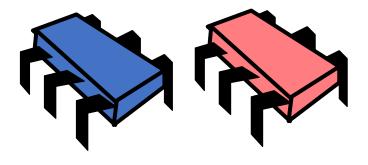
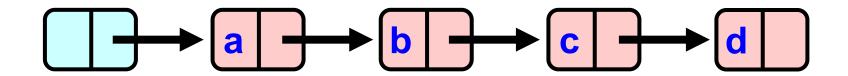
CSE113: Parallel Programming

March 13, 2024

- Topics:
 - Concurrent general set





Last day of class!

Grading

- HW 2 is graded. Please let us know ASAP if there are any issues.
 - Let us know by Thursday (tomorrow) if there are issues
 - Auto grading is difficult here, so don't hesitate to reach out! Make a private post on piazza or see a TA
 - Trying to have HW 3 graded by the end of the week

- HW 5 was released last Friday
 - Due on the day of the final
 - Last day to turn it in is the 21
 - It could be useful to work on for the final
 - You should have everything you need to complete the homework

Final

Allowed 3 pages of notes, front and back

Similar to the midterm (50% longer)

• Time: Monday March 18: 7:30 – 10:30 PM

SETs are out, please do them! It helps us out a lot

Both bad things and good things!

Video games for parallel programming education

- Joint project with the CM department
- Performing a user-study
- Max 160 minutes, \$30 cash
- Play a puzzle video game with parallel programming concepts
- Located in the UC Santa Cruz Silicon Valley Campus
- Includes a tour of the campus, meet & greet with the CM researchers there
- I'll post more information in canvas

The C++ relaxed memory order provides

- no orderings at all
- orderings only between accesses of the same address
- TSO memory behaviors when run on an x86 system
- o an easy way to accidentally introduce horrible bugs into your program

Relaxed memory order

language C++11 (sequential consistency)

ı

S

NO	NO
NO	NO

language C++11 (memory_order_relaxed)

. S

different different address

different different different address address

S

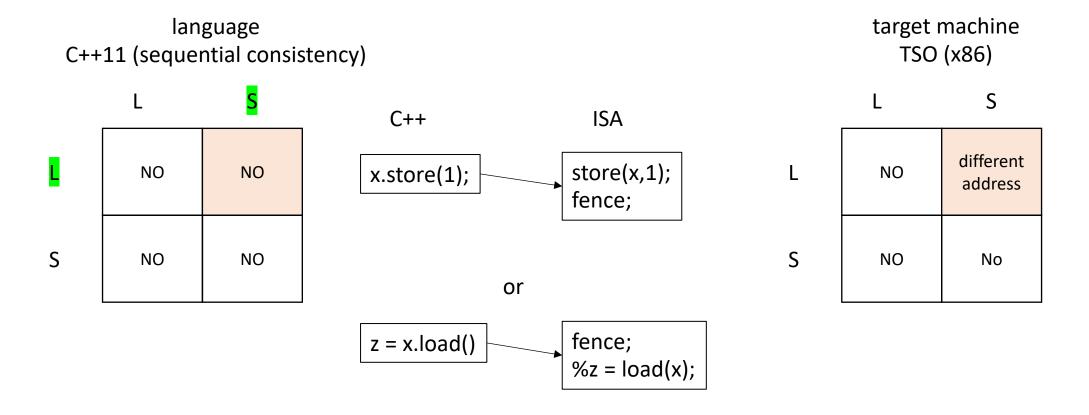
basically no orderings except for accesses to the same address

In terms of memory models, the compiler needs to ensure the following property:

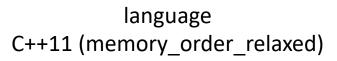
- Any weak behavior allowed in the language is also allowed in the ISA
- O Any weak behaviors that are disallowed in the language need to be disallowed in the ISA
- The compilation ensures that the program has sequentially consistent behavior at the ISA level
- The compiler does not need to reason about relaxed memory

C++11 atomic operation compilation

start with both of the grids for the two different memory models



Compiling memory order relaxed



L S

different address address

S different address different address

lots of mismatches!

But language is more relaxed than machine

so no fences are needed

S

target machine TSO (x86)

. S

NO	different address
NO	No

A program that uses mutexes and has no data conflicts does not have weak memory behaviors for which of the following reasons?

- Mutexes prevent memory accesses from happening close enough in time for weak behaviors to occur
- O The OS has built in support for Mutexes that disable architecture features, such as the store buffer
- A correct mutex implementation uses fences in lock and unlock to disallow weak behaviors

Assuming you had a sequentially consistent processor, any C/++ program you ran on it would also be sequentially consistent, regardless of if there are data-conflicts or not.

○ True

False

If you put a fence after every memory instruction, would that be sufficient to disallow all weak behaviors on a weak architecture? Please write a few sentences explaining your answer.

General concurrent set

Set Interface

- Unordered collection of items
- No duplicates

We will implement this as a sorted linked list

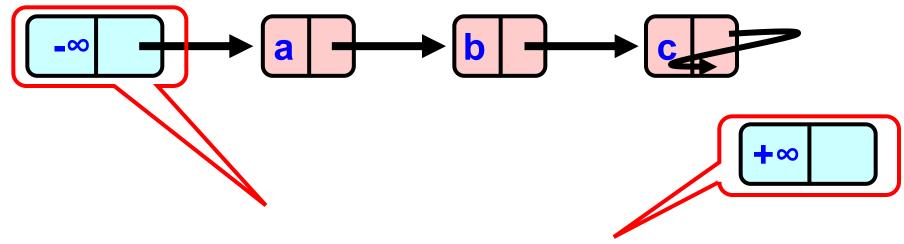
Set Interface

- Unordered collection of items
- No duplicates
- Methods
 - add (x) put x in set
 - remove (x) take x out of set
 - contains (x) tests if x in set

List Node

```
class Node {
  public:
    Value v;
    int key;
    Node *next;
}
```

The List-Based Set



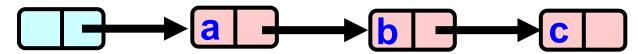
Sorted with Sentinel nodes (min & max possible keys)

Sequential List Based Set

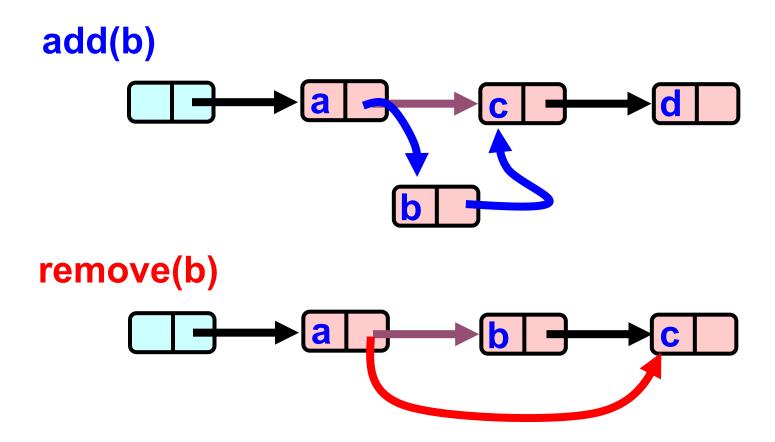
add(b)



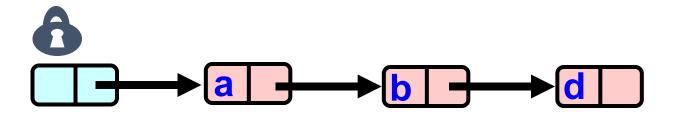
remove(b)



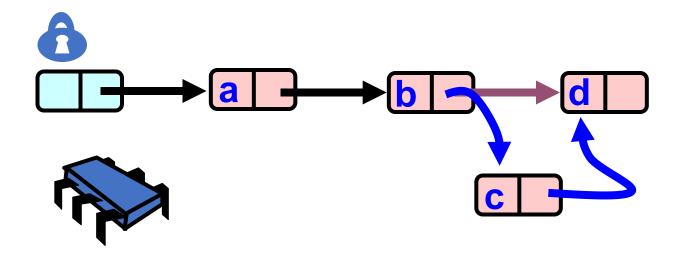
Sequential List Based Set



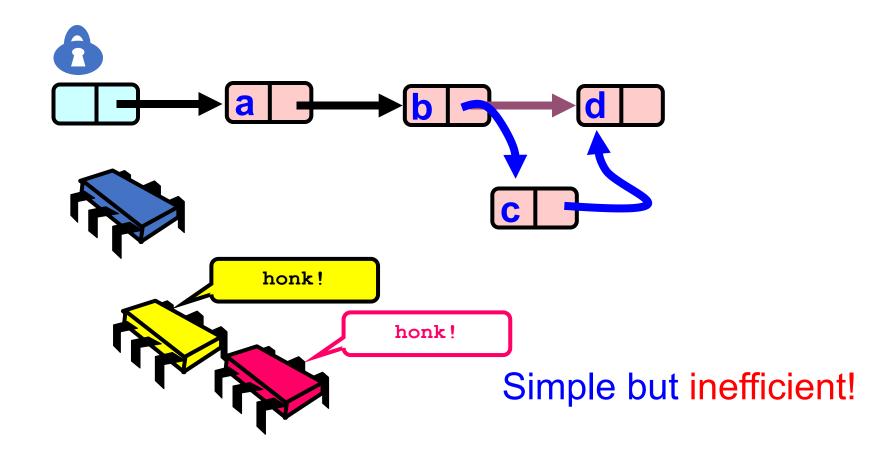
Coarse-Grained Locking



Coarse-Grained Locking

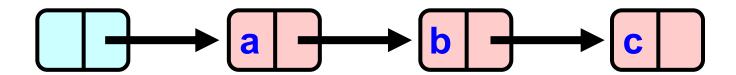


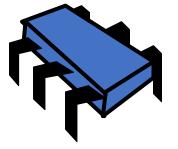
Coarse-Grained Locking

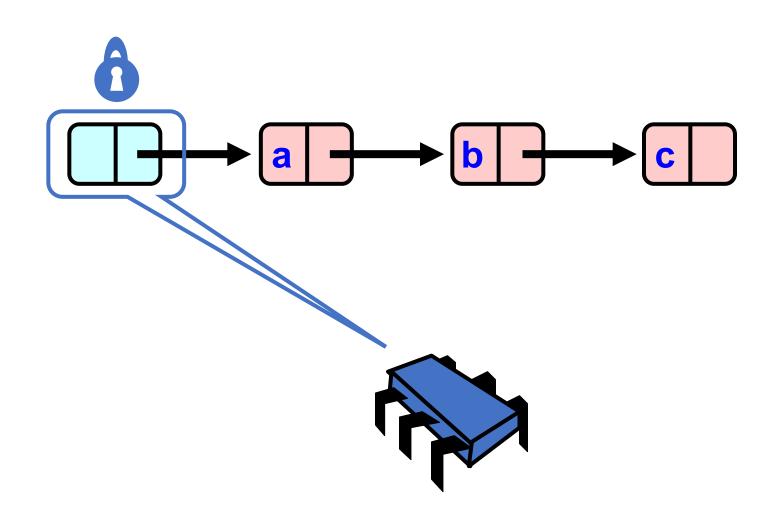


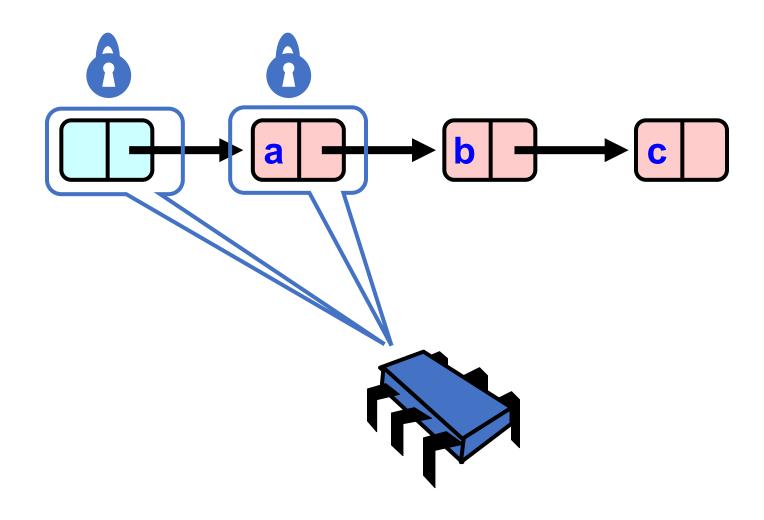
Fine-grained Locking

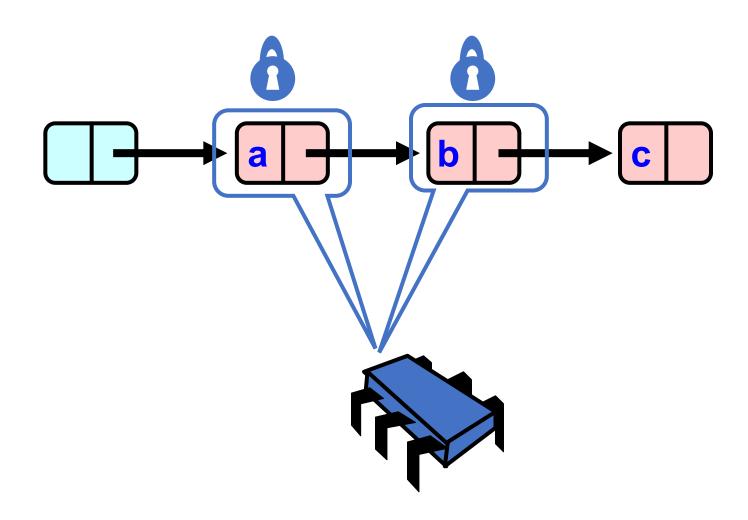
- Requires careful thought
- Split object into pieces
 - Each piece has own lock
 - Methods that work on disjoint pieces need not exclude each other

