

SORUSH ZARE

PhD Candidate | University of Virginia | Mechanical and Aerospace Engineering

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in [Soroush Zare](#)

g [Soroush Zare](#) ^{id}

PROFESSIONAL INTERESTS

Experienced Mechanical Engineer specializing in the design and control of robotic systems and soft exoskeletons. Expertise in Brain-Computer Interface (BCI) technologies, particularly in EEG-based motor imagery classification for rehabilitation applications. Proficient in mechanical design, rapid prototyping, and integrating mechanical systems with AI-driven controls. Committed to advancing the capabilities of robotics and AI through multidisciplinary collaboration.

EDUCATION

University of Virginia | GPA: 4 out of 4

Charlottesville, VA

Ph.D. Candidate in Mechanical and Aerospace Engineering

Jan. 2023-Present

- National Science Foundation (NSF) Project

[BRITE Synergy: Programmable Wearable Textile Robotics for Ubiquitous Assistance](#)

Principal Investigator: Ye (Sarah) Sun

- Contributed to a significant NSF-funded project aimed at developing innovative wearable textile robotics, focusing on enhancing accessibility and usability in everyday life applications.
- Developed an EEG-based approach for motor imagery classification to aid disabled individuals in controlling rehabilitative devices using their minds.

University of Tehran | GPA: 3.9 out of 4

Tehran, Iran

Master of Science Degree in Mechanical Engineering

Sept. 2018-July 2021

- Thesis: Deep Reinforcement Learning Control of Suspended Under-Constrained Cable-Driven Robot Creating 3D Graphical Model of Objects (Experimental Project).

Shiraz University | GPA: 3.6 out of 4

Shiraz, Iran

Bachelor of Science Degree in Mechanical Engineering

Sept. 2014-July 2018

- Thesis: Build and Analysis a model of a Bladeless Wind Turbine (Experimental Project).

PUBLICATION

- **Soroush Zare**, and Ye Sun, “NeuroMotion: EEG-Based Motor Imagery Control of a Wearable Soft Active Upper Limb Exoskeleton for Rehabilitation”. (In preparation)
- **Soroush Zare**, and Ye Sun, “Understanding Human Motion Intention from Motor Imagery EEG based on Convolutional Neural Network”, [Smart Health](#). (Under review)
- Kayla Blalack, Leo Wang, Maximus Maldonado, Lauren Marbury, **Soroush Zare**, and Ye Sun, “A Low-Cost Wearable Exoskeleton for Sitting and Standing Assistance”, [IEEE-EMBS 21st International Conference on Body Sensor Networks \(BSN\) \(2024\)](#). (Accepted)
- **Soroush Zare**, and Ye Sun, “[EEG Motor Imagery Classification using Integrated Transformer-CNN for Assistive Technology Control](#)”, IEEE/ACM Conference on Connected Health: Applications, Systems and Engineering Technologies (CHASE) (2024).
- Chukwuemeka Ochieze, **Soroush Zare**, and Ye Sun, “[Wearable upper limb robotics for pervasive health: A review](#)”, Progress in Biomedical Engineering (2023).
- **Soroush Zare**, Mohammad Reza Hairi Yazdi, Mehdi Tale Masouleh, Dan Zhang, Sahand Ajami, and Amirhossein Afkhami, “[Experimental Study on the Control of a Suspended Cable-driven Parallel Robot for Object Tracking Purpose](#)”, Robotica 40.11 (2022): 3863–3877.

- **Soroush Zare**, Morteza Shahamiri Haghighi, Mohammad Reza Hairi Yazdi, Ahmad Kalhor, and Mehdi Tale Masouleh, “[Kinematic Analysis of an Under-constrained Cable-driven Robot Using Neural Networks](#)”, (2020) 28th Iranian Conference on Electrical Engineering (ICEE).
- **Soroush Zare**, Mohammad Ghanatian, Mohammad Reza Hairi Yazdi, and Mehdi Tale Masouleh, “[Re-constructing 3-D Graphical Model Using an Under-Constrained Cable-Driven Parallel Robot](#)”, (2020) 6th Iranian Conference on Signal Processing and Intelligent Systems (ICSPIS).
- Mohammad ghanatian, **Soroush Zare**, Mohammad Reza Hairi Yazdi, and Mehdi Tale Masouleh, “[MIMO Dynamic Control of a Suspended Underactuated Cable Robot Using Genetic Algorithm](#)”, (2020) 10th Annual National and Student Conference of The Iranian Society of Mechanical Engineers (ISME).

HONORS & AWARDS

- **NSF Student Travel Award**, IEEE/ACM CHASE 2024 *Apr. 2024*
- **GRADESTAR Fellowship** *Aug. 2023, Jan. 2024*
- **Chairperson’s Fellowship** *Jan. 2023*
 - Awarded to the Entrance Ph.D. Student
- **York Graduate Scholarship** *Oct. 2023*
 - Awarded to the Top Incoming Graduate Student
- Ranked 2nd among solid design Bachelor of Science students of School of Mechanical Engineering, Shiraz University
- Offered Direct Entrance to Master of Science Program in School of Mechanical Engineering, Shiraz University for Exceptional Talents

PROFESSIONAL LEADERSHIP & SERVICES

- **Vice President**, [Graduate Student Board, Mechanical and Aerospace Engineering, UVA, 2024](#)
 - Spearheading initiatives to enhance community engagement and academic support among graduate students.
 - Facilitating the integration of innovative academic programs and technologies to enhance student learning and research capabilities.
 - Collaborating with department heads and faculty to address student concerns and improve graduate student life.
 - Leading strategic planning sessions to identify and implement improvements within the department.
 - Promoting a culture of excellence and inclusivity within the graduate student community.
- **Recruitment Chair**, Graduate Student Board, Mechanical and Aerospace Engineering, UVA, 2023
 - Organized and executed comprehensive three-day visits for prospective students, including tours of key research facilities such as [Link Lab](#).
 - Coordinated bi-weekly meetings to discuss and plan recruitment strategies and student engagement activities.
 - Managed poster demonstrations that highlighted current research projects and student achievements to visitors and faculty.
 - Developed effective communication strategies to ensure smooth logistics, fostering a welcoming and informative environment for all attendees.
 - Addressed immediate logistical challenges during events, ensuring all planned activities proceeded without interruption.
- Student Member of Institute of Electrical and Electronics Engineers (IEEE)

- **Reviewer** of [IEEE BSN 2024 Conference](#)
- **Reviewer** of [IEEE/ACM CHASE 2024 Conference](#)
- **Reviewer** of [ACM Transactions on Computing for Healthcare](#)
- **Reviewer** of [Smart Health](#)
- **Reviewer** of The 2023 ASEE Annual Conference & Exposition, Baltimore, MD
- **Reviewer** of [Journal of Biomedical Physics & Engineering Express](#)
- **Reviewer** of [Journal of Vibration and Control](#)
- **Reviewer** of The Third International Conference on Artificial Intelligence, Information Processing and Cloud Computing (AIIPCC 2022)
- **Reviewer** of The 5th International Conference on Mechanical, Electric, and Industrial Engineering (MEIE 2022)
- Member of Iranian Society of Engineering Education (ISEE)

RESEARCH EXPERIENCE

- **Research Assistant** at University of Virginia (Charlottesville, VA) *Jan. 2023 — Present*
 - Designing and developing soft upper limb rehabilitation exoskeleton.
 - Contributed to the design and control of wearable soft rehabilitation robots using soft materials and 3D printing techniques.
 - Implementing reinforcement learning frameworks to enable intuitive control of soft wearable robots via EEG signals.
 - Collaborating in interdisciplinary teams to integrate high-resolution EEG technologies with real-time motor function support systems.
 - Innovating non-invasive EEG sensor technology to reduce setup complexity and enhance user comfort in real-world applications.
 - Contributing to the development of deep learning models for early detection of neurodegenerative diseases, aiming to revolutionize preventative healthcare.
- **Research Assistant** at York University (Toronto, Canada) *Sept. 2022 — Jan. 2023*
 - Lead Project (Smart Grasping Using Deep Reinforcement Learning)
 - Developed and simulated robotic grasping mechanisms using UR5 robotic arm in ROS (Robot Operating System).
 - Utilized Gazebo for real-time simulation and testing of robotic control algorithms.
- **Research Assistant** at University of Tehran (Tehran, Iran) *Sept. 2018 — Sept. 2022*
 - **Member** of [Human and Robot Interaction Laboratory \(TaarLab\)](#)
 - Control Cable-Driven Parallel Robot (CDPR) Using Deep Reinforcement Learning
 - Construct 3-D model of Objects Using CDPR
 - AI-based Object Tracking Using CDPR

TEACHING ASSISTANT

- Gradaute Course
 - **Advanced Control** *Four Semesters 2019–2022*
Department of Mechanical Engineering, University of Tehran, Tehran, Iran

- **Game Theory** *Fall 2020*
Department of Economics, University of Tehran, Tehran, Iran
- **Advanced Mathematics** *Fall 2019*
Department of Mechanical Engineering, University of Tehran Tehran, Iran
- Undergraduate Course
- **Dynamics** *Fall 2022*
Department of Mechanical Engineering, York University, Toronto, Canada
- **Game Theory** *Fall 2020*
Department of Economics, University of Tehran, Tehran, Iran
- **Automatic Control** *Fall 2020*
Department of Mechanical Engineering, University of Tehran, Tehran, Iran
- **Dynamics of Machinery and Vibration Lab** *Fall 2018*
Department of Mechanical Engineering, University of Tehran Tehran, Iran
- **Engineering Mathematics** *Fall 2017*
Department of Mechanical Engineering, Shiraz University, Shiraz, Iran

CERTIFICATES

- [2023 Peer Review Excellence Online Training Graduate](#) | IOP Publishing
- [Human Research IRB-HSR Researcher Basic Course](#) | University of Virginia
- [Human Research IRB-SBS Researcher Basic Course-NO PRISONERS](#) | University of Virginia
- [Reinforcement Learning Specialization](#) | University of Alberta (Coursera)
- [Introduction to Machine Learning in Production](#) | DeepLearning.AI (Coursera)
- [Neural Networks and Deep Learning](#) | DeepLearning.AI (Coursera)
- [Machine Learning](#) | Stanford University (Coursera)
- [Getting started with TensorFlow 2](#) | Imperial College London (Coursera)