CSE110A: Compilers

June 3, 2024

Topics:

- Advanced Loop Optimizations
- Intro to instruction scheduling

Announcements

- HW 5 is due on Friday
 - Hope you've made good progress on it.
 - Several office hours remaining from TAs, tutors, and me.

 We are doing our best on grading. HW 3 grades should be released imminently.

No more quizzes for the rest of the quarter

Announcements

- Final Exam
 - In Person
 - Monday June 10: Noon 3 PM
 - 3 pages of notes (front and back)
 - Like the midterm
 - Designed to be 2x as long, but final has 3x time.
 - 4 questions instead of 3
 - Comprehensive, slightly more weight to last part of class

Topics to study for final

- **Module 1:** Token definitions, Regular expressions, Scanner API, Scanner implementations.
- Module 2: Grammars (BNF Form), parse trees, ambiguous grammars (and how to fix them). Precedence, associativity (of the operators in your homework), Top down parsers
- **Module 3:** ASTs how to create them, node types and members, modifications. Simple type systems, linearizing ASTs into 3 address code.
- Module 4: basic blocks, local value numbering, for loop analysis (loop unrolling).

More loop optimizations

More loop transforms

Loop nesting order

Loop tiling

General area is called polyhedral compilation

New constraints:

- Typically requires that loop iterations are independent
 - You can do the loop iterations in any order and get the same result

are these independent?

```
for (int i = 0; i < 2; i++) {
  counter += 1;
}</pre>
```

VS

```
for (int i = 0; i < 1024; i++) {
   counter = i;
}</pre>
```

adds two arrays

what about a random order?

```
for (int i = 0; i < SIZE; i++) {
  a[i] = b[i] + c[i];
}</pre>
```

```
for (pick i randomly) {
   a[i] = b[i] + c[i];
}
```

adds elements with neighbors

```
for (int i = 0; i < SIZE; i++) {
  a[i] += a[i+1];
}</pre>
```

```
for (pick i randomly) {
   a[i] += a[i+1];
}
```

DSL example

Image processing:





pretty straight forward computation for brightening

(1 pass over all pixels)

Taken from Halide: A DSL project out of MIT

This computation is known as the "Local Laplacian Filter". Requires visiting all pixels 99 times





We want to be able to do this fast and efficiently!

Main results in from an image DSL show a 1.7x speedup with 1/5 the LoC over hand optimized versions at Adobe

Image processing:





pretty straight forward computation for brightening

(1 pass over all pixels)

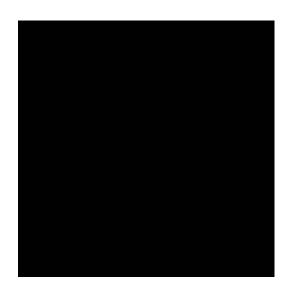
Taken from Halide: A DSL project out of MIT

This computation is known as the "Local Laplacian Filter". Requires visiting all pixels 99 times





DSL provides two languages: one for the computation, and one for the optimizations and orders



```
for (int y = 0; y < 4; y++) {
    for (int x = 0; x < 4; x++) {
        output[y,x] = x + y;
    }
}</pre>
```

you can compute the pixels in any order you want, you just have to compute all of them!



```
for (int y = 0; y < 4; y++) {
    for (int x = 0; x < 4; x++) {
        output[y,x] = x + y;
    }
}</pre>
```

you can compute the pixels in any order you want, you just have to compute all of them!



```
for (int x = 0; x < 4; x++) {
    for (int y = 0; y < 4; y++) {
        output[y,x] = x + y;
    }
}</pre>
```

What is the difference here? What will the difference be?

Demo

• Why do we see the performance difference?