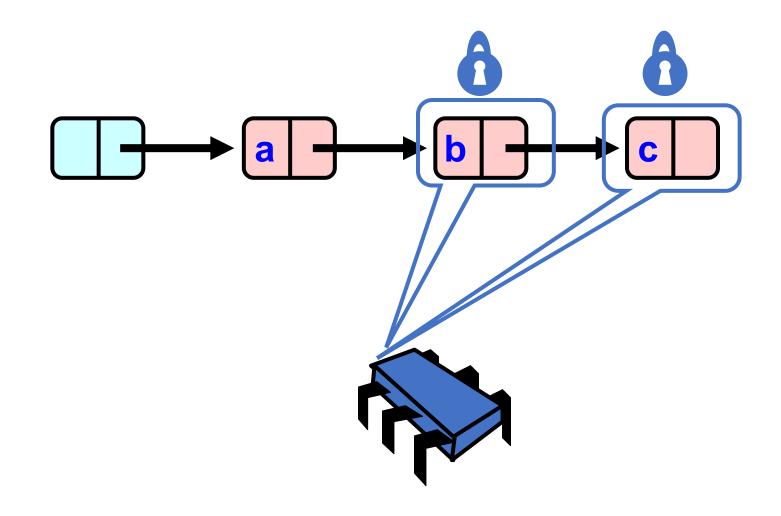


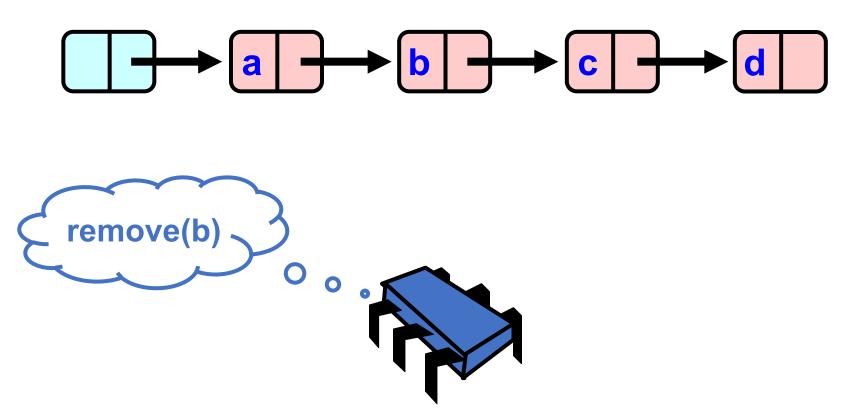


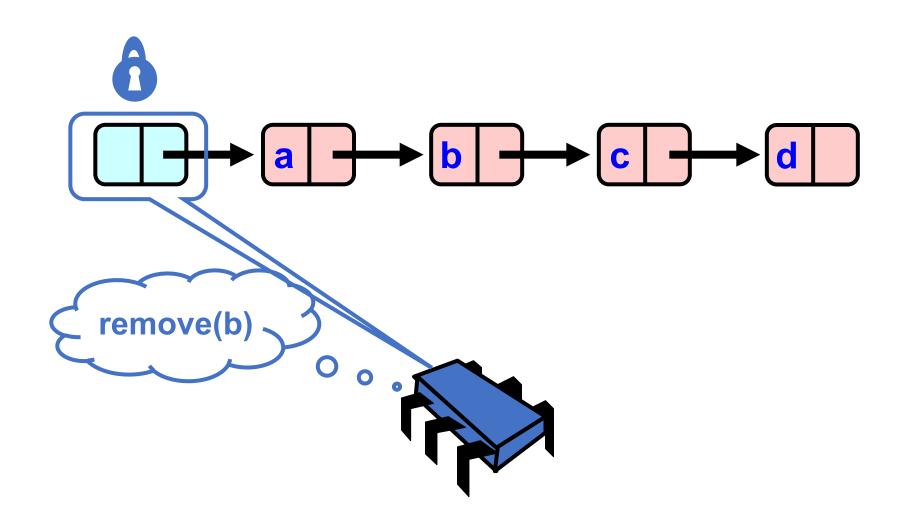


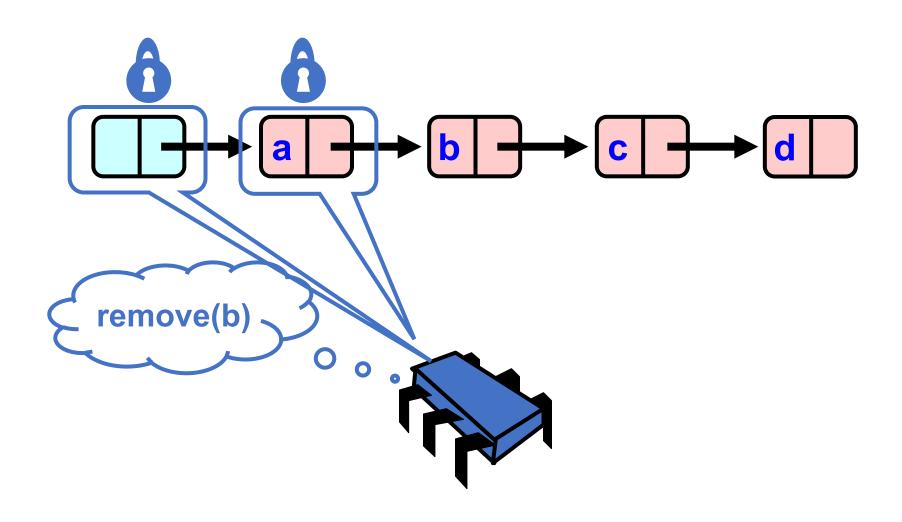


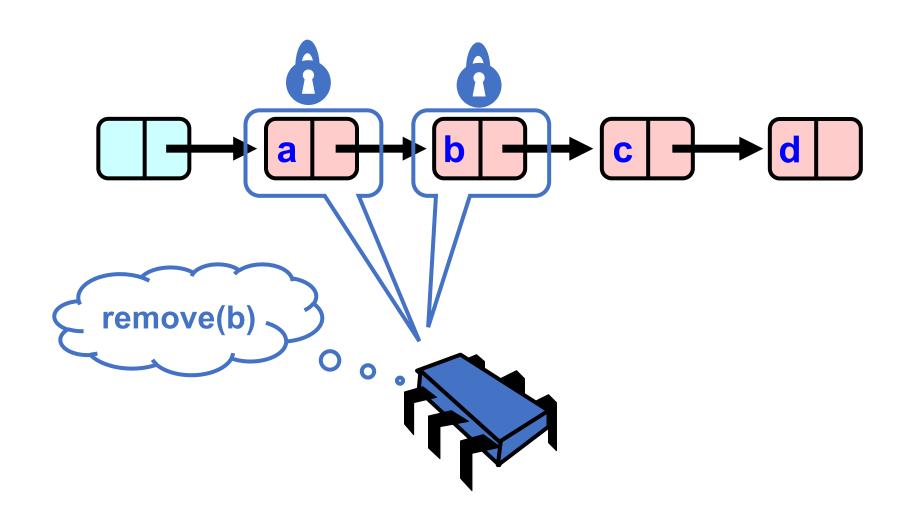


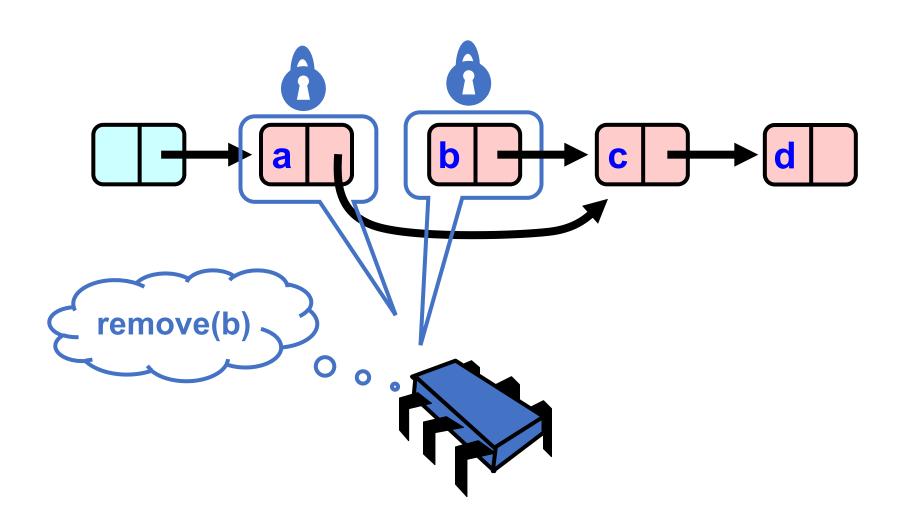


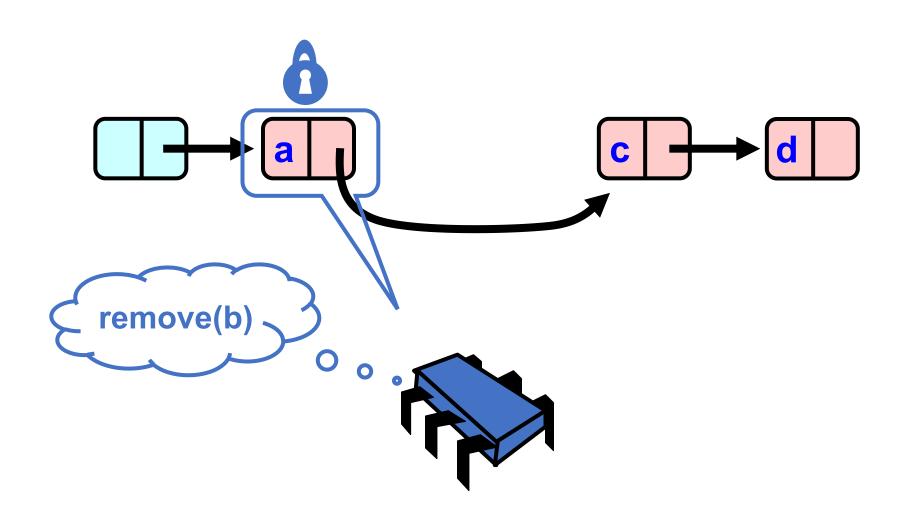


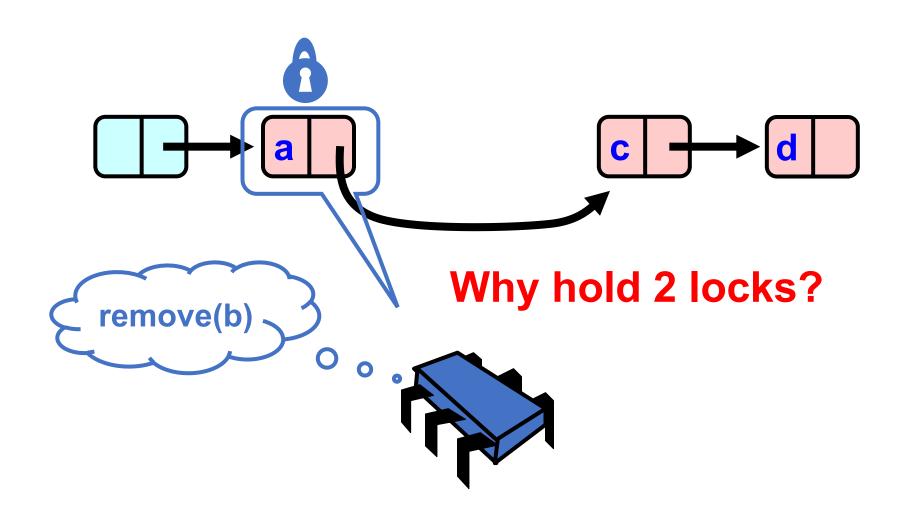


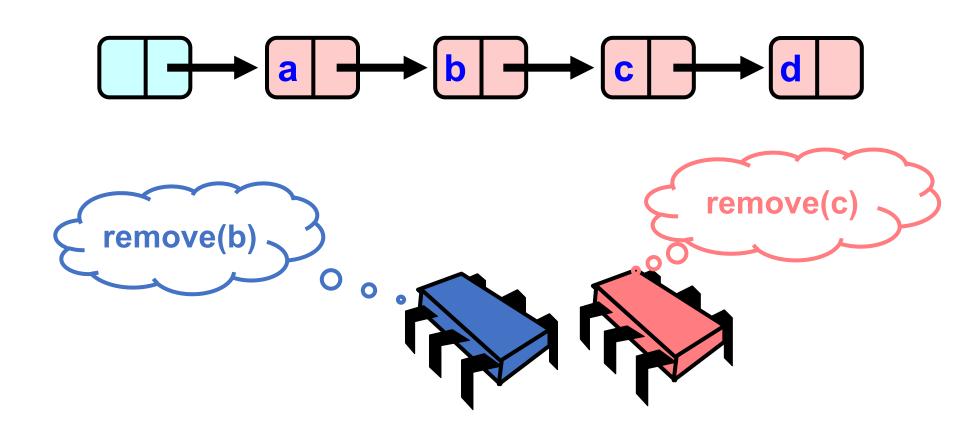


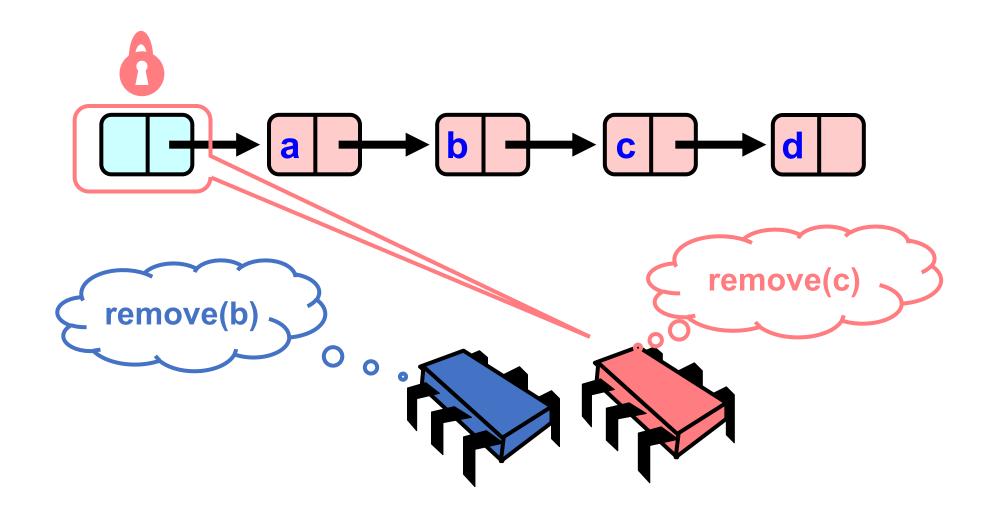


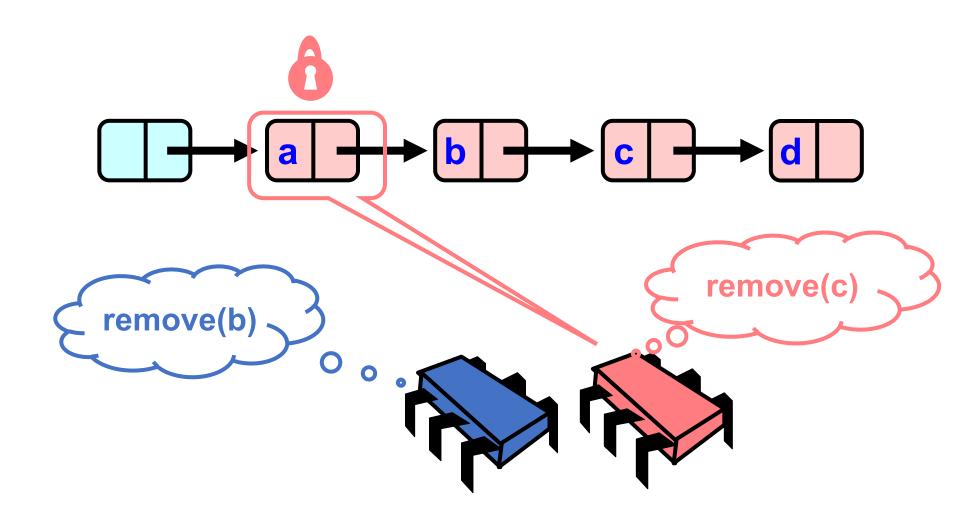


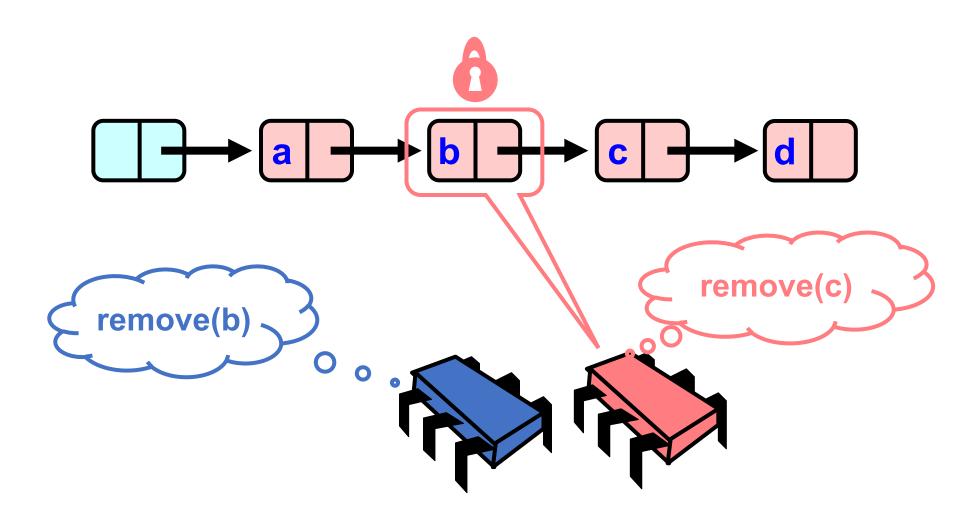


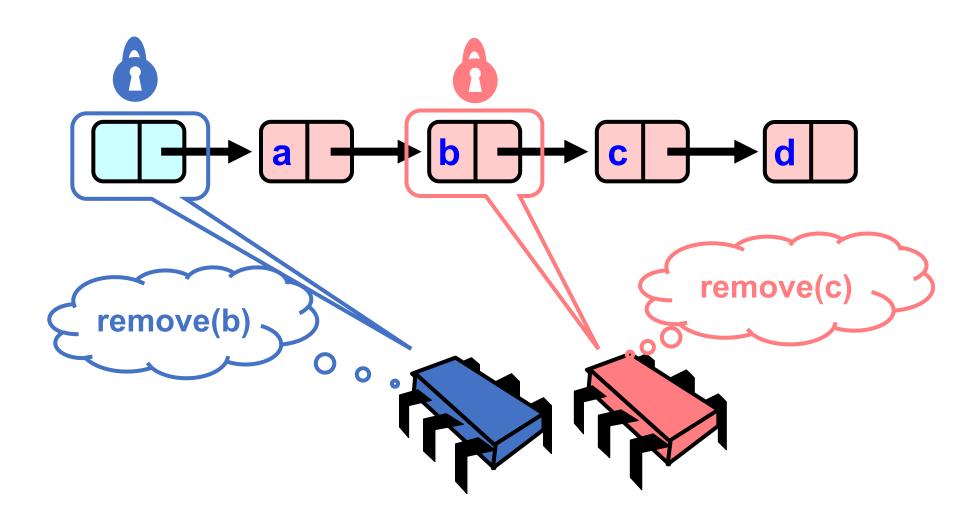


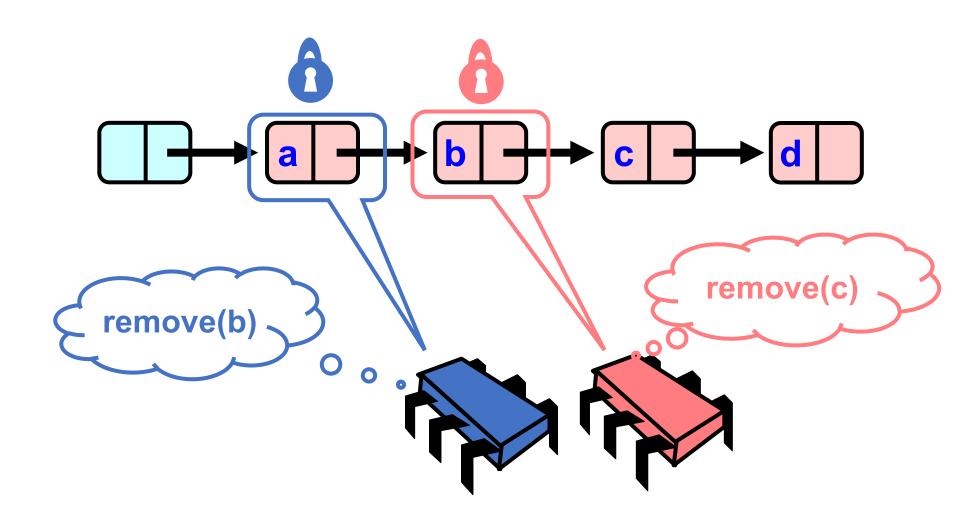


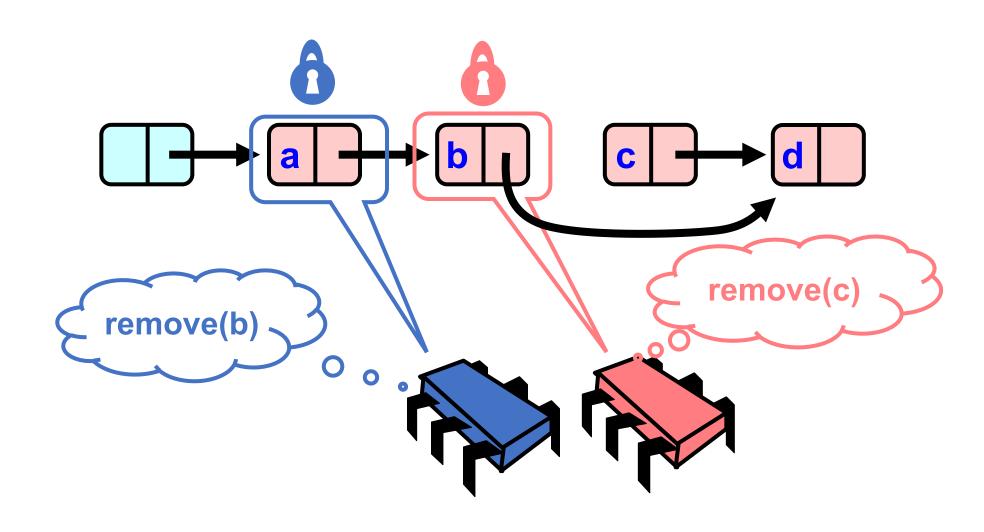


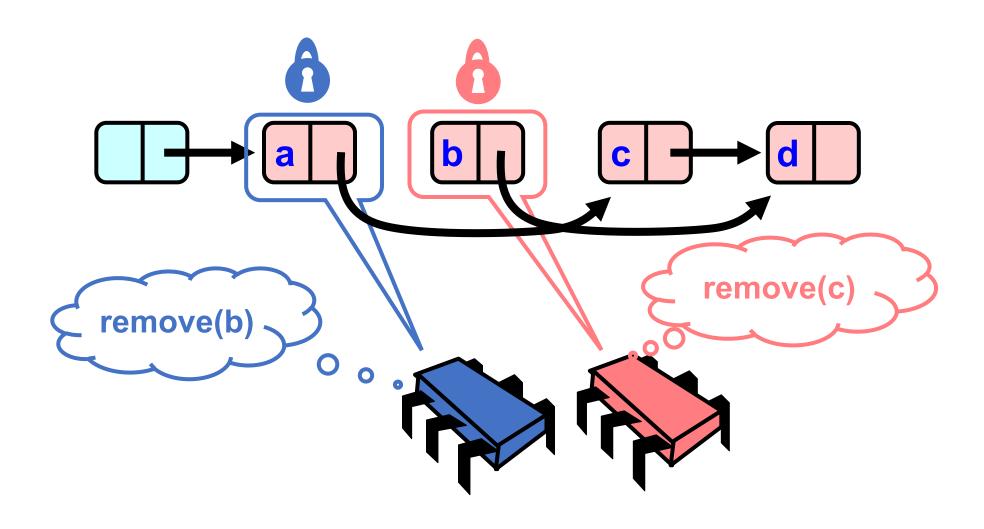




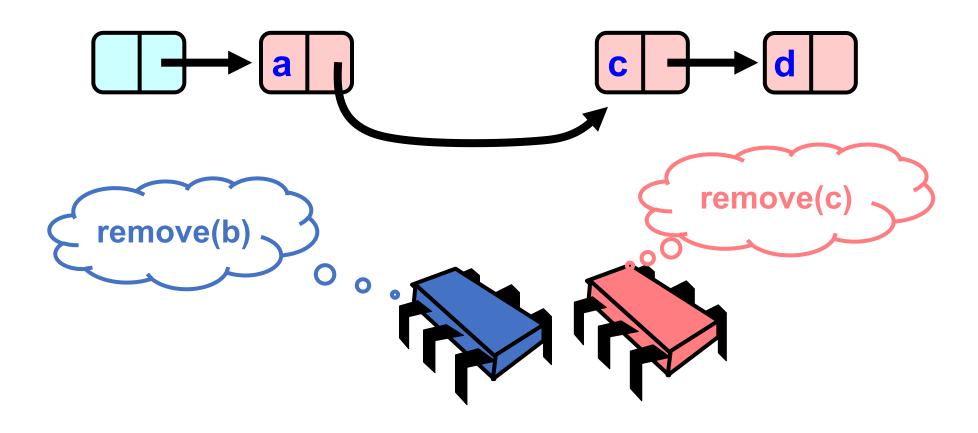






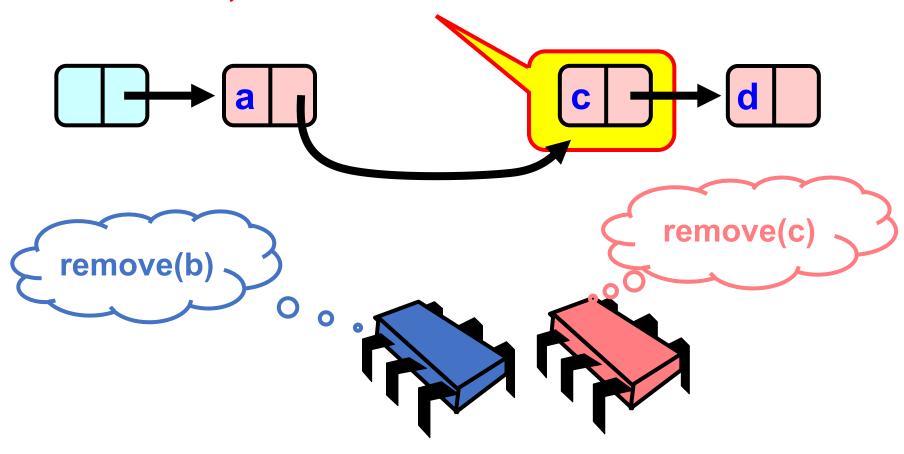


Uh, Oh



Uh, Oh

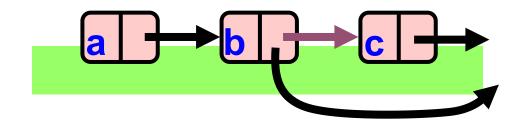
Bad news, c not removed

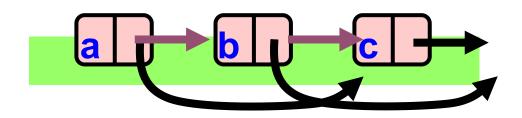


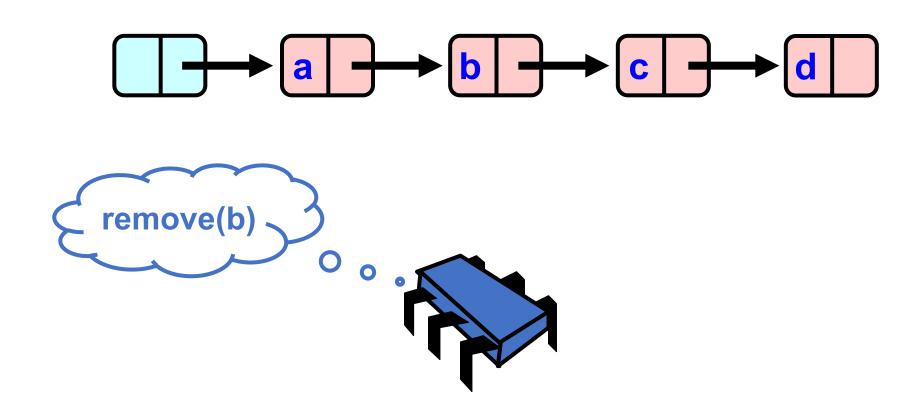
Problem

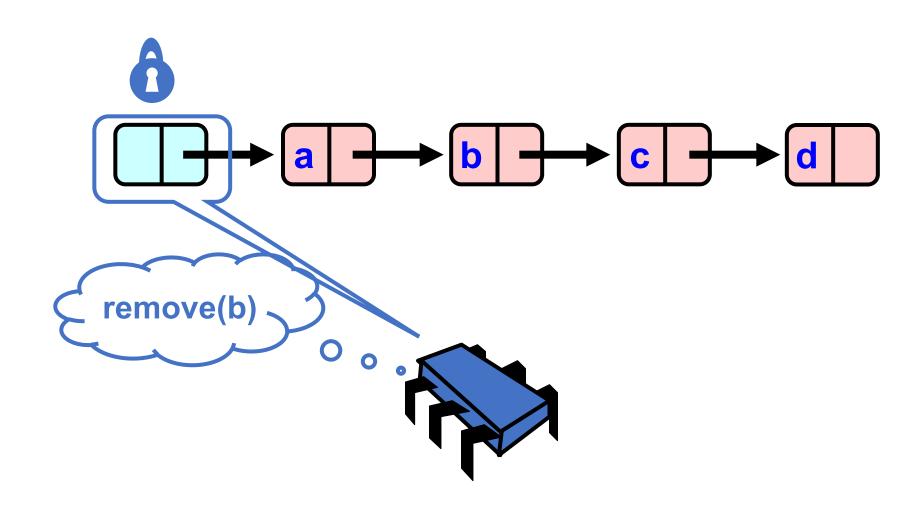
- To delete node c
 - Swing node b's next field to d

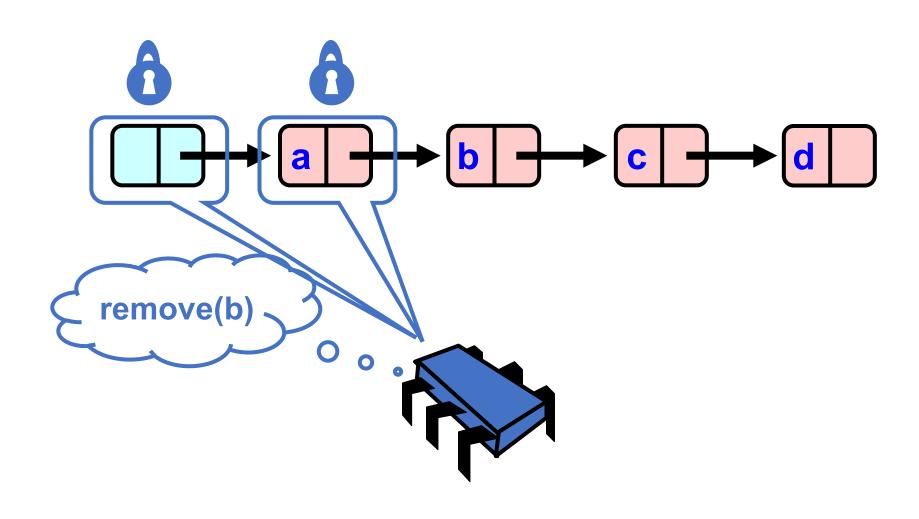
- Problem is,
 - Data conflict:
 - Someone deleting b concurrently could direct a pointer to C

