

# **Chapter 3-Webster**

## **Amplifiers and Signal Processing**

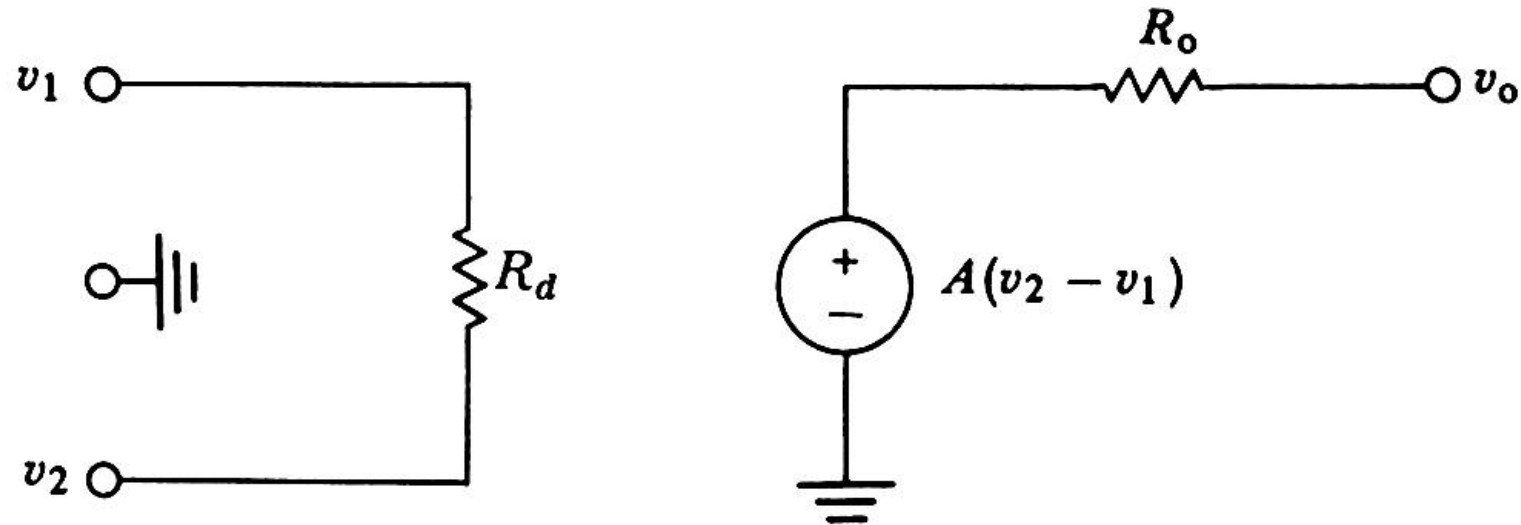
# Applications of Operational Amplifier In Biological Signals and Systems

The three major operations done on biological signals using Op-Amp:

- 1) Amplifications and Attenuations
- 2) DC offsetting: add or subtract a DC
- 3) Filtering: Shape signal's frequency content

