

Solving Proximity Constraints

Sophie Hofmanninger & Jan-Michael Holzinger

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1 Theory

2 System Model

3 Workflow





Motivation

For proving theorems, a frequently occurring problem is to find common instances of formulae.

Example 1

Let f be a function, a, b constants and x a variable. The two expressions

$$f(a,x)$$
 and $f(a,b)$

can be unified with $\{x \mapsto b\}$.



Motivation

For proving theorems, a frequently occurring problem is to find common instances of formulae.

Example 2

Let f, g be functions, a, b constants and x a variable. The two expressions

$$f(a,x)$$
 and $g(a,b)$

cannot be unified as $f \neq g$.



Motivation

In 1965 Robinson presented his unification algorithm and solved this problem, his algorithm was improved for better(=faster) performance since.

If we consider now the unification problem

$$f(a,x) \simeq^? g(a,b)$$

again, we might wonder, if we could not ignore $f \neq g$, if they are "close" to each other, i.e. if they are equal in a fuzzy logic sense. Being close is represented as a proximity relation, which are symmetric and reflexive, but not necessarily transitive. C. Pau and T. Kutsia solved this problem, presenting an algorithm, which we implemented.



Introduction

4 sets:

- P: unification problem to be solved
- C: neighborhood constraint
- lacksquare σ : set of pre-unifier
- $lack \psi$: name-class mapping

Pre-Unification rules

```
(Tri) Trivial: . . .
(Dec) Decomposition: . . .
. . .
```



Rules for Neigborhood Constraints

```
(FFS) Function Symbols: . . .
(NFS) Name vs Function Symbol: . . .
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Simple example

Problem to solve: p(x, y) = ?q(f(a), g(b))

Solution: ...



Steps Pre-Unification





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Steps Constraint-Simplification



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System Model



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Workflow