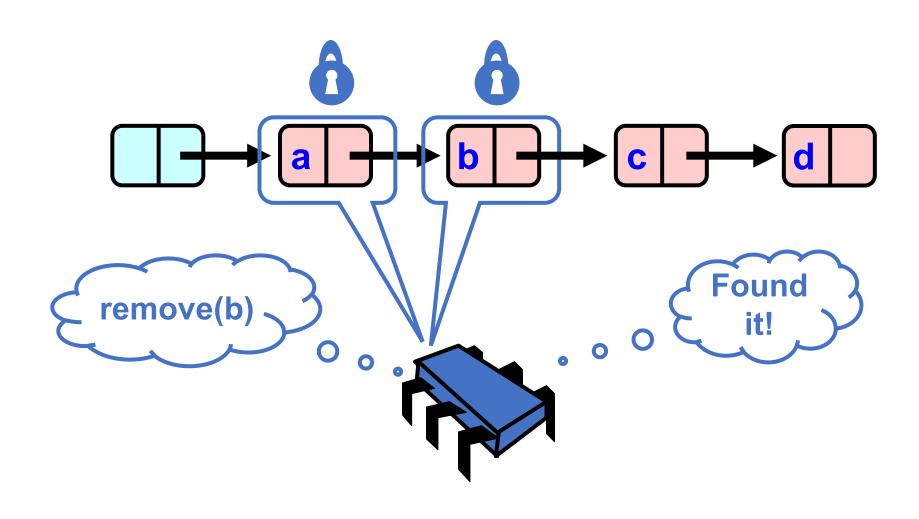


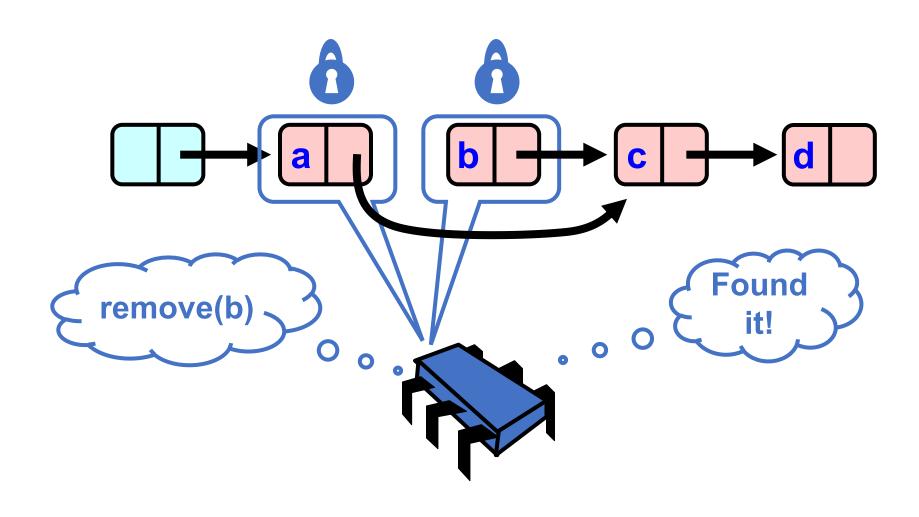


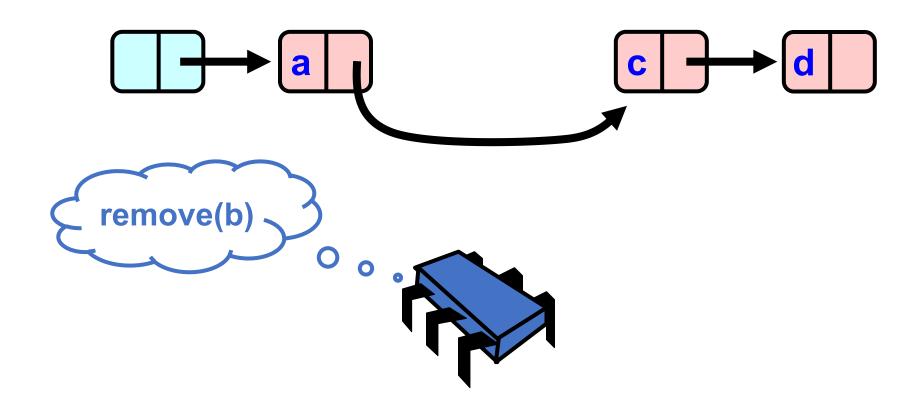


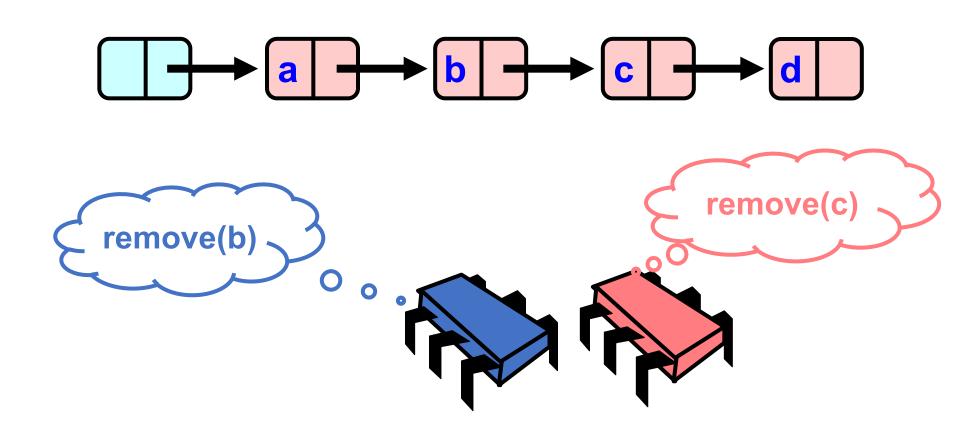


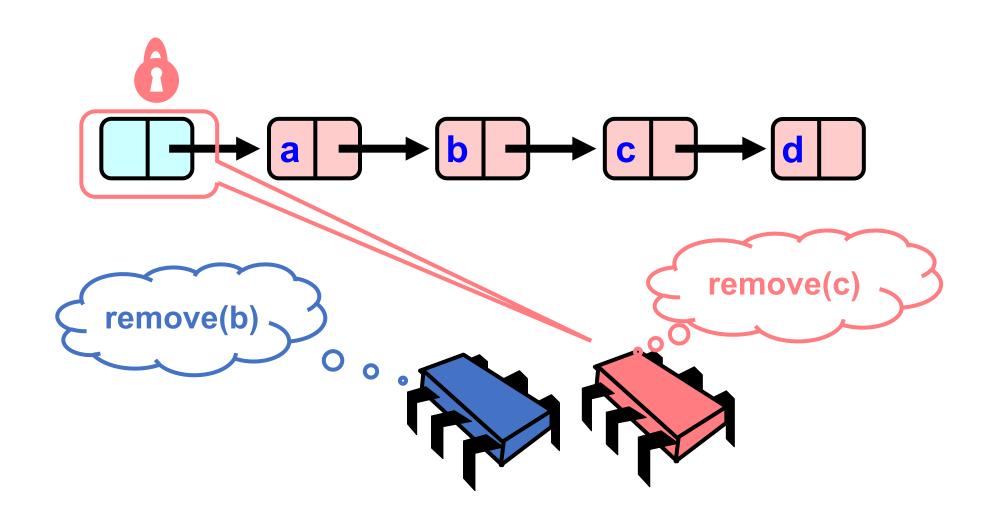


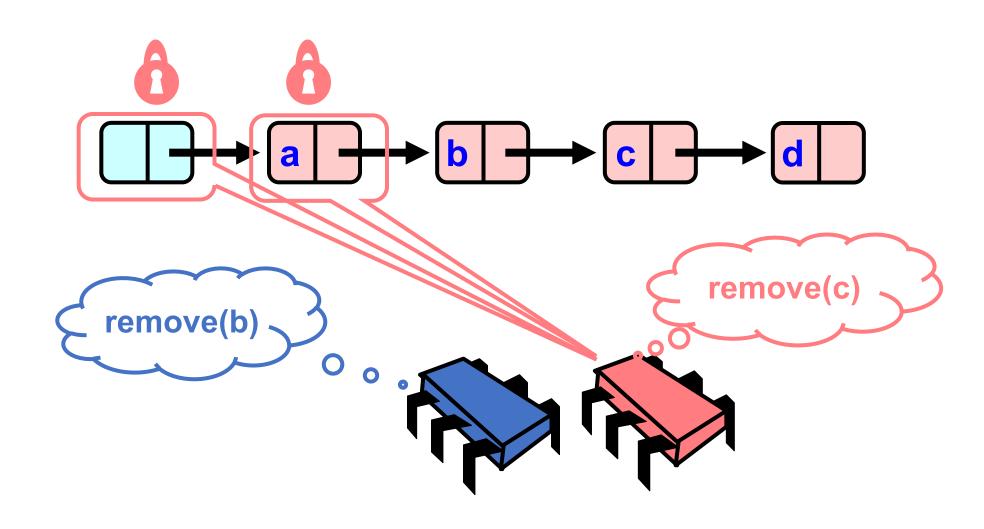


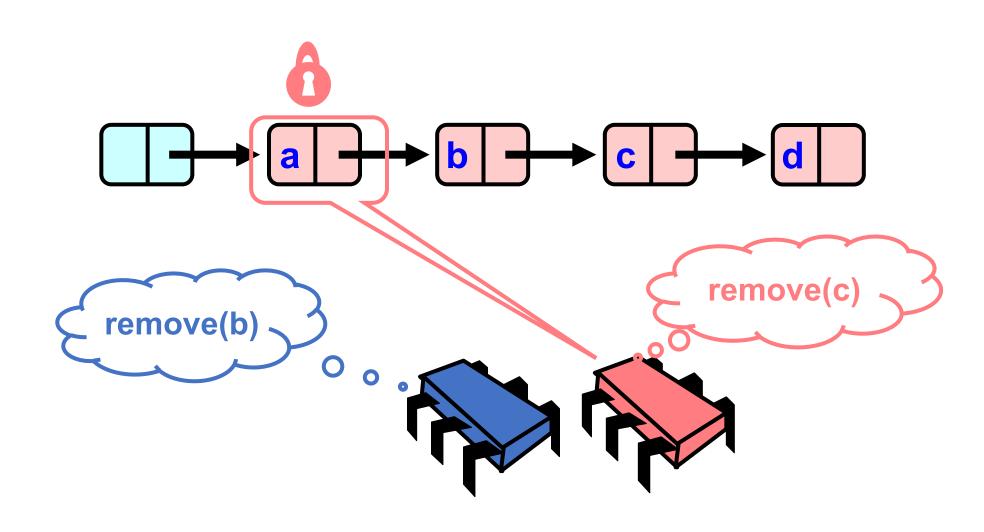


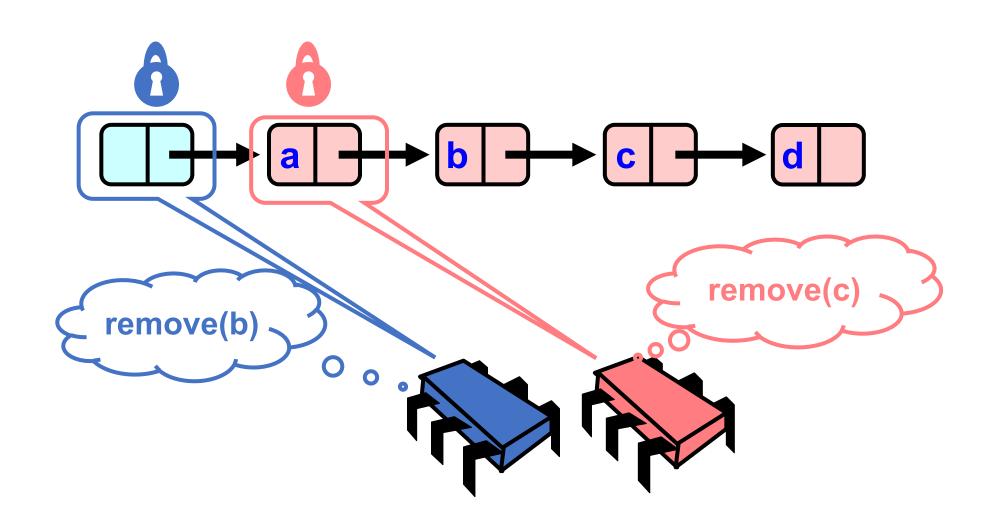


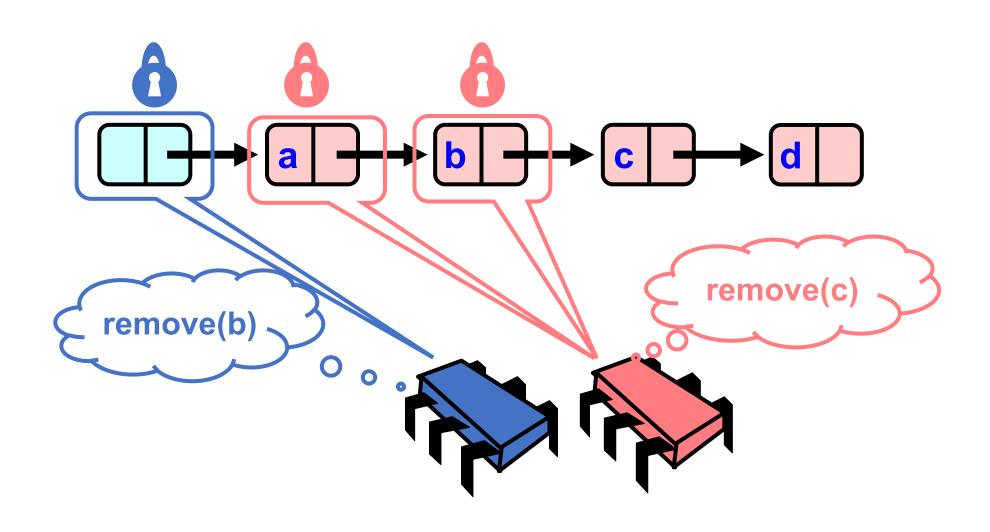


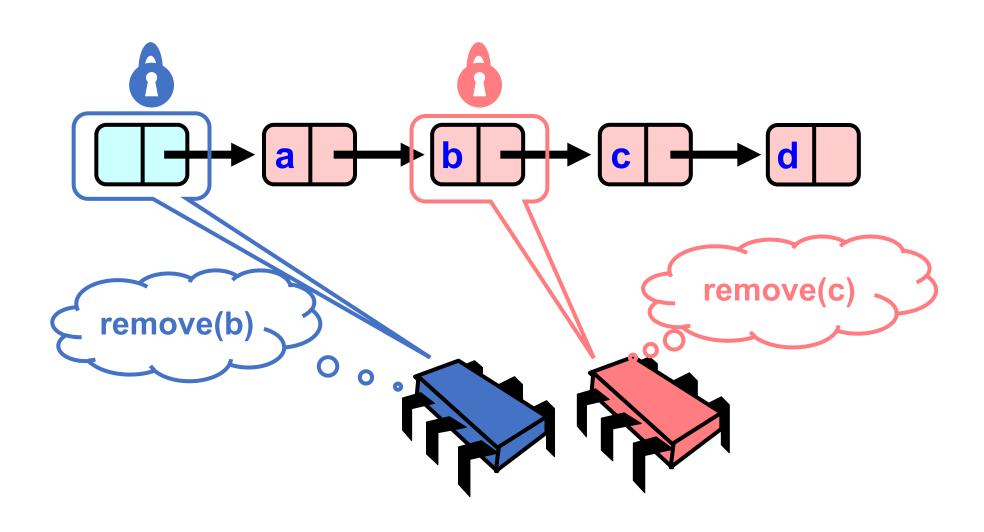


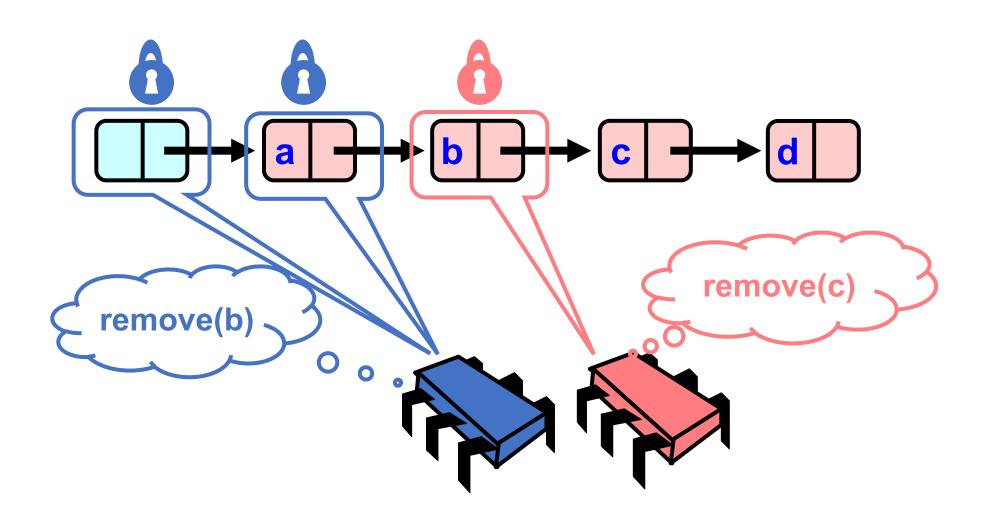


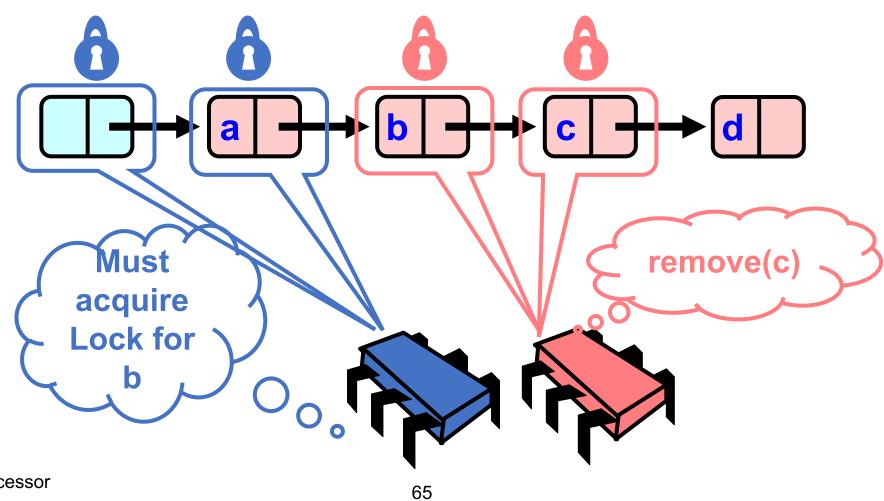


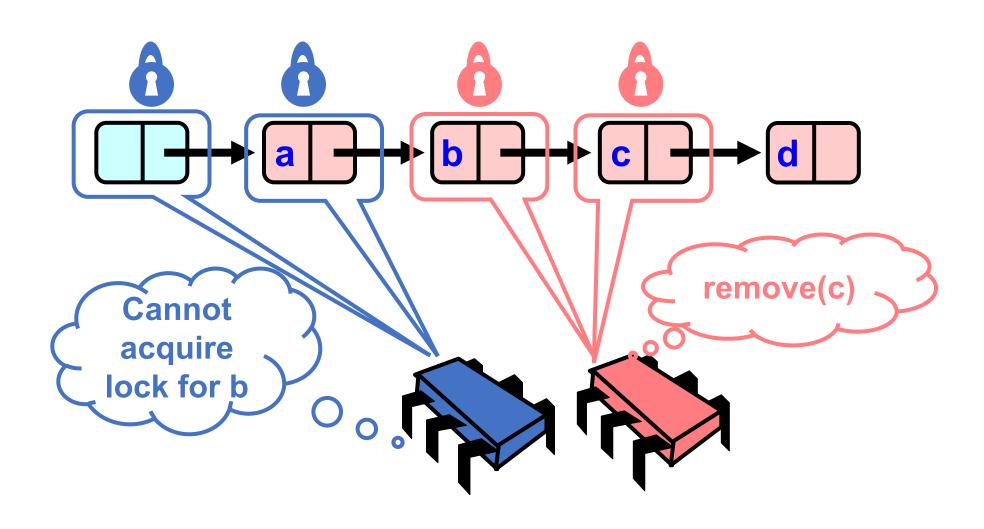


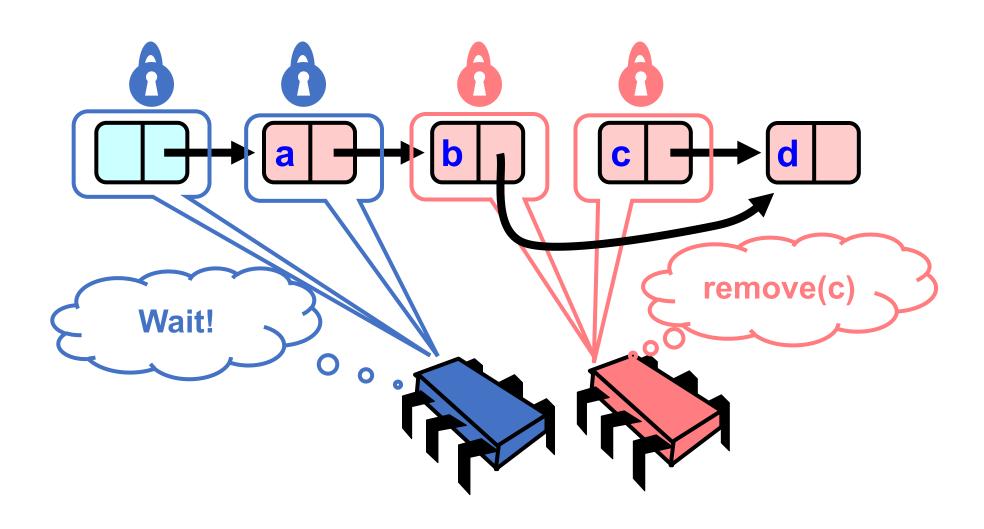


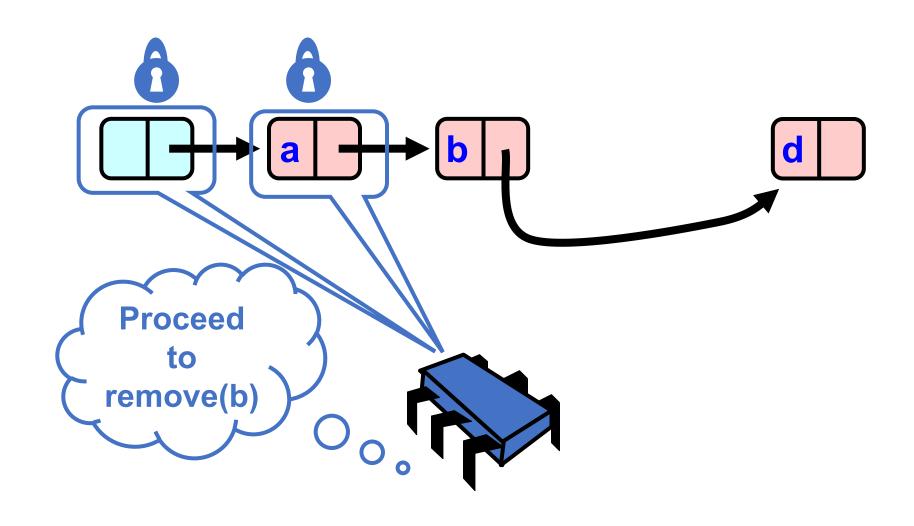


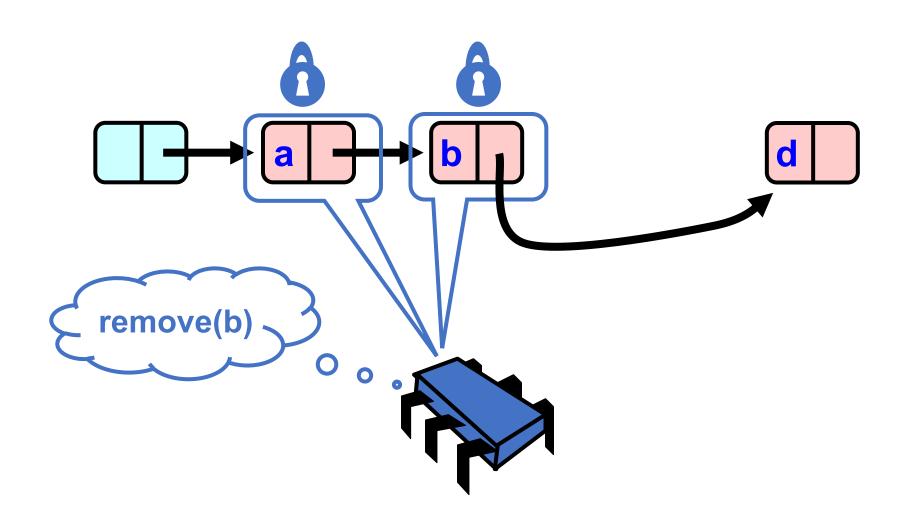


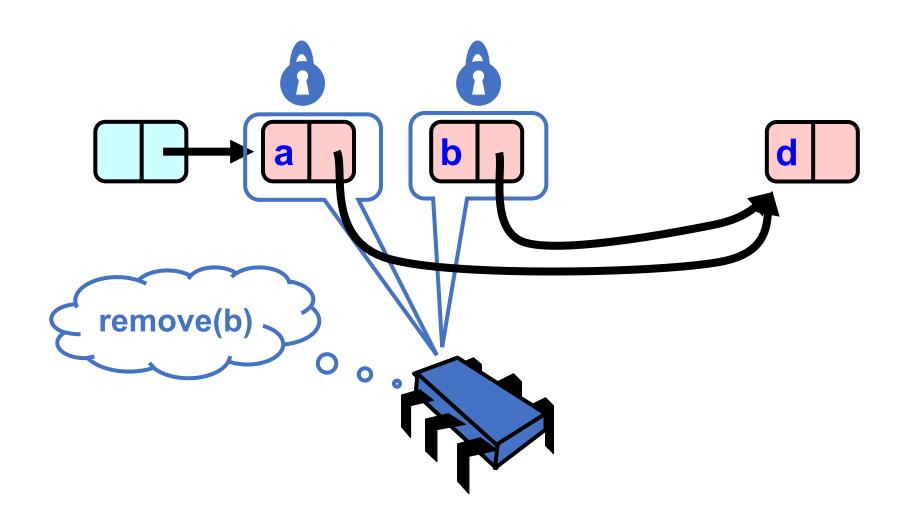


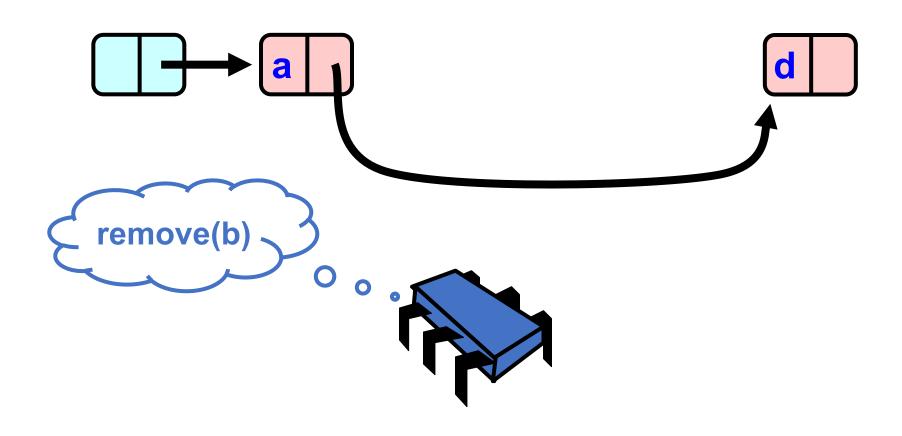


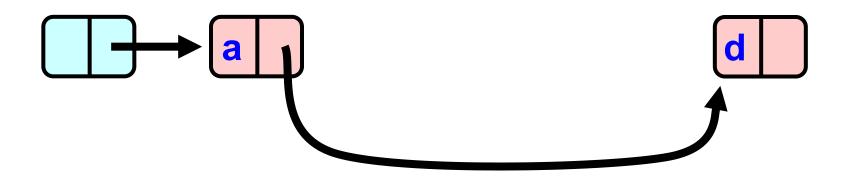












Adding Nodes

- To add node e
 - Must lock predecessor
 - Must lock successor
- Neither can be deleted

Drawbacks

- Better than coarse-grained lock
 - Threads can traverse in parallel
- Still not ideal
 - Long chain of acquire/release
 - Inefficient

How can we improve

- Acquires and releases lock for every node traversed
 - If we have a long list to search, it can be bad!
 - reduces concurrency (traffic jams)

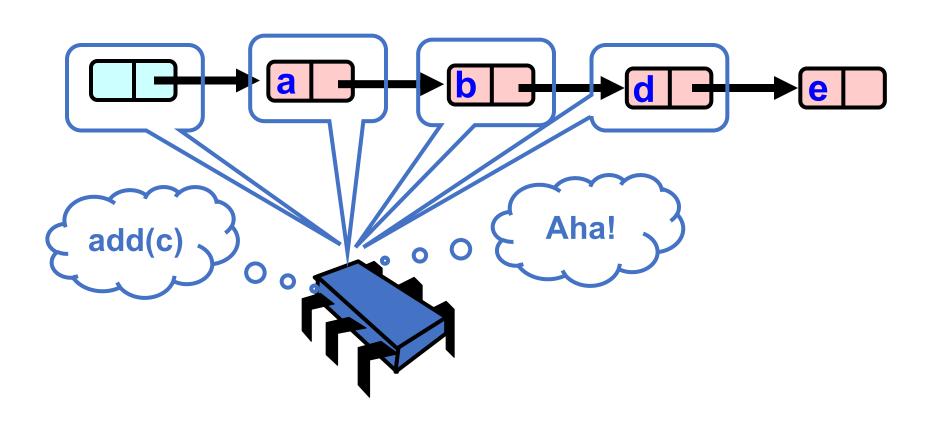
Assume there will be no conflicts. Check before committing. If there was a conflict, try again.

