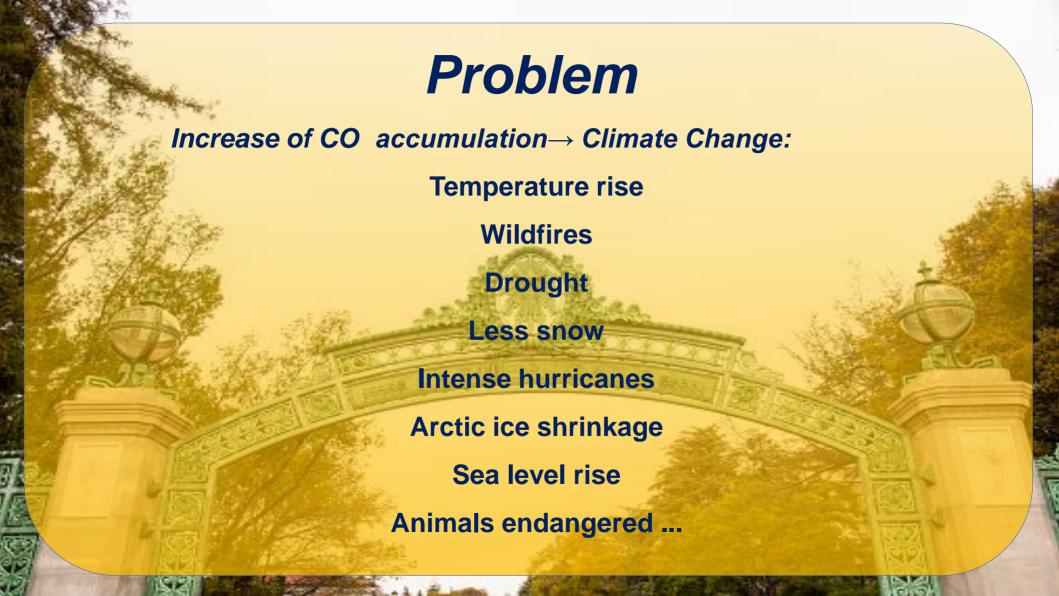


Sophia Hart, M.Sc., M.Eng.

sophia.t.hart@gmail.com

A project for my Data Science Certificate at UC Berkeley Extension







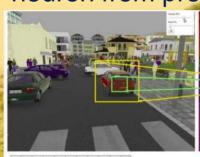
Fundamental of Convolutional Neural Networks (CNN)

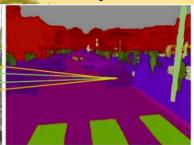
Neural network
with
fully connected
layers

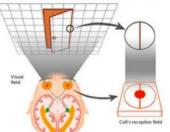


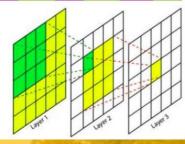
CNN utilizes receptive field

Neuron not connected to every neuron from previous layer

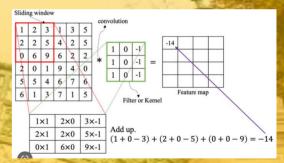








Convolution

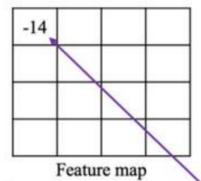


Kernel for CNN

Sliding window

1	2	3	1	3	5
2	2	5	4	2	5
0	6	9	6	2	2
2	0	1	9	4	0
5	5	4	6	7	6
6	1	3	7	1	5
	/				

convolution



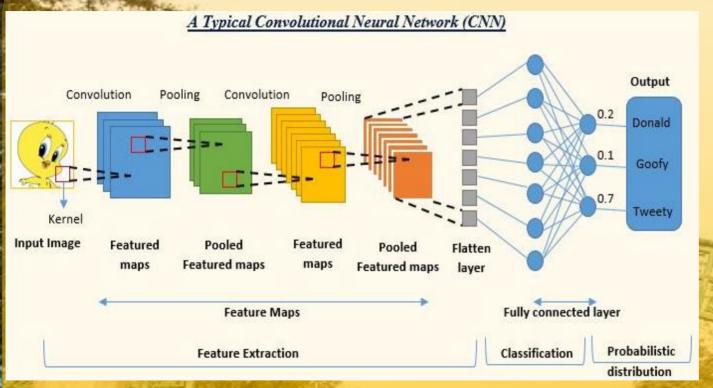
Filter or Kernel

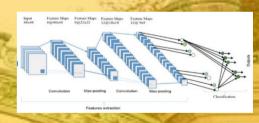
1×1	2×0	3×-1
2×1	2×0	5×-1
0×1	6×0	9×-1

Add up.

$$(1+0-3)+(2+0-5)+(0+0-9)=-14$$

CNN Architecture





Goal: Learn the weights/parameters for these kernels in the convolution layers.

