

Problem Set I

Computing Models

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ALON FILLER¹

1 Automatas

Given the automata $D = (Q^D, \{a, b\}, \delta^D, q_0^D, F^D)$

Problem 1.1.

Imagine a new automata $E = (Q^E, \{a, b\}, \delta^E, q_0^E, F^E)$ s.t:

- $Q^E = Q^D \cup \{q_0^E\}$
- $F^E = F^D$
- $\delta^E(q, \sigma) = \begin{cases} \delta^D(q, \sigma) & q \in Q^D \\ q_0^D & q = q_0^E, \sigma = a \\ q_0^E & q = q_0^E, \sigma = b \end{cases}$

Define:

- $L(A)$

Solution.

It would be non but rational to divide this construction into three divisions, each corresponding to a different set of circumstances recognised by the transitions function.

One of those aforementioned circumstances is $q = q_0^E, \sigma = b$, the study of such case lead me to determine that for the character input of b , under the assumption that the current state is q_0^E , the state would lead back to itself, meaning that that an instance of $\{b\}^$ at the beginning of the input would not affect the output of the automata. And hence $\{b\}^*$ should be imbued to the language $L(A)$.*

Another set of circumstances is $q = q_0^E, \sigma = a$, which implies the current state to be the one added to Q^D in order to craft Q^E , and that the input character is 'a'. Such circumstances appear to be digested by the automata to return q_0^D , the first state of the previous automata D . Accordingly, it would only be after the appearance of an 'a' character in the input that the state would be changed. And hence, $\{a\}$ must be added to the language $L(A)$.

¹With Soror

The last of such circumstances addressed in δ^E appears to be $q \in Q^D$. For such case, the function would make the transition from the current state to the one returned by δ^D , accordingly, $L(D)$ must be concatenated at the end of $L(E)$

Hence - I may declare that $L(A) = \{b\}^* \cdot \{a\} \cdot L(D)$. ■

Problem 1.2.

Consider the previous automata² $E = (Q^E, \{a, b\}, \delta^E, q_0^E, F^E)$
And a new automata $E' = (Q^E, \{a, b\}, \delta^E, q_0^D, F^E)$

Define:

- $L(E')$

Solution.

In the previous problem³ I have explained in great detail the effects caused by the declaration of a new state q_0^E to be the initial state of E . Considering q_0^E not to be part of Q^D , it can be seen with vividness that δ^E , known as E' 's transitions function would cease to return it as output as soon as it no longer is the current state. Therefore, knowing E' does not use q_0^E as its initial state it is cogent that it would never be returned. Accordingly, the only circumstances relevant to the transitions function would be $q \in Q^D$, and thus the addition of $\{b\}^* \cdot \{a\}$ to the beginning of $L(E)$ must be undone for $L(E')$ to be precise. And hence $L(E') = L(D)$ ■

Problem 1.3.

Consider the previous automata⁴ $E = (Q^E, \{a, b\}, \delta^E, q_0^E, F^E)$
And a new automata $E' = (Q^E, \{a, b\}, \delta^E, q_0^D, F^D \cup q_0^E)$

Define:

- $L(E')$

Solution.

Now that q_0^E is an accepting state, I should like for $L(E')$ to support it. Thus, anything that happens to follow $\{b\}^*$ is merely optional. And hence it might be defined as such: $L(E') = \{b\}^* \cdot \{\{\epsilon\} \cup (\{a\} \cdot L(D))\}$ ■

²Problem 1.1

³Problem 1.1

⁴Problem 1.2