Find nodes without locking

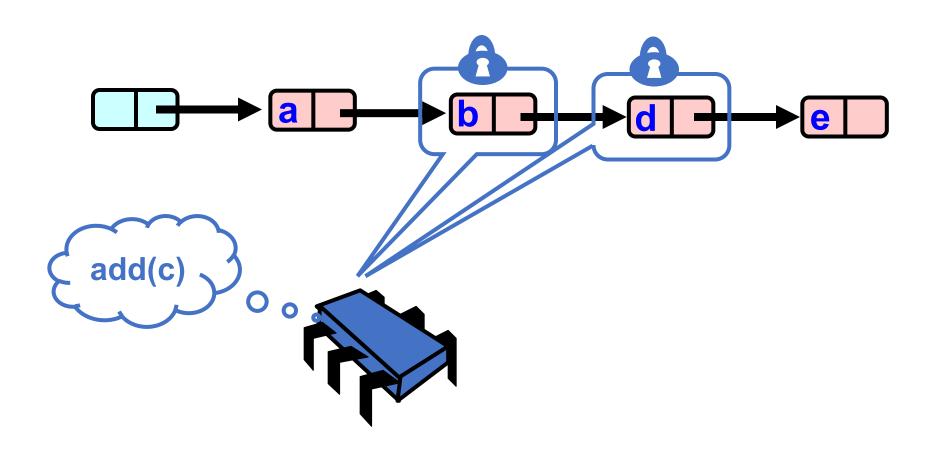
- Find nodes without locking
- Lock nodes

- Find nodes without locking
- Lock nodes
- Check that everything is OK

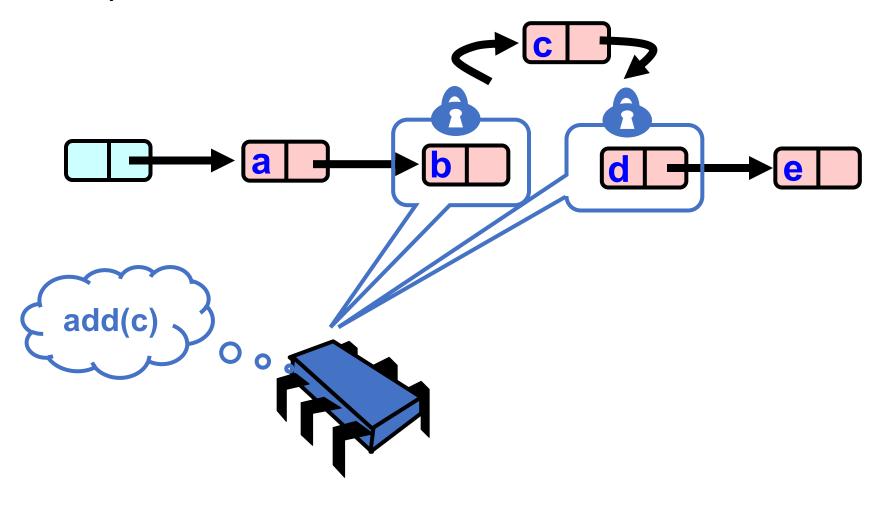
Optimistic: Traverse without Locking

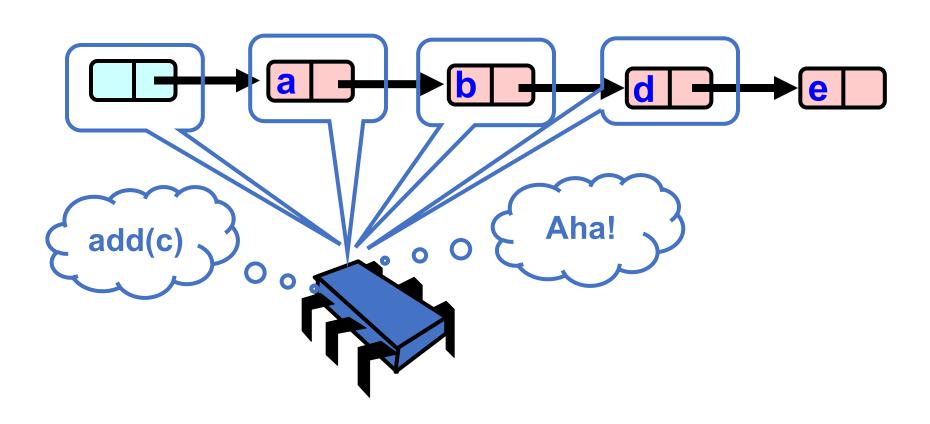


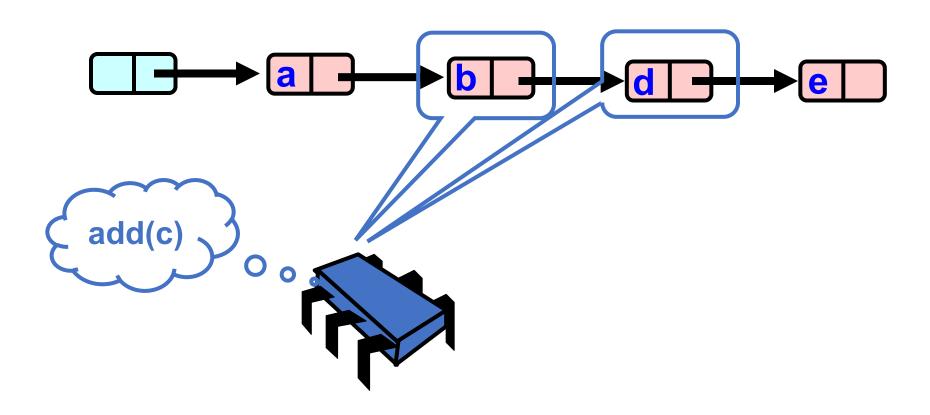
Optimistic: Lock and Load

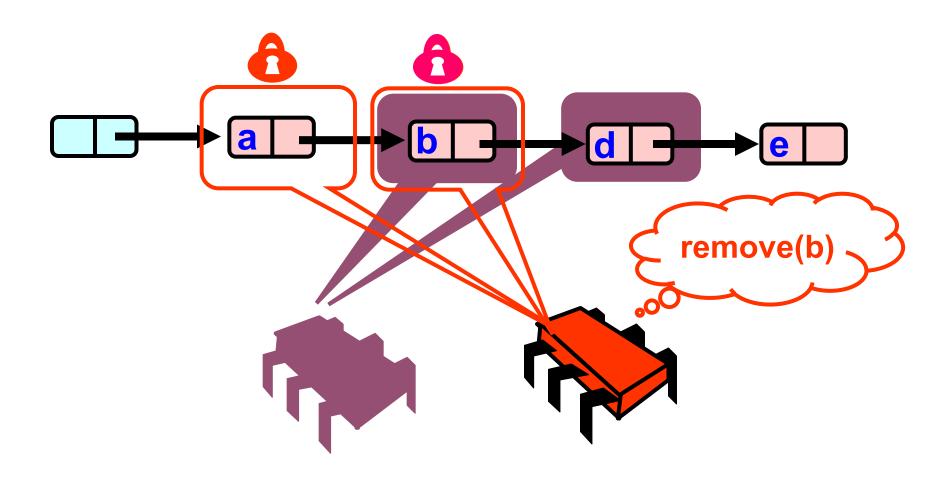


Optimistic: Lock and Load









Data conflict!

- Red thread has the lock on a node (so it can modify the node)
- Blue thread is traversing without locks

• What do we do?

Data conflict!

- Red thread has the lock on a node (so it can modify the node)
- Blue thread is traversing without locks

• What do we do? We decided that locking when traversing is too expensive.

• We can use atomic variables

 Default atomic accesses are documented to be sequentially consistent.

```
class Node {
  public:
    Value v;
    int key;
    Node *next;
}
```

 Default atomic accesses are documented to be sequentially consistent.

```
class Node {
  public:
    Value v;
    int key;
    atomic<Node*> next;
}
```

Atomic template in C++

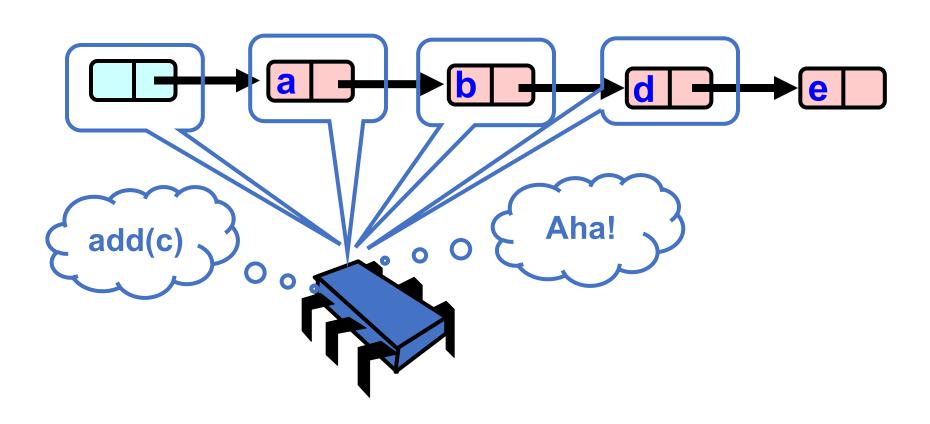
• demo

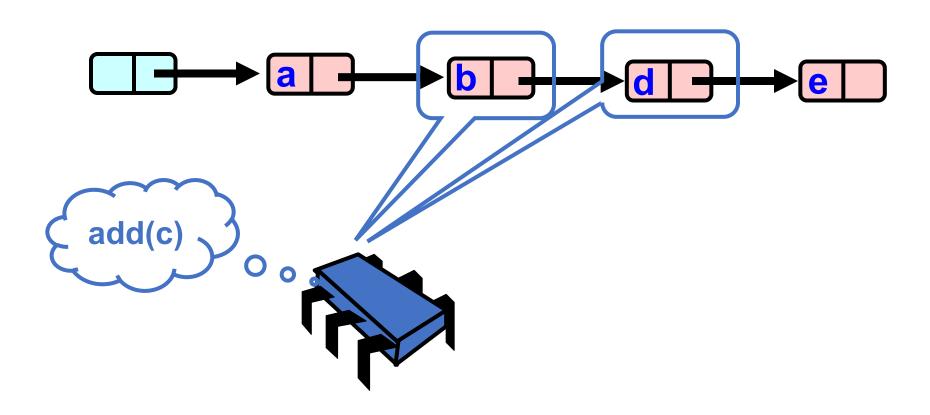
 Default atomic accesses are documented to be sequentially consistent.

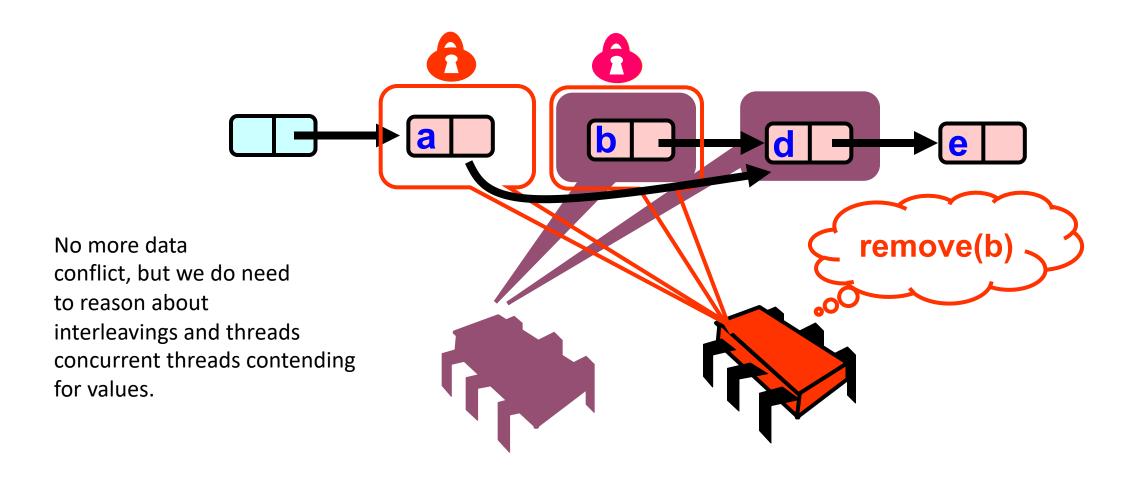
```
void traverse(node *n) {
  while (n->next != NULL) {
    n = n->next;
  }
}
```

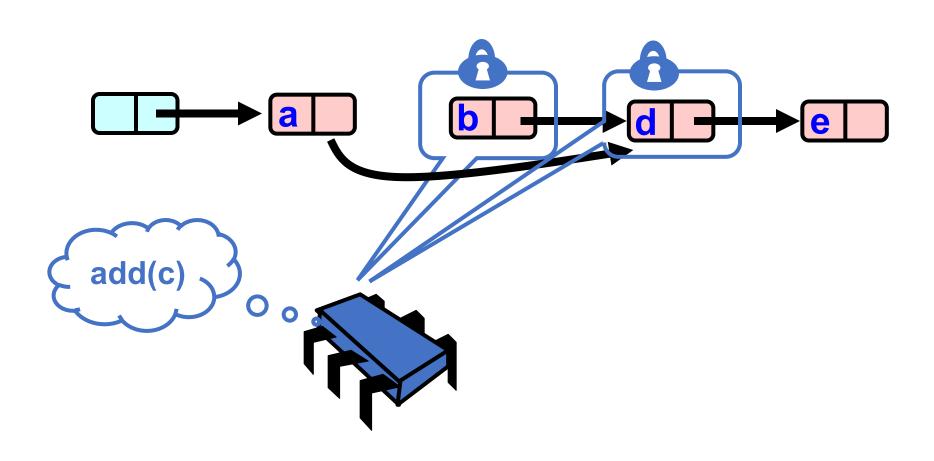
 Default atomic accesses are documented to be sequentially consistent.

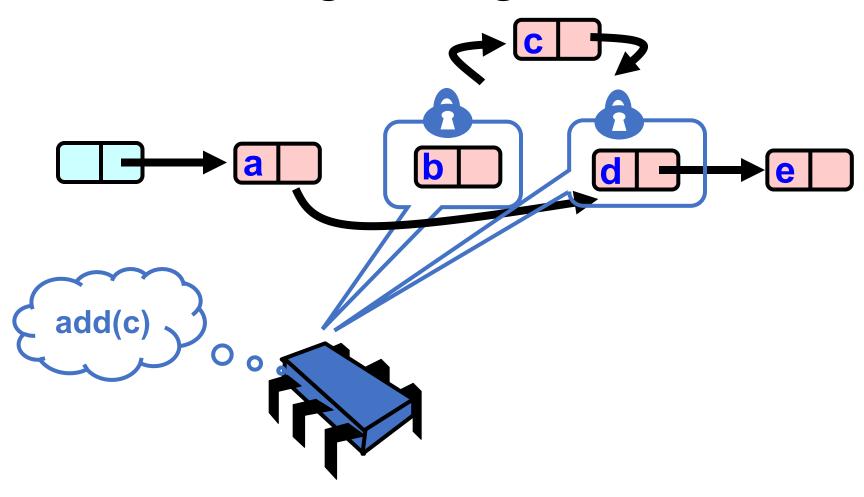
```
void traverse(node *n) {
  while (n->next.load() != NULL) {
    n = n->next.load();
  }
}
```

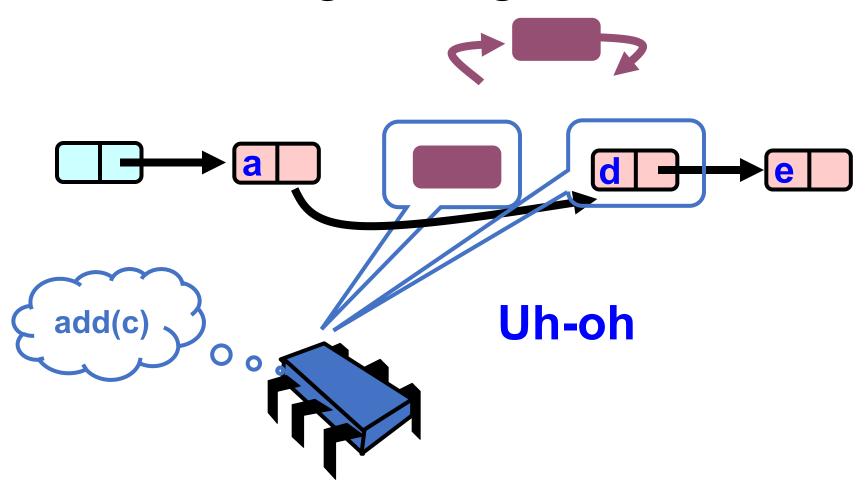




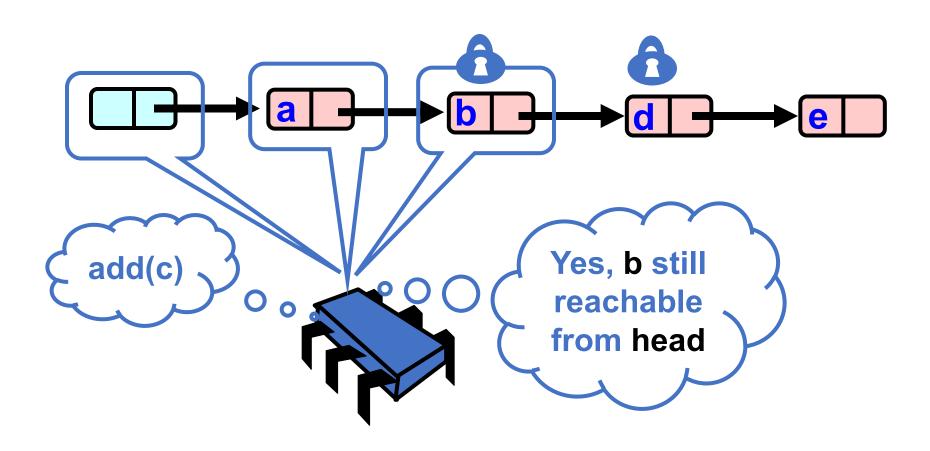








Validate – Part 1



What happens if failure?

• Ideas?

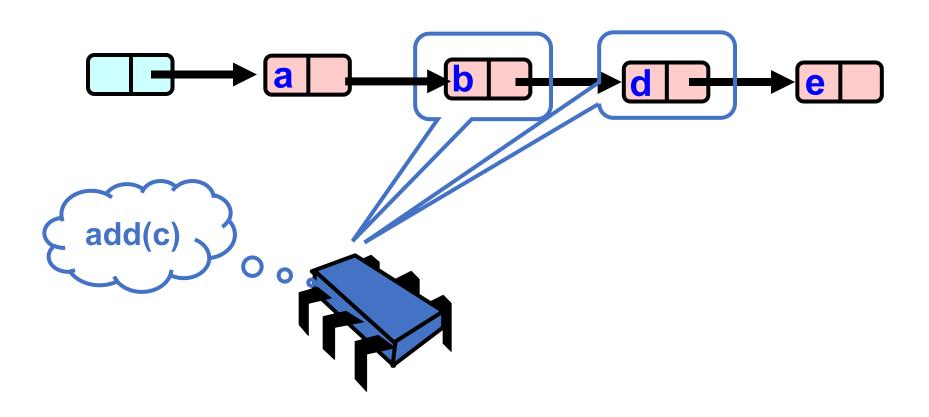
What happens if failure?

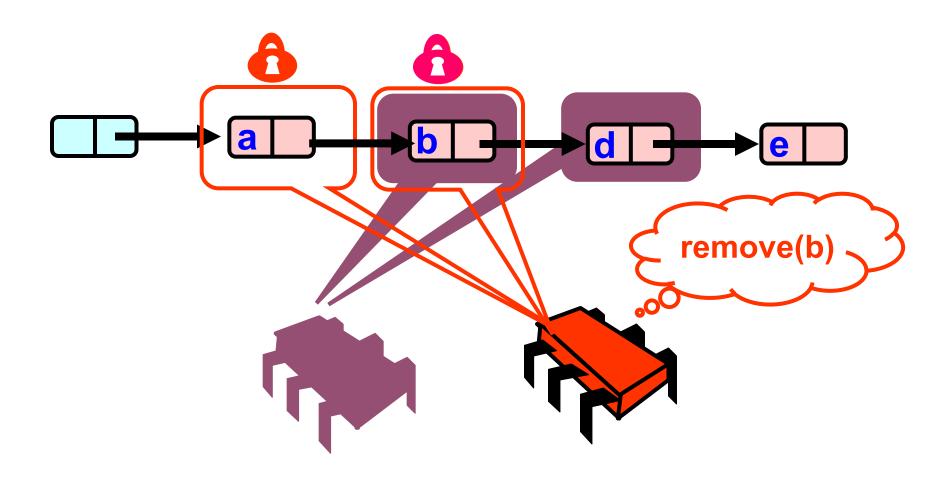
- Could try to recover? Back up a node?
 - Very tricky!
 - Just start over!

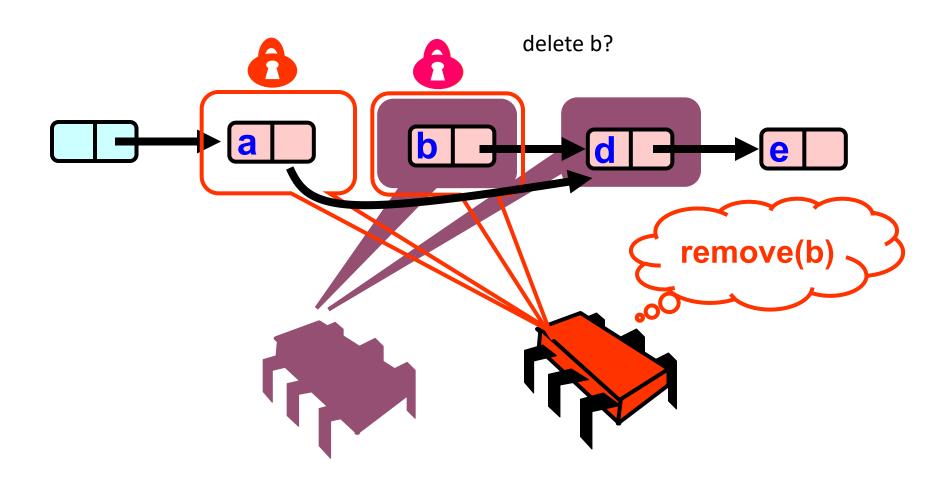
What happens if failure?

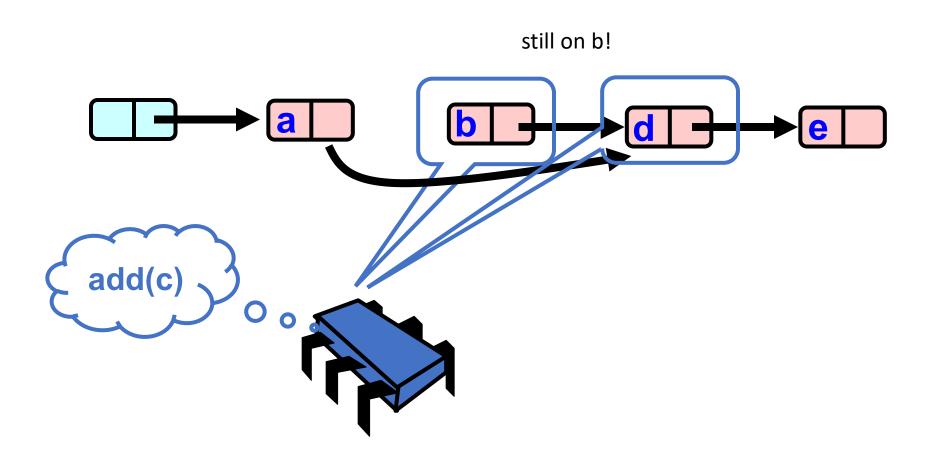
- Could try to recover? Back up a node?
 - Very tricky!
 - Just start over!
- Private method:
 - try_remove
 - remove loops on try_remove until it succeeds

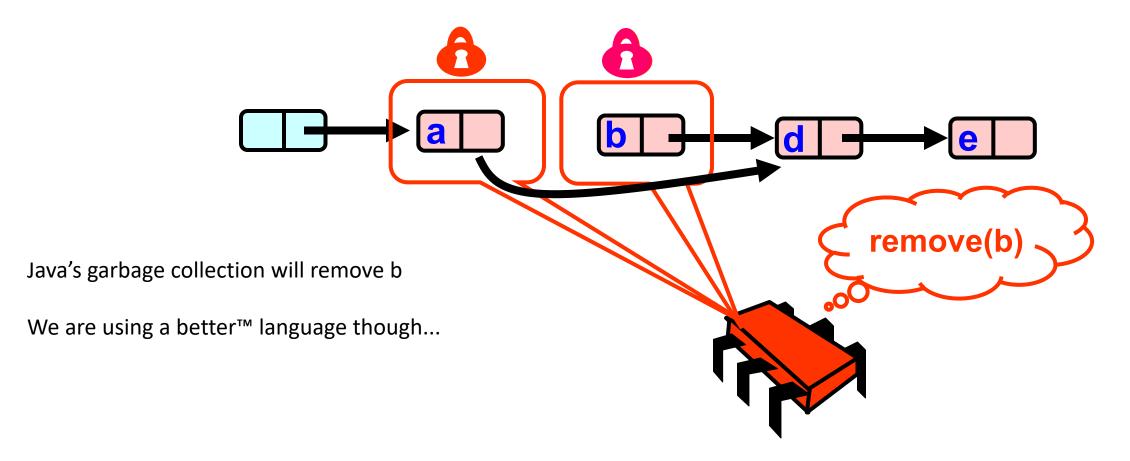
What about deletion?













