

## Segment 3: Causal Inference with Regression (in randomized studies)

### Section 06: Causal Inference as Model-Based Imputation

#### Model-Based Imputation for Estimation of Causal Effects

- ▶ Build a model for all potential outcomes (depending on unknown parameters)
- ▶ Use observed data to learn these parameters
- ▶ View model as an *imputation model*
  - ▶ To *predict* the unobserved potential outcomes
- ▶ Predict the “unobserved” potential outcome for each unit
- ▶ Evaluate the causal effect  $\tau_{SATE} \equiv \frac{1}{n} \sum (Y_i^1 - Y_i^0)$
- ▶ Repeat...most naturally motivated from a Bayesian perspective

#### Motivating Toy Example with 6 Units

Adapted from textbook by Imbens and Rubin

Randomized evaluation of a job training program:

- ▶ The National Supported Work Program
  - ▶ Originally analyzed by Lalonde (1986), now standard dataset for illustration
- ▶ Treatment ( $Z$ ): Random assignment to a job training program or a control group
- ▶ Units: Men substantially disadvantaged in the labor market
- ▶ Outcome ( $Y$ ): Post-program earnings

## Motivating Toy Example with 6 Units

**Table 8.2.** First Six Observations from NSW Program Data

Unit	Potential Outcomes		Treatment $(Z_i)$ $W_i$	Observed Outcome $Y_i^{obs}$
	$Y_i(0)$	$Y_i(1)$		
1	0	?	0	0
2	?	9.9	1	9.9
3	12.4	?	0	12.4
4	?	3.6	1	3.6
5	0	?	0	0
6	?	24.9	1	24.9

Note: Question marks represent missing potential outcomes.

## Regression: Causal Effect is a Parameter

We know in this case that an estimate of  $\tau_{SATE}$  can come from a linear regression model:

$$Y_i = \alpha + \underset{\substack{\uparrow \\ ATE}}{\tau} W_i + \epsilon_i$$

- ▶ Estimation of regression parameters  $\Leftrightarrow$  estimation of  $\tau_{SATE} = \frac{1}{6} \sum_{i=1}^6 (Y_i^t - Y_i^c)$
- ▶ Consider an alternative perspective where estimation of  $\tau$  will derive from imputations from the model
- ▶ This can ground a more general perspective on causal inference as a solution to a missing data problem
  - ▶ In general, the *causal estimand* may not correspond to a *model parameter*

## Example of Simple Imputation Procedure

Estimand of interest: Average Treatment Effect

$$\begin{aligned}
 \tau_{SATE} &= \frac{1}{6} \sum_{i=1}^6 (Y_i^t - Y_i^c) \\
 &= \frac{1}{6} \sum_{i=1}^6 (W_i(Y_i^{obs} - Y_i^{mis}) + (1 - W_i)(Y_i^{mis} - Y_i^{obs})) \\
 &\quad \dots \text{impute a predicted value for each } Y_i^{mis} \rightarrow \hat{Y}_i^{mis} \\
 \hat{\tau} &= \frac{1}{6} \sum_{i=1}^6 (W_i(Y_i^{obs} - \hat{Y}_i^{mis}) + (1 - W_i)(\hat{Y}_i^{mis} - Y_i^{obs}))
 \end{aligned}$$

But how to impute  $\hat{Y}_i^{mis}$ ?

Simple, naive: Impute each missing outcome with the average of the observed potential outcome with that treatment

**Table 8.3. The Average Treatment Effect Using Imputation of Average Observed Outcome Values within Treatment and Control Groups for the NSW Program Data**

Unit	Potential Outcomes		Treatment $W_i$	Observed Outcome $Y_i^{obs}$
	$Y_i(0)$	$Y_i(1)$		
1	0	(12.8)	0	0
2	(4.13)	9.9	1	9.9
3	12.4	(12.8)	0	12.4
4	(4.13)	3.6	1	3.6
5	0	(12.8)	0	0
6	(4.13)	24.9	1	24.9
Average	4.13	12.8		
Diff (ATE):		8.67		

## Not Surprising but....

- ▶ Estimated effect (8.7) is the same as the simple  $\bar{Y}_t^{obs} - \bar{Y}_c^{obs}$ 
  - ▶ Not surprising given the imputation method
- ▶ But no uncertainty in imputed values,  $\hat{Y}_i^{mis}$ 
  - ▶ Looks particularly suspect given the observed data...
- ▶ Randomization allows us to deduce the *mean* of  $Y_i^{mis}$ , but not the exact values
- ▶ I.e., Pretty easy to get the imputations right “on average”

## Another Simple Approach

Instead of just set  $\hat{Y}_i^{mis}$  equal to  $\bar{Y}^{obs}$  in the “other” treatment group...

Draw  $Y_i^{mis}$  from the random distribution of  $Y_j^{obs}$  in the “other” treatment group.

E.g., for unit with  $W_i = 0$ , draw  $Y_i^{mis} = Y_i^t$  from the empirical distribution of  $Y_i^{obs} | W_i = t$ .

In the  $N = 6$  example, for unit 1 with  $W_i = 0$ , draw  $Y_i^{mis}$  to be 9.9, 3.6, or 24.9 with probability 1/3 each.

Repeat for each unit and calculate the ATE

Repeat multiple times...