Computer Vision using Transfer Learning

Not necessary to reinvent the wheel.

Improved learning of a new task from a related task that's been learned.

If there's not enough training data, good idea to reuse lower layers of pretrained model.

ImageNet Large Scale Visual Recognition Challenge (ILSVRC)

>15 million labeled images, 1000 category of objects Took 62,000 GPU hours to train (?)

Question: Is model trained for classifying objects applicable for classifying wildfire?

Computer Vision using Transfer Learning

Keras has access to Pretrained models

Pretrained models types:

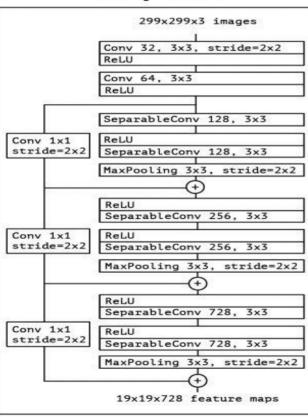
- AlexNet
- VGG
- Inception (Google)
- ResNet (Microsoft)
- EfficientNet (Google)

	Comparison						
	Network	Year	Salient Feature	top5 accuracy	Parameters	FLOP	
	AlexNet	2012	Deeper	84.70%	62M	1.5B	
	VGGNet	2014	Fixed-size kernels	92.30%	138M	19.6B	
	Inception	2014	Wider - Parallel kernels	93.30%	6.4M	2B	
)	ResNet-152	2015	Shortcut connections	95.51%	60.3M	11B	

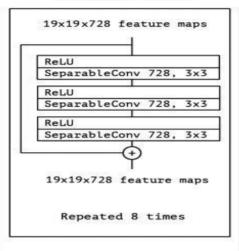
My base model - Xception (Extreme Inception)
Proposed in 2016 by François Chollet, author of Keras
Less memory, exceptional accuracy

Xception Architecture

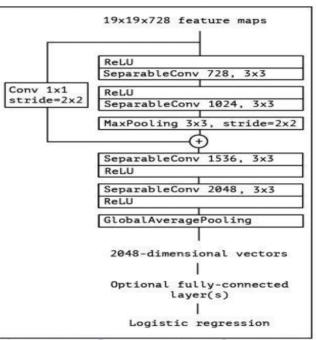




Middle flow



Exit flow



Batch Normalization follows SeparableConvolution (solved gradient vanishing/exploding – breakthrough in deep learning)

François Chollet

Dataset

Forest images
50 no fire
50 with fire

Data Augmentation (flips) 400 images total

Keep 3 channels (color important feature of fire)



