

Knowledge Extraction with No Observable Data

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Summary

KEGNET (Knowledge Extraction with Generative Networks)

- **Input:** a trained neural network M without data
- **Output:** a generator G that estimates unknown p_x
- **Main idea:** G is trained as a function $(y, z) \rightarrow x$
- **GitHub:** <https://github.com/snudatalab/KegNet>

Knowledge Extraction

Research motivation

- *A trained network is given, but no data available*
- *How can we distill the knowledge without data?*
- It is intractable to estimate directly $p_x(x)$
- Estimate $p(x|y, z)$ given random variables y and z
 - y is a probability vector representing a label
 - z is a low-dimensional embedding vector of data

Objective function

- Generate artificial data examples:

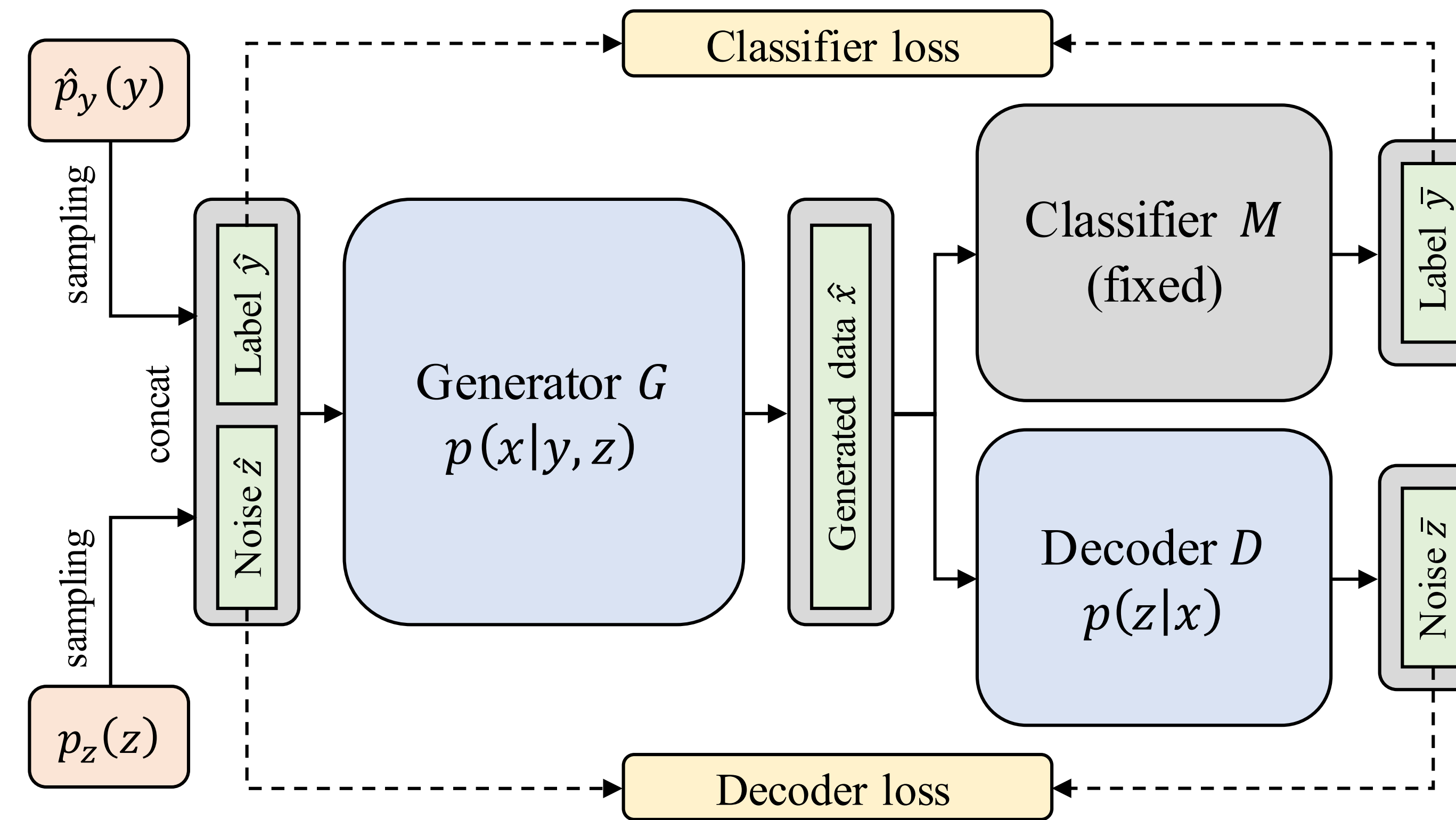
$$\mathcal{D} = \left\{ \underset{\hat{x}}{\operatorname{argmax}} p(\hat{x}|\hat{y}, \hat{z}) \mid \hat{y} \sim \hat{p}_y(y) \text{ and } \hat{z} \sim p_z(z) \right\}$$