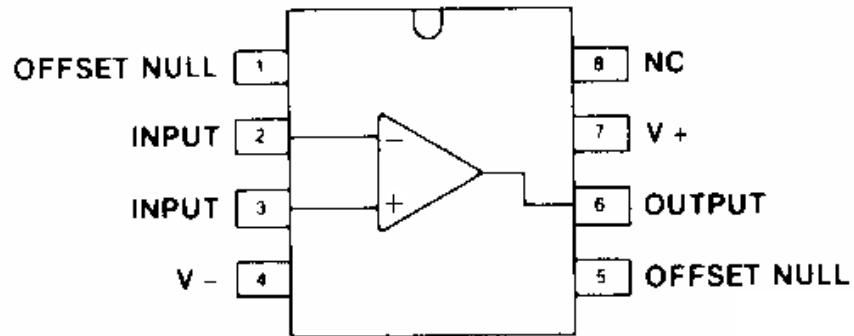
# Ideal Op-Amp

Most bioelectric signals are small and require amplifications



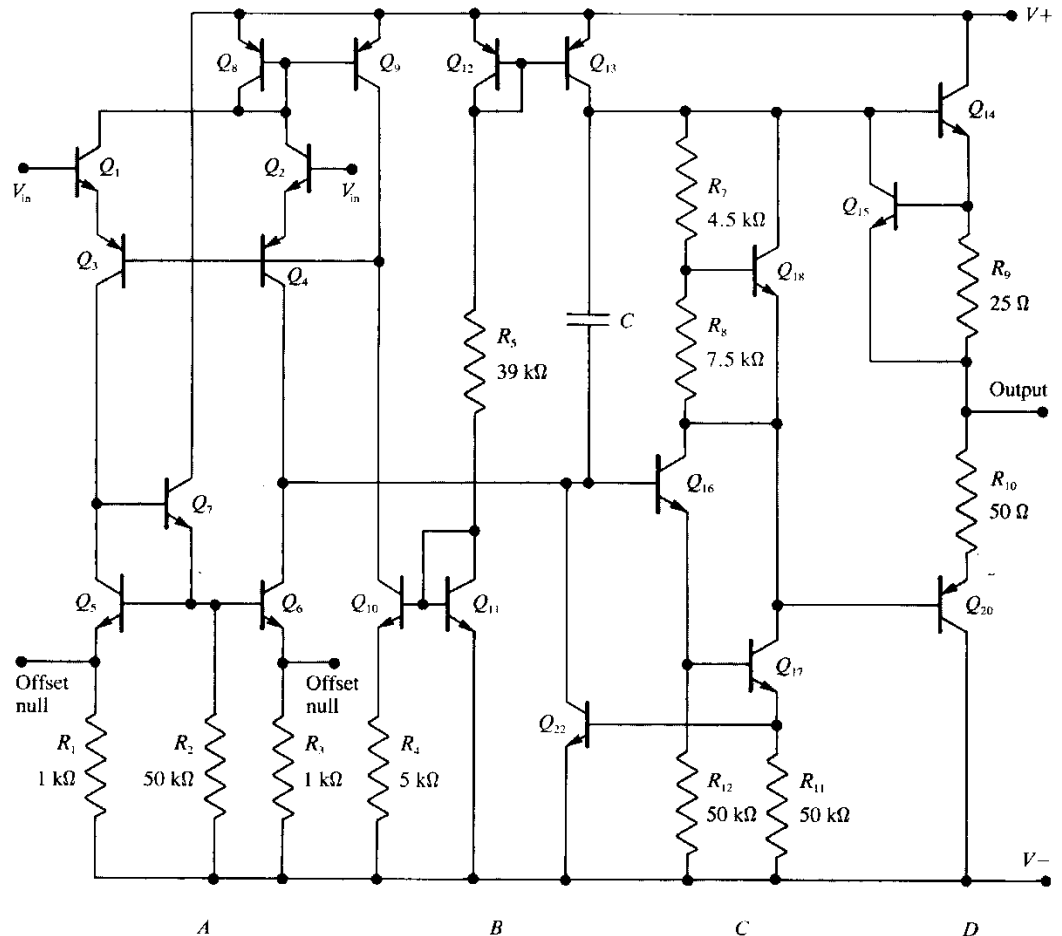
**Figure 3.1 Op-amp equivalent circuit.**  
The two inputs are  $v_1$  and  $v_2$ . A differential voltage between them causes current flow through the differential resistance  $R_d$ . The differential voltage is multiplied by  $A$ , the gain of the op amp, to generate the output-voltage source. Any current flowing to the output terminal  $v_o$  must pass through the output resistance  $R_o$ .

