## Introduction to Deep Learning for Computer Vision

Adhyayan '23 - ACA Summer School Department of Computer Science and Engineering Indian Institute of Technology Kanpur

Lecture 6

## Unsupervised Learning: Learning without Labels!

• **Definition**: Learning from *unlabeled data*, where the goal is to *discover* patterns, structure, or representations without explicit labels or supervision.

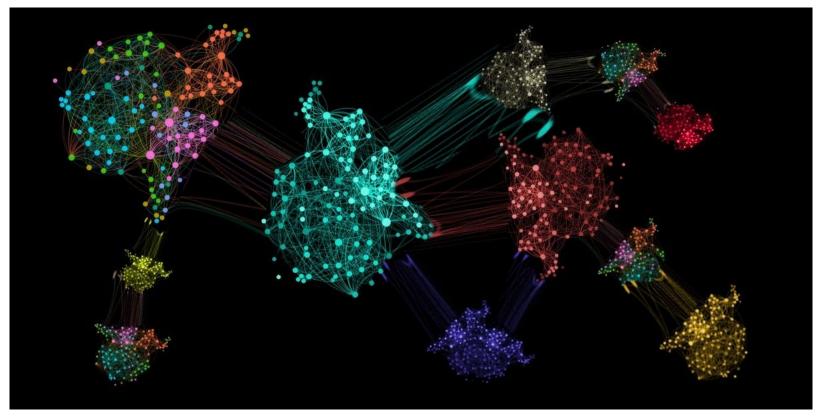
- **Definition**: Learning from *unlabeled data*, where the goal is to *discover* patterns, structure, or representations without explicit labels or supervision.
- Advantages:

- **Definition**: Learning from *unlabeled data*, where the goal is to *discover* patterns, structure, or representations without explicit labels or supervision.
- Advantages:
  - Utilizing Unlabeled Data

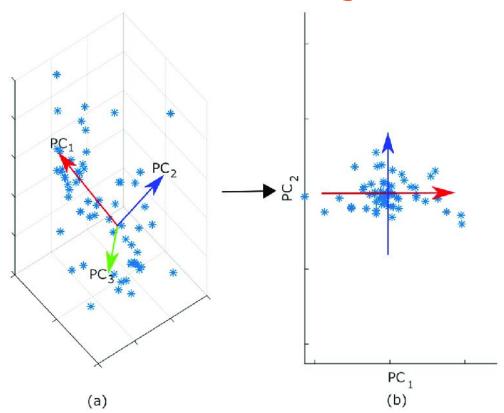
- **Definition**: Learning from *unlabeled data*, where the goal is to *discover* patterns, structure, or representations without explicit labels or supervision.
- Advantages:
  - Utilizing Unlabeled Data
  - Discovery of Hidden Patterns

- **Definition**: Learning from *unlabeled data*, where the goal is to *discover* patterns, structure, or representations without explicit labels or supervision.
- Advantages:
  - Utilizing Unlabeled Data
  - Discovery of Hidden Patterns
  - Handling Unlabeled or Scarce Labeled Data