Multiple Imputation

# Multiple Imputations of $Y^{mis}$

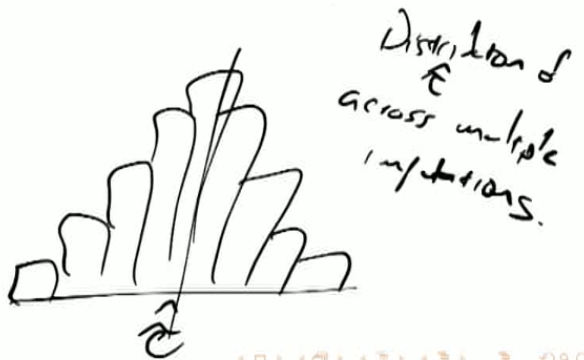
2 imputations

**Table 8.4. The Average Treatment Effect Using Imputed Draws from the Empirical Distributions within Treatment and Control Groups for the First Six Units from the NSW Program Data**

Unit	Potential Outcomes		Treatment $W_i$	Observed Outcome $y_i^{\text{obs}}$
	$Y_i(0)$	$Y_i(1)$		
Panel A: First draw				
1	0	(3.6)	0	0
2	(12.4)	9.9	1	9.9
3	12.4	(9.9)	0	12.4
4	(12.4)	3.6	1	3.6
5	0	(9.9)	0	0
6	(0)	24.9	1	24.9
Average	6.2	10.3		
Diff (ATE):		4.1		
Panel B: Second draw				
1	0	(9.9)	0	0
2	(0)	9.9	1	9.9
3	12.4	(24.9)	0	12.4
4	(0)	3.6	1	3.6
5	0	(3.6)	0	0
6	(0)	24.9	1	24.9
Average	2.1	12.8		
Diff (ATE):		10.7		

## Result: A Distribution of Effect Estimates

- ▶ In this simple example, there are  $3^6 = 729$  different imputations, all equally likely
- ▶ Calculate the corresponding ATE for each
  - ▶ "Overall" point estimate is the mean of the 729 estimates
  - ▶ Standard deviation of the 729 estimates
- ▶ Result:  $\hat{\tau} = 8.7$  with standard deviation 3.1
- ▶ Now we have an entire distribution of the average treatment effect



## General Motivation

- ▶ We have already seen that causal inference problems can be motivated as missing data problems
- ▶ Reliable model for  $\mathbf{Y}^{mis} \Rightarrow$  reliable model for causal effects
- ▶ General stochastic simulation
  1. Sample (or “impute”) values for  $\mathbf{Y}^{mis}$
  2. Calculate causal effects
  3. Repeat...

## Predicting Unobserved Potential Outcomes with Regression

We have seen how to generate (posterior) predictions from linear regression models:

- ▶ `posterior_predict(model, newdata)`: Predictive distribution of  $y$ 
  - ▶ Useful for making predictions for a particular unit
  - ▶  $\rightarrow \tau_{SATE}$
- ▶ `posterior_linpred(model, newdata)`: Posterior distribution of *average* response
  - ▶ Useful for making predictions for what would happen on average across the population
  - ▶  $\rightarrow \tau_{PATE}$



## Predicting Potential Outcomes with Regression

Use the mechanics of Bayesian prediction to estimate the causal effect:

- ▶ Fit the regression model
  - ▶ `stan_glm(model, data)`
- ▶ Then repeat for  $k = 1, 2, \dots, K$ 
  1. Predict unobserved potential outcomes from the model
    - ▶ `posterior_predict(model, newdata)` for  $\tau_{SATE}$
    - ▶ `posterior_linpred(model, newdata)` for  $\tau_{PATE}$
  2. Calculate the causal estimand
    - ▶ E.g.,  $\hat{\tau}^{(k)} = \frac{1}{n} \sum_{i=1}^n (W_i(Y_i^{obs} - \hat{Y}_i^{mis(k)}) + (1 - W_i)(\hat{Y}_i^{mis(k)} - Y_i^{obs}))$
- ▶ Use simulations  $\hat{\tau}^{(1)}, \hat{\tau}^{(2)}, \dots, \hat{\tau}^{(K)}$  to calculate estimates/uncertainty for the causal effect
- ▶ (Will be equivalent to parameter from *linear regression model*, but not necessarily true for other models)

## Predicting Unobserved Potential Outcomes

Linear regression with interactions between  ~~$Z$~~  and all  $X$  has the following features:

- ▶ Essentially imputes the missing potential outcomes
- ▶ Does so separately for the treated and control units
- ▶ Imputing  $Y_i^0$  for  $Z_i = 1$  units, only uses  $Y_i^{obs}$  for  $Z_i = 0$  units, without dependence on  $Y_i^1$ 
  - ▶ And vice versa
- ▶ Entails some robustness properties by clearly separating imputation of control and treated outcomes

## Regression with Covariates and Interactions

(still with complete randomization)

$Y_i^{obs} = \alpha + \theta Z_i + X_i \beta + Z_i X_i \gamma + \epsilon_i$   $\epsilon_i \sim N(0, \sigma^2)$

For  $Z_i = 1$ :

- ▶  $\hat{Y}_i(0) = \hat{\alpha} + X_i \hat{\beta} + \epsilon_i \Rightarrow \sim N(\hat{\alpha} + X_i \hat{\beta}, \sigma^2)$
- ▶  $\hat{\tau}_i = Y_i^{obs} - \hat{Y}_i(0)$

For  $Z_i = 0$ :

- ▶  $\hat{Y}_i(1) = \hat{\alpha} + \hat{\theta} + X_i \hat{\beta} + X_i \hat{\gamma} + \epsilon_i \Rightarrow \sim N(\hat{\alpha} + \hat{\theta} + X_i \hat{\beta} + X_i \hat{\gamma}, \sigma^2)$
- ▶  $\hat{\tau}_i = \hat{Y}_i(1) - \hat{Y}_i(0)$

$$\frac{1}{N} \sum_{i=1}^N \hat{\tau}_i = \sum_{i=1}^N (Z_i(Y_i^1 - \hat{Y}_i^0) + (1 - Z_i)(\hat{Y}_i^1 - Y_i^0)) = \hat{\tau}^{ols}$$