# Inside the Op-Amp (IC-chip)

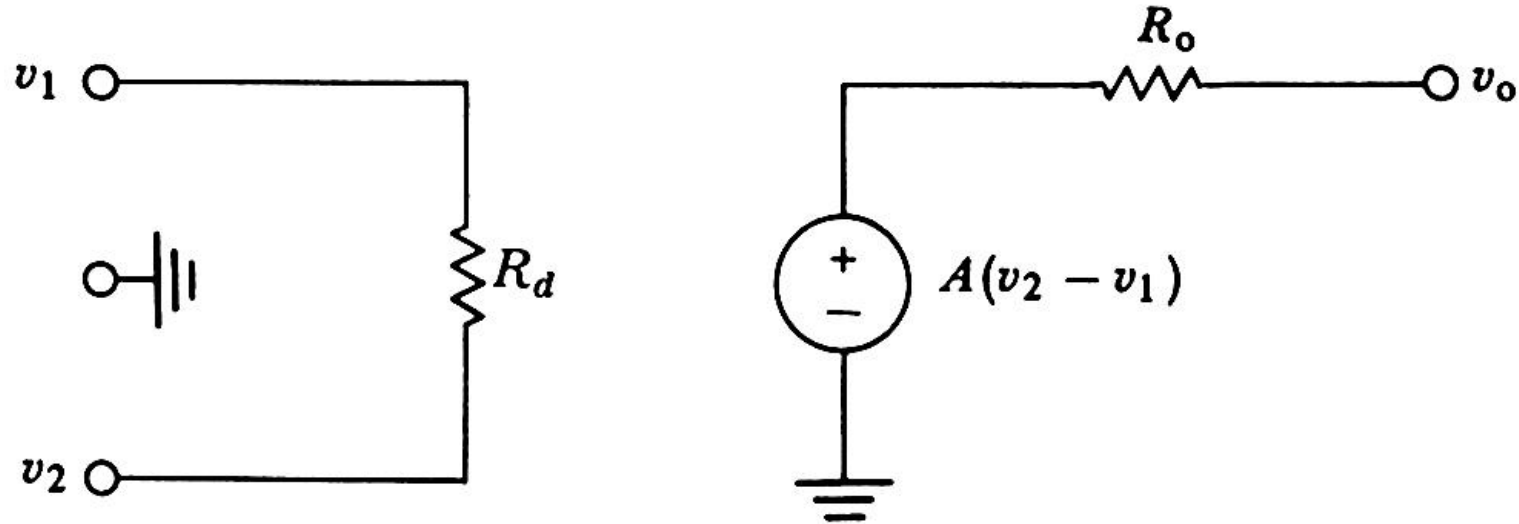


**741 op amp**

20 transistors  
11 resistors  
1 capacitor

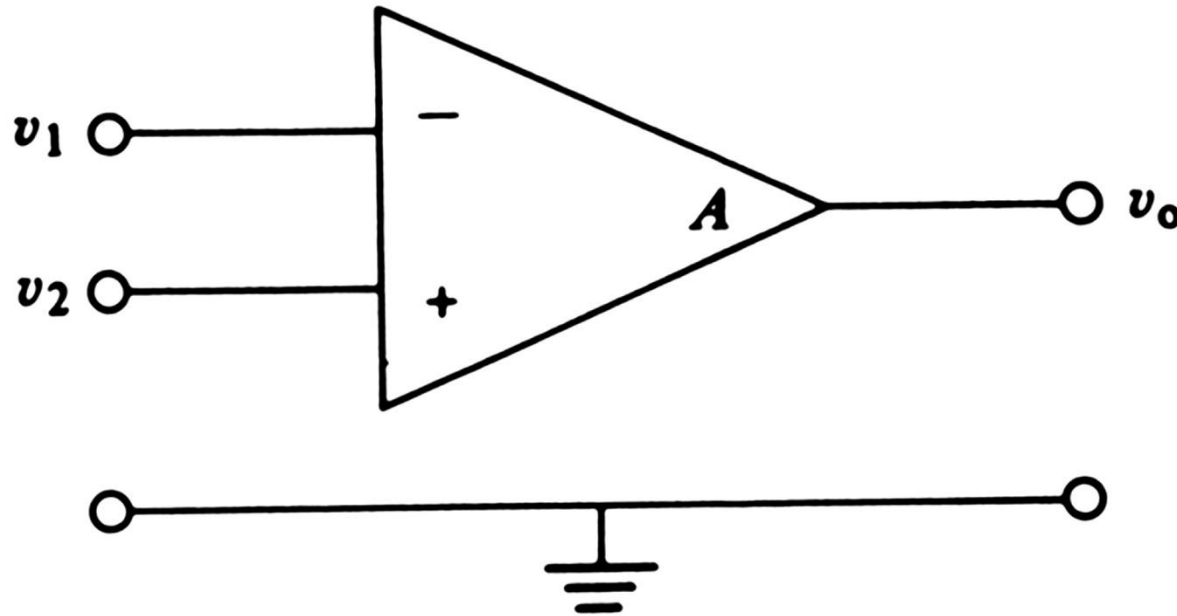


# Ideal Characteristics



- 1-  $A = \infty$  (gain is infinity)
- 2-  $V_o = 0$ , when  $v_1 = v_2$  (no offset voltage)
- 3-  $R_d = \infty$  (input impedance is infinity)
- 4-  $R_o = 0$  (output impedance is zero)
- 5- Bandwidth  $= \infty$  (no frequency response limitations) and no phase shift

# Two Basic Rules



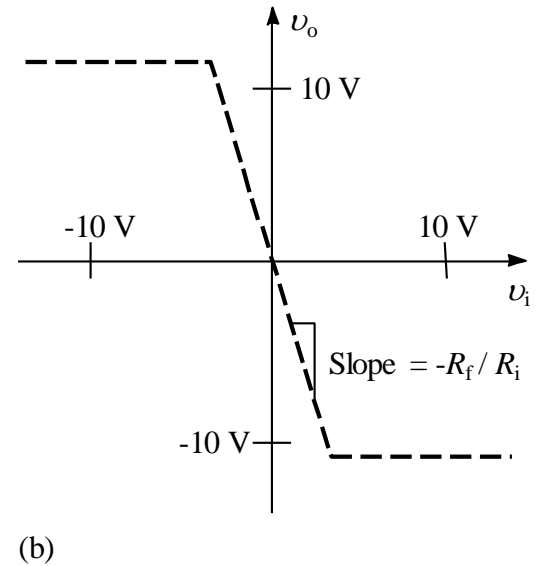
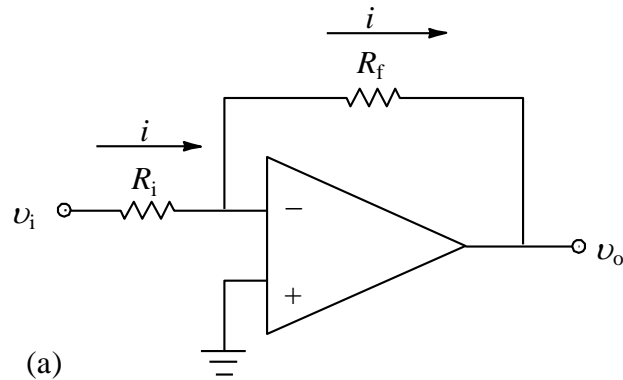
## Rule 1

When the op-amp output is in its linear range, the two input terminals are at the same voltage.

## Rule 2

No current flows into or out of either input terminal of the op amp.

# Inverting Amplifier



$$v_o = -\frac{R_f}{R_i} v_i$$

$$G = \frac{v_o}{v_i} = -\frac{R_f}{R_i}$$

Figure 3.3 (a) An inverting amplifier. Current flowing through the input resistor  $R_i$  also flows through the feedback resistor  $R_f$ . (b) The input-output plot shows a slope of  $-R_f / R_i$  in the central portion, but the output saturates at about  $\pm 13$  V.