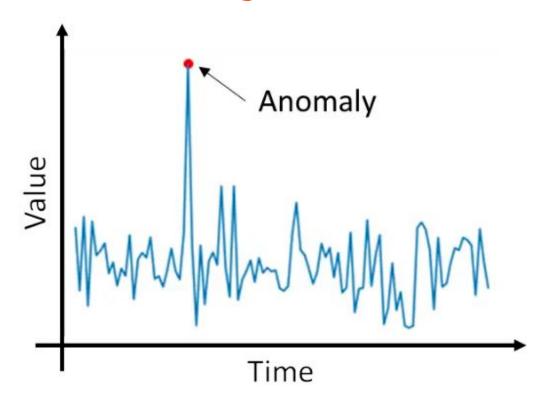
#### **Applications: Clustering**



#### **Applications: Dimensionality Reduction**



#### **Applications: Anomaly Detection**

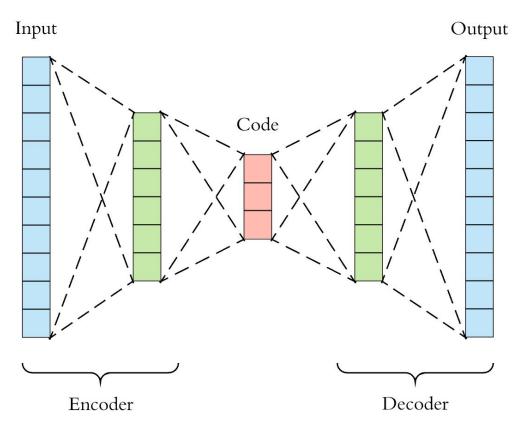


#### **Applications: Generative Modelling**

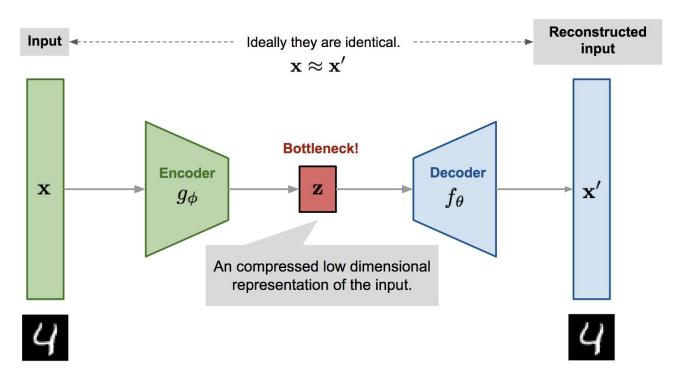


# Unsupervised Deep Learning!

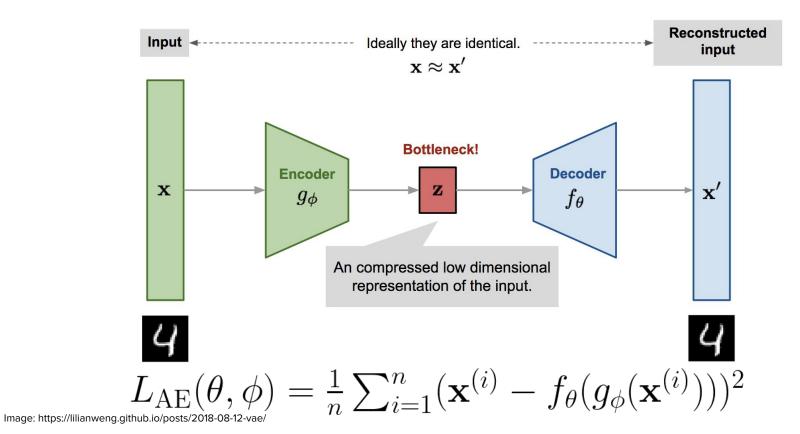
#### **Autoencoders**



#### **Autoencoders**



#### **Autoencoders**



#### **Denoising Autoencoder**

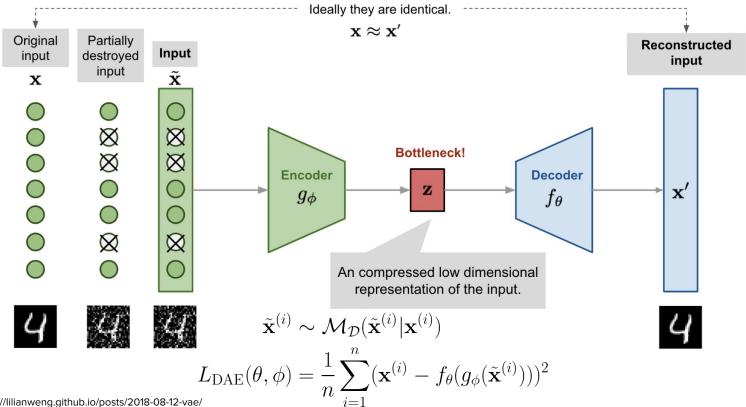


Image: https://lilianweng.github.io/posts/2018-08-12-vae/

• Latent Space: The latent space is a lower-dimensional representation that captures the underlying structure of the input data. It allows for continuous interpolation and exploration of the data distribution.

- Latent Space: The latent space is a lower-dimensional representation that captures the underlying structure of the input data. It allows for continuous interpolation and exploration of the data distribution.
- **Key Idea**: Instead of mapping the input into a *fixed vector*, we want to map it into a *distribution*.

- Latent Space: The latent space is a lower-dimensional representation that captures the underlying structure of the input data. It allows for continuous interpolation and exploration of the data distribution.
- **Key Idea**: Instead of mapping the input into a *fixed vector*, we want to map it into a *distribution*.
- Notations:
  - Data: x

- Latent Space: The latent space is a lower-dimensional representation that captures the underlying structure of the input data. It allows for continuous interpolation and exploration of the data distribution.
- **Key Idea**: Instead of mapping the input into a *fixed vector*, we want to map it into a *distribution*.
- Notations:
  - Data: x
  - Latent Space: z

- Latent Space: The latent space is a lower-dimensional representation that captures the underlying structure of the input data. It allows for continuous interpolation and exploration of the data distribution.
- **Key Idea**: Instead of mapping the input into a *fixed vector*, we want to map it into a *distribution*.