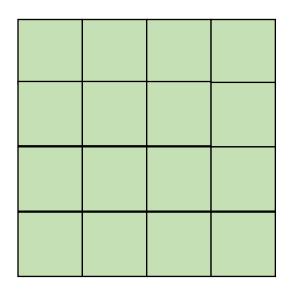
Demo

Memory accesses

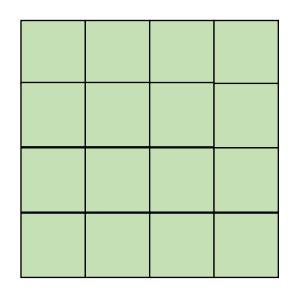
$$A = B + C$$

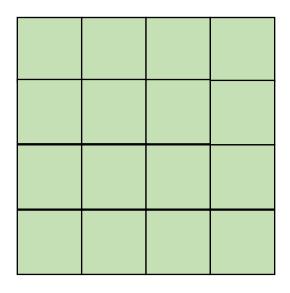
B

 \mathcal{C}



A





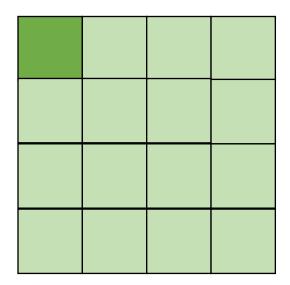
Demo

Memory accesses

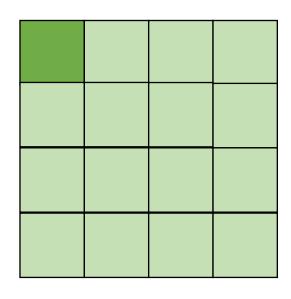
$$A = B + C$$

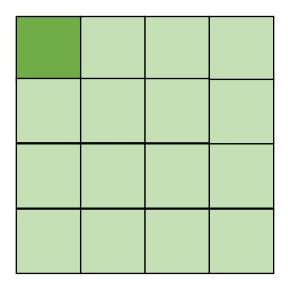
B

C



 \boldsymbol{A}





Cache miss for all of them

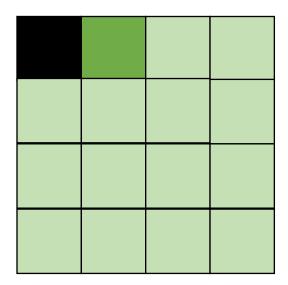
Demo

Memory accesses

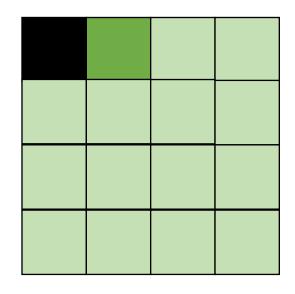
$$A = B + C$$

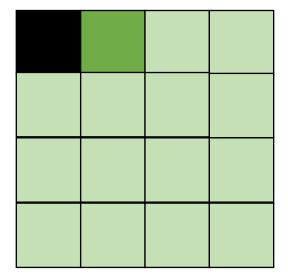
B

 \mathcal{C}



 \boldsymbol{A}





Cache HIT for all of them

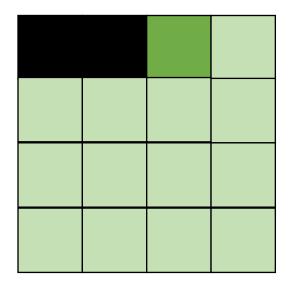
Demo

Memory accesses

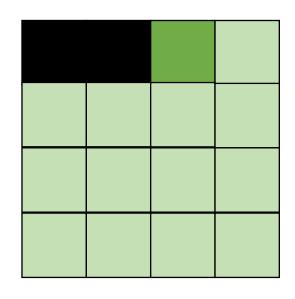
$$A = B + C$$

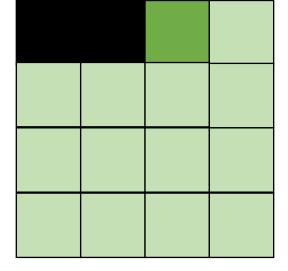
B

С



 \boldsymbol{A}





Cache HIT for all of them

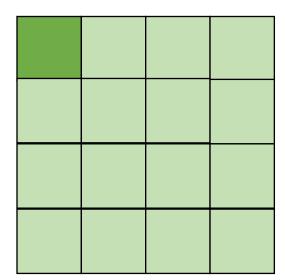
Demo

Memory accesses

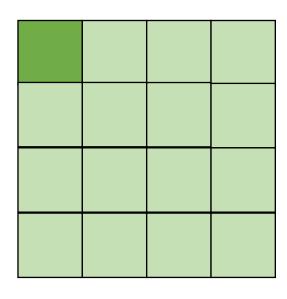
$$A = B + C$$

В

C



 \boldsymbol{A}



Rewind!