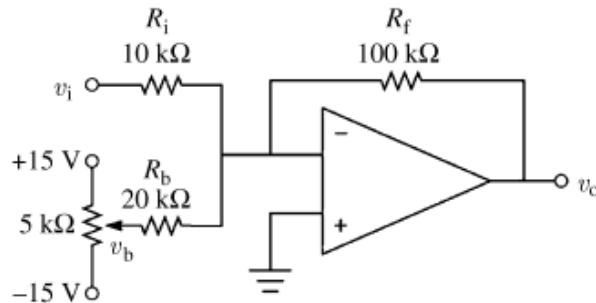
## Example 3.1

The output of a biopotential preamplifier that measures the electro-oculogram is an undesired dc voltage of  $\pm 5$  V due to electrode half-cell potentials, with a desired signal of  $\pm 1$  V superimposed. Design a circuit that will balance the dc voltage to zero and provide a gain of -10 for the desired signal without saturating the op amp.

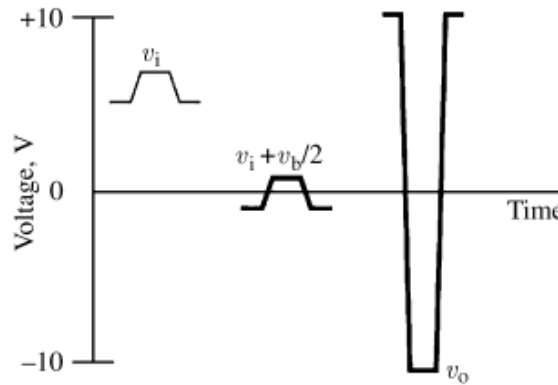


# Answer 3.1

(a) shows the design. We assume that the balancing voltage ( $v_b$ ), available from the 5 k $\Omega$  potentiometer is,  $\pm 10$  V. The undesired voltage at  $v_i = 5$  V. For  $v_o = 0$ , the current through  $R_f$  is zero. Therefore the sum of the currents through  $R_i$  and  $R_b$ , is zero.



(a)



(b)

Figure E3.1 (a) This circuit sums the input voltage  $v_i$  plus one-half of the balancing voltage  $v_b$ . Thus the output voltage  $v_o$  can be set to zero even when  $v_i$  has a nonzero dc component, (b) The three waveforms show  $v_i$ , the input voltage;  $(v_i + v_b / 2)$ , the balanced-out voltage; and  $v_o$ , the amplified output voltage. **If  $v_i$  were directly amplified, the op amp would saturate.**

$$\frac{v_i}{R_i} + \frac{v_b}{R_b} = 0$$

$$R_b = \frac{-R_i v_b}{v_i} = \frac{-10^4(-10)}{5} = 2 \times 10^4 \Omega$$

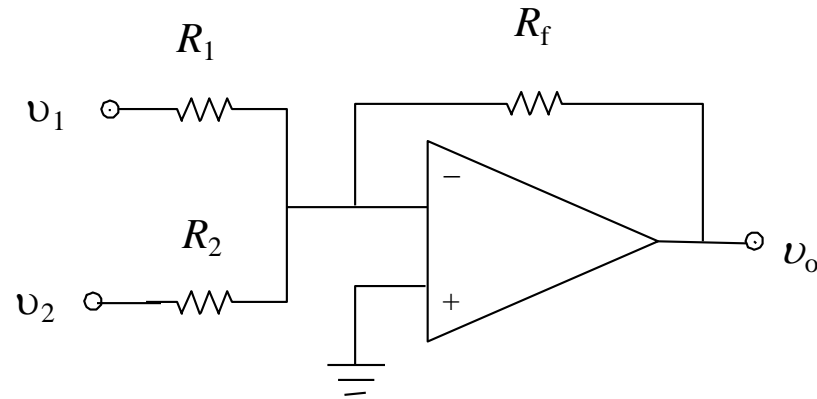
For a gain of -10,  $R_f / R_i = 10$ ; or  $R_f = 100$  k $\Omega$ . The circuit equation is