#### Notations:

- Data: x
- Latent Space: z
- Prior Distribution:  $p_{\theta}(\mathbf{z})$

- Latent Space: The latent space is a lower-dimensional representation that captures the underlying structure of the input data. It allows for continuous interpolation and exploration of the data distribution.
- Key Idea: Instead of mapping the input into a fixed vector, we want to map it into a distribution.

#### Notations:

- Data: x
- Latent Space: z
- o Prior Distribution:  $p_{\theta}(\mathbf{z})$
- Likelihood:  $p_{\theta}(\mathbf{x}|\mathbf{z})$

- Latent Space: The latent space is a lower-dimensional representation that captures the underlying structure of the input data. It allows for continuous interpolation and exploration of the data distribution.
- **Key Idea**: Instead of mapping the input into a *fixed vector*, we want to map it into a *distribution*.

#### • Notations:

- Data: x
- Latent Space: z
- Prior Distribution:  $p_{\theta}(\mathbf{z})$
- $\circ$  Likelihood:  $p_{\theta}(\mathbf{x}|\mathbf{z})$
- $\circ$  Posterior:  $p_{\theta}(\mathbf{z}|\mathbf{x})$

VAEs are Generative Models.

- VAEs are Generative Models.
- We should be able to sample new data from a VAE. How?

- VAEs are Generative Models.
- We should be able to sample new data from a VAE. How?
  - $\circ$  Sample $\mathbf{z}^{(i)}$ from the prior distribution  $p_{ heta^*}(\mathbf{z})$

- VAEs are Generative Models.
- We should be able to sample new data from a VAE. How?
  - $\circ$  Sample  $\mathbf{z}^{(i)}$  from the prior distribution  $p_{ heta^*}(\mathbf{z})$
  - $\circ \quad \mathbf{x}^{(i)}$  is generated from a conditional distribution  $p_{ heta^*}(\mathbf{x}|\mathbf{z}=\mathbf{z}^{(i)})$

- VAEs are Generative Models.
- We should be able to sample new data from a VAE. How?
  - $\circ$  Sample  $\mathbf{z}^{(i)}$  from the prior distribution  $p_{ heta^*}(\mathbf{z})$
  - $\circ$   $\mathbf{x}^{(i)}$  is generated from a conditional distribution  $p_{\theta^*}(\mathbf{x}|\mathbf{z}=\mathbf{z}^{(i)})$
- Optimal Parameter  $\theta^*$  is the one that maximizes the probability of generating real data samples:  $\theta^* = \arg \max_{\theta} \prod_{i=1}^n p_{\theta}(\mathbf{x}^{(i)})$

- VAEs are Generative Models.
- We should be able to sample new data from a VAE. How?
  - $\circ$  Sample  $\mathbf{z}^{(i)}$  from the prior distribution  $p_{ heta^*}(\mathbf{z})$
  - $\circ$   $\mathbf{x}^{(i)}$  is generated from a conditional distribution  $p_{\theta^*}(\mathbf{x}|\mathbf{z}=\mathbf{z}^{(i)})$
- Optimal Parameter  $\theta^*$  is the one that maximizes the probability of generating real data samples:  $\theta^* = \arg \max_{\theta} \prod_{i=1}^n p_{\theta}(\mathbf{x}^{(i)})$
- Commonly we use the log probabilities to convert the product on RHS to a sum:  $\theta^* = \arg \max_{\theta} \sum_{i=1}^n \log p_{\theta}(\mathbf{x}^{(i)})$