- The argmax function is approximated as follows:

$$\underset{\hat{x}}{\operatorname{argmax}} p(\hat{x}|\hat{y}, \hat{z}) \approx \underset{\hat{x}}{\operatorname{argmax}} (\log p(\hat{y}|\hat{x}) + \log p(\hat{z}|\hat{x}))$$

- Thus, we have two **reconstruction terms** for \hat{y} and \hat{z}

Proposed Architecture



Classifier M

- Given and fixed; our only evidence for estimation
- *LeNet4* or *ResNet14* in our experiments

Generator G

- Estimate $p(x|y, z)$ by a generator network
- Its structure is based on *ACGAN* in our experiments
- **Classifier loss** makes $M(G(\hat{y}))$ similar to \hat{y}

Decoder D

- Estimate $p(z|x)$ to find the meaning of \hat{x}
- Increase the variance of various \hat{x} given the same \hat{y}
- **Decoder loss** makes $D(G(\hat{y}))$ similar to \hat{z}

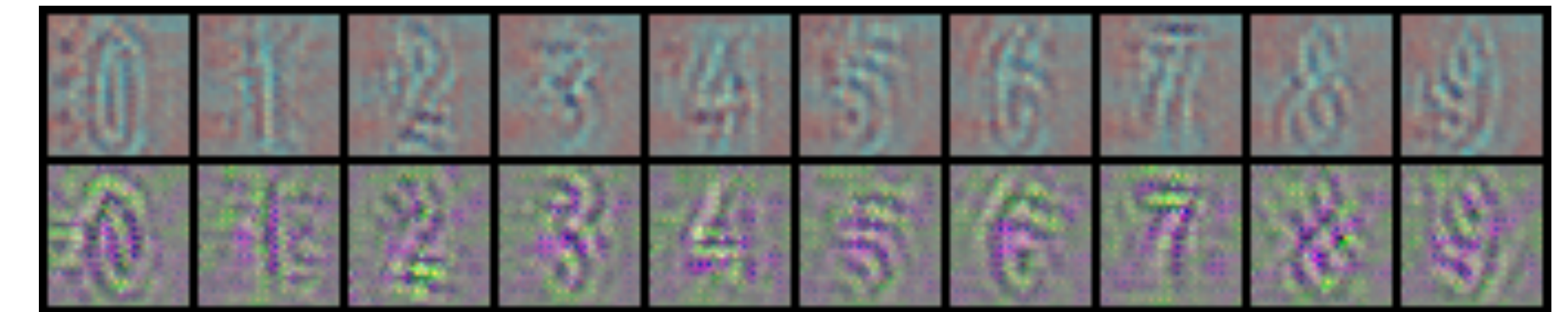
Experiments

Data-free model compression

- **Models:** *LeNet5* and *ResNet14*
- **Datasets:** *MNIST*, *SVHN*, and *Fashion MNIST*
- **Competitors**
 - **Tucker (T):** Tucker decomposition without fine-tuning
 - **T+Uniform:** Estimate p_x as the uniform dist. $\mathcal{U}(-1, 1)$
 - **T+Gaussian:** Estimate p_x as the normal dist. $\mathcal{N}(0, 1)$

Dataset	Model	Approach	Student 1	Student 2
SVHN	ResNet14	Original	93.23%	93.23%
SVHN	ResNet14	Tucker (T)	19.31% (1.44 \times)	11.02% (1.65 \times)
SVHN	ResNet14	T+Uniform	33.08 \pm 1.47%	63.08 \pm 1.77%
SVHN	ResNet14	T+Gaussian	26.58 \pm 1.61%	60.22 \pm 4.17%
SVHN	ResNet14	T+KEGNET	69.89 \pm 1.24%	87.26 \pm 0.46%

Generated images for SVHN from two generators



Latent space walking from label 0 to label 5 in SVHN