Java's garbage collection will remove b

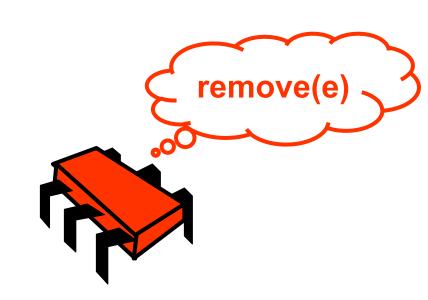
We are using a better™ language though...



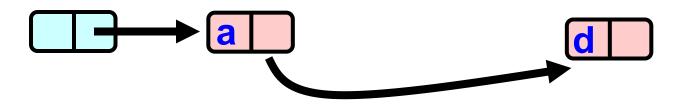


Java's garbage collection will remove b

We are using a better™ language though...

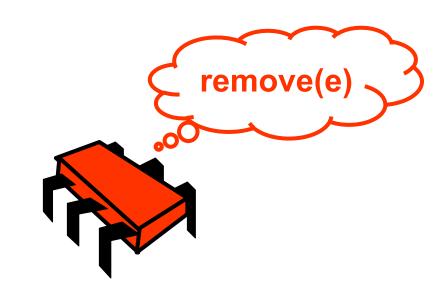


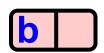




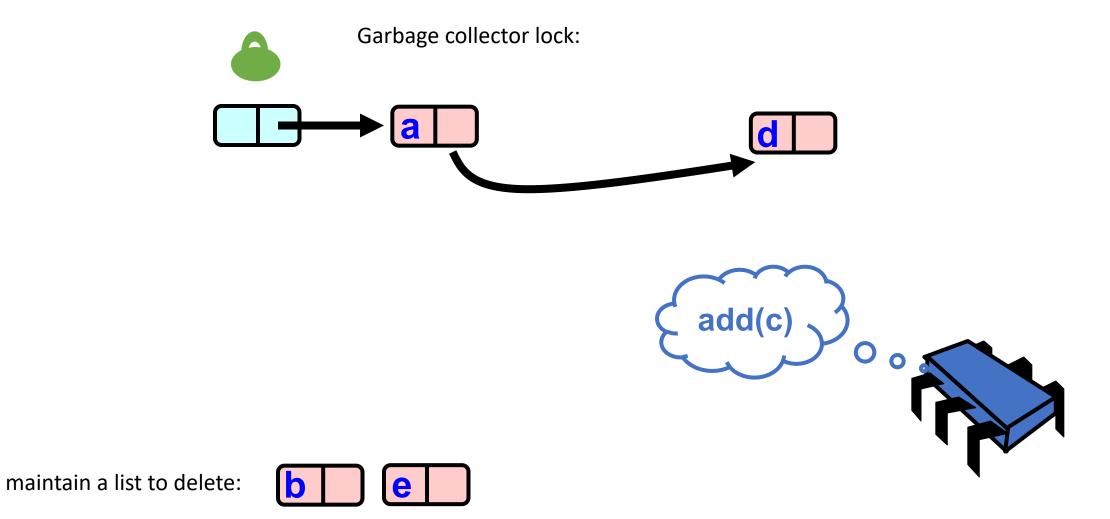
Java's garbage collection will remove b

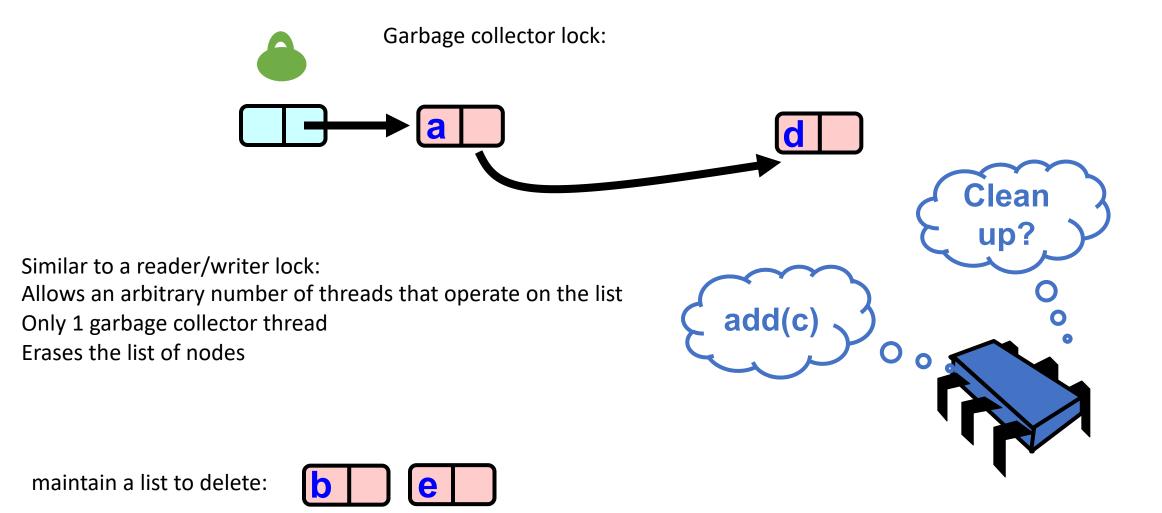
We are using a better™ language though...









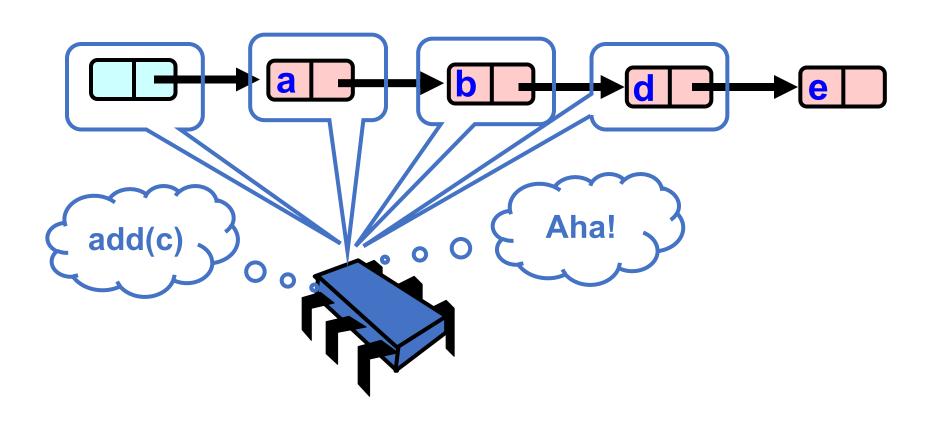


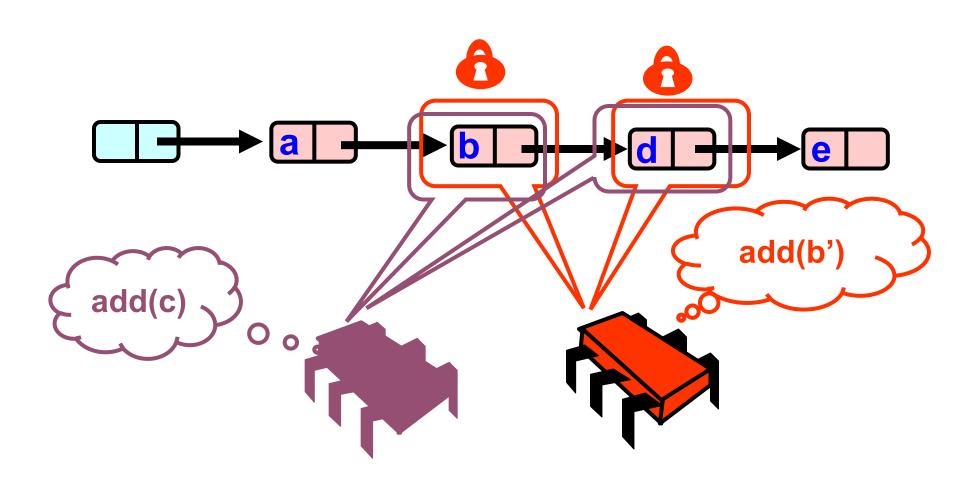
Garbage collector lock

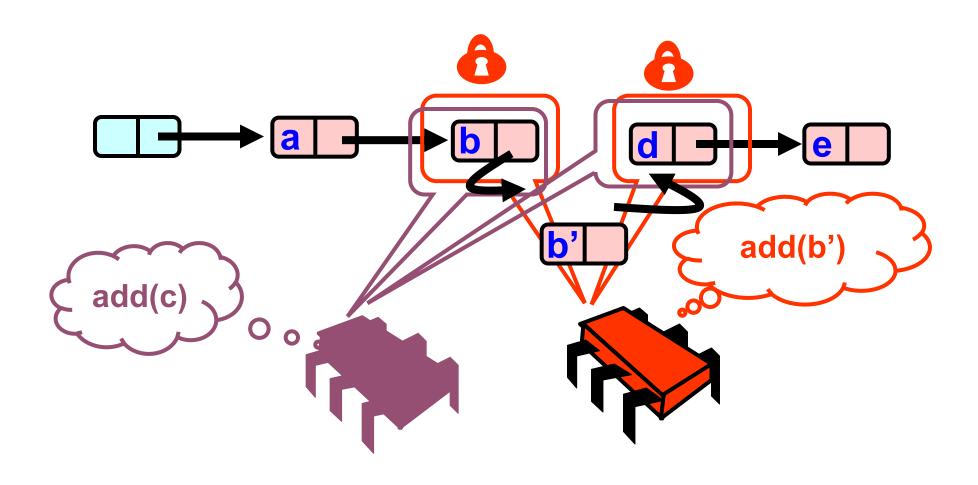
- Many strategies!
 - A big research area ~10 years ago
- **Strat 1:** Threads always try once to take the garbage collector lock:
 - if failed, no worries, the next operation will get a chance
 - if succeeded, then there was no contention
 - can starve garbage collection
- Strat 2: Wait until size grows to a threshold:
 - Wait on the lock (hope for a fair implementation!)
 - Can cause performance spikes

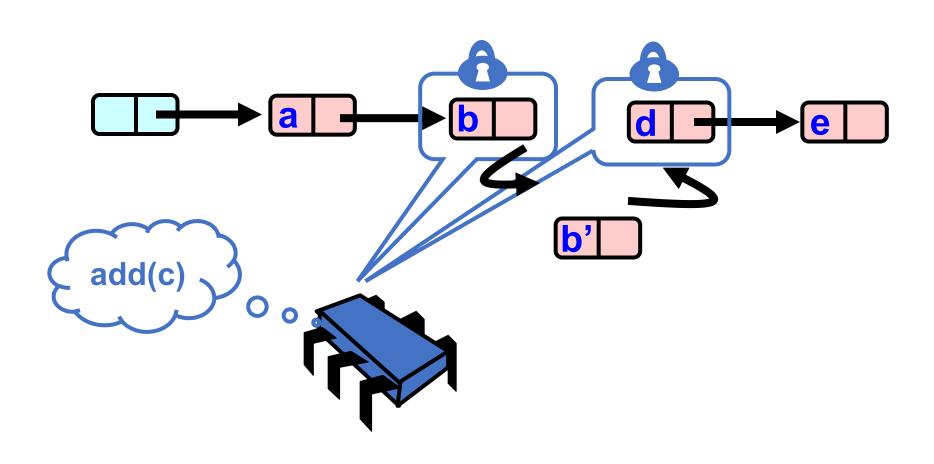
Back to the linked list

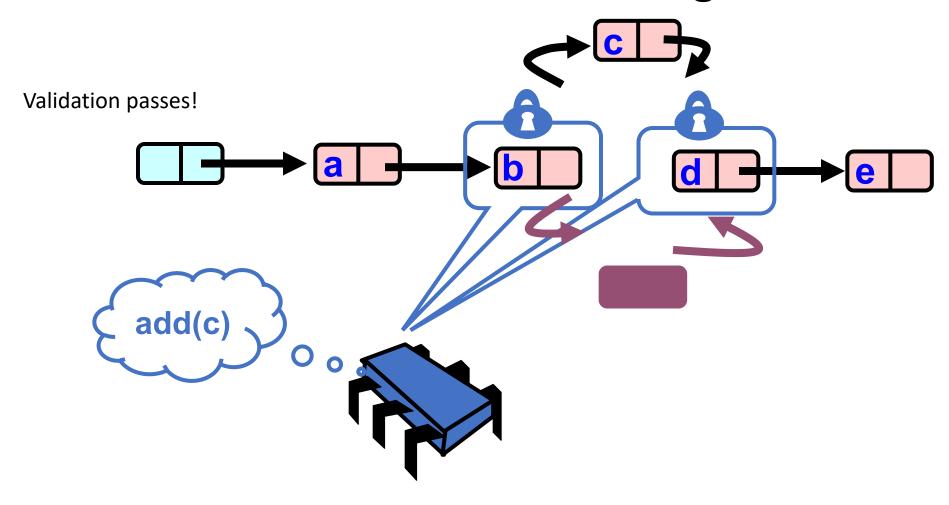
What if 2 threads try to add a node in the same position?



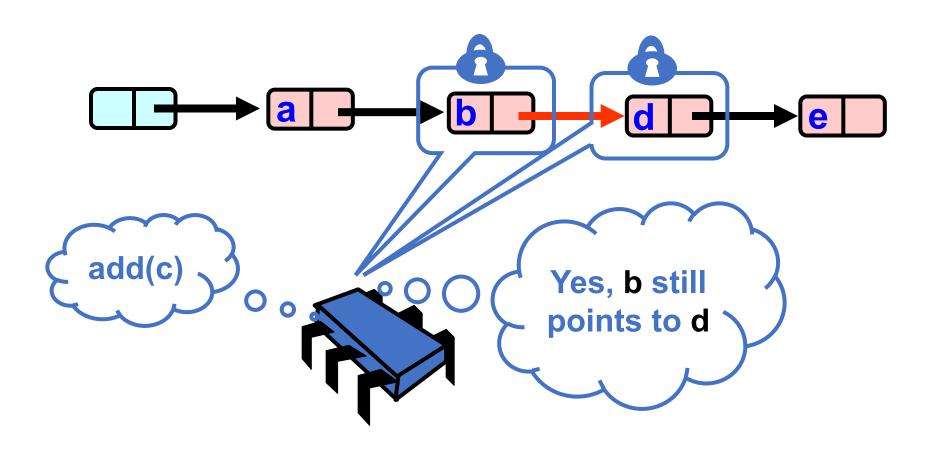








Validate Part 2 (while holding locks)



Summary

- We traverse without lock
 - Traversal may access nodes that are locked
 - Its okay because we have atomic pointers!
- We might traverse deleted nodes
 - Its okay because we validate after we obtain locks
 - Two validations:
 - our node is still reachable (it was not deleted)
 - Our insertion point is still valid (no thread has inserted in the meantime)
- We don't actually free node memory, but we put them in a list to be freed later

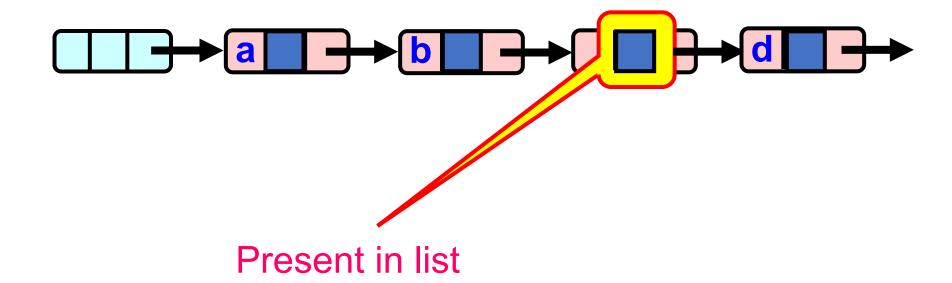
Can we optimize more?

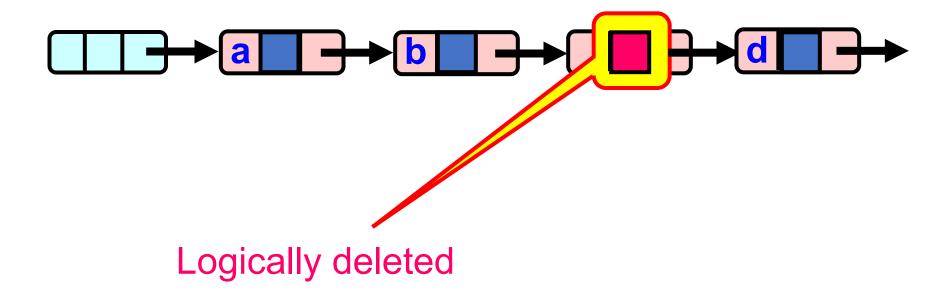
• Scan the list once?

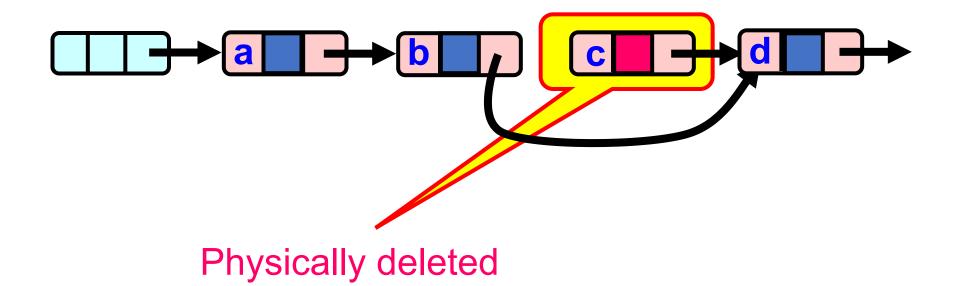
Two step removal List

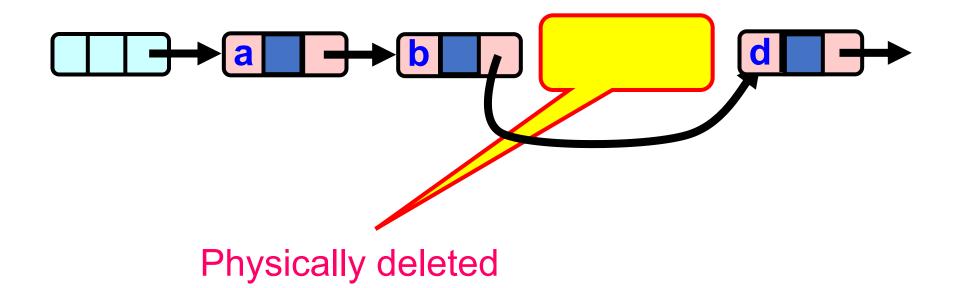
- remove()
 - Scans list (as before)
 - Locks predecessor & current (as before)
- Logical delete
 - Marks current node as removed (new!)
- Physical delete
 - Redirects predecessor's next (as before)









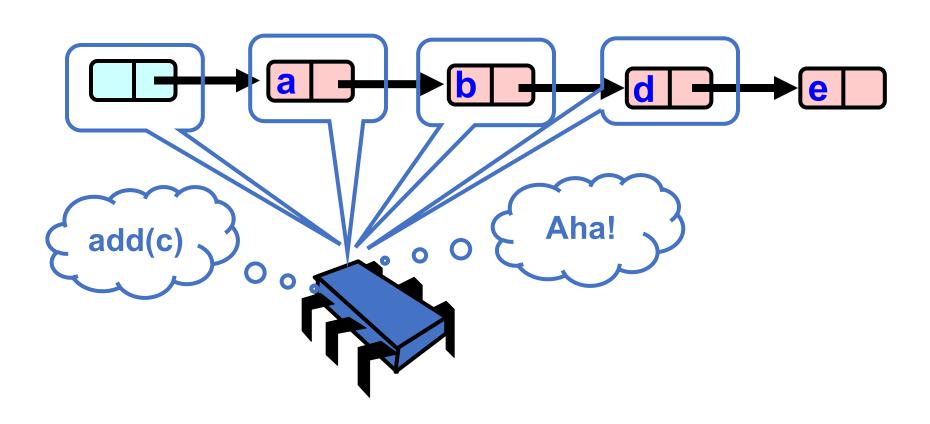


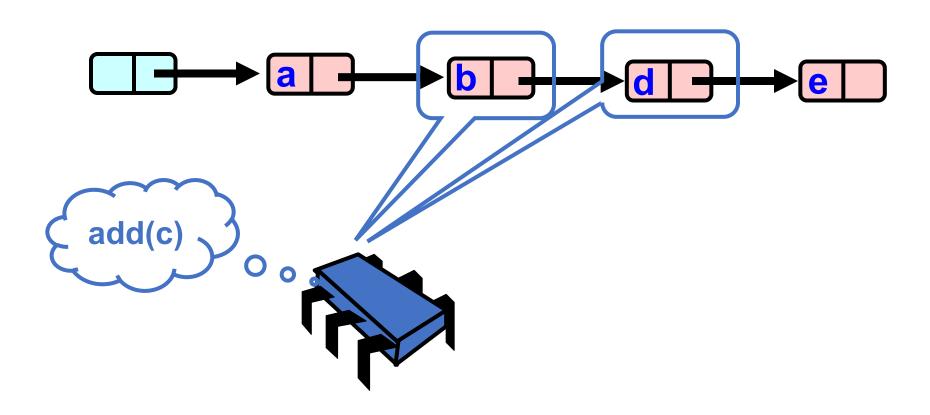
Two step remove list

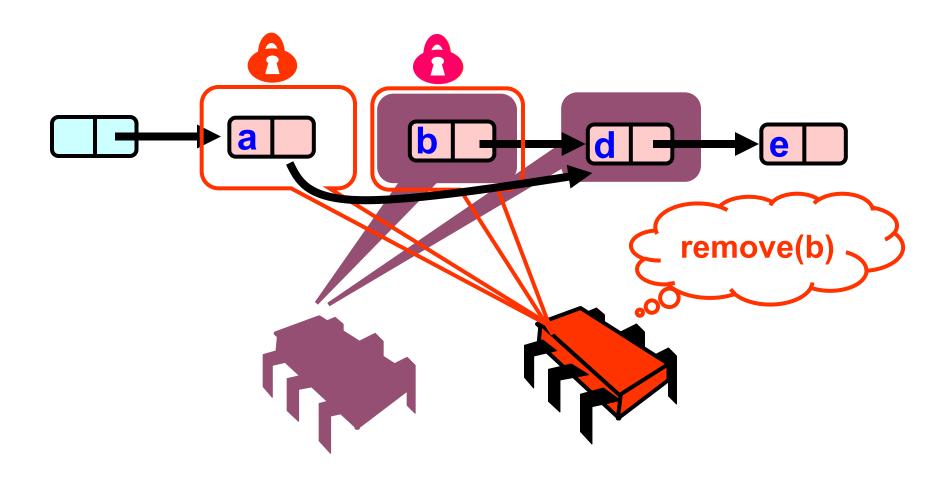
- All Methods
 - Scan through locked and marked nodes
- Must still lock pred and curr nodes.