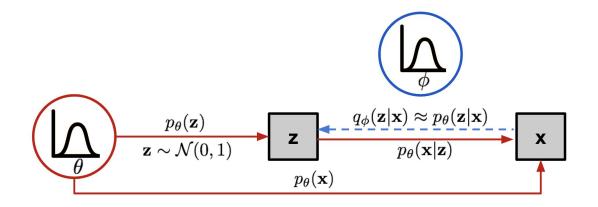
- VAEs are Generative Models.
- We should be able to sample new data from a VAE. How?
  - $\circ$  Sample  $\mathbf{z}^{(i)}$  from the prior distribution  $p_{ heta^*}(\mathbf{z})$
  - $\circ$   $\mathbf{x}^{(i)}$  is generated from a conditional distribution  $p_{\theta^*}(\mathbf{x}|\mathbf{z}=\mathbf{z}^{(i)})$
- Optimal Parameter  $\theta^*$  is the one that maximizes the probability of generating real data samples:  $\theta^* = \arg \max_{\theta} \prod_{i=1}^n p_{\theta}(\mathbf{x}^{(i)})$
- Commonly we use the log probabilities to convert the product on RHS to a sum:  $\theta^* = \arg \max_{\theta} \sum_{i=1}^n \log p_{\theta}(\mathbf{x}^{(i)})$
- Let's expand on the probability of generating real samples:

$$p_{\theta}(\mathbf{x}^{(i)}) = \int p_{\theta}(\mathbf{x}^{(i)}|\mathbf{z})p_{\theta}(\mathbf{z})d\mathbf{z}$$

- VAEs are Generative Models.
- We should be able to sample new data from a VAE. How?
  - $\circ$  Sample  $\mathbf{z}^{(i)}$  from the prior distribution  $p_{ heta^*}(\mathbf{z})$
  - $\circ$   $\mathbf{x}^{(i)}$  is generated from a conditional distribution  $p_{\theta^*}(\mathbf{x}|\mathbf{z}=\mathbf{z}^{(i)})$
- Optimal Parameter  $\theta^*$  is the one that maximizes the probability of generating real data samples:  $\theta^* = \arg \max_{\theta} \prod_{i=1}^n p_{\theta}(\mathbf{x}^{(i)})$
- Commonly we use the log probabilities to convert the product on RHS to a sum:  $\theta^* = \arg \max_{\theta} \sum_{i=1}^n \log p_{\theta}(\mathbf{x}^{(i)})$
- Let's expand on the probability of generating real samples:

$$p_{\theta}(\mathbf{x}^{(i)}) = \int p_{\theta}(\mathbf{x}^{(i)}|\mathbf{z})p_{\theta}(\mathbf{z})d\mathbf{z}$$

Not easy to compute. Need to approximate!



- Unfortunately it is not easy to compute  $p_{\theta}(\mathbf{x}^{(i)})$
- Better Idea: Introduce a new approximation function to output what is a likely code given an input,  $\mathbf{X}$   $q_{\phi}(\mathbf{z}|\mathbf{x})$ , parameterized by  $\phi$
- Now the structure resembles an Autoencoder:
  - $\circ p_{\theta}(\mathbf{x}|\mathbf{z})$  is similar to the decoder  $f_{\theta}(\mathbf{x}|\mathbf{z})$ . Also known as *probabilistic decoder*.
  - $\circ q_{\phi}(\mathbf{z}|\mathbf{x})$  is similar to the encoder  $g_{\phi}(\mathbf{z}|\mathbf{x})$ . Also known as *probabilistic encoder*.

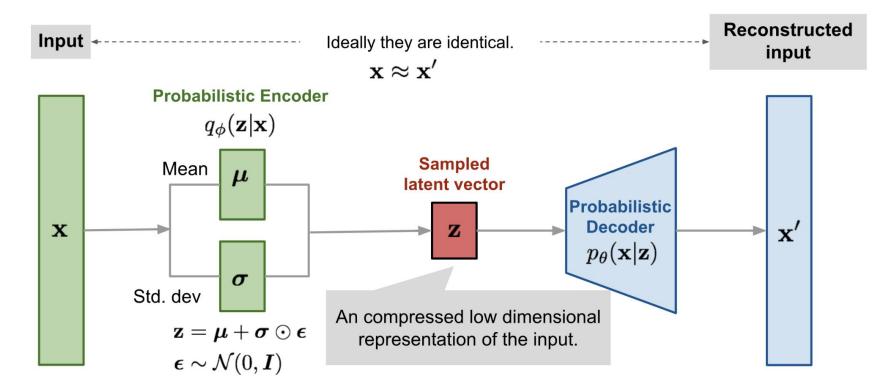


Image: https://lilianweng.github.io/posts/2018-08-12-vae/

• Target: Estimated Posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$  should be very close to the real one $p_{\theta}(\mathbf{z}|\mathbf{x})$ 

- ullet Target: Estimated Posterior $q_\phi(\mathbf{z}|\mathbf{x})$  should be very close to the real one  $p_ heta(\mathbf{z}|\mathbf{x})$
- How do we quantify closeness of distributions?

