edges in the remaining-edges list that are incoming to currentE's terminating vertex are counted.
 - If the incoming edge count is 0, then currentE's terminating vertex is added to the no-incoming-edges vertex list.

```
GraphTopologicalSort(graph) {
   resultList = empty list of vertices
   noIncoming = list of all vertices with no incoming edges
   remainingEdges = list of all edges in the graph

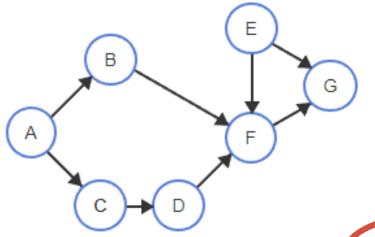
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    currentV = remove any vertex from noIncoming
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    for each edge currentE in outgoingEdges {
        inCount = GraphGetIncomingEdgeCount(remainingEdges, currentE-->toVertex)
        if (inCount == 0)
            Add currentE-->toVertex to noIncoming
        }
    }
    return resultList
```





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```



resultList:

E

noIncoming:

Α

remainingEdges:

AB AC BF CD DF FG

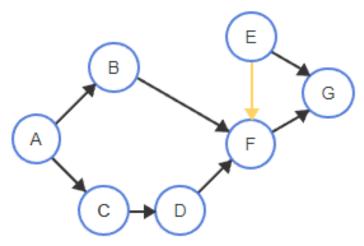
currentV: E

outgoingEdges

EF EG

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resultList:

lΕ

noIncoming:

A

remainingEdges:

AB AC BF CD DF FG

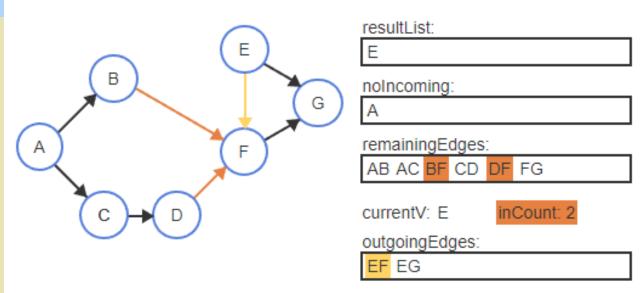
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outgoingEdges:

EF EG

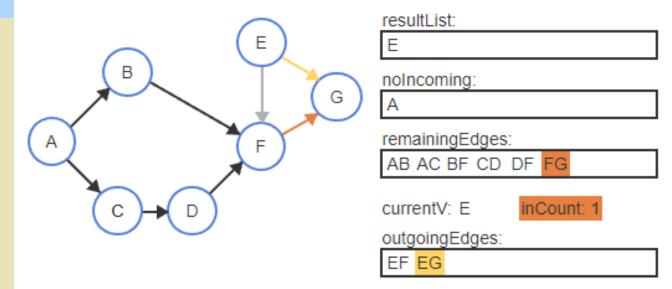
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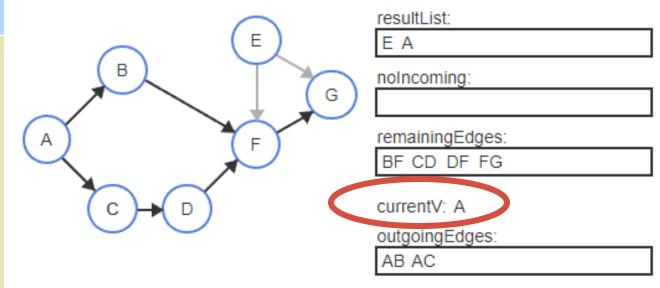
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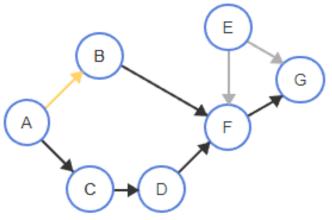
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resultList:

IE A

noIncoming:

remainingEdges:

BF CD DF FG

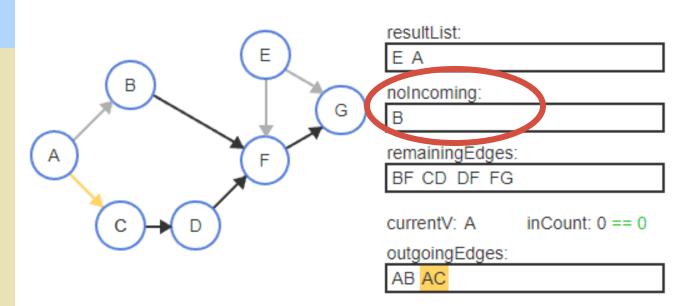
currentV: A inCount: 0 == 0

outgoingEdges:

AB AC

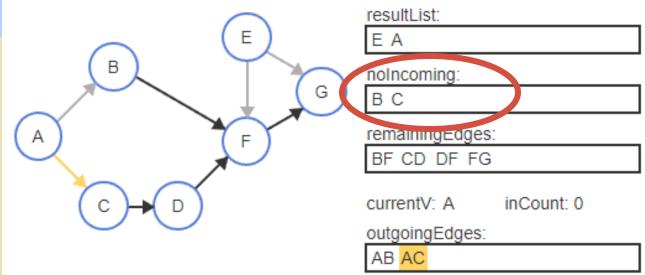
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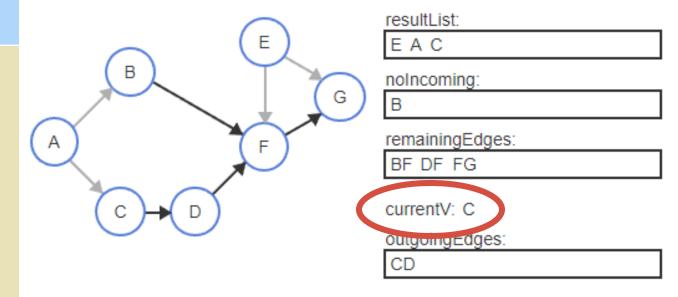




