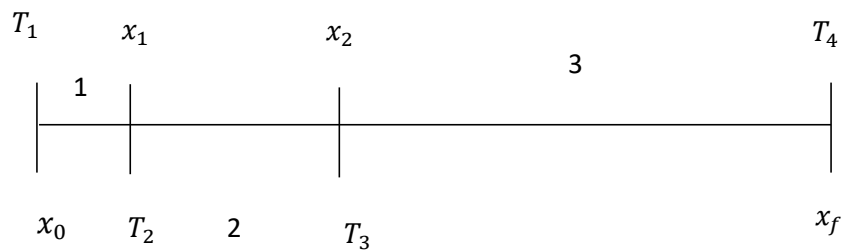


## Método de los elementos finitos para el problema de transferencia de calor en una dimensión con funciones de forma lineales y con peso de Galerkin



Mallado:

Asumimos que la respuesta está en los nodos:

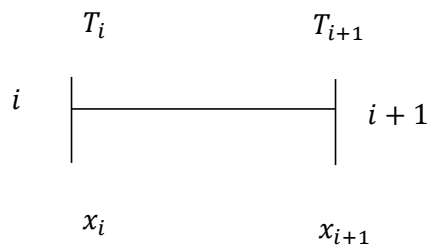


Interpolación:

Utilizaremos funciones de forma lineales para una dimensión.

$$T_i = N_i T_i + N_{i+1} T_{i+1}$$

Para el elemento  $i$ :



$$N_i = \frac{x_{i+1} - x}{x_{i+1} - x_i}, \quad N_{i+1} = \frac{x - x_i}{x_{i+1} - x_i}$$

| Elemento | $i$ | $i + 1$ |
|----------|-----|---------|
| 1        | 1   | 2       |
| 2        | 2   | 3       |
| 3        | 3   | 4       |

Nuestros elementos tienen diferentes longitudes:

$$d = x_{i+1} - x_i$$

$$\frac{d}{dx} \left( k \frac{dT}{dx} \right) = Q, \quad k \wedge Q = kte$$

$$T = [N_1 \quad N_2] \begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$$

$$\hat{T} \approx \mathbf{NT}, \quad \mathbf{N}_{(x)}$$

Discretización:

$$\frac{d}{dx} \left( k \frac{dT}{dx} \right) = Q$$

$$\frac{d}{dx} \left( k \frac{d\hat{T}}{dx} \right) \approx Q \equiv \frac{d}{dx} \left( k \frac{d\mathbf{N}_{(x)}}{dx} \right) \mathbf{T} \approx Q$$

Calculo Residual:

$$\frac{d}{dx} \left( k \frac{d\mathbf{N}_{(x)}}{dx} \right) \mathbf{T} - Q = \xi$$

Método de los residuos ponderados:

$$\int_{\Omega} \xi_i w_i d\Omega = 0$$

$$\int_{\Omega} w \left[ \frac{d}{dx} \left( k \frac{d\mathbf{N}}{dx} \right) \mathbf{T} - Q \right] d\Omega = 0$$

$$\frac{d}{dx} [N_i \quad N_{i+1}] = \left[ \frac{d}{dx} N_i \quad \frac{d}{dx} N_{i+1} \right]$$

$$\frac{d}{dx} N_i = \frac{-1}{x_{i+1} - x_i}$$

$$\frac{d}{dx} N_{i+1} = \frac{1}{x_{i+1} - x_i}$$

$$\int_{\Omega} w \left[ \frac{d}{dx} \left[ \frac{-k}{x_{i+1} - x_i} \quad \frac{k}{x_{i+1} - x_i} \right] \mathbf{T} - \mathbf{Q} \right] d\Omega = 0$$

$$\int_{\Omega} \mathbf{w} \left[ \frac{d}{dx} \left[ \frac{-k}{x_{i+1} - x_i} \quad \frac{k}{x_{i+1} - x_i} \right] \mathbf{T} - \mathbf{Q} \right] d\Omega = 0$$

$$\mathbf{w} = \begin{bmatrix} w_{x_i} \\ w_{x_{i+1}} \end{bmatrix}$$

$$\int_{\Omega} \begin{bmatrix} w_{x_i} \\ w_{x_{i+1}} \end{bmatrix} \left[ \frac{d}{dx} \left[ \frac{-k}{x_{i+1} - x_i} \quad \frac{k}{x_{i+1} - x_i} \right] \mathbf{T} - \mathbf{Q} \right] d\Omega = 0$$