- ullet Target: Estimated Posterior $q_\phi(\mathbf{z}|\mathbf{x})$  should be very close to the real one  $p_ heta(\mathbf{z}|\mathbf{x})$
- How do we quantify closeness of distributions? Ans: KL Divergence!

$$D_{\mathrm{KL}}(P|Q) = \mathbb{E}_{z \sim P(z)} \log \frac{P(z)}{Q(z)}$$

- Target: Estimated Posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$  should be very close to the real one  $p_{\theta}(\mathbf{z}|\mathbf{x})$
- How do we quantify closeness of distributions? Ans: KL Divergence!

$$D_{\mathrm{KL}}(P|Q) = \mathbb{E}_{z \sim P(z)} \log \frac{P(z)}{Q(z)}$$

•  $D_{\mathrm{KL}}(X|Y)$  measures how much information is lost if the distribution Y is used to represent X.

- Target: Estimated Posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$  should be very close to the real one  $p_{\theta}(\mathbf{z}|\mathbf{x})$
- How do we quantify closeness of distributions? Ans: KL Divergence!

$$D_{\mathrm{KL}}(P|Q) = \mathbb{E}_{z \sim P(z)} \log \frac{P(z)}{Q(z)}$$

- $D_{\mathrm{KL}}(X|Y)$  measures how much information is lost if the distribution Y is used to represent X.
- We want to minimize  $D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})|p_{\theta}(\mathbf{z}|\mathbf{x}))$  with respect to  $\boldsymbol{\Phi}$ .

- Target: Estimated Posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$  should be very close to the real one  $p_{\theta}(\mathbf{z}|\mathbf{x})$
- How do we quantify closeness of distributions? Ans: KL Divergence!

$$D_{KL}(P||Q) = \int_z P(z) \log \frac{P(z)}{Q(z)} dz$$

- $D_{\mathrm{KL}}(X|Y)$  measures how much information is lost if the distribution Y is used to represent X.
- We want to minimize  $D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})|p_{\theta}(\mathbf{z}|\mathbf{x}))$  with respect to  $\boldsymbol{\Phi}$ .
- Why use  $D_{\rm KL}(q_\phi|p_\theta)$  (reverse KL) instead of  $D_{\rm KL}(p_\theta|q_\phi)$  (forward KL)? Ans: <a href="https://blog.evjang.com/2016/08/variational-bayes.html">https://blog.evjang.com/2016/08/variational-bayes.html</a>

#### **Loss Function: ELBO**

$$L_{\text{VAE}}(\theta, \phi) = -\mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} \log p_{\theta}(\mathbf{x}|\mathbf{z}) + D_{\text{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x}) || p_{\theta}(\mathbf{z}))$$

$$\theta^*, \phi^* = \arg \min_{\theta, \phi} L_{\text{VAE}}$$
Reconstruction Loss Regularization

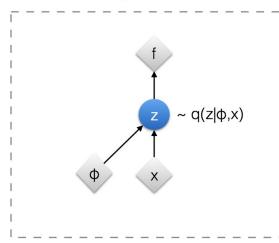
#### **Reparameterization Trick**

- The expectation term in the loss function invokes generating samples from  $\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})$
- Sampling is a stochastic process. Backpropagation is not possible.
- To make it trainable, the reparameterization trick is introduced:
  - o It is often possible to express the random variable z as a deterministic variable  $\mathbf{z} = \mathcal{T}_{\phi}(\mathbf{x}, \boldsymbol{\epsilon})$  where is an auxiliary independent random variable, and the transformation function  $\mathcal{T}_{\phi}$  parameterized by  $\boldsymbol{\Phi}$  converts  $\boldsymbol{\epsilon}$  to  $\mathbf{z}$ .

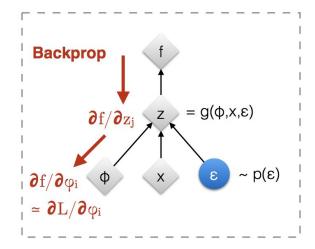
$$\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x}^{(i)}) = \mathcal{N}(\mathbf{z}; \boldsymbol{\mu}^{(i)}, \boldsymbol{\sigma}^{2(i)}\boldsymbol{I})$$
  
 $\mathbf{z} = \boldsymbol{\mu} + \boldsymbol{\sigma} \odot \boldsymbol{\epsilon}$ , where  $\boldsymbol{\epsilon} \sim \mathcal{N}(0, \boldsymbol{I})$ ; Reparameterization trick.