Challenge of Computer Vision for Wildfire





No-fire

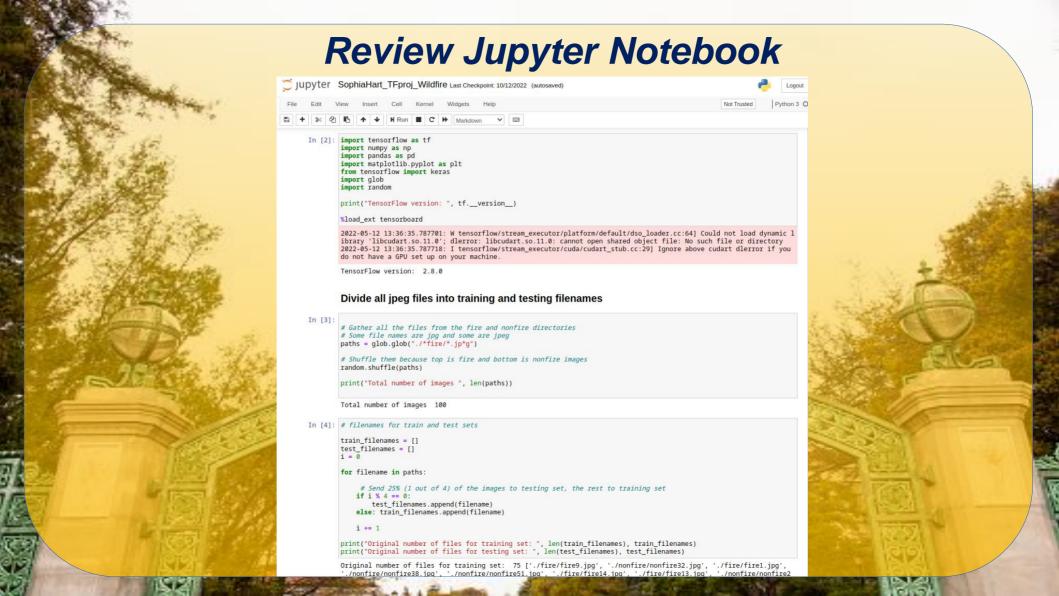


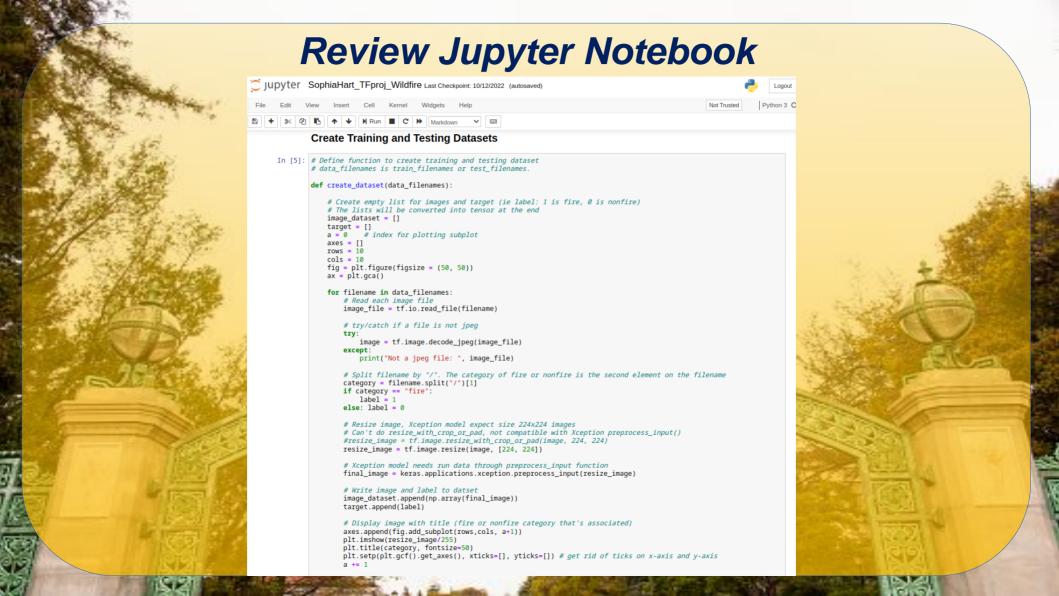
Both flame and sunset or Autumn leaves appear orange-red