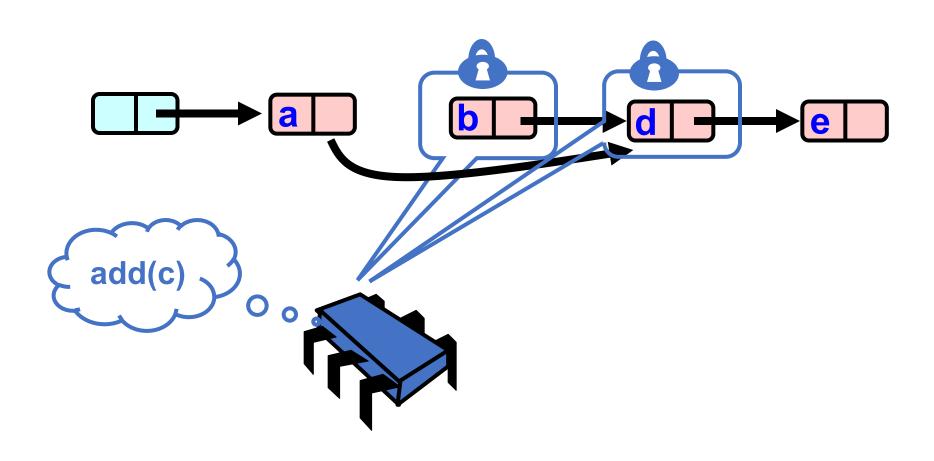
Validation

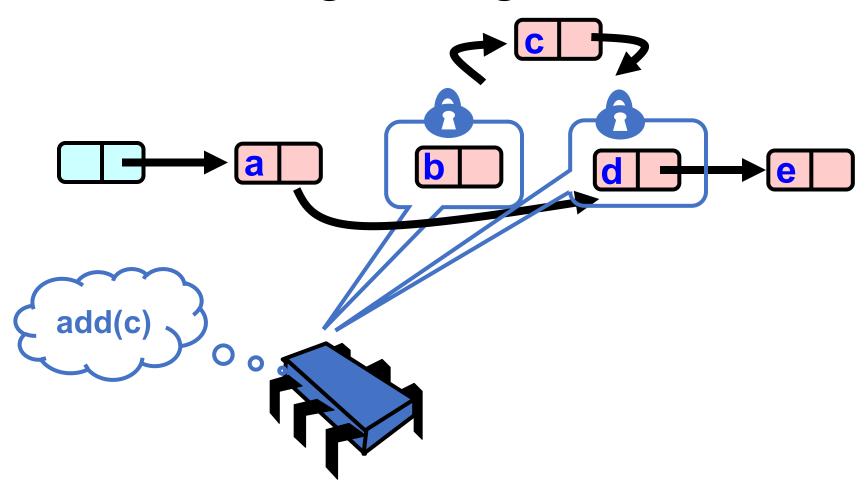
- No need to rescan list!
- Check that pred is not marked
- Check that curr is not marked
- Check that pred points to curr

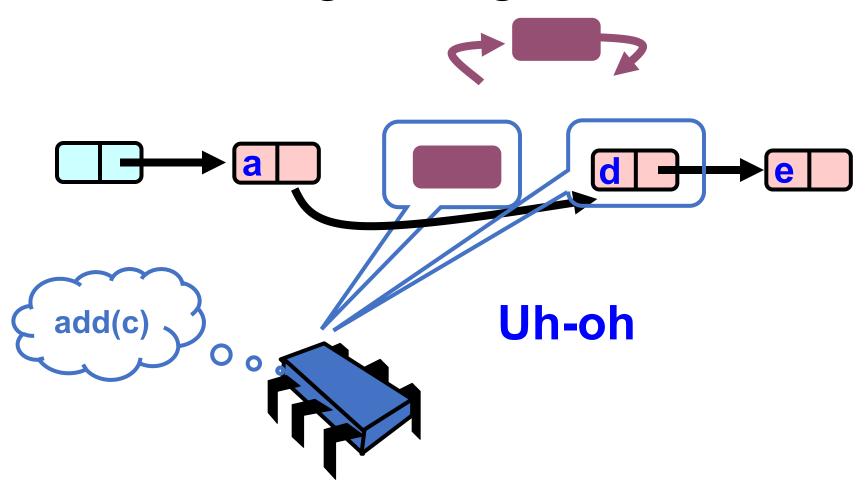


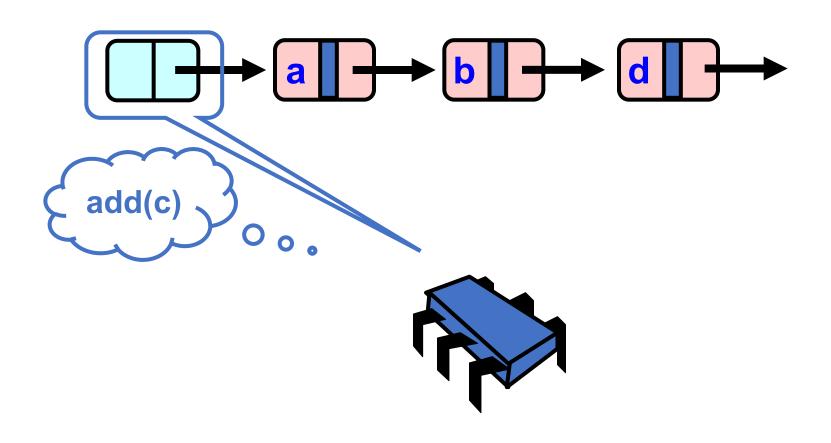


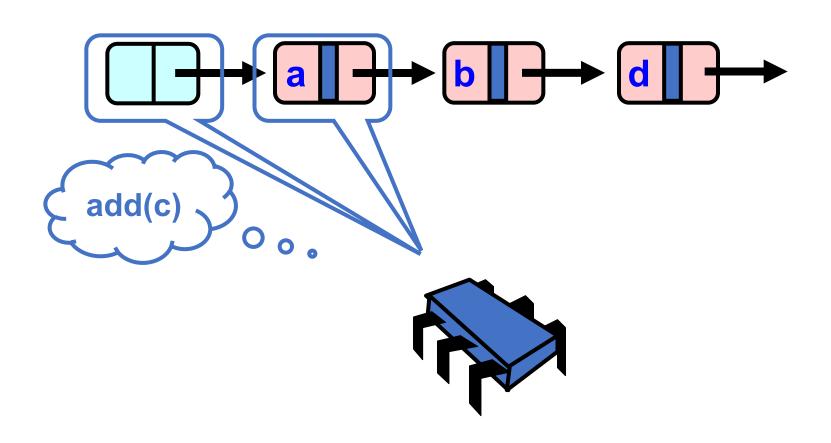


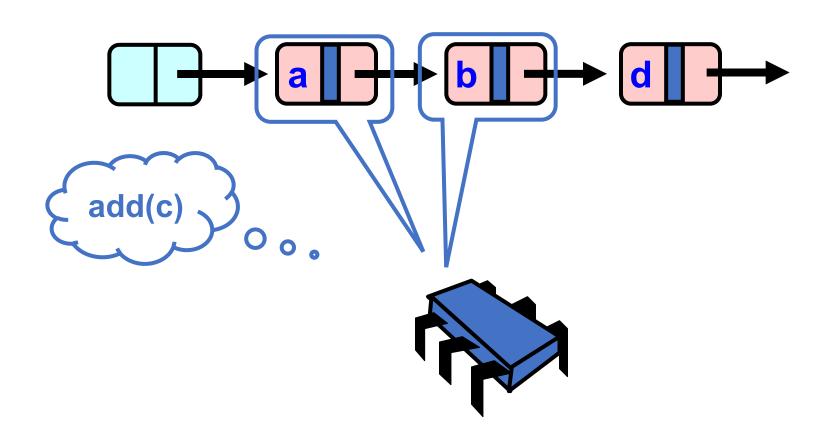


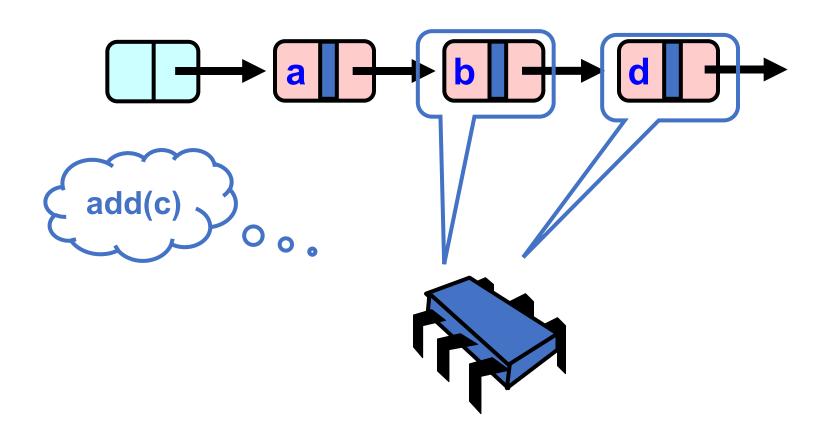


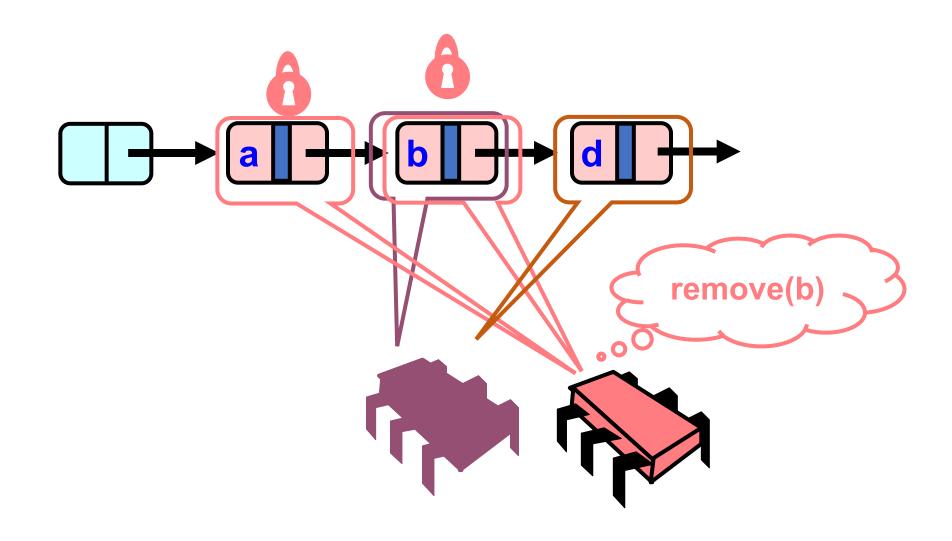


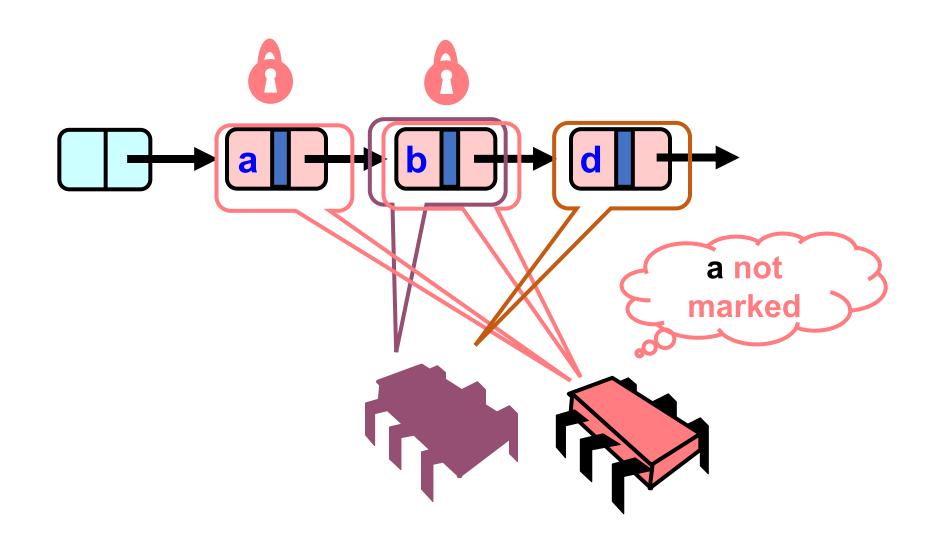


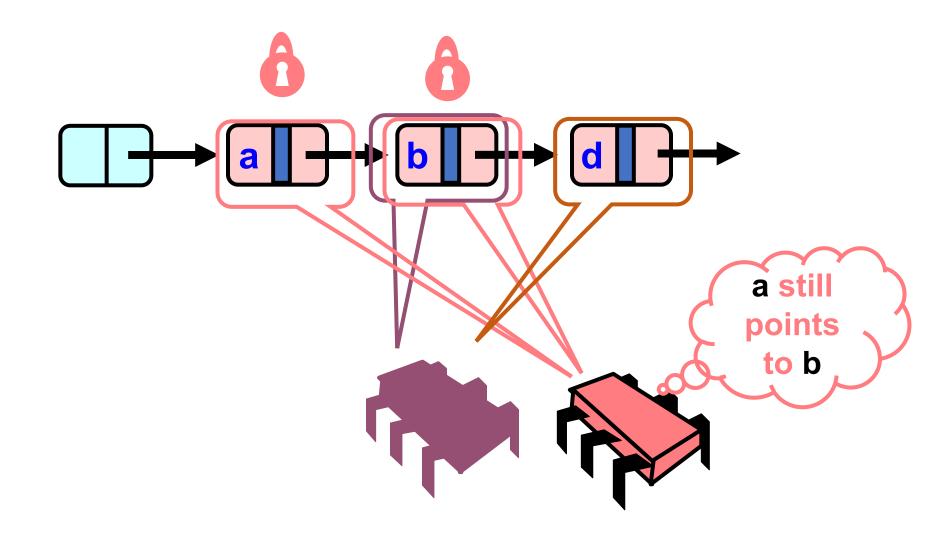


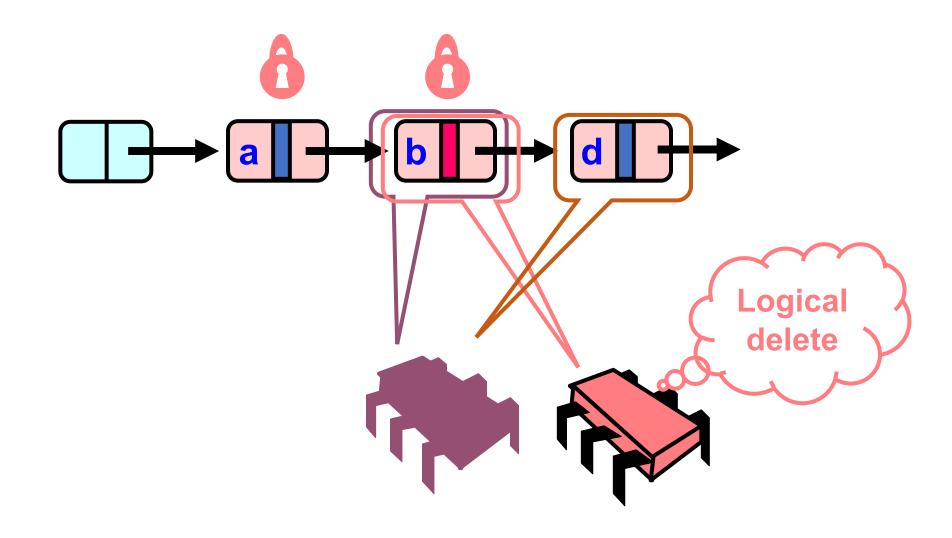


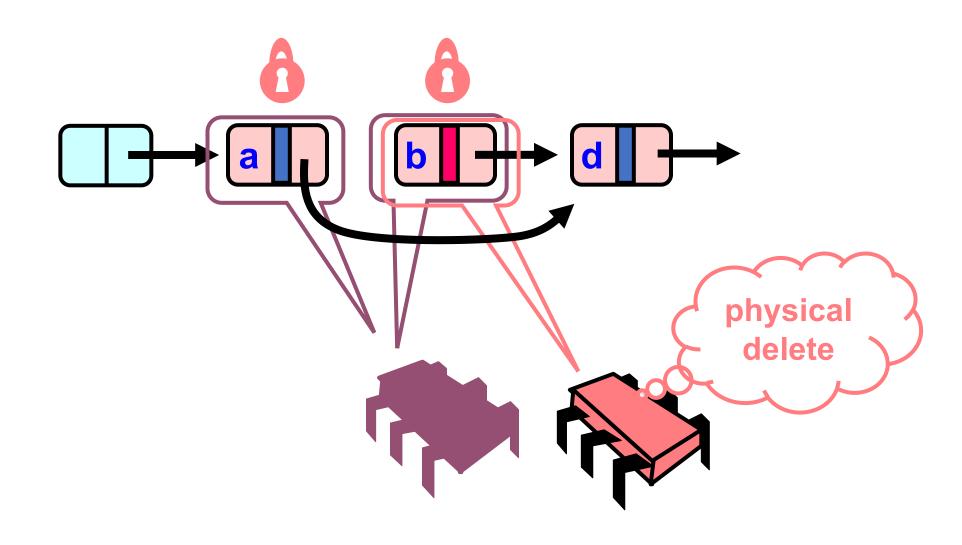


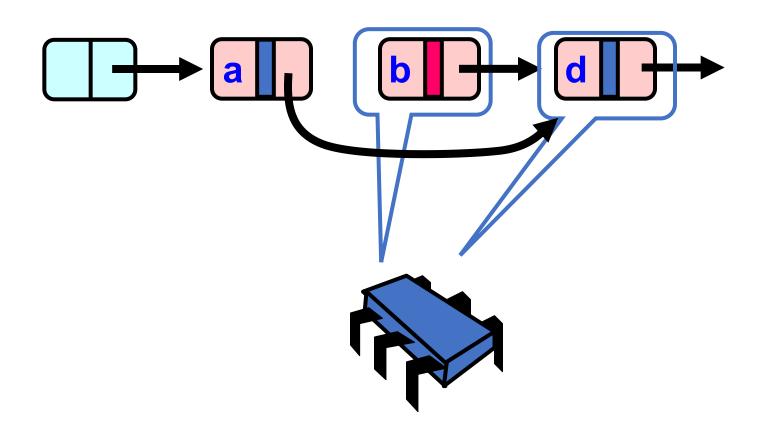


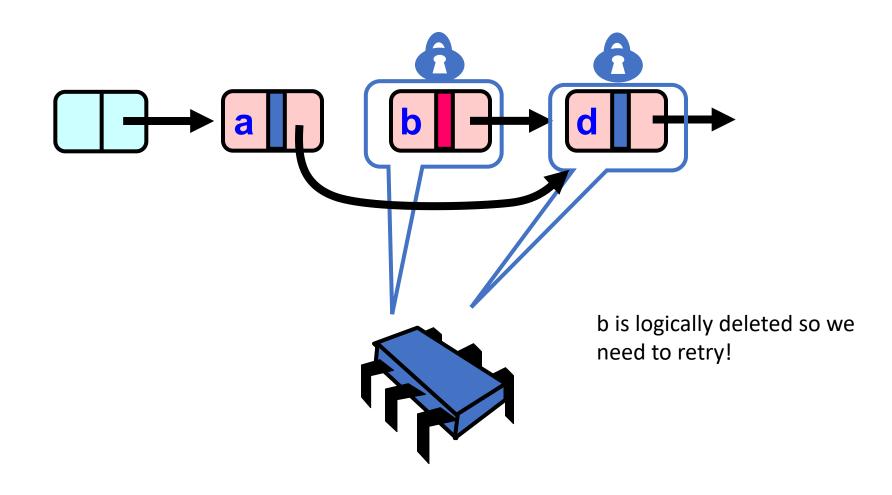












To complete the picture

Need to do similar reasoning with all combination of object methods.

More information in the book!

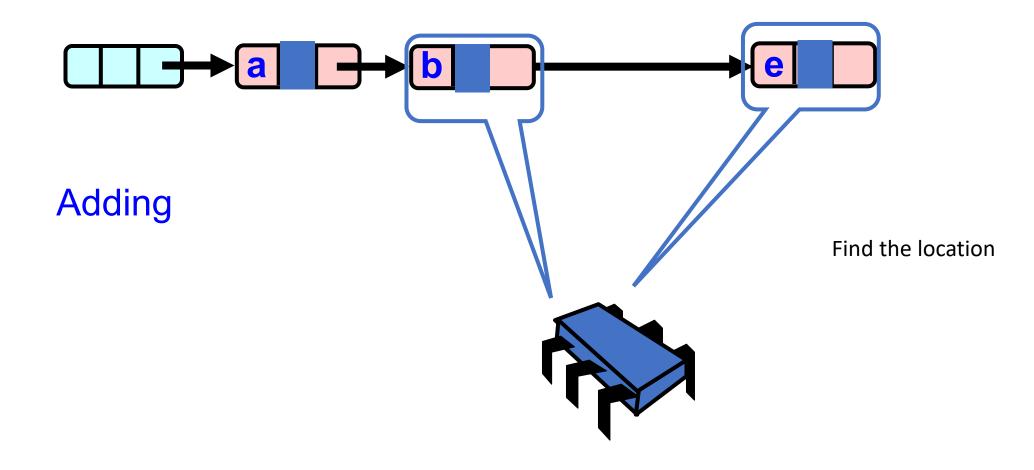
Evaluation

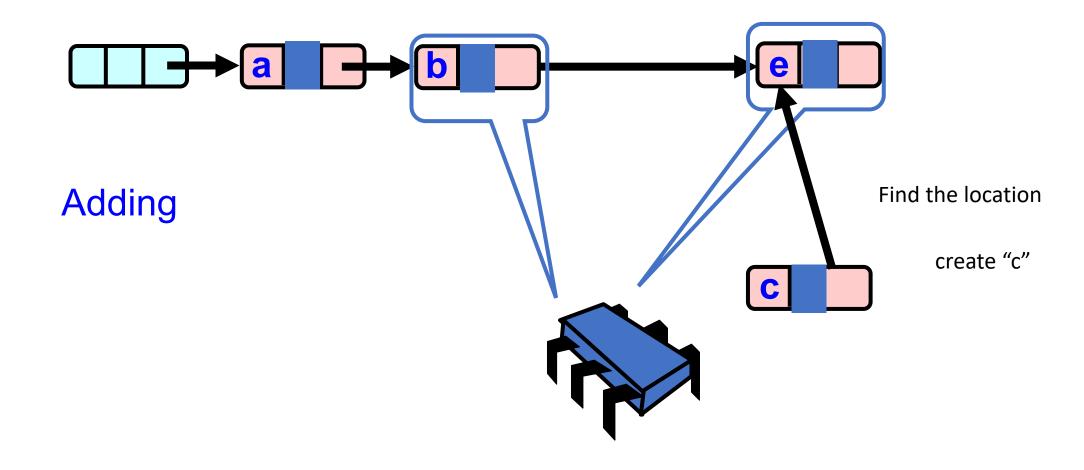
- Good:
 - Uncontended calls don't re-traverse
- Bad
 - add() and remove() use locks

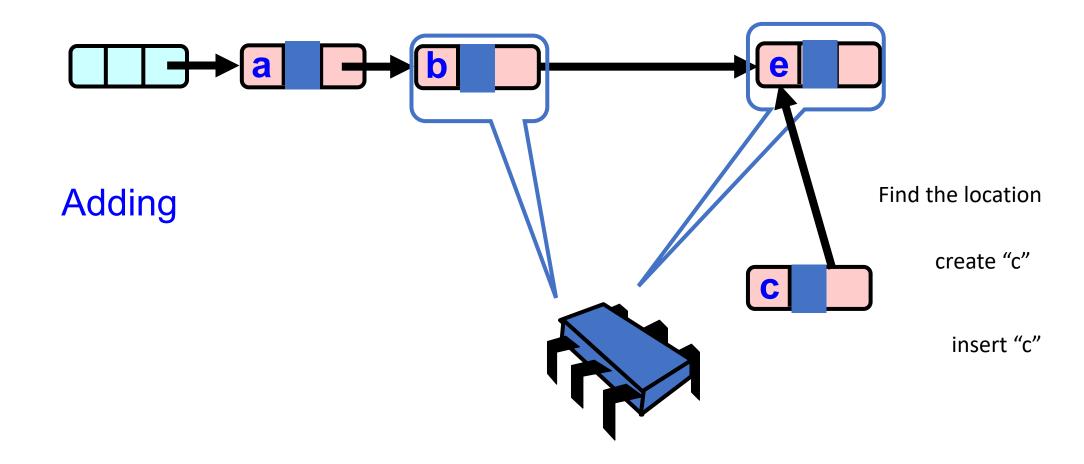
- Next logical step
 - lock-free add() and remove()
- What sort of atomics do we need?
 - Loads/stores?
 - RMWs?