$$v_o = -R_f \left( \frac{v_i}{R_i} + \frac{v_b}{R_b} \right)$$

$$v_o = -10^5 \left( \frac{v_i}{10^4} + \frac{v_b}{2 \times 10^4} \right)$$

$$v_o = -10 \left( v_i + \frac{v_b}{2} \right)$$

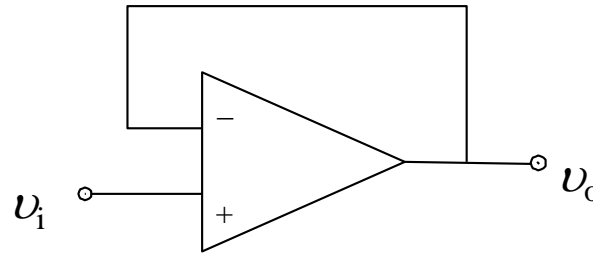
# Summing Amplifier



$$v_o = -R_f \left( \frac{v_1}{R_1} + \frac{v_2}{R_2} \right)$$

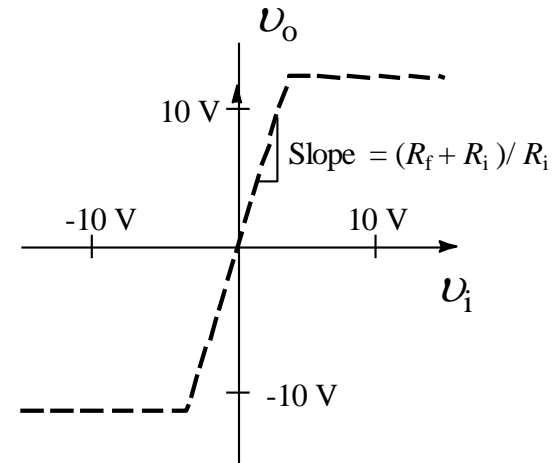
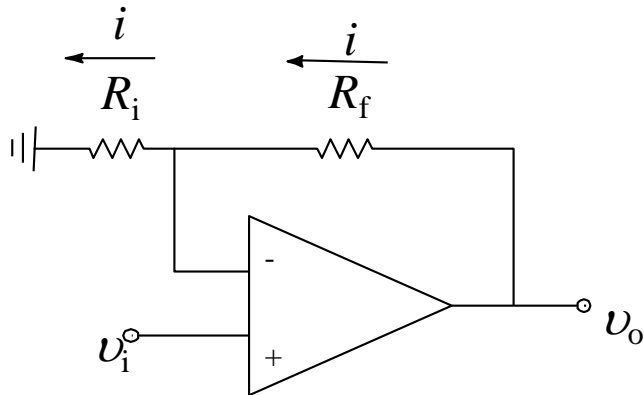
# Follower ( buffer)

Used as a buffer, to prevent a high source resistance from being loaded down by a low-resistance load. In another word it prevents drawing current from the source.



$$v_o = v_i \qquad G = 1$$

# Noninverting Amplifier



$$v_o = \frac{R_f + R_i}{R_i} v_i$$

$$G = \frac{R_f + R_i}{R_i} = \left( 1 + \frac{R_f}{R_i} \right)$$

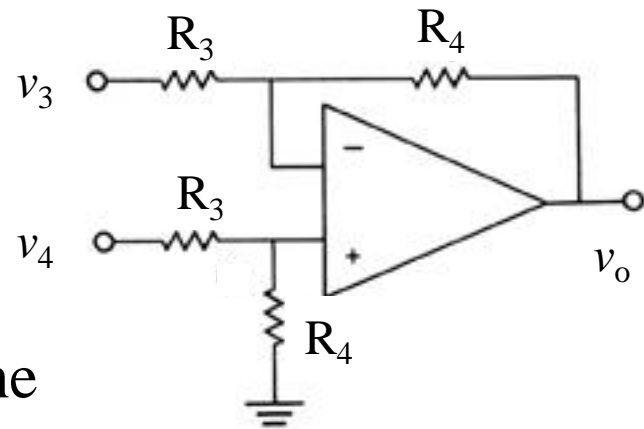
# Differential Amplifiers

## Differential Gain $G_d$

$$G_d = \frac{v_o}{v_4 - v_3} = \frac{R_4}{R_3}$$

## Common Mode Gain $G_c$

For ideal op amp if the inputs are equal then the output = 0, and the  $G_c = 0$ . No differential amplifier perfectly rejects the common-mode voltage.