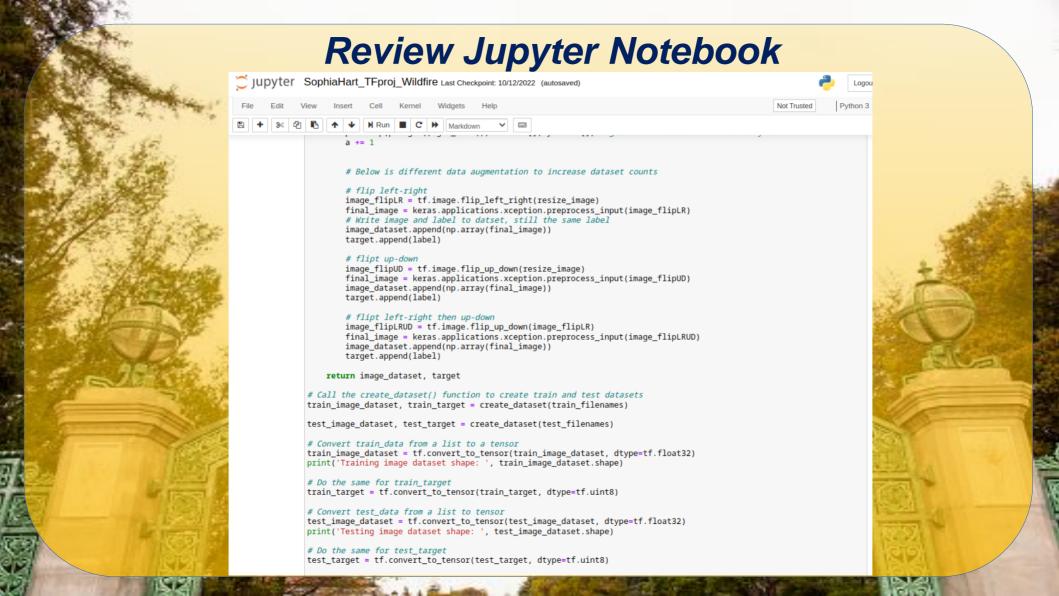




Smoke and cloud appear similar







Training Dataset (part 1 of 3)

Training image dataset shape: (300, 224, 224, 3) Testing image dataset shape: (100, 224, 224, 3)

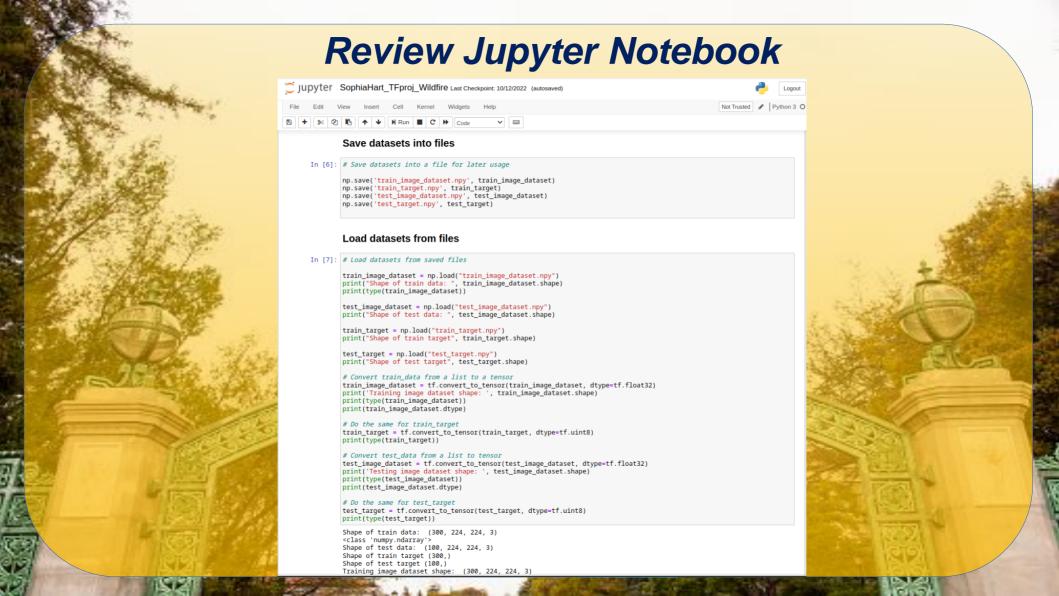


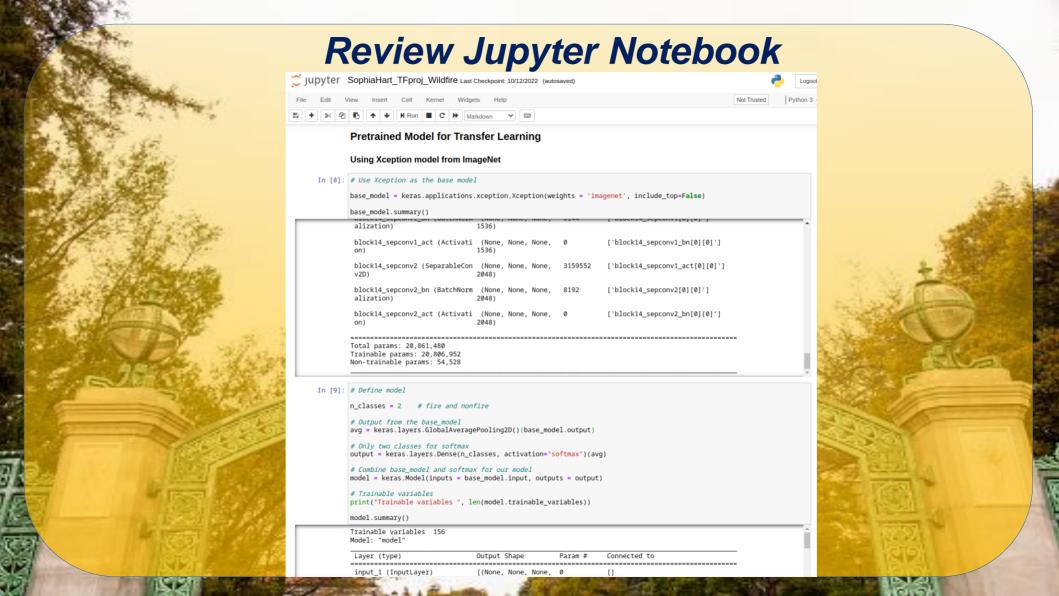
Training Dataset (part 2 of 3) nonfire nonfire fire nonfire fire fire fire fire fire fire nonfire nonfire fire nonfire fire fire nonfire fire fire nonfire nonfire nonfire fire fire fire fire nonfire nonfire fire