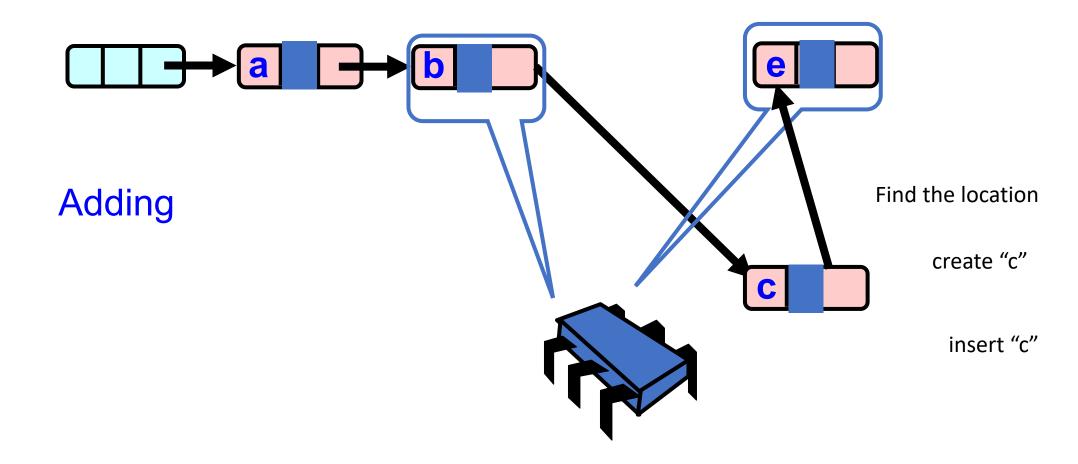


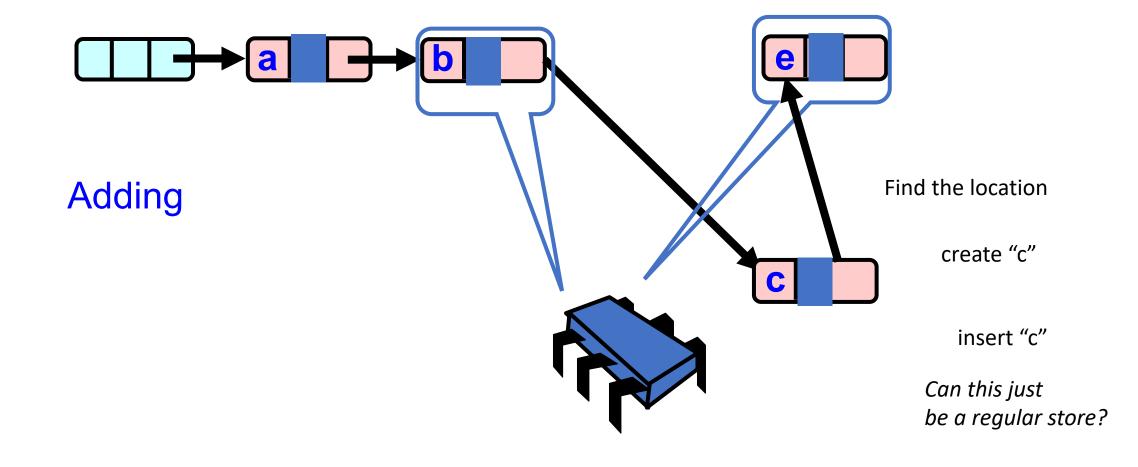
Adding

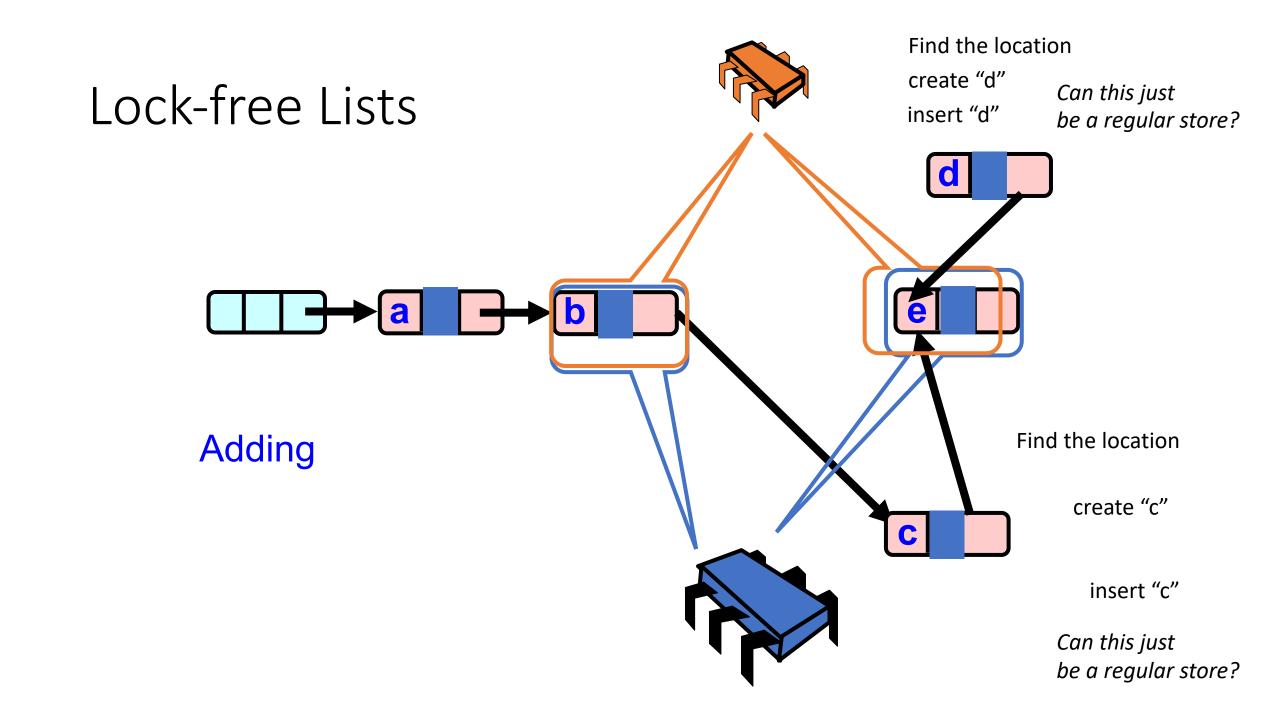


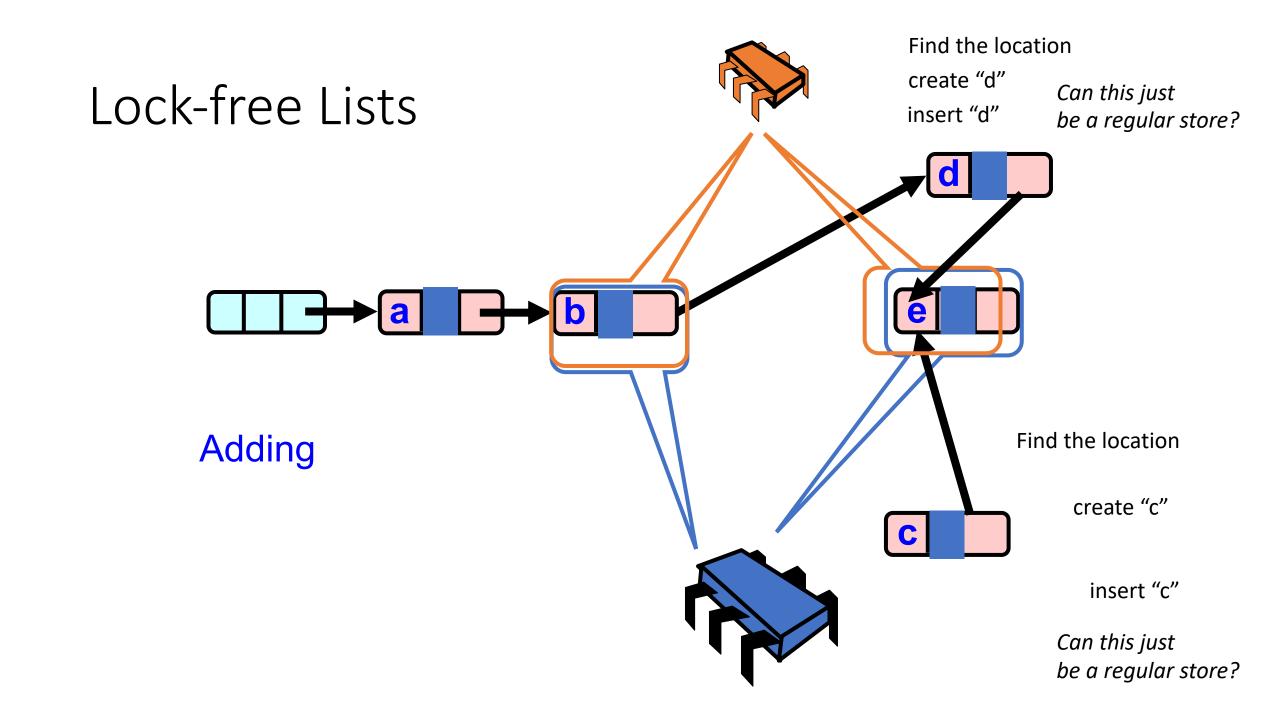


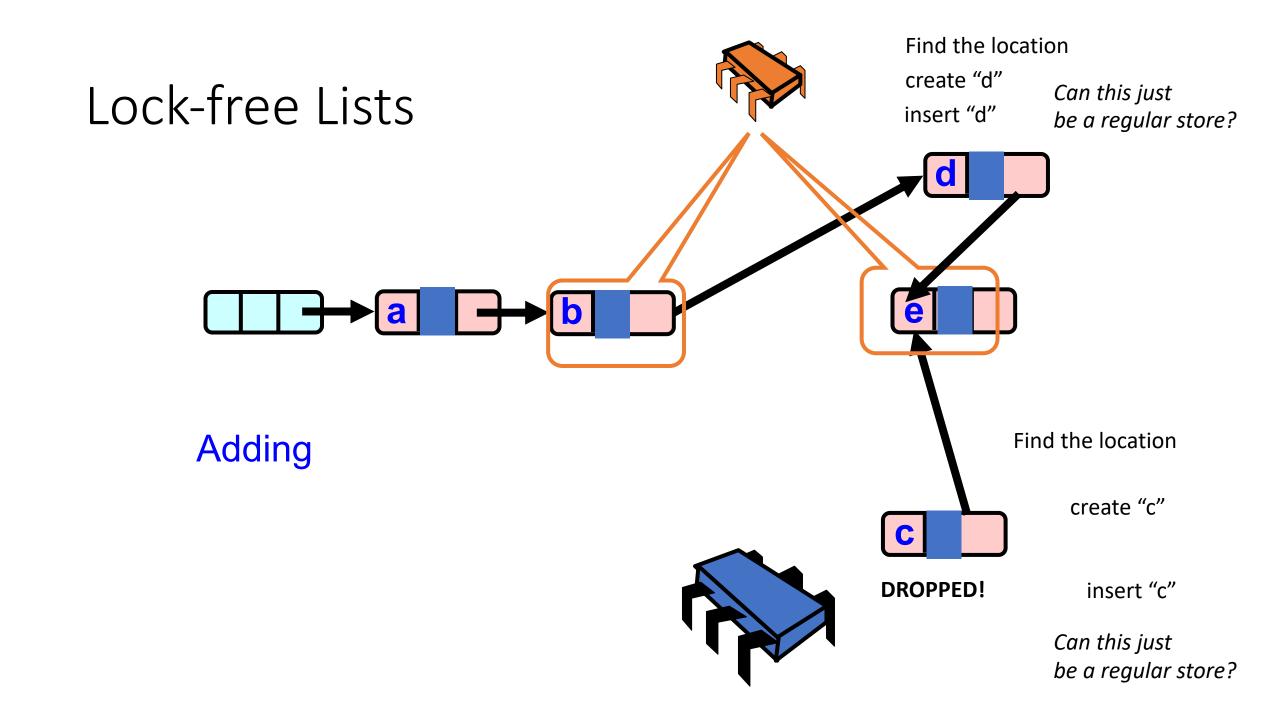


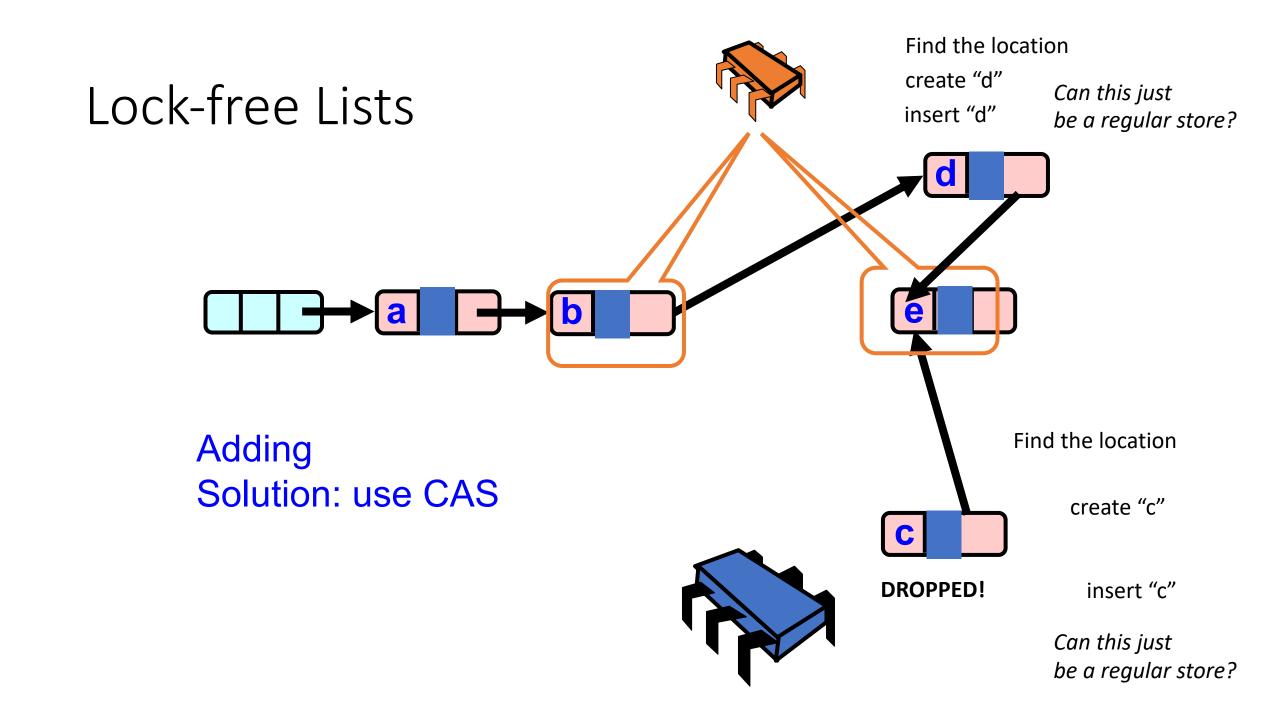






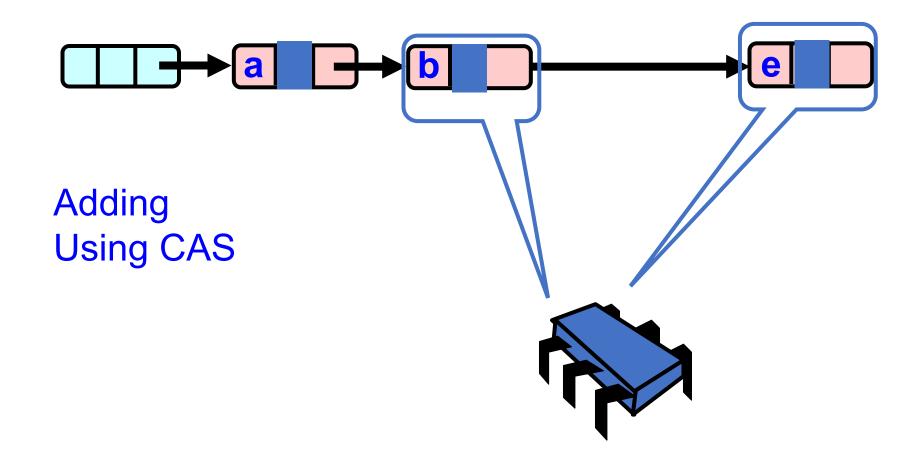






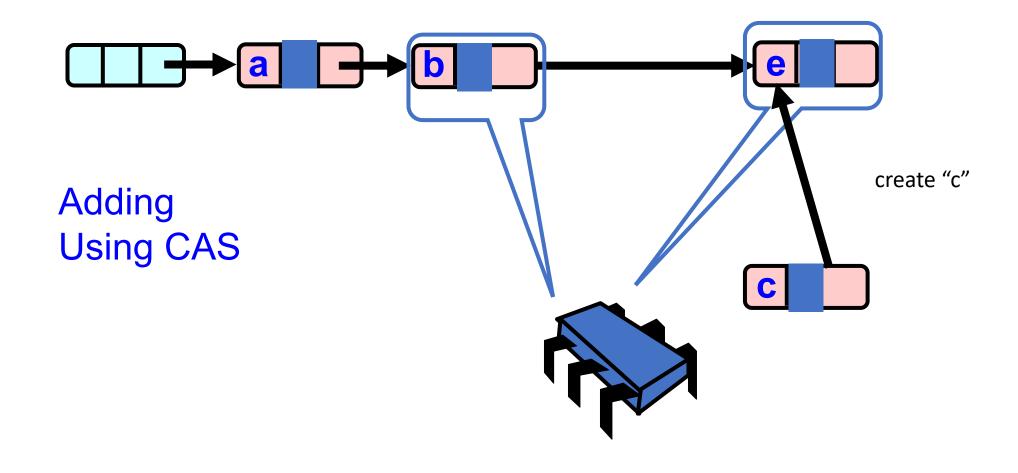
Find the location
Cache your insertion
point!

b.next == e



Find the location
Cache your insertion
point!

b.next == e

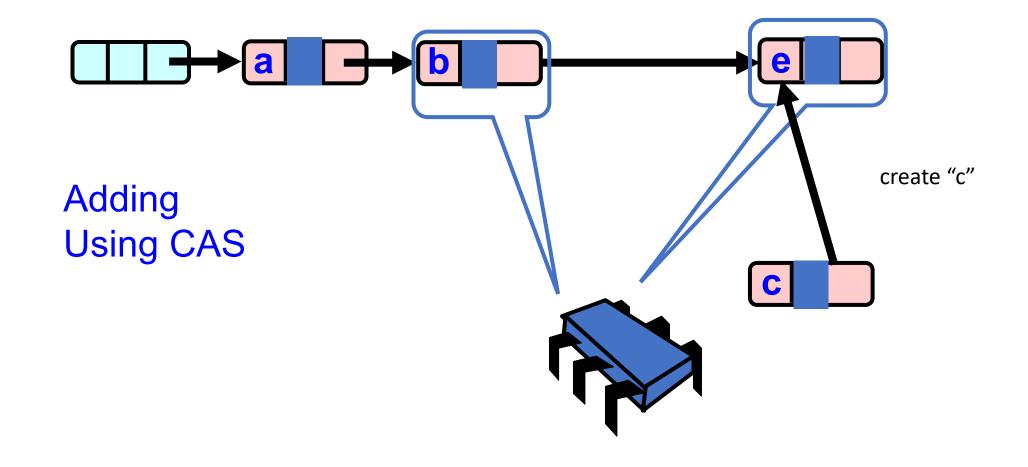


Only insert if your insertion point is valid!

CAS(b.next, e, c);

Find the location Cache your insertion point!

b.next == e

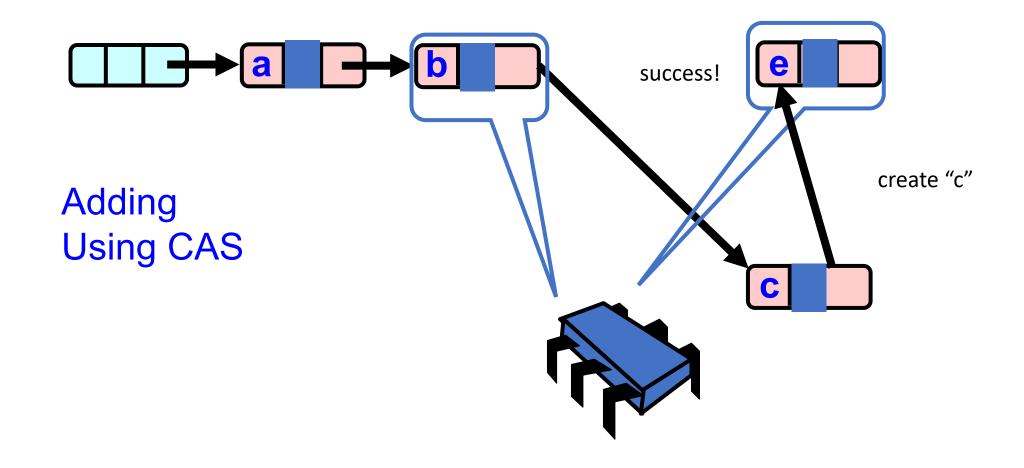


Only insert if your insertion point is valid!

CAS(b.next, e, c);

Find the location Cache your insertion point!

b.next == e

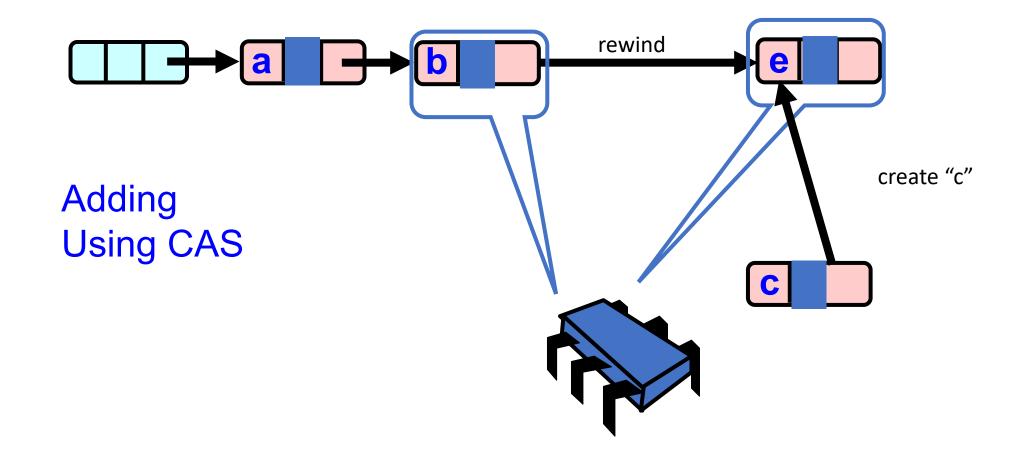


Only insert if your insertion point is valid!

CAS(b.next, e, c);

Find the location Cache your insertion point!

b.next == e

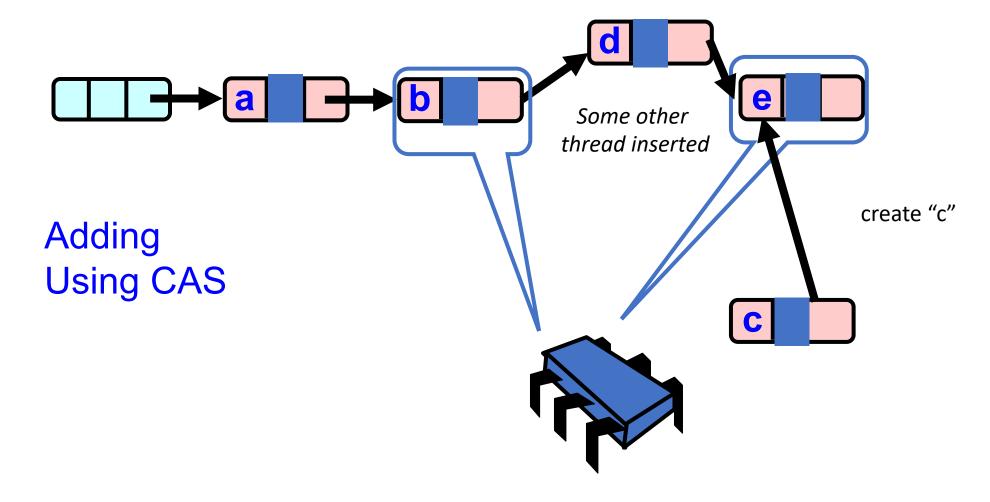


Only insert if your insertion point is valid!

CAS(b.next, e, c);

Find the location Cache your insertion point!

b.next == e

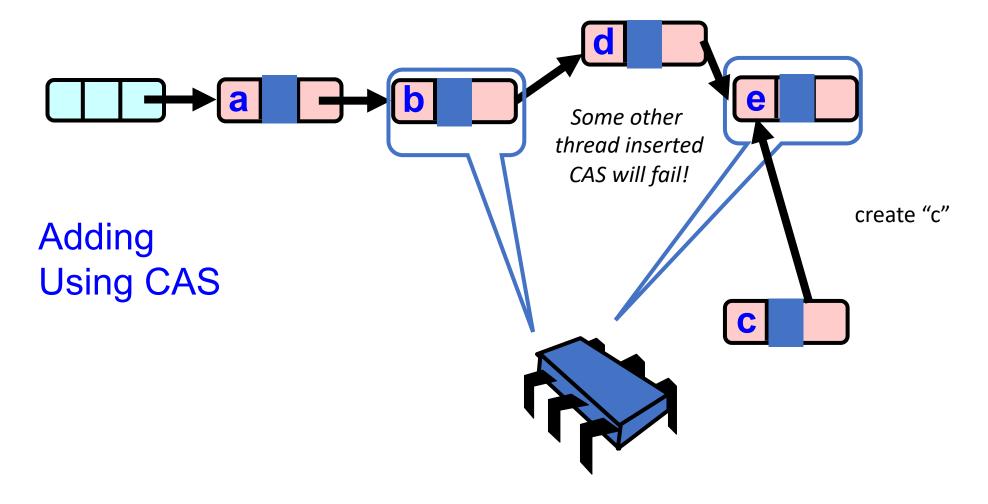


Only insert if your insertion point is valid!