Cache miss for all of them

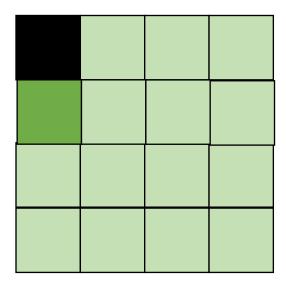
Demo

Memory accesses

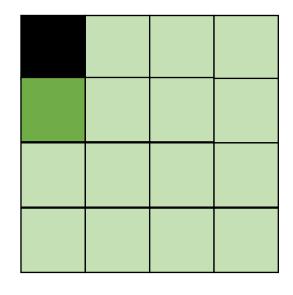
$$A = B + C$$

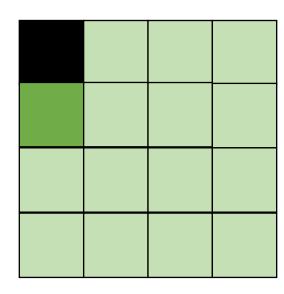
B

 \mathcal{C}



 \boldsymbol{A}





Rewind!

Cache miss for all of them

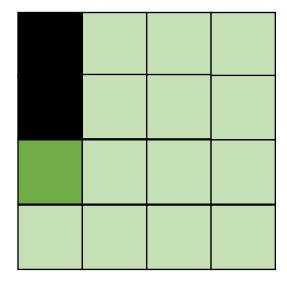
Demo

Memory accesses

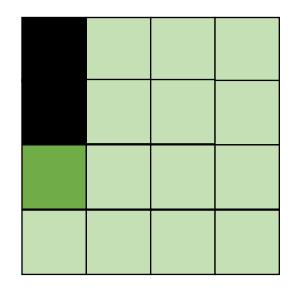
$$A = B + C$$

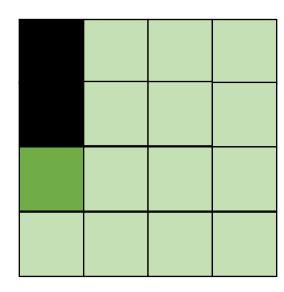
B

 \mathcal{C}



 \boldsymbol{A}





Rewind!

Cache miss for all of them

But sometimes there isn't a good ordering

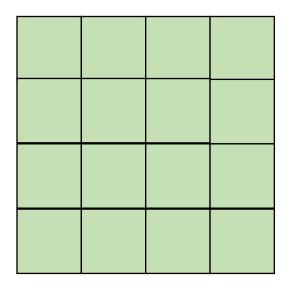
• In some cases, there might not be a good nesting order for all accesses:

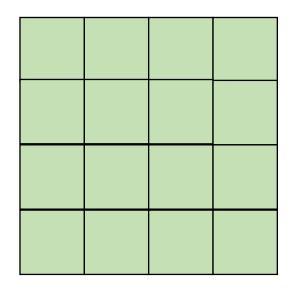
$$A = B + C^T$$

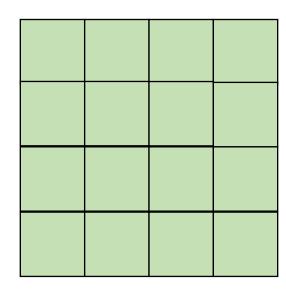
 \boldsymbol{A}

B

L





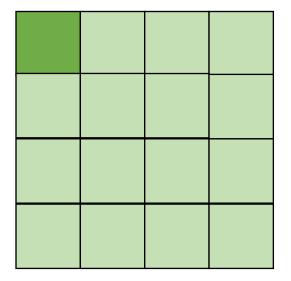


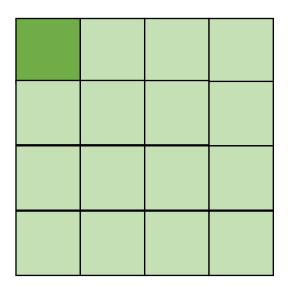
 In some cases, there might not be a good nesting order for all accesses:

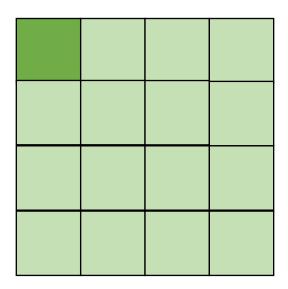
$$A = B + C^T$$

 \boldsymbol{A}

В







cold miss for all of them

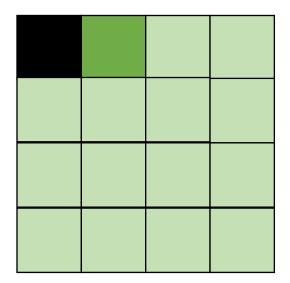
 In some cases, there might not be a good nesting order for all accesses:

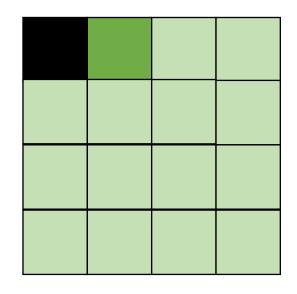
$$A = B + C^T$$

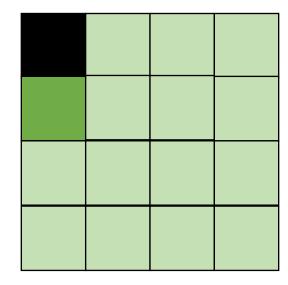
 \boldsymbol{A}

B

C







Hit on A and B. Miss on C

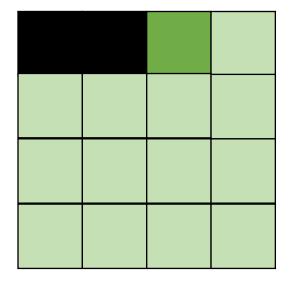
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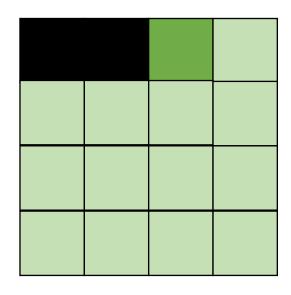
$$A = B + C^T$$

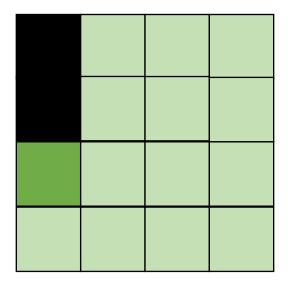
 \boldsymbol{A}

B

C







Hit on A and B. Miss on C

What happens here?

• Demo

How can we fix it?

• Can we use the compiler?

Does loop order matter?

```
for (int y = 0; y < 4; y++) {
    for (int x = 0; x < 4; x++) {
        output[y,x] = x + y;
    }
}</pre>
```

Loop Splitting

First unroll,
Then put back into a loop

```
for (int y = 0; y < 4; y++) {
    for (int x = 0; x < 4; x++) {
        output[y,x] = x + y;
    }
}</pre>
```

Loop splitting:

```
for (int y = 0; y < 4; y++) {
    for (int x_outer = 0; x_outer < 4; x_outer+=2) {
        for (int x = x_outer; x < x_outer+2; x++) {
            output[y,x] = x + y;
            }
        }
    }
}</pre>
```

What is the difference here?

Does loop splitting by itself work?

- Lets try it
 - demo

We can chain optimizations

- Lets try chaining loop splitting and reorder
 - Demo

We can chain optimizations

- Lets try chaining loop splitting and reorder
 - Demo
- What happened?!