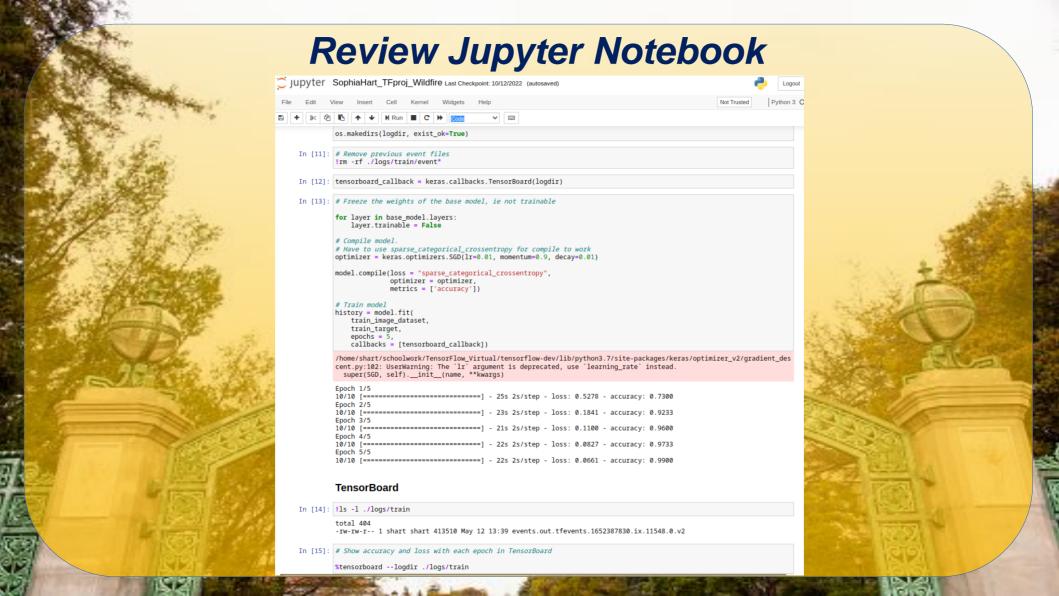


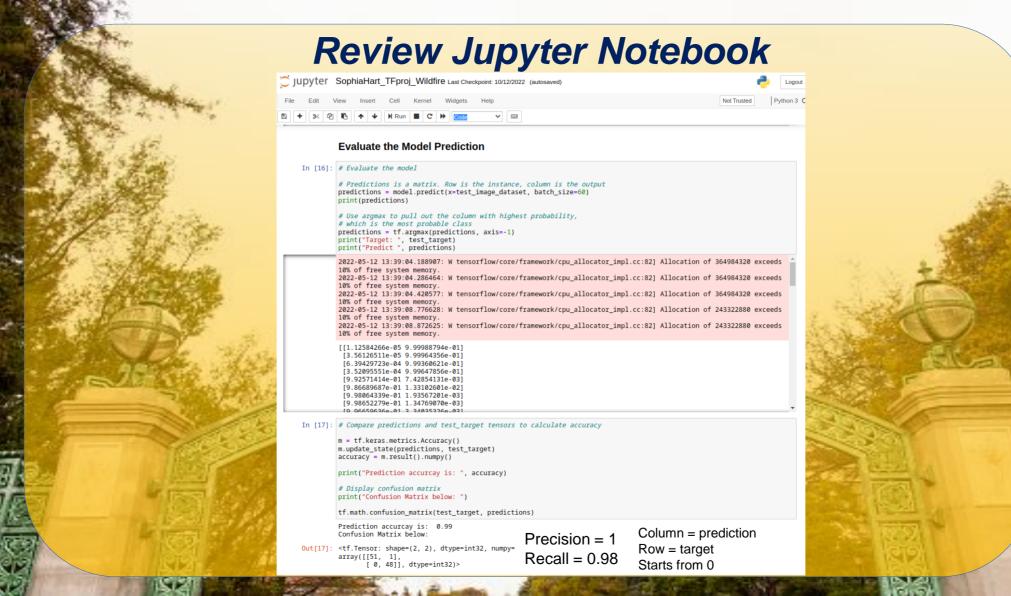
Test Dataset





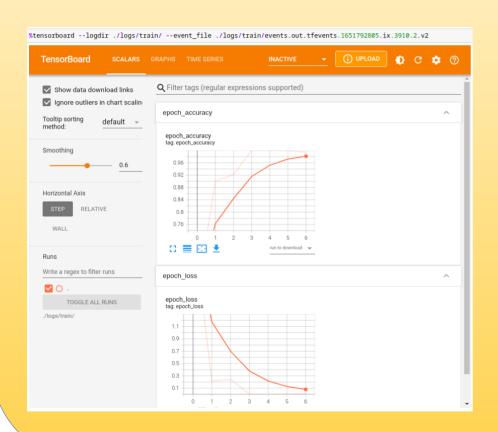


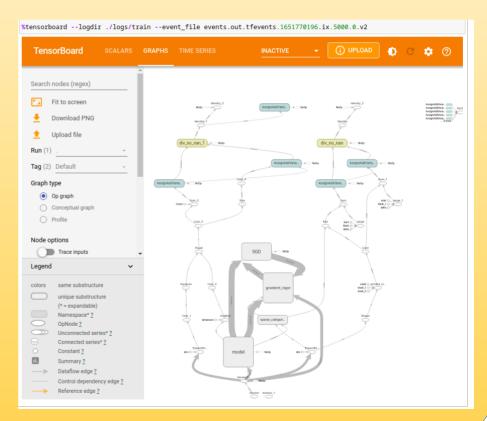




Model achieves 95.7% test accuracy over 12 runs Accuracy on Test Images **Total Images**

Accuracy improves over time in learning





Model Fine-tuning

- 1. Unfreeze top 22 layers, trainable weights
- 2. Add a dropout layer on the top layer (don't need dropout if Batch Normalization)
- 3. Change optimizer (SGD → Adam)
- → Didn't improve accuracy

Conclusion

Computer vision with transfer learning is helpful in speed, accuracy and simplicity. And it requires less training data.