$$v_o = \frac{R_4}{R_3} (v_4 - v_3)$$

## Common-mode rejection ratio $CMRR$

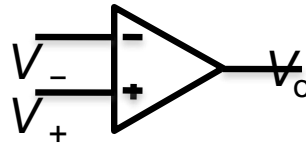
$$CMRR = \frac{G_d}{G_c}$$

Typical values range from 100 to 10,000

Disadvantage of one-op-amp differential amplifier is its low input resistance

## ➤ Common-mode rejection ratio

- The **common-mode rejection ratio** (CMRR) of a differential amplifier (or other device) measures the tendency of the device to reject input signals common to both input leads.
- Ideally, a differential amplifier takes the voltages  $V_+$  and  $V_-$  on its two inputs and produces an output voltage  $V_o = A_d(V_+ - V_-)$ , where  $A_d$  is the differential gain.



- However, the output of a real differential amplifier is better described as

$$V_o = A_d(V_+ - V_-) + \frac{1}{2}A_s(V_+ + V_-),$$

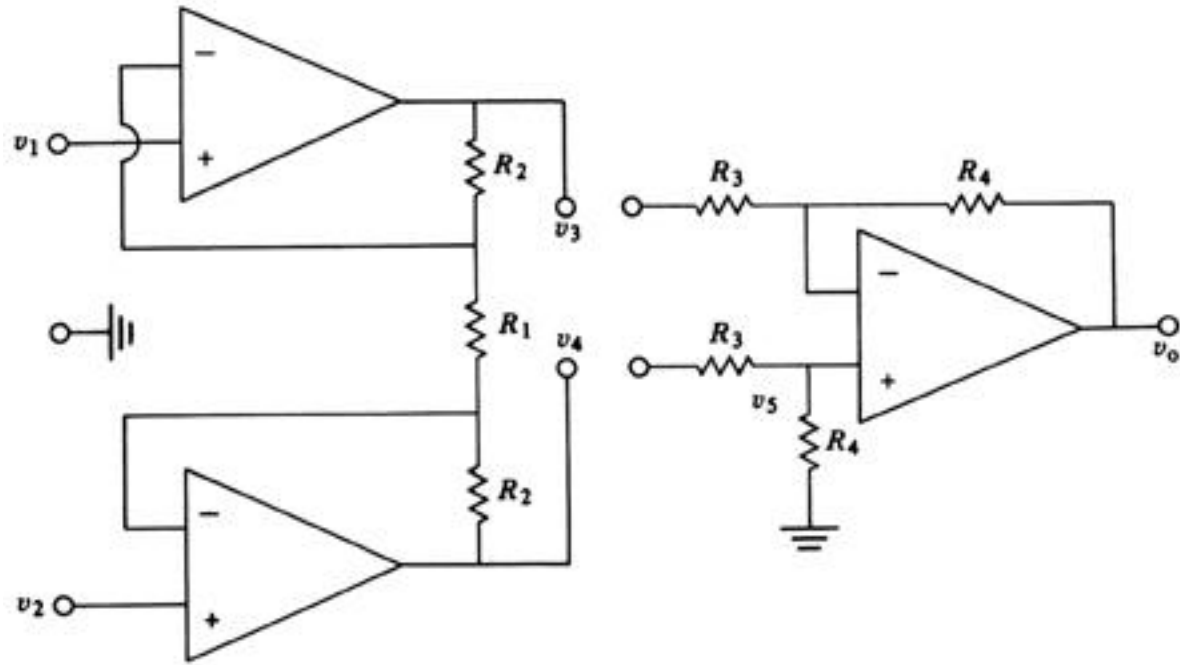
where  $A_s$  is the common-mode gain, which is typically much smaller than the differential gain.