Our new schedule looks like this:



Why is this beneficial?

from: https://halide-lang.org/tutorials/tutorial_lesson_05_scheduling_1.html

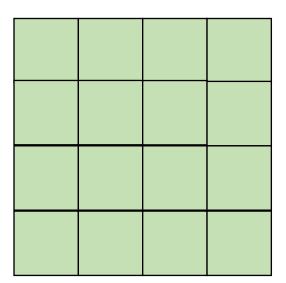
blocking

blocking

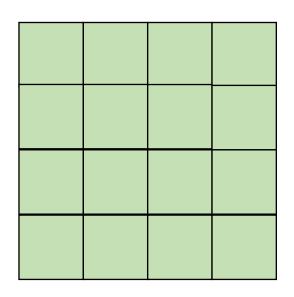
 Blocking operates on smaller chunks to exploit locality in column increment accesses. Example 2x2

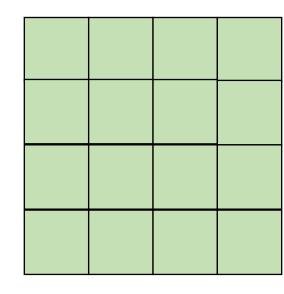
$$A = B + C^T$$

 \boldsymbol{A}



B

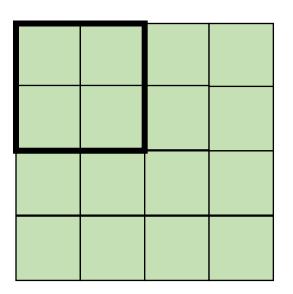




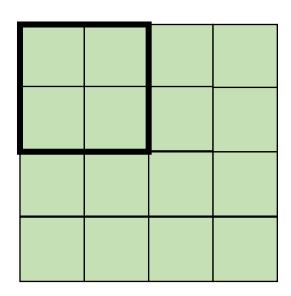
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$$A = B + C^T$$

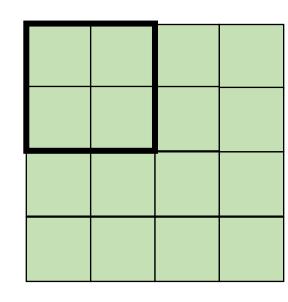
 \boldsymbol{A}



В



 \mathcal{C}



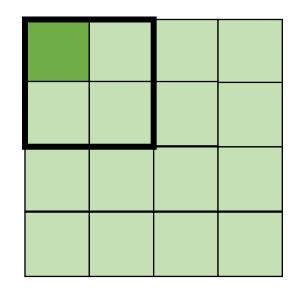
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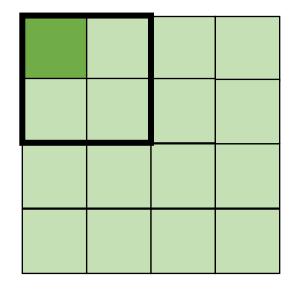
$$A = B + C^T$$

 \boldsymbol{A}



B





cold miss for all of them

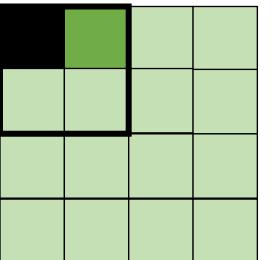
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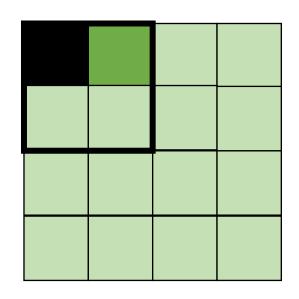
$$A = B + C^T$$

 \boldsymbol{A}

A

B





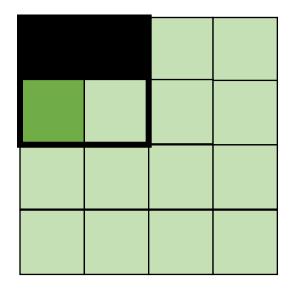
Miss on C

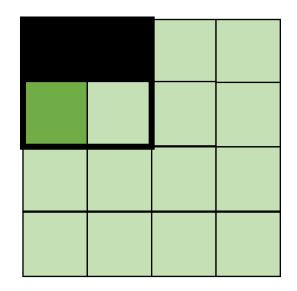
• Blocking operates on smaller chunks to exploit locality in column increment accesses. Example 2x2