The more data we have, the wider distribution the data can be. So the two categories don't have to have a clear cut (i.e. fire and no-fire images look drastically different) to have outstanding prediction accuracy.

Machine Learning can be implemented to detect wildfire to flag the Information for human review and fire management decisions. This saves time and money, and ensures early detection which is important to control the spread of wildfire.



References

Aurélien Géron, Hands-on Machine Learning with Scikit-Learn, Keras & TensorFlow, 2 Ed. O'Reilly

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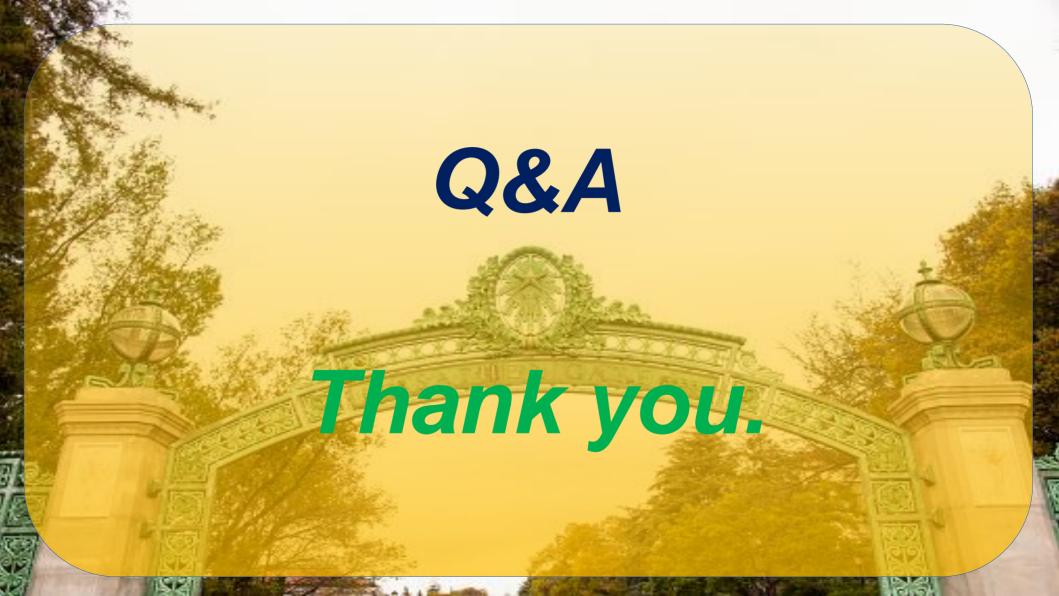
Franc ois Chollet, Xception: Deep Learning with Depthwise Separable Convolutions, CVPR, Computer Vision Foundation Open Access version

https://theaisummer.com/receptive-field/

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https://towardsdatascience.com/4-pre-trained-cnn-models-to-use-for-computer-vision-with-transfer-learning-885cb1b2dfc

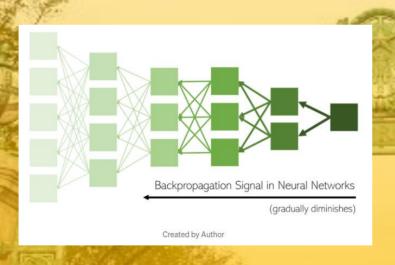
https://towardsdatascience.com/batch-normalization-the-greatest-breakthrough-in-deep-learning-77e64909d81d

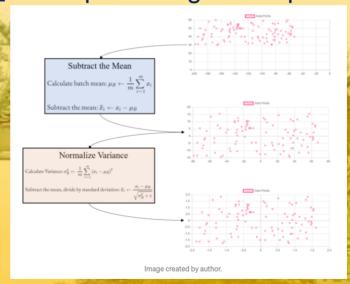


Appendix A Batch Normalization for Deep Learning

Batch Normalization solves gradient vanishing and exploding problems.

One of the greatest breakthrough in deep learning development.

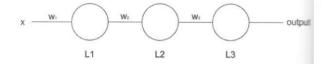




Reference

Appendix B: Chain Rule for Back Propagation

Let's assume a really simply network, with one input, one output, and two hidden layers with a single neuron. Both hidden and output neurons will be sigmoids and the loss will be calculated using cross entropy. Such a network should look like:



Let's define L1 as the output of first hidden layer, L2 the output of the second, and L3 the final output of the network:

$$L1 = sigmoid(w_1.x)$$

$$L2 = sigmoid(w_2.L1)$$

$$L3 = sigmoid(w_3.L2)$$

Finally, the loss of the network will be:

$$loss = cross_entropy(L3, y_{expected})$$

To run one step of gradient decent, we need to calcuate the partial derivatives of the loss function with respect of the three weights in the network. We will start from the output layer weights, applying the chain rule:

$$\frac{\partial loss}{\partial w_3} = cross_entropy'(L3, y_{expected}). sigmoid'(w_3. L2). L2$$

L2 is just a constant for this case as it doesn't depend on w_3

To simplify the expression we could define:

$$loss' = cross_entropy'(L3, y_{expected})$$

$$L3' = sigmoid'(w_3 . L2)$$

The resulting expression for the partial derivative would be:

$$\frac{\partial loss}{\partial w_3} = loss' . L3' . L2$$

Now let's calculate the derivative for the second hidden layer weight, w_2 :

$$L2' = sigmoid'(w_2 . L1)$$

$$\frac{\partial loss}{\partial w_2} = loss' \cdot L3' \cdot L2' \cdot L1$$

And finally the derivative for w_1 :

$$L1' = sigmoid'(w_1.x)$$

$$\frac{\partial loss}{\partial w_1} = loss' \cdot L3' \cdot L2' \cdot L1' \cdot x$$

You should notice a pattern. The derivative on each layer is the product of the derivatives of the layers after it by the output of the layer before. That's the magic of the chain rule and what the algorithm takes advantage of.

We go forward from the inputs calculating the outputs of each hidden layer up to the output layer. Then we start calculating derivatives going backwards through the hidden

Abrahams, Hafner, Erwitt, Scarpinelli, TensorFlow for Machine Intelligence