- The CMRR is defined as the ratio of the powers of the differential gain over the common-mode gain, measured in positive decibels (thus using the 20 log rule):

$$\text{CMRR} = 10 \log_{10} \left( \frac{A_d}{A_s} \right)^2 = 20 \log_{10} \left( \frac{A_d}{|A_s|} \right)$$

- The **CMRR of the measurement instrument determines the attenuation applied to the offset or noise.**

# Instrumentation Amplifiers



Differential Mode Gain

$$v_3 - v_4 = i(R_2 + R_1 + R_2)$$

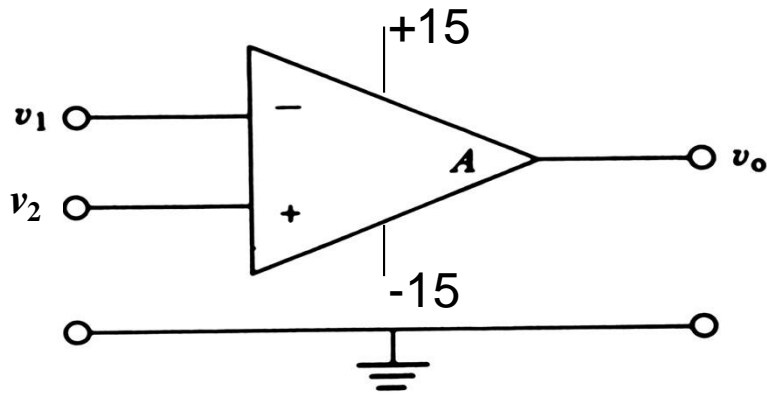
$$v_1 - v_2 = iR_1$$

$$G_d = \frac{v_3 - v_4}{v_1 - v_2} = \frac{2R_2 + R_1}{R_1}$$

$$v_o = \left( \frac{2R_2 + R_1}{R_1} \right) \frac{R_4}{R_3} (v_2 - v_1)$$

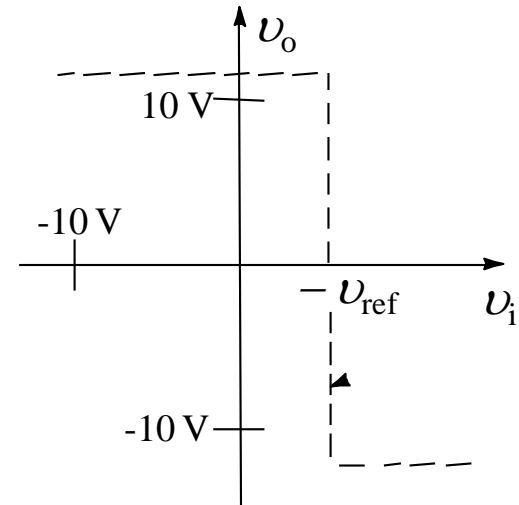
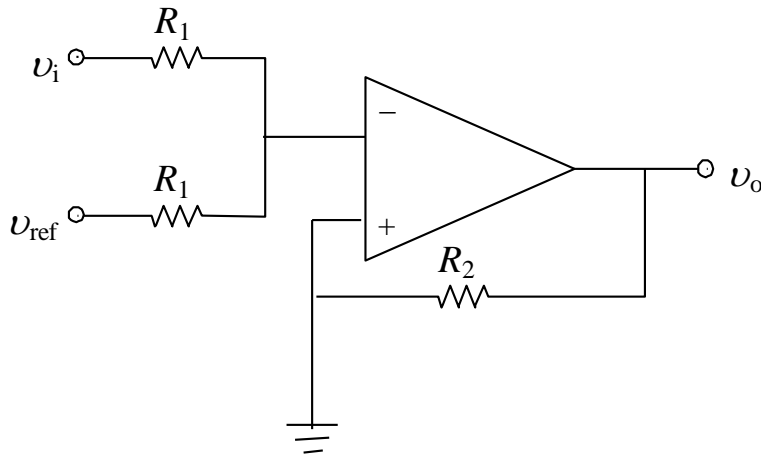
Advantages: High input impedance, a high CMRR, Variable gain

# Comparator – No Hysteresis



$$v_1 > v_2, v_o = -13 \text{ V}$$

