

2. Siempre en la ecuación de transferencia de calor, ahora modifique toda la formulación del MEF, considerando que ahora k no es constante, sino que viene dada por la siguiente función:

$$k = k(x) = e^x - \frac{x}{2}$$

Mallado:

$$\frac{d}{dx} \left( k(x) \frac{dT}{dx} \right) = -Q, \quad Q = kte$$

$$T = [N_i \quad N_{i+1}] \begin{bmatrix} T_i \\ T_{i+1} \end{bmatrix}$$

$$\hat{T} \approx \mathbf{N}\mathbf{T}, \quad \mathbf{N}_{(x)}$$

Discretización:

$$\frac{d}{dx} \left( k(x) \frac{dT}{dx} \right) = -Q$$

$$\frac{d}{dx} \left( k(x) \frac{d\hat{T}}{dx} \right) \approx -Q \equiv \frac{d}{dx} \left( k(x) \frac{d\mathbf{N}_{(x)}}{dx} \right) \mathbf{T} \approx -Q$$

Residuos:

$$\frac{d}{dx} \left( k(x) \frac{d\mathbf{N}_{(x)}}{dx} \right) \mathbf{T} + Q = \xi$$

Método de los residuos ponderados:

$$\int_{\Omega} \xi_i w_i d\Omega = 0$$

$$\int_{\Omega} w \left[ \frac{d}{dx} \left( k(x) \frac{d\mathbf{N}}{dx} \right) \mathbf{T} + Q \right] d\Omega = 0$$

$$\frac{d}{dx} [N_i \quad N_{i+1}] = \left[ \frac{d}{dx} N_i \quad \frac{d}{dx} N_{i+1} \right]$$

$$\frac{d}{dx} N_i = \frac{-1}{x_{i+1} - x_i}$$

$$\frac{d}{dx} N_{i+1} = \frac{1}{x_{i+1} - x_i}$$

$$\int_{\Omega} w \left[ \frac{d}{dx} k(x) \begin{bmatrix} -1 & 1 \\ x_{i+1} - x_i & x_{i+1} - x_i \end{bmatrix} \mathbf{T} + \mathbf{Q} \right] d\Omega = 0$$

$$\int_{\Omega} \mathbf{w} \left[ \frac{d}{dx} k(x) \begin{bmatrix} -1 & 1 \\ x_{i+1} - x_i & x_{i+1} - x_i \end{bmatrix} \mathbf{T} + \mathbf{Q} \right] d\Omega = 0$$

$$\mathbf{w} = \begin{bmatrix} w_{x_i} \\ w_{x_{i+1}} \end{bmatrix}$$

$$\int_{\Omega} \begin{bmatrix} w_{x_i} \\ w_{x_{i+1}} \end{bmatrix} \left[ \frac{d}{dx} k(x) \begin{bmatrix} -1 & 1 \\ x_{i+1} - x_i & x_{i+1} - x_i \end{bmatrix} \mathbf{T} + \mathbf{Q} \right] d\Omega = 0$$

Método de Galerkin

$$W_i = N_i$$

Forma Fuerte:

$$\int_{x_i}^{x_{i+1}} \mathbf{N}^T \left[ \frac{d}{dx} k(x) \begin{bmatrix} -1 & 1 \\ x_{i+1} - x_i & x_{i+1} - x_i \end{bmatrix} \mathbf{T} + \mathbf{Q} \right] dx = 0$$

Integración por partes:

$$\int_{x_i}^{x_{i+1}} \mathbf{N}^T \frac{d}{dx} k(x) \left( \frac{-1}{x_{i+1} - x_i} \frac{1}{x_{i+1} - x_i} \right) \mathbf{T} dx + \mathbf{Q} \int_{x_i}^{x_{i+1}} \mathbf{N}^T dx = 0$$

$$\int u dv = uv - v \int du$$

$$u = \mathbf{N}^T$$

$$du = \frac{d}{dx} \mathbf{N}^T dx$$

$$dv = \frac{d}{dx} \left( \frac{d}{dx} (k(x) \mathbf{N}^T) \right) dx$$

$$v = \frac{d}{dx} (k(x) \mathbf{N}^T)$$

$$\mathbf{N}^T \frac{d}{dx} (k(x) \mathbf{N}^T) - \int \frac{d}{dx} \mathbf{N}^T \frac{d}{dx} (k(x) \mathbf{N}^T) dx$$

