Practical uses of synchronized clocks in distributed systems

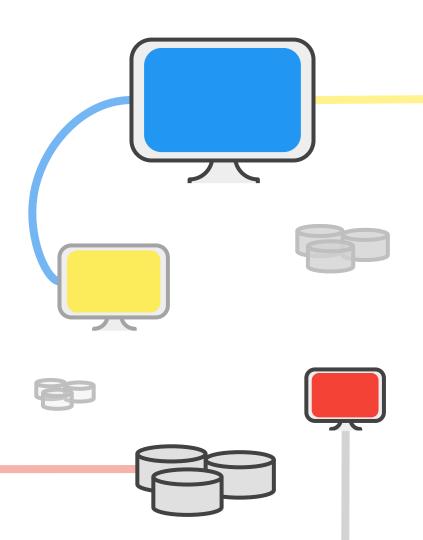
Liskov, Barbara. "Practical uses of synchronized clocks in distributed systems." Distributed Computing 6.4 (1993): 211-219.

"Memory is the diary that we all carry about with us".

~Oscar Wilde, The Importance of Being Earnest

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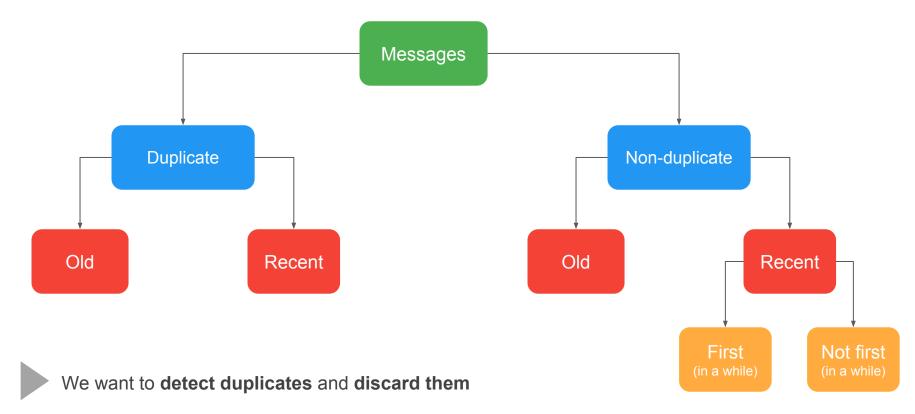
Introduction

Motivation

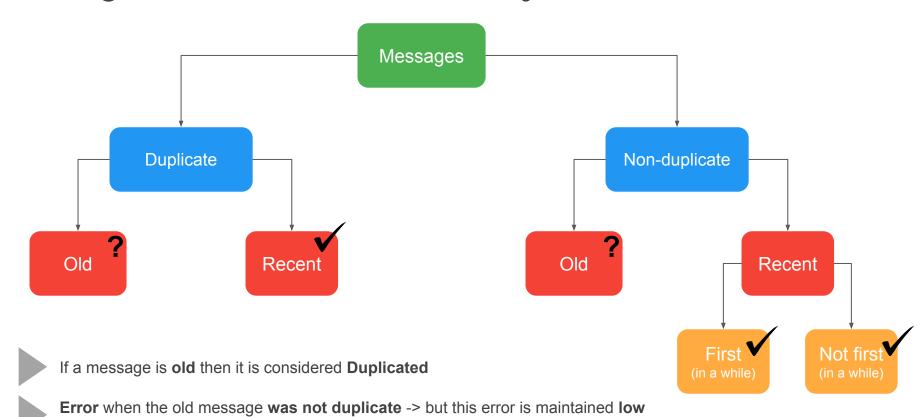
- SCs can improve the performance of a distributed algorithm replacing communication with local computation.
- This paper describes the practical role of SC in distributed algorithms of current/future use.
- We assume a CS algorithm already exists: ∀ clocks
 c₁,c₂ P (|Tc₁-Tc₂| < ε) ≈ 1

At-most-once messages

A possible classification of messages



This algorithm identifies correctly



1st algorithm using SC: SCMP

Guarantees at-most-once delivery at low cost.

 Provides an absolute guarantee that all duplicate messages will be detected.

Building block for protocols with higher performance.

1st algorithm using SC: SCMP

Receivers keep a table of active senders to determine duplicated messages -> how large?

- If no info about the sender then accept/reject? reject
 1st time in-a-while messages? Handshakes (channel): not always cost-effective.
- SCMP (synchronized clock message passing) uses SC to remember recent communications.
- What is a recent message?

1st algorithm using SC: SCMP

PROS: never accept a duplicate.

CONS: Non-duplicated messages are rejected sometimes.

Protocol ingredients

- Every node reads G.time from local clock
- Every message m has a unique message id with:
 - Time-stamp m.ts (same ts for copies of m)
 - Connection identifier m.conn (different for each sender and type of message)
- Every receiver has:
 - Connection table G.CT: has timestamp of the last message accepted on the connection
 - If G.CT[C].ts≤G.time-ρ-ε then C is old

ρ=message lifetime interval.