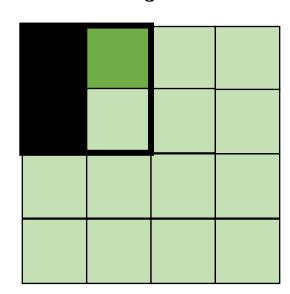
$$A = B + C^T$$

 \boldsymbol{A}

B







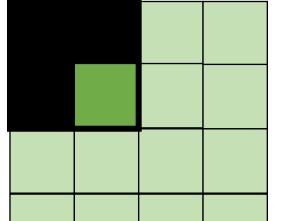
Miss on A,B, hit on C

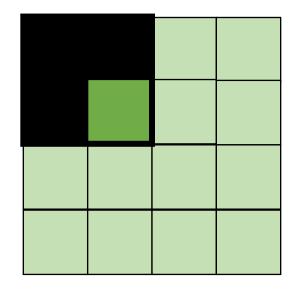
• Blocking operates on smaller chunks to exploit locality in column increment accesses. Example 2x2

$$A = B + C^T$$

 \boldsymbol{A}

В





Hit on all!

Other uses of loop split

• Say your processor can vectorize 4 elements at a time

```
for (int y = 0; y < 4; y++) {
               for (int x = 0; x < 8; x++) {
                   output[y, x] = x + y;
for (int y = 0; y < 4; y++) {
    for (int x outer = 0; x outer < 8; x outer+=4) {</pre>
        for (int x = x_outer; x < x outer+4; x++) {
           output[y,x] = x + y;
```

Other uses of loop split

```
for (int y = 0; y < 4; y++) {
    for (int x_outer = 0; x_outer < 8; x_outer+=4) {
        for (int x = x_outer; x < x_outer+4; x++) {
            output[y,x] = x + y;
            }
        }
    }
}</pre>
```



Loop transformation summary

 If the compiler can prove different properties about your loops, you can automatically make code go a lot faster

- It is hard in languages like C/C++. But in constrained languages (often called domain specific languages (DSLs) it is easier!
 - Hot topic right now for Machine learning, graphics, graph analytics, etc!





Main results in from an image DSL show a 1.7x speedup with 1/5 the LoC over hand optimized versions at Adobe

from: https://people.csail.mit.edu/sparis/publi/2011/siggraph/

New material – Instruction Level Parallelism

- Parallelism from a single stream of instructions.
 - Output of program must match exactly a sequential execution!

- Widely applicable:
 - most mainstream programming languages are sequential
 - most deployed hardware has components to execute ILP

• Done by a combination of programmer, compiler, and hardware

• What type of instructions can be done in parallel?

What type of instructions can be done in parallel?

two instructions can be executed in parallel if they are independent

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two instructions can be executed in parallel if they are independent

$$x = z + w;$$

 $a = b + c;$

Two instructions are independent if the operand registers are disjoint from the result registers

(assume all letter variables are registers)

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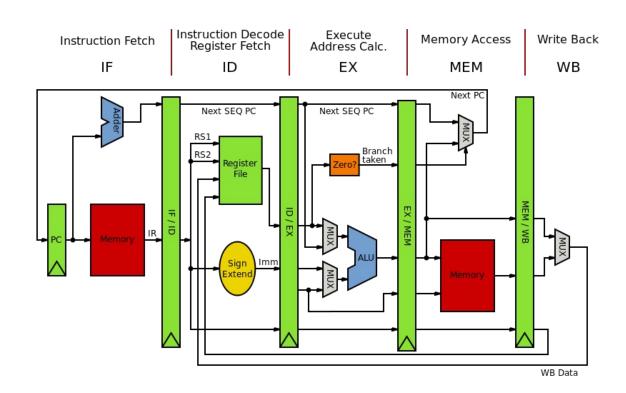
 $a = b + x;$

Many times, dependencies can be easily tracked in the compiler:

How can hardware execute ILP?

