

Kick-Off Meeting

Thursday September 3, 2015

Sponsored by





What Is SCR?

- Umbrella organization for robotics competition teams
- Leadership structure:
 - Each team has its own captain, leads, and members
 - SCR has a President, VP, Secretary, Treasurer, and a number of Technical Advisors
- SCR provides:
 - Technical and managerial experience
 - Resource management
 - Financial & Human
 - Central hub





Our Teams



- SCR houses 4 competition teams:
 - ASEE, a freshman and sophomore only autonomous robot competition
 - Mercury, a teleoperated robot competition held by OSU and open to anyone
 - IEEE, an autonomous robot competition open to all undergraduates
 - KIPR, an annual robotics competition open to anyone
- We are looking into starting a VEX U team, provided we acquire the funds for it.



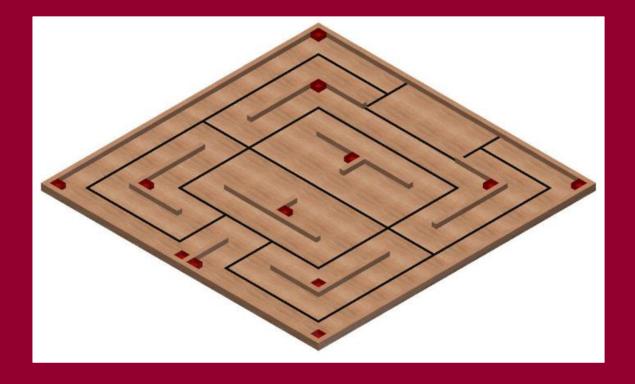
What is it like to be on a team?

- Each team may have a single Captain or a Lead Engineer and Project Manager acting as head of that team
- Teams are generally divided into three sub teams: Electrical, Mechanical, and Software, each with their own team lead
- Teams will generally meet once a week for 1-1.5 hrs in the Fall and may meet more often in the Spring as competition nears
- No experience necessary



ASEE 2016 Challenge

Objective: To design and build an autonomous robot that can deposit one ring in each of 12 boxes located along the "parade route" on the track.



- Monday, June 27th, 2016
- New Orleans, LA
- Open to freshmen and sophomores only



IEEE 2016 Challenge

Objective: To design and build an autonomous robot that can successfully navigate a course while completing various objectives that deal with computer vision and mobile manipulation

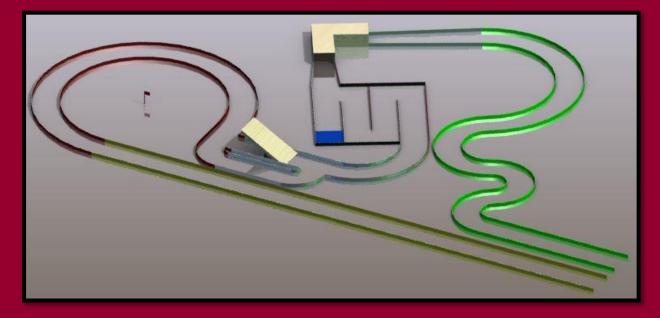


- •Saturday April 9th, 2016
- •Kansas City, MO
- •Open to undergraduates only



Mercury 2016 Challenge

Objective: To design and build a teleoperated robot that can navigate successfully through a number of obstacles such as picking up a payload and successfully carrying it through the course to the delivery zone, and climbing up a See-Saw structure without dropping the payload or damaging the robot.

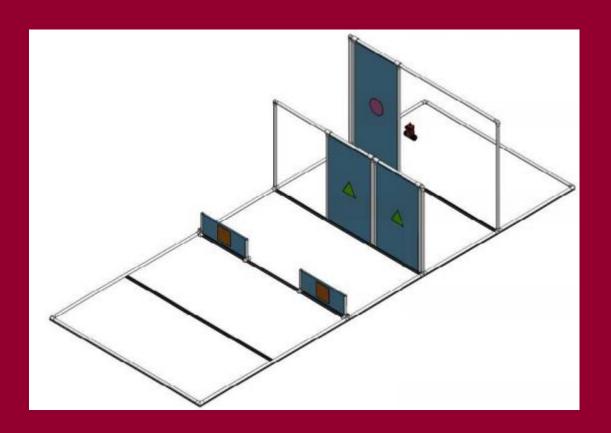


- Saturday, April 16, 2016
- Stillwater, OK
- Open to anyone



KIPR 2016 Challenge

Objective: Botball style ground and aerial based competitions

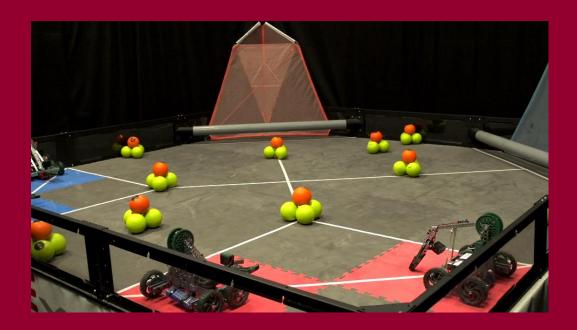


- July 6-10, 2016
- St. Augustine, FL
- KIPR Open open to anyone
- KIPR Aerial open to high school and college students



VEX U 2016 Challenge

Objective: To design and build two teleoperated and autonomous robots that can successfully complete a skills based challenge.



- Numerous dates throughout 2016
- Tournament
 - I. League City, Texas
 - II. Louisville, Kentucky (worlds champ.)
- Skills challenge
 - I. Houston, Texas
 - II. Lawton, Oklahoma
- Open to all college students

For more information...

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