CAS(b.next, e, c);

Find the location Cache your insertion point!

b.next == e

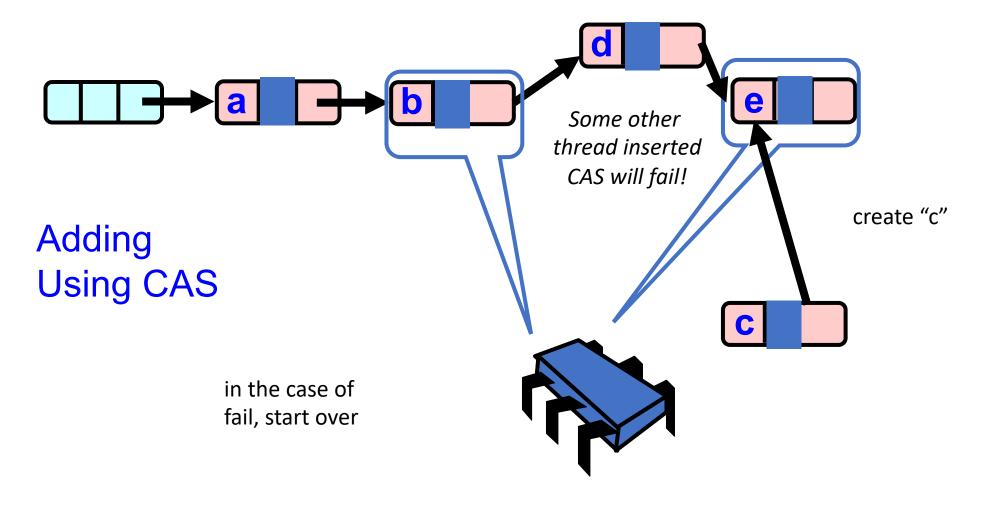


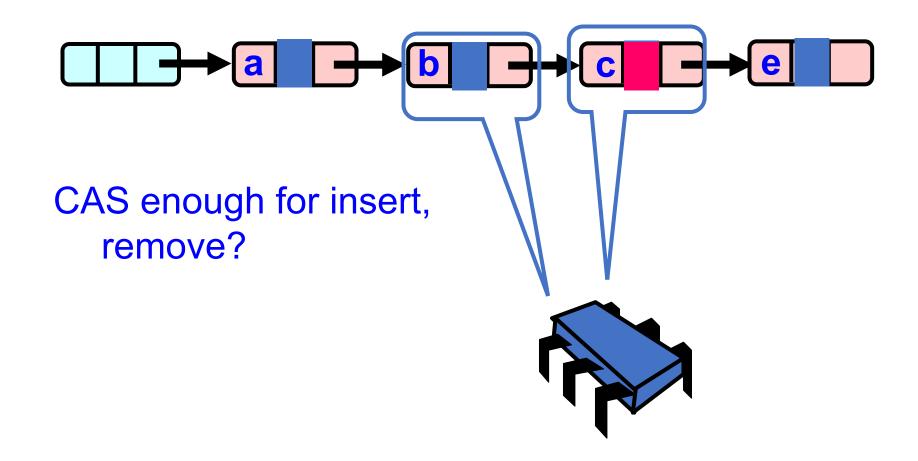
Only insert if your insertion point is valid!

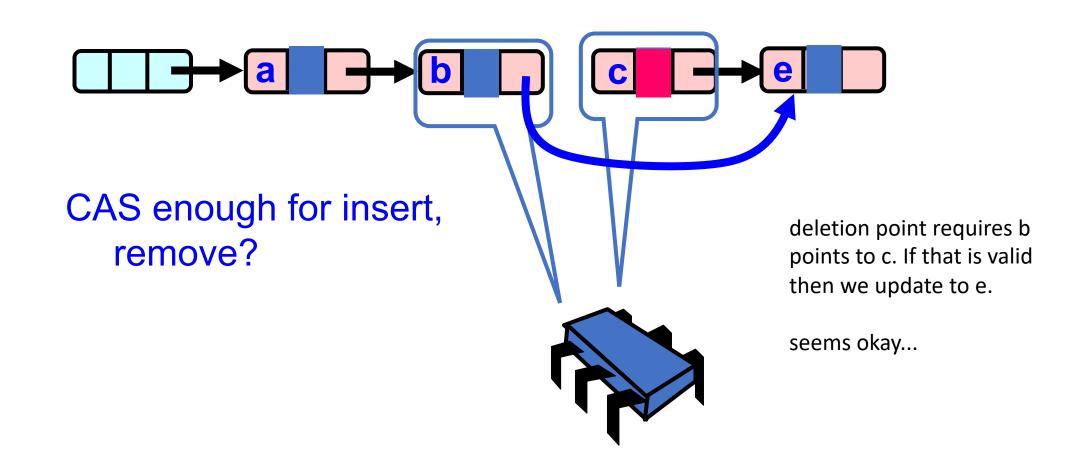
CAS(b.next, e, c);

Find the location Cache your insertion point!

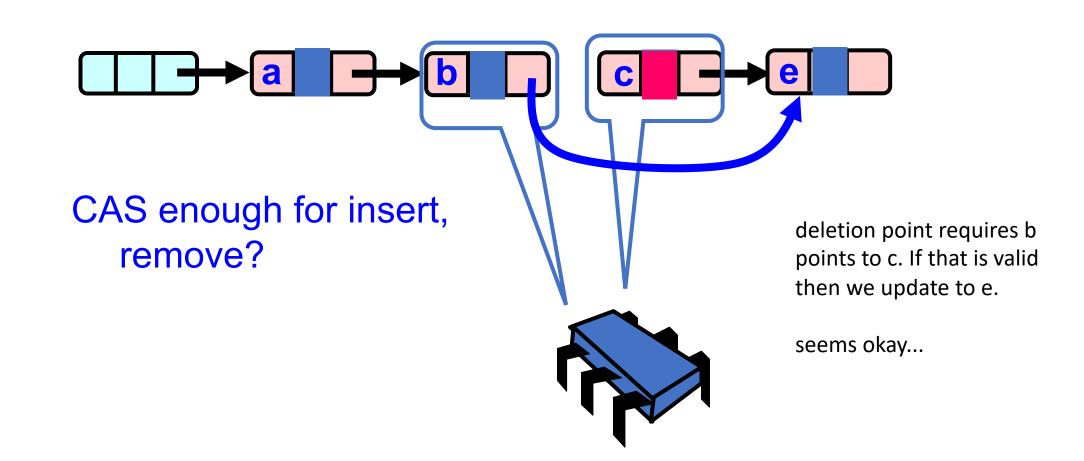
b.next == e



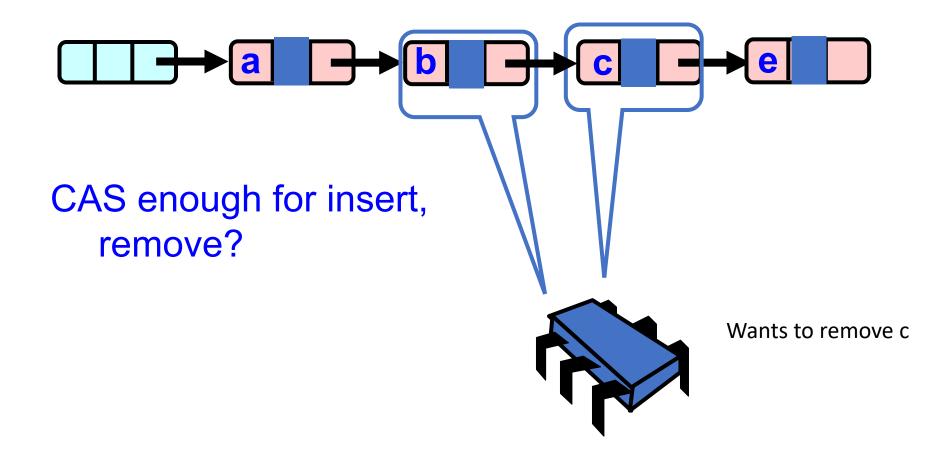


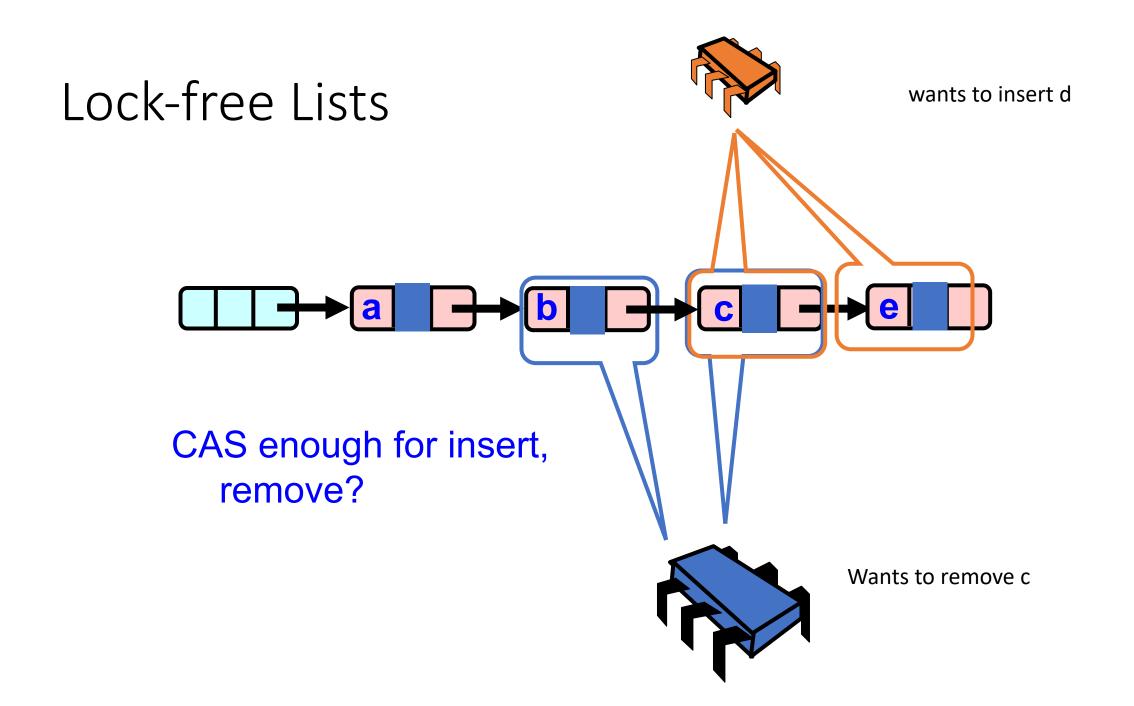


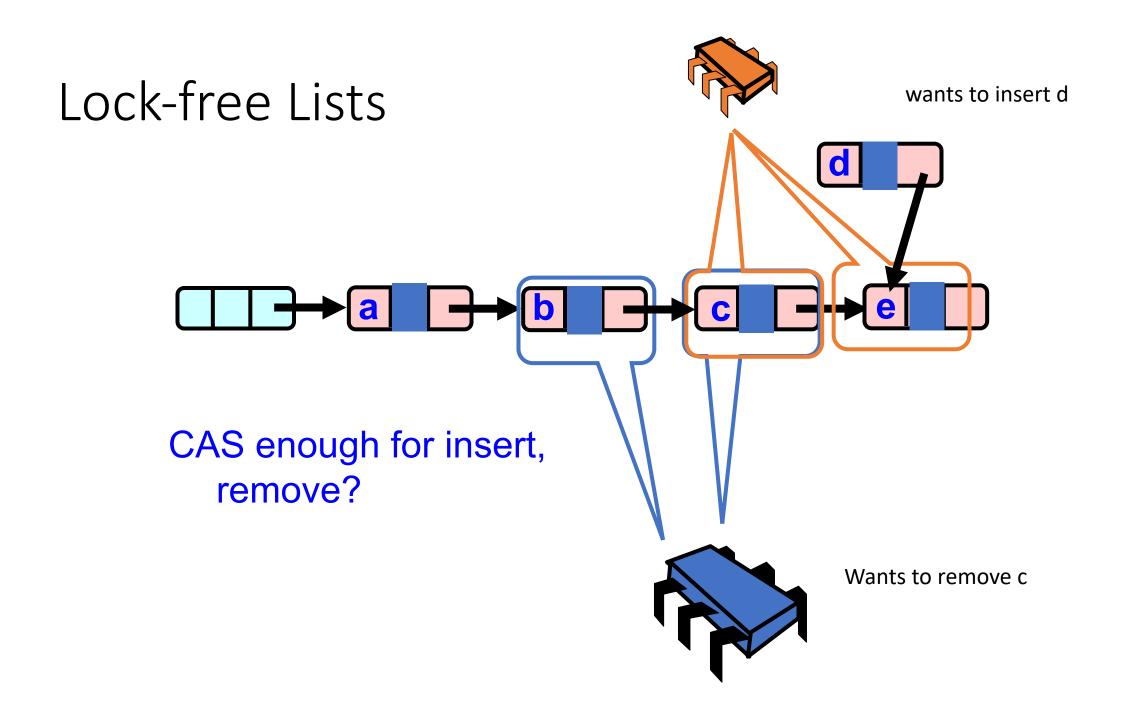
ensures that nobody has inserted a node between b and c

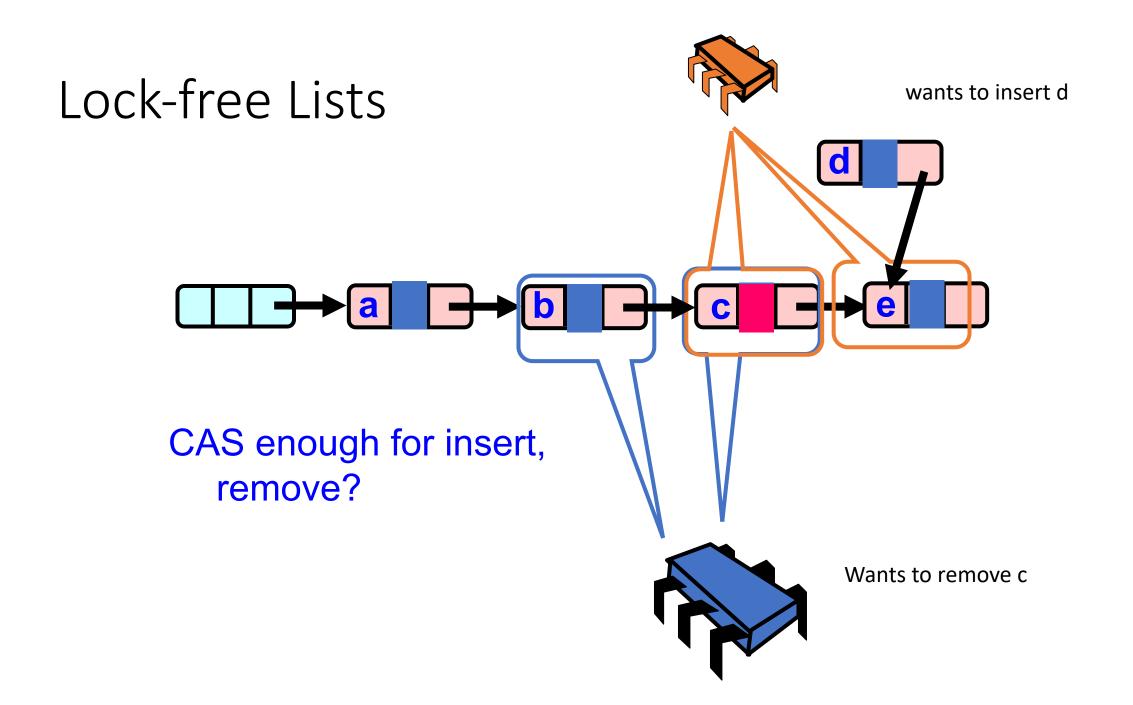


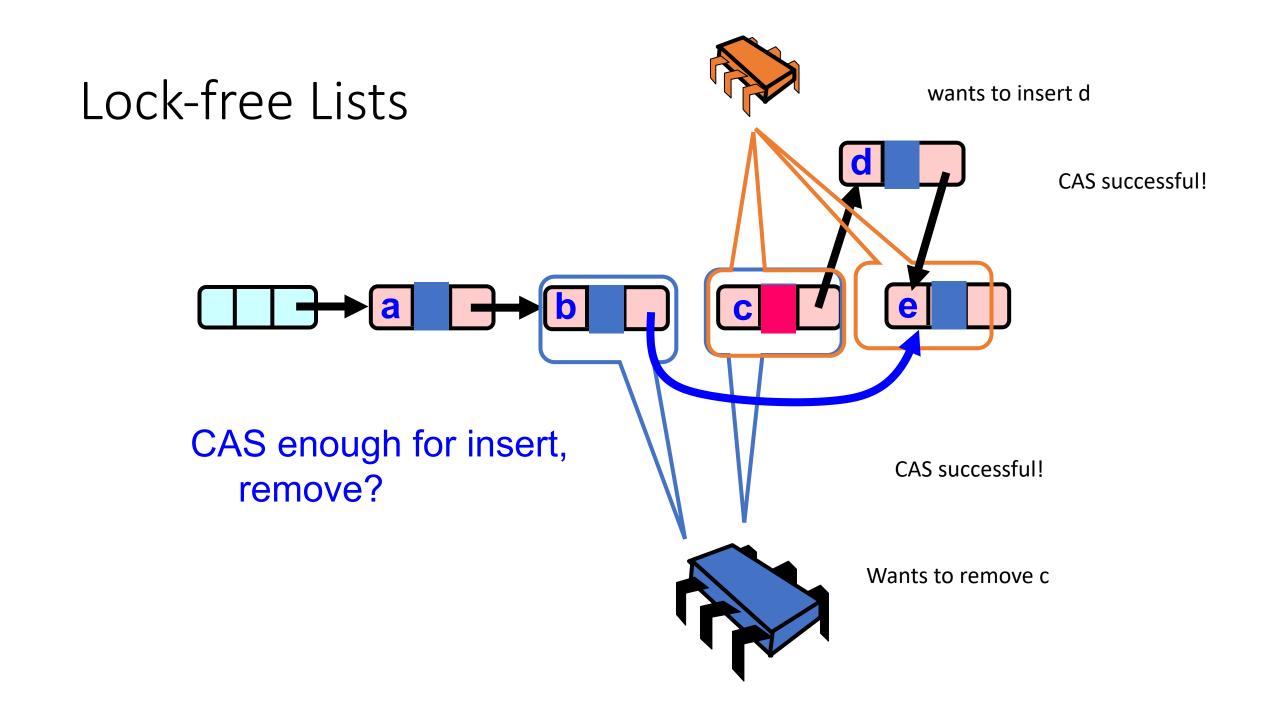
Rewind

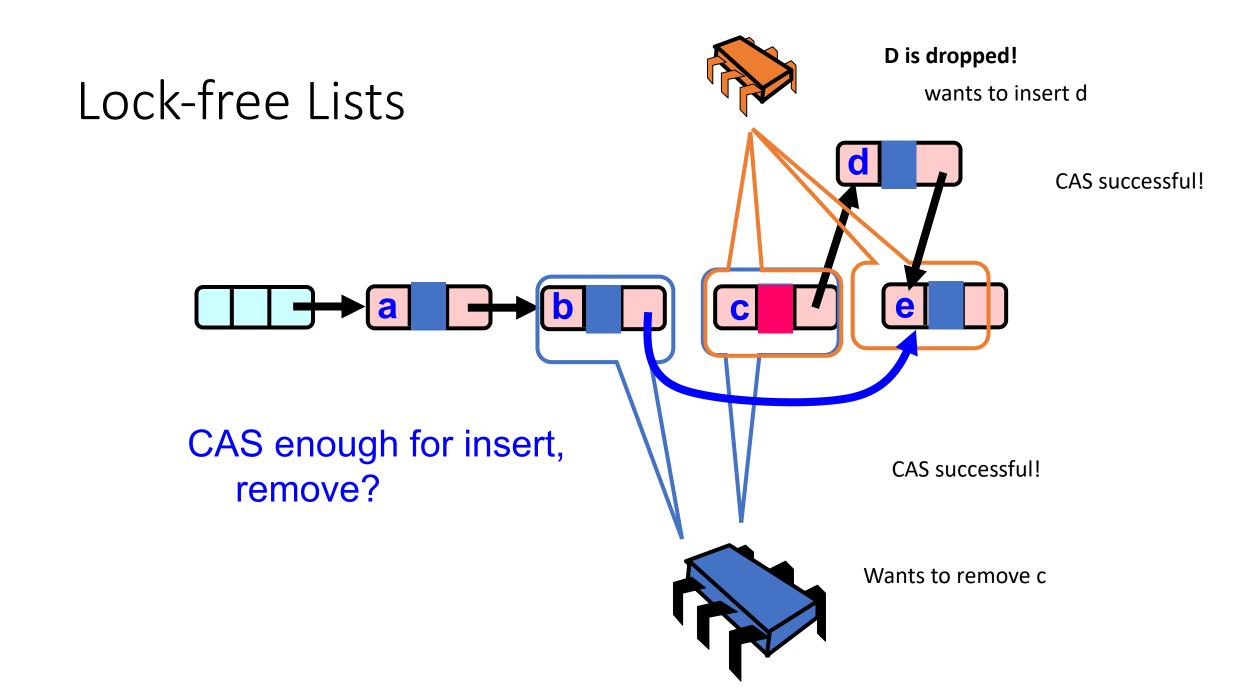






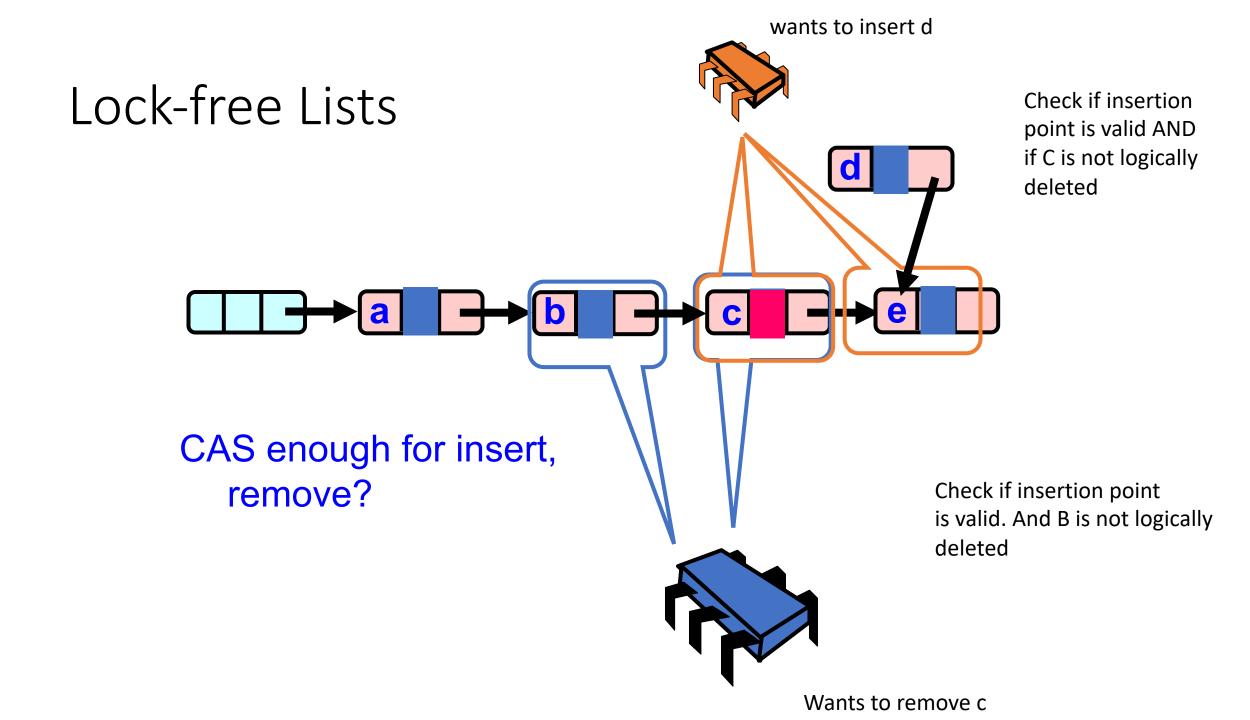






Solution

- Use AtomicMarkableReference
- Atomic CAS that checks not only the address, but also a bit
- We can say: update pointer if the insertion point is valid AND if the node has not been logically removed.



Marking a Node

- AtomicMarkableReference class
 - Java.util.concurrent.atomic package
 - But we're using a better[™] language (C++)



This stuff is tricky

- Focus on understanding the concepts:
 - locks are easiest, but can impede performance
 - fine-grained locks are better, but more difficult
 - optimistic concurrency can take you far
 - CAS is your friend
- When reasoning about correctness:
 - You have to consider all combination of adds/removes
 - thread sanitizer will help, but not as much as in mutexes
 - other tools can help (Professor Flanagan is famous for this!)