• Pipeline parallelism

- Abstract mental model:
 - N-stage pipeline
 - N instructions can be in-flight
 - Dependencies stall pipeline



• Pipeline parallelism

 Abstract mental model for compiler:

- N-stage pipeline
- N instructions can be in-flight
- Dependencies stall pipeline

instr1;

instr2;

instr3;

stage 1

stage 2

stage 3

Pipeline parallelism

 Abstract mental model for compiler:

N-stage pipeline

• N instructions can be in-flight

• Dependencies stall pipeline

stage 1

stage 2

stage 3

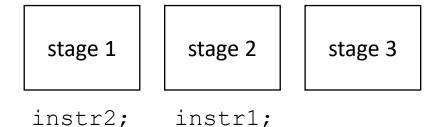
```
instr1;
```

instr2;

instr3;

• Pipeline parallelism

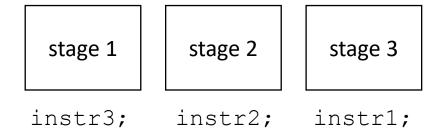
- Abstract mental model for compiler:
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instr3;

Pipeline parallelism

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Pipeline parallelism

- Abstract mental model for compiler:
 - N-stage pipeline
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stage 1 stage 2

stage 3

6 cycles for 3 independent instructions

Converges to 1 instruction per cycle

Pipeline parallelism

 Abstract mental model for compiler:

- N-stage pipeline
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stage 1

stage 2

stage 3

instr1;
instr2;
instr3;

Pipeline parallelism

 Abstract mental model for compiler:

- N-stage pipeline
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stage 1

stage 2

stage 3

instr1;

What if the instructions depend on each other?

instr2;

instr3;

Pipeline parallelism

 Abstract mental model for compiler:

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instr2;
instr3;

Pipeline parallelism

 Abstract mental model for compiler:

N-stage pipeline

• N instructions can be in-flight

• Dependencies stall pipeline

stage 1

stage 2

stage 3

instr1;

instr2;
instr3;

Pipeline parallelism

 Abstract mental model for compiler:

• N-stage pipeline

• N instructions can be in-flight

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stage 1

stage 2

stage 3

instr2;
instr3;

Pipeline parallelism

 Abstract mental model for compiler:

- N-stage pipeline
- N instructions can be in-flight
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stage 1

stage 2

stage 3

instr2;

instr3;

Pipeline parallelism

 Abstract mental model for compiler:

- N-stage pipeline
- N instructions can be in-flight
- Dependencies stall pipeline

stage 1 stage 2 stage 3

instr3;

and so on...

Pipeline parallelism

 Abstract mental model for compiler:

- N-stage pipeline
- N instructions can be in-flight
- Dependencies stall pipeline

stage 1

stage 2

stage 3

What if the instructions depend on each other?

9 cycles for 3 instructions

converges to 3 cycles per instruction

Pipeline parallelism

 Abstract mental model for compiler:

- N-stage pipeline
- N instructions can be in-flight
- Dependencies stall pipeline

instr1;
instrX0;
instrX1;
instr2;
instrX2;
instrX3;
instrX3;

stage 1

stage 2

stage 3

Pipeline parallelism

- Abstract mental model for compiler:
 - N-stage pipeline
 - N instructions can be in-flight
 - Dependencies stall pipeline

```
instrX0;
instrX1;
instr2;
instrX2;
instrX3;
instr3;
```

stage 1 stage 2 stage 3

instr1;

• Pipeline parallelism

- Abstract mental model for compiler:
 - N-stage pipeline
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```
instrX1;
instr2;
instrX2;
instrX3;
instrX3;
```

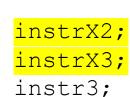
• Pipeline parallelism

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 - Dependencies stall pipeline

```
instr2;
instrX2;
instrX3;
instr3;
```

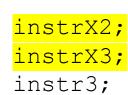
• Pipeline parallelism

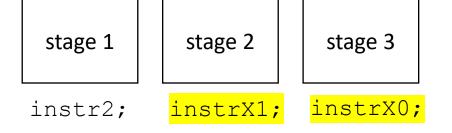
- Abstract mental model for compiler:
 - N-stage pipeline
 - N instructions can be in-flight
 - Dependencies stall pipeline



Pipeline parallelism

- Abstract mental model for compiler:
 - N-stage pipeline
 - N instructions can be in-flight
 - Dependencies stall pipeline





and so on...

We converge to 1 cycle per instruction again!

How can hardware execute ILP?

- Executing multiple instructions at once:
- Superscalar architecture:
 - Several sequential operations are issued in parallel
 - hardware detects dependencies