#### **Reparameterization Trick**

#### Original form



#### Reparameterised form



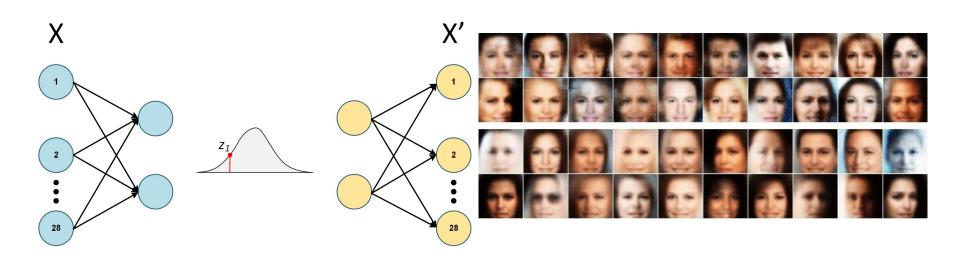
: Deterministic node



: Random node

[Kingma, 2013] [Bengio, 2013] [Kingma and Welling 2014] [Rezende et al 2014]

#### **Sample Generation using VAE**



#### $\beta$ -VAE : Regularizing the Regularizer!

$$L_{\text{BETA}}(\phi, \beta) = -\mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} \log p_{\theta}(\mathbf{x}|\mathbf{z}) + \beta D_{\text{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}))$$

# Next Lecture: GANs, Diffusion Models!

#### **Expanding the KL Divergence**

$$D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}|\mathbf{x}))$$

$$= \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log \frac{q_{\phi}(\mathbf{z}|\mathbf{x})}{p_{\theta}(\mathbf{z}|\mathbf{x})} d\mathbf{z}$$

$$= \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log \frac{q_{\phi}(\mathbf{z}|\mathbf{x})p_{\theta}(\mathbf{x})}{p_{\theta}(\mathbf{z},\mathbf{x})} d\mathbf{z} \qquad ; \text{Because } p(z|x) = p(z,x)/p(x)$$

$$= \int q_{\phi}(\mathbf{z}|\mathbf{x}) \left( \log p_{\theta}(\mathbf{x}) + \log \frac{q_{\phi}(\mathbf{z}|\mathbf{x})}{p_{\theta}(\mathbf{z},\mathbf{x})} \right) d\mathbf{z}$$

$$= \log p_{\theta}(\mathbf{x}) + \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log \frac{q_{\phi}(\mathbf{z}|\mathbf{x})}{p_{\theta}(\mathbf{z},\mathbf{x})} d\mathbf{z} \qquad ; \text{Because } f(z|x) dz = 1$$

$$= \log p_{\theta}(\mathbf{x}) + \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log \frac{q_{\phi}(\mathbf{z}|\mathbf{x})}{p_{\theta}(\mathbf{x}|\mathbf{z})p_{\theta}(\mathbf{z})} d\mathbf{z} \qquad ; \text{Because } p(z,x) = p(x|z)p(z)$$

$$= \log p_{\theta}(\mathbf{x}) + \mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} [\log \frac{q_{\phi}(\mathbf{z}|\mathbf{x})}{p_{\theta}(\mathbf{z})} - \log p_{\theta}(\mathbf{x}|\mathbf{z})]$$

$$= \log p_{\theta}(\mathbf{x}) + D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z})) - \mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} \log p_{\theta}(\mathbf{x}|\mathbf{z})$$

#### **Deriving the Evidence Lower Bound**

$$D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}|\mathbf{x})) = \log p_{\theta}(\mathbf{x}) + D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z})) - \mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} \log p_{\theta}(\mathbf{x}|\mathbf{z})$$

$$\log p_{\theta}(\mathbf{x}) - D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}|\mathbf{x})) = \mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} \log p_{\theta}(\mathbf{x}|\mathbf{z}) - D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}))$$

$$L_{\mathrm{VAE}}(\theta, \phi) = -\log p_{\theta}(\mathbf{x}) + D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}|\mathbf{x}))$$

$$= -\mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} \log p_{\theta}(\mathbf{x}|\mathbf{z}) + D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}))$$

$$\theta^*, \phi^* = \arg \min_{\theta, \phi} L_{\mathrm{VAE}}$$

$$-L_{\mathrm{VAE}} = \log p_{\theta}(\mathbf{x}) - D_{\mathrm{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z}|\mathbf{x})) \leq \log p_{\theta}(\mathbf{x})$$