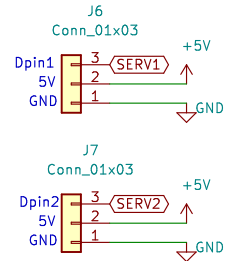
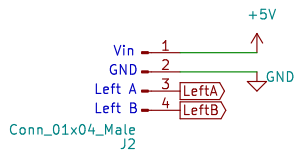
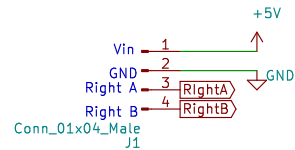


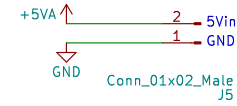
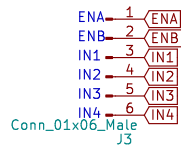
JST connections for 2 servo motors for the arm design, subject to change for mechanical needs



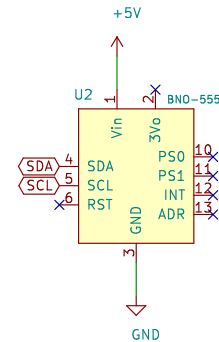
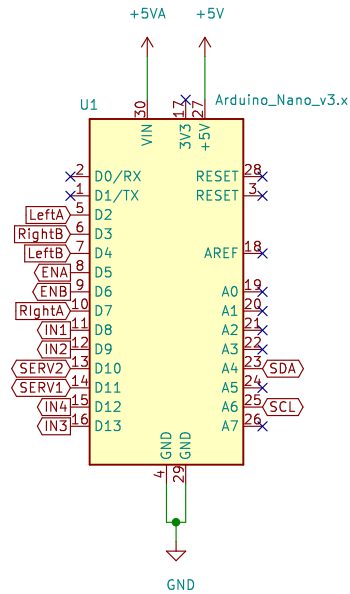
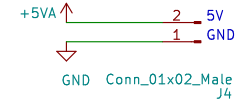
JSTs to the motor encoders powering and sending data.



JST Connector to send data to the motor controller.



2 seperate JST Connecters both for powering and accessing 5 volts from the buck converter.



IMU Chip sending Gyroscope data to the microprocessor

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File: ArduinoBreakoutboardControl.sch

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