Forma débil:

$$\mathbf{N}^T \frac{d}{dx} (k(x) \mathbf{N}^T) \Big|_{\Gamma} - \int_{x_i}^{x_{i+1}} \frac{d}{dx} \mathbf{N}^T \frac{d}{dx} (k(x) \mathbf{N}^T) dx + Q \int_{x_i}^{x_{i+1}} \mathbf{N}^T dx = 0$$

$$\frac{d}{dx} \mathbf{N}^T = \frac{d}{dx} \begin{bmatrix} N_i \\ N_{i+1} \end{bmatrix} = \begin{bmatrix} \frac{dN_i}{dx} \\ \frac{dN_{i+1}}{dx} \end{bmatrix} = \frac{1}{x_{i+1} - x_i} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\frac{d}{dx} k(x) \mathbf{N} = \left[ \left( e^x - \frac{1}{2} \right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left( e^x - \frac{x}{2} \right)}{x_{i+1} - x_i} \frac{x_i(2e^x - 1) + 2x - 2e^x(x + 1)}{-2(x_{i+1} - x_i)} \right]$$

$$\frac{d}{dx} \mathbf{N}^T \frac{d}{dx} k(x) \mathbf{N} = \frac{1}{x_{i+1} - x_i} \begin{bmatrix} -1 \\ 1 \end{bmatrix} \left[ \left( e^x - \frac{1}{2} \right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left( e^x - \frac{x}{2} \right)}{x_{i+1} - x_i} \frac{x_i(2e^x - 1) + 2x - 2e^x(x + 1)}{-2(x_{i+1} - x_i)} \right]$$

$$= \frac{1}{x_{i+1} - x_i} \begin{bmatrix} - \left( e^x - \frac{1}{2} \right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left( e^x - \frac{x}{2} \right)}{x_{i+1} - x_i} \frac{x_i(2e^x - 1) + 2x - 2e^x(x + 1)}{-2(x_{i+1} - x_i)} \\ \left( e^x - \frac{1}{2} \right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left( e^x - \frac{x}{2} \right)}{x_{i+1} - x_i} \frac{x_i(2e^x - 1) + 2x - 2e^x(x + 1)}{-2(x_{i+1} - x_i)} \end{bmatrix}$$

$$\int_{x_i}^{x_{i+1}} \frac{1}{x_{i+1} - x_i} \begin{bmatrix} -\left(e^x - \frac{1}{2}\right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left(e^x - \frac{x}{2}\right)}{x_{i+1} - x_i} - \frac{x_i(2e^x - 1) + 2x - 2e^x(x+1)}{-2(x_{i+1} - x_i)} \\ \left(e^x - \frac{1}{2}\right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left(e^x - \frac{x}{2}\right)}{x_{i+1} - x_i} - \frac{x_i(2e^x - 1) + 2x - 2e^x(x+1)}{-2(x_{i+1} - x_i)} \end{bmatrix} \mathbf{T} dx$$

$$Q \int_{x_i}^{x_{i+1}} \mathbf{N}^T dx = \frac{Q}{(x_{i+1} - x_i)} \int_{x_i}^{x_{i+1}} \begin{bmatrix} x_{i+1} - x \\ x - x_i \end{bmatrix} dx = \frac{Q}{(x_{i+1} - x_i)} \begin{bmatrix} \int_{x_i}^{x_{i+1}} x_{i+1} - x dx \\ \int_{x_i}^{x_{i+1}} x - x_i dx \end{bmatrix}$$