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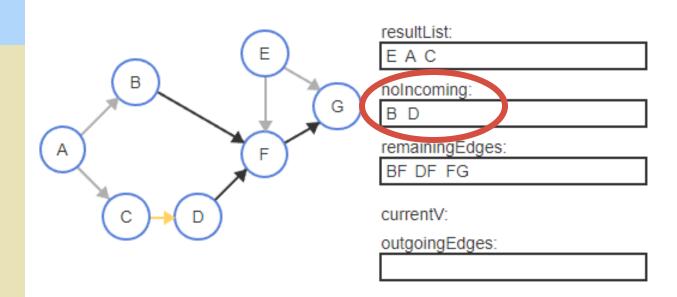




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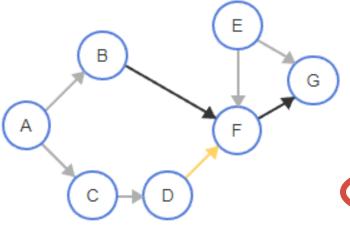




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resultList:

EACD

noIncoming:

В

remainingEdges:

BF FG

currentV: D

outgoingEdges:

DF

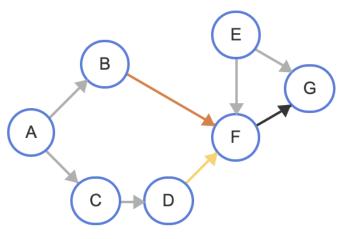


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return resultList



resultList:

EACD

noIncoming:

В

remainingEdges:

BF FG

currentV: D

inCount: 1 != 0

outgoingEdges:

DF





ResultList:

E A C D B

nolncoming:

remainingEdges:

BF FG

currentV: B

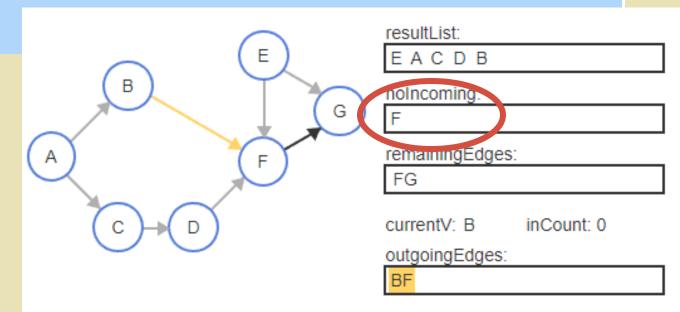
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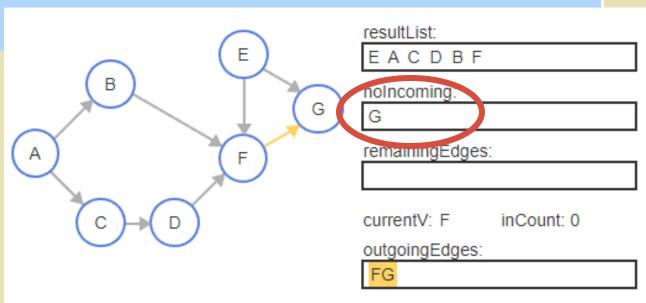
	E	resultList:
В	CE C	EACDBF
	G	noIncoming:
A	(F)	remainingEdges:
~		
(c)→(D)		currentV: F
\circ		catgoing Edges:
		FG



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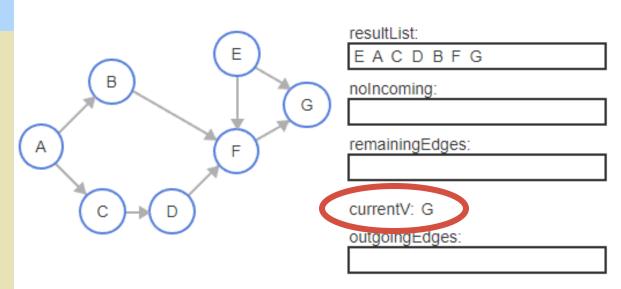






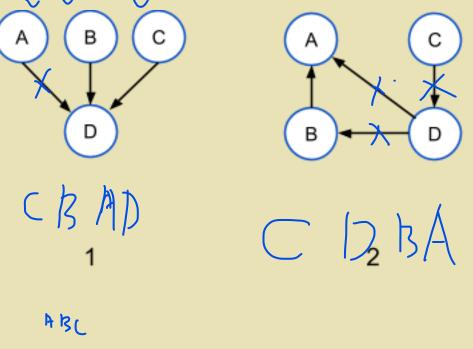
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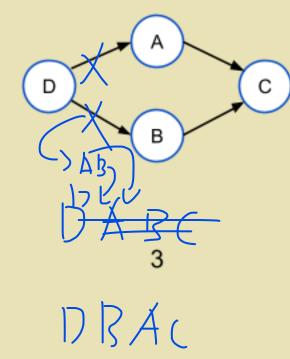






 Write down a valid topological sort for each of the given graph.







Algorithm efficiency

- The two vertex lists used in the topological sort algorithm will at most contain all the vertices in the graph. The remaining-edge list will at most contain all edges in the graph.
- For a graph with a set of vertices V and a set of edges E, the space complexity of topological sorting is O(|V|+|E|).
- If a graph implementation allows for retrieval of a vertex's incoming and outgoing edges in constant time, then the time complexity of topological sorting is also O(|V|+|E|).



That's about this lecture!

