Applied Optimization Exercise 5 - Line Search Methods

Lucien Gremaud Chenrui Fan Tristan Henchoz

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Exact line search for the convex quadratic function

$$f(x) = \frac{1}{2}x^T Q x + q^T x + c$$

$$t := \operatorname*{argmin}_{s>0} f(x + s\Delta x)$$

Let's start by defining and computing $g(s) := f(x + s\Delta x)$:

$$g(s) := f(x + s\Delta x) = \frac{1}{2}(x + s\Delta x)^T Q(x + s\Delta x) + q^T(x + s\Delta x) + c$$

$$= f(x) + \frac{1}{2}s\Delta x^T Q x + \frac{1}{2}x^T Q s\Delta x + \frac{1}{2}s\Delta x^T Q s\Delta x + q^T s\Delta x$$

$$= f(x) + s\left(\frac{1}{2}\Delta x^T Q x + \frac{1}{2}x^T Q \Delta x + q^T \Delta x\right) + s^2 \frac{1}{2}\Delta x^T Q \Delta x$$

As we are looking to minimize g(s) for s, let's compute the derivative of g and search s such as g'(s) = 0:

$$\frac{dg(s)}{ds} = \left(\frac{1}{2}\Delta x^T Q x + \frac{1}{2}x^T Q \Delta x + q^T \Delta x\right) + s\Delta x^T Q \Delta x = 0$$

$$\Leftrightarrow$$

$$s\Delta x^T Q \Delta x = -\left(\frac{1}{2}\Delta x^T Q x + \frac{1}{2}x^T Q \Delta x + q^T \Delta x\right)$$

$$\Leftrightarrow$$

$$s = -\frac{\frac{1}{2}\Delta x^T Q x + \frac{1}{2}x^T Q \Delta x + q^T \Delta x}{\Delta x^T Q \Delta x}$$

Therefore, as f(x) is convex and $s \ge 0$, for an arbitrary x

$$t = \max\left(-\frac{\Delta x^T Q x + x^T Q \Delta x + 2q^T \Delta x}{2\Delta x^T Q \Delta x}, 0\right)$$

Gradient descent with exact line search

Given the unconstrained optimisation problem minimize $f(x) := \frac{1}{4}x_1^2 + x_2^2$, we want to perform one iteration of the gradient descent algorithm from the starting point $x^{(0)} = (2,1)$ with exact line search. As Δx is define for the gradient descent as $\Delta x := -\nabla f(x)$, let's start by computing the gradient $\nabla f(x)$ and the line search parameter t:

$$\nabla f(x) = \begin{pmatrix} \frac{1}{2}x_1 \\ 2x_2 \end{pmatrix}$$

$$t := \underset{s \ge 0}{\operatorname{argmin}} f(x + s\Delta x)$$

$$\frac{df(x + s\Delta x)}{ds} = \frac{1}{2}(x_1 + s\Delta x_1)\Delta x_1 + 2(x_2 + s\Delta x_2)\Delta x_2$$

$$= s\left(\frac{\Delta x_1^2}{2} + 2\Delta x_2^2\right) + \frac{x_1}{2}\Delta x_1 + 2x_2\Delta x_2$$

$$t = \max\left\{-\frac{\frac{x_1}{2}\Delta x_1 + 2x_2\Delta x_2}{\frac{\Delta x_1^2}{2} + 2\Delta x_2^2}, 0\right\}$$

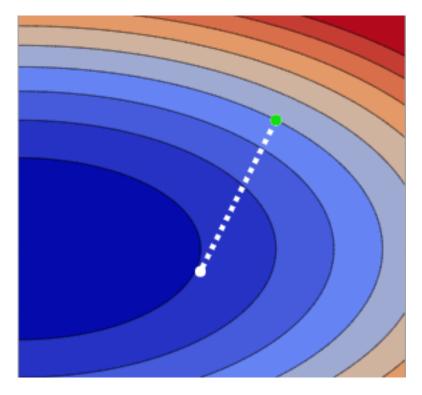


FIGURE 1 – First iteration of the gradient descent algorithm with exact line search for f(x)

This give us the plot 1 and following parameter for the first step:

$$\Delta x^{(0)} = -\nabla f(x^{(0)}) = \begin{pmatrix} -1 \\ -2 \end{pmatrix}$$
$$t^{(0)} = \max \left\{ -\frac{\frac{2}{2}(-1) + 2 \cdot 1(-2)}{\frac{(-1)^2}{2} + 2(-2)^2}, 0 \right\} = \frac{10}{17}$$

Therefore,

$$x^{(1)} := x^{(0)} + t^{(0)} \Delta x^{(0)} = \frac{3}{17} \begin{pmatrix} 8 \\ -1 \end{pmatrix}$$
$$\left| \left| \nabla f \left(x^{(0)} \right) \right| \right|^2 = \frac{1}{4} 2^2 + 4 \cdot 1^2 = 5$$
$$\left| \left| \nabla f \left(x^{(1)} \right) \right| \right|^2 = \frac{1}{4} \left(\frac{24}{17} \right)^2 + 4 \left(\frac{-3}{17} \right)^2 = \frac{180}{289} \approx 0.62$$