Método de Galerkin

$$W_i = N_i$$

Forma Fuerte:

$$\int_{x_i}^{x_{i+1}} \mathbf{N}^T \left[ \frac{d}{dx} \left[ \frac{-k}{x_{i+1} - x_i} \quad \frac{k}{x_{i+1} - x_i} \right] \mathbf{T} - \mathbf{Q} \right] dx = 0$$

Integración por partes:

$$\int_{x_i}^{x_{i+1}} \mathbf{N}^T \frac{d}{dx} \left( \frac{-k}{x_{i+1} - x_i} \quad \frac{k}{x_{i+1} - x_i} \right) \mathbf{T} dx - \mathbf{Q} \int_{x_i}^{x_{i+1}} \mathbf{N}^T dx = 0$$

$$\int u dv = uv - v \int du$$

$$u = \mathbf{N}^T$$

$$du = \frac{d}{dx} \mathbf{N}^T dx$$

$$dv = k \frac{d\mathbf{N}^T}{dx} dx$$

$$v = k \frac{d\mathbf{N}^T}{dx}$$

$$\mathbf{N}^T k \frac{d\mathbf{N}^T}{dx} - \int \frac{d}{dx} \mathbf{N}^T k \frac{d\mathbf{N}^T}{dx} dx$$

Forma débil:

$$\mathbf{N}^T k \frac{d\mathbf{N}^T}{dx} \Big|_{\Gamma} - \int_{x_i}^{x_{i+1}} \frac{d}{dx} \mathbf{N}^T k \frac{d\mathbf{N}^T}{dx} dx - Q \int_{x_i}^{x_{i+1}} \mathbf{N}^T dx = 0$$

$$\frac{d}{dx} \mathbf{N}^T = \frac{d}{dx} \begin{bmatrix} N_i \\ N_{i+1} \end{bmatrix} = \begin{bmatrix} \frac{dN_i}{dx} \\ \frac{dN_{i+1}}{dx} \end{bmatrix} = \frac{1}{x_{i+1} - x_i} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\frac{d}{dx} \mathbf{N} = \frac{1}{x_{i+1} - x_i} \begin{bmatrix} -1 & 1 \end{bmatrix}$$

$$\frac{d}{dx} \mathbf{N}^T \frac{d}{dx} \mathbf{N} = \frac{1}{(x_{i+1} - x_i)^2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$k \int_{x_i}^{x_{i+1}} \frac{1}{(x_{i+1} - x_i)^2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \mathbf{T} dx$$

$$\frac{k}{(x_{i+1} - x_i)^2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} (x_{i+1} - x_i) \mathbf{T} = \frac{k}{(x_{i+1} - x_i)} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} T_i \\ T_{i+1} \end{bmatrix}$$

$$-Q \int_{x_i}^{x_{i+1}} \mathbf{N}^T dx = \frac{-Q}{(x_{i+1} - x_i)} \int_{x_i}^{x_{i+1}} \begin{bmatrix} x_{i+1} - x \\ x - x_i \end{bmatrix} dx = \frac{-Q}{(x_{i+1} - x_i)} \begin{bmatrix} \int_{x_i}^{x_{i+1}} x_{i+1} - x dx \\ \int_{x_i}^{x_{i+1}} x - x_i dx \end{bmatrix}$$

$$\frac{-Q}{(x_{i+1} - x_i)} \begin{bmatrix} \int_{x_i}^{x_{i+1}} x_{i+1} - x dx \\ \int_{x_i}^{x_{i+1}} x - x_i dx \end{bmatrix} = \frac{-Q}{(x_{i+1} - x_i)} \begin{bmatrix} \frac{(x_{i+1} - x_i)^2}{2} \\ \frac{(x_{i+1} - x_i)^2}{2} \end{bmatrix} = \frac{-Q(x_{i+1} - x_i)}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\frac{k}{(x_{i+1} - x_i)} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} T_i \\ T_{i+1} \end{bmatrix} = \frac{-Q(x_{i+1} - x_i)}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \mathbf{N}^T k \frac{d\mathbf{N}T}{dx}$$

$$\mathbf{kT} = \mathbf{b}$$

Para cada elemento  $i$ :

$$\mathbf{k} = \begin{bmatrix} k_{i1} & k_{i2} \\ k_{i3} & k_{i4} \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} b_{i1} \\ b_{i2} \end{bmatrix}$$