$$\frac{Q}{(x_{i+1} - x_i)} \begin{bmatrix} \int_{x_i}^{x_{i+1}} x_{i+1} - x dx \\ \int_{x_i}^{x_{i+1}} x - x_i dx \end{bmatrix} = \frac{Q}{(x_{i+1} - x_i)} \begin{bmatrix} \frac{(x_{i+1} - x_i)^2}{2} \\ \frac{(x_{i+1} - x_i)^2}{2} \end{bmatrix} = \frac{Q(x_{i+1} - x_i)}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\int_{x_i}^{x_{i+1}} \frac{1}{x_{i+1} - x_i} \begin{bmatrix} -\left(e^x - \frac{1}{2}\right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left(e^x - \frac{x}{2}\right)}{x_{i+1} - x_i} - \frac{x_i(2e^x - 1) + 2x - 2e^x(x+1)}{-2(x_{i+1} - x_i)} \\ \left(e^x - \frac{1}{2}\right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left(e^x - \frac{x}{2}\right)}{x_{i+1} - x_i} - \frac{x_i(2e^x - 1) + 2x - 2e^x(x+1)}{-2(x_{i+1} - x_i)} \end{bmatrix} \mathbf{T} dx = \frac{-Q(x_{i+1} - x_i)}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \mathbf{N}^T \frac{d}{dx} (k(x) \mathbf{N} \mathbf{T}) \Big|_{\Gamma}$$

$$\frac{1}{x_{i+1} - x_i} \int_{x_i}^{x_{i+1}} \begin{bmatrix} -\left(e^x - \frac{1}{2}\right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left(e^x - \frac{x}{2}\right)}{x_{i+1} - x_i} - \frac{x_i(2e^x - 1) + 2x - 2e^x(x+1)}{-2(x_{i+1} - x_i)} \\ \left(e^x - \frac{1}{2}\right) \frac{(x_{i+1} - x)}{x_{i+1} - x_i} - \frac{\left(e^x - \frac{x}{2}\right)}{x_{i+1} - x_i} - \frac{x_i(2e^x - 1) + 2x - 2e^x(x+1)}{-2(x_{i+1} - x_i)} \end{bmatrix} \mathbf{T} dx = \frac{-Q(x_{i+1} - x_i)}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \mathbf{N}^T \frac{d}{dx} (k(x) \mathbf{N} \mathbf{T}) \Big|_{\Gamma}$$

$$\mathbf{kT} = \mathbf{b}$$

Para cada elemento  $i$ :

$$\mathbf{k} = \begin{bmatrix} k_{i1} & k_{i2} \\ k_{i3} & k_{i4} \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} b_{i1} \\ b_{i2} \end{bmatrix}$$

Ensamblaje:

Elemento	$i$	$i + 1$
1	1	2
2	2	3
3	3	4

$$\begin{bmatrix} k_{11} & k_{12} & 0 & 0 \\ k_{13} & k_{14} + k_{21} & k_{22} & 0 \\ 0 & k_{23} & k_{24} + k_{31} & k_{32} \\ 0 & 0 & k_{33} & k_{34} \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \end{bmatrix} = \begin{bmatrix} b_{11} \\ b_{12} + b_{21} \\ b_{22} + b_{31} \\ b_{32} \end{bmatrix}$$

$$KT = B$$

Condiciones de contorno:

Condiciones de Neumann:  $\frac{dT}{dx} = T_0$  en  $\Gamma_N, \Gamma_N \subseteq \Gamma$

$$\mathbf{N}^T k \frac{d\mathbf{N}\mathbf{T}}{dx} \Big|_{\Gamma} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} k_{11} & k_{12} & 0 & 0 \\ k_{13} & k_{14} + k_{21} & k_{22} & 0 \\ 0 & k_{23} & k_{24} + k_{31} & k_{32} \\ 0 & 0 & k_{33} & k_{34} \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \end{bmatrix} = \begin{bmatrix} b_{11} \\ b_{12} + b_{21} \\ b_{22} + b_{31} \\ b_{32} \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 3 \end{bmatrix}$$

Condiciones de Dirichlet:  $T = T_0$  en  $\Gamma_D, \Gamma_D \subseteq \Gamma$

$$\begin{bmatrix} 10 \\ T_2 \\ T_3 \\ T_4 \end{bmatrix}$$