```
issue-width is maximum number of instructions that can be issued in parallel
instr0;
instr1;
instr2;
if instr0 and instr1 are independent, they will be issued in parallel
```

It's even more complicated

- Out-of-order execution delays dependent instructions
 - Reorder buffers (RoB) track dependencies
 - Load-Store Queues (LSQ) hold outstanding memory requests

What does this look like in the real world?

- Intel Haswell (2013):
 - Issue width of 4
 - 14-19 stage pipeline
 - OoO execution
- Intel Nehalem (2008)
 - 20-24 stage pipeline
 - Issue width of 2-4
 - OoO execution
- ARM
 - V7 has 3 stage pipeline; Cortex V8 has 13
 - Cortex V8 has issue width of 2
 - OoO execution

- RISC-V
 - Ariane and Rocket are In-Order
 - 3-6 stage pipelines
 - some super scaler implementations (BOOM)

What does this mean for us?

 We should have an abstract and parametrized performance model for instruction scheduling (the order of instructions)

Try not to place dependent instructions in sequence

• Many times the compiler will help us here, but sometimes it cannot!

Three techniques to optimize for ILP

Independent for loops (loop unrolling)

Reduction for loops (loop unrolling)

Priority topological ordering (if there is time)

What is loop unrolling?

can we unroll this loop?

```
for (int i = 0; i < 4; i++) {
  a[i] = b[i] + c[i];
}</pre>
```

• for loops with independent chains of computation

```
for (int i = 0; i < SIZE; i++) {
    SEQ(i);
}</pre>
```

and let instr(N) depends on instr(N-1)

loops only write to memory addressed by the loop variable

• Simple loop unrolling:

```
for (int i = 0; i < SIZE; i+=2) {
    SEQ(i);
    SEQ(i+1);
}</pre>
```

Saves one addition and one comparison per loop, but doesn't help with ILP

• Simple loop unrolling:

```
for (int i = 0; i < SIZE; i+=2) {
    SEQ(i);
    SEQ(i+1);</pre>
```

Let green highlights indicate instructions from iteration i.

Let blue highlights indicate instructions from iteration i + 1.

• Simple loop unrolling:

```
for (int i = 0; i < SIZE; i+=2) {
    SEQ(i);
    SEQ(i+1);
}</pre>
```

Let SEQ(i,j) be the jth instruction of SEQ(i).

Let each instruction chain have N instructions

Simple loop unrolling:

```
for (int i = 0; i < SIZE; i+=2) {
    SEQ(i,1);
    SEQ(i,2);
    SEQ(i,N); // end iteration for i
    SEQ(i+1,1);
    SEQ(i+1,2);
    SEQ(i+1, N); // end iteration for i + 1
```

Let SEQ(i,j) be the jth instruction of SEQ(i).

Let each instruction chain have N instructions

Simple loop unrolling:

```
for (int i = 0; i < SIZE; i+=2) {
    SEQ(i,1);
    SEQ(i+1,1);
    SEQ(i,2);
    They can be interleaved
    SEQ(i+1,2);
    ...
    SEQ(i,N);
    SEQ(i+1, N);
}</pre>
```

Simple loop unrolling:

```
for (int i = 0; i < SIZE; i+=2) {
    SEQ(i,1);
    SEQ(i+1,1);
    SEQ(i,2);
    SEQ(i+1,2);
    ...
    SEQ(i,N);
    SEQ(i+1, N);</pre>
```

They can be interleaved

two instructions can be pipelined, or executed on a superscalar processor

General case

- Dependency graphs
 - Nodes are IR instructions
 - Edges are dependencies
 - Different traversals can provide better ILP!
 - Not enough time to go into detail this quarter, but the topic is known as instruction scheduling