Remove C from G.CT

Minimizes probability of false positives

■ Update bound: G.upper=max(G.upper, G.CT[C].ts). G.upper is a representative of old messages.

Algorithm

- Idea: determine a per-connection bound that distinguishes recent from old:
 - if m.conn ∈ G.CT then its bound is the most recent timestamp and recent
 - Check if is duplicated
 - else (it is first or old) its bound is G.upper:
 - if t_{last}≤G.upper≤G.time-ρ-ε then old and discard
 - G.upper<m.ts, then first and store in G.CT
- How to determine if a message that arrives after crash is a duplicate of a message that arrived before a crash?
 - Keep on stable storage a timestamp G.latest=G.time+b>m.ts for all m
 - If m.ts > G.latest then discard or delay.
 - After a crash G.upper=G.latest

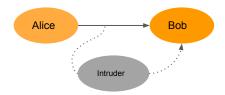
Algorithm

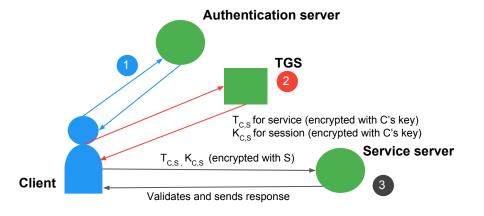
- We established a quantitative notion of recent and old.
- A reasonable way to detect duplicates.
- We avoided frequent communications.
- We saved storage at receivers by only keeping recent messages
- If clocks get out of synch there is no risk of accept duplicates but:
 - Clock is slower: its messages are more prone to be considered duplicates
 - Clock is faster: it considers messages as duplicates more easily

Authentication tickets in Kerberos

Kerberos

- Allows secure and authenticated communication between client-server.
- Uses private keys encrypted with DES
- Uses synchronized clocks to limit use of tickets and to help detect replay attacks.





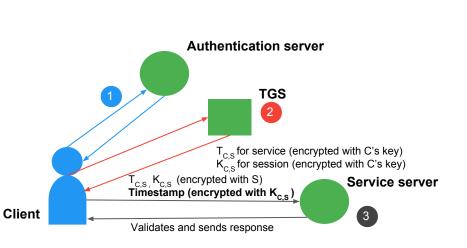
CONTROL USE OF TICKETS-KEYS!

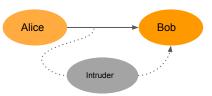
Limit use of keys: Avoid tickets to be stolen in absence of logout.

- Tickets have expiration time E: E<Cs-ε ticket is valid
- SC avoids communication between server and TGS

Kerberos

- Kerberos protects from malicious users trying to steal keys or trick the system about keys.
- Using CS in Kerberos requires that the CS algorithm is protected against similar threats like turning clocks very slow.





Help detect replay attacks:

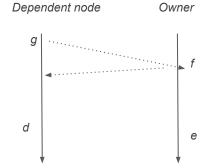
- Uses authenticators: encrypted timestamps
- Very difficult to recreate: replayer can only reuse them
- Intercepted messages arrive later
- Messages with old authenticators are discarded
- Replays are still possible but rare if done quickly or if server is slow

Synchronized rates

How to use Synchronized rates

In abstract:

- Event of interest e (expiration of a privilege)
- Owner of the event e, say O
- o T is the real time at which e occurs
- Other nodes D depend on e and approximate to it using d occurring at T_d
- We want to guarantee $T_d \le T_e$



$$T_d = T_g + \lambda - \varepsilon$$

 λ is the expiration interval, ϵ skew on how rates vary over λ

$$T_e = T_f + \lambda$$

$$T_g \le T_f$$
 then $T_d \le T_e$

When to use them?

- When there is a communication already that allows the dependent node to estimate when the event of interest happens.
 - "At-most-once messages": Owner sends message to dependent without notification -> can't use rates
 - Kerberos: we can use rates
 - Event of interest: expiration of ticket.
 - Server is dependent, TGS is owner
 - If TGS communicate with the server before granting the ticket then the response of server is g
 - f is TGS's granting of the ticket.
 - But server doesn't communicate with TGS

Discussion

Remarks

- What if clocks get out of synchronization?
 - No effect in correctness in both algorithms (in Kerberos server should keep timestamps)
 - Other failures matter more: overuse tickets in Kerberos vs stolen tickets.
- We need to approximate "real rates":
 - At-most-once messages: ρ should be approximate real delay
 - Kerberos: a ticket that is intended to last for one hour should last that hour
- How to incorporate SC in a distributed algorithm?
 - Find a way to avoid communication using timestamps (retain state for example)
 - Analyze consequences under worst case

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References

- Krzyzanowski, Paul. "Clock Synchronization." Lectures on distributed systems 2002 (2000).
- Liskov, Barbara, Liuba Shrira, and John Wroclawski. "Efficient at-most-once messages based on synchronized clocks." ACM Transactions on Computer Systems (TOCS) 9.2 (1991): 125-142.
- Liskov, Barbara. "Practical uses of synchronized clocks in distributed systems." Distributed Computing 6.4 (1993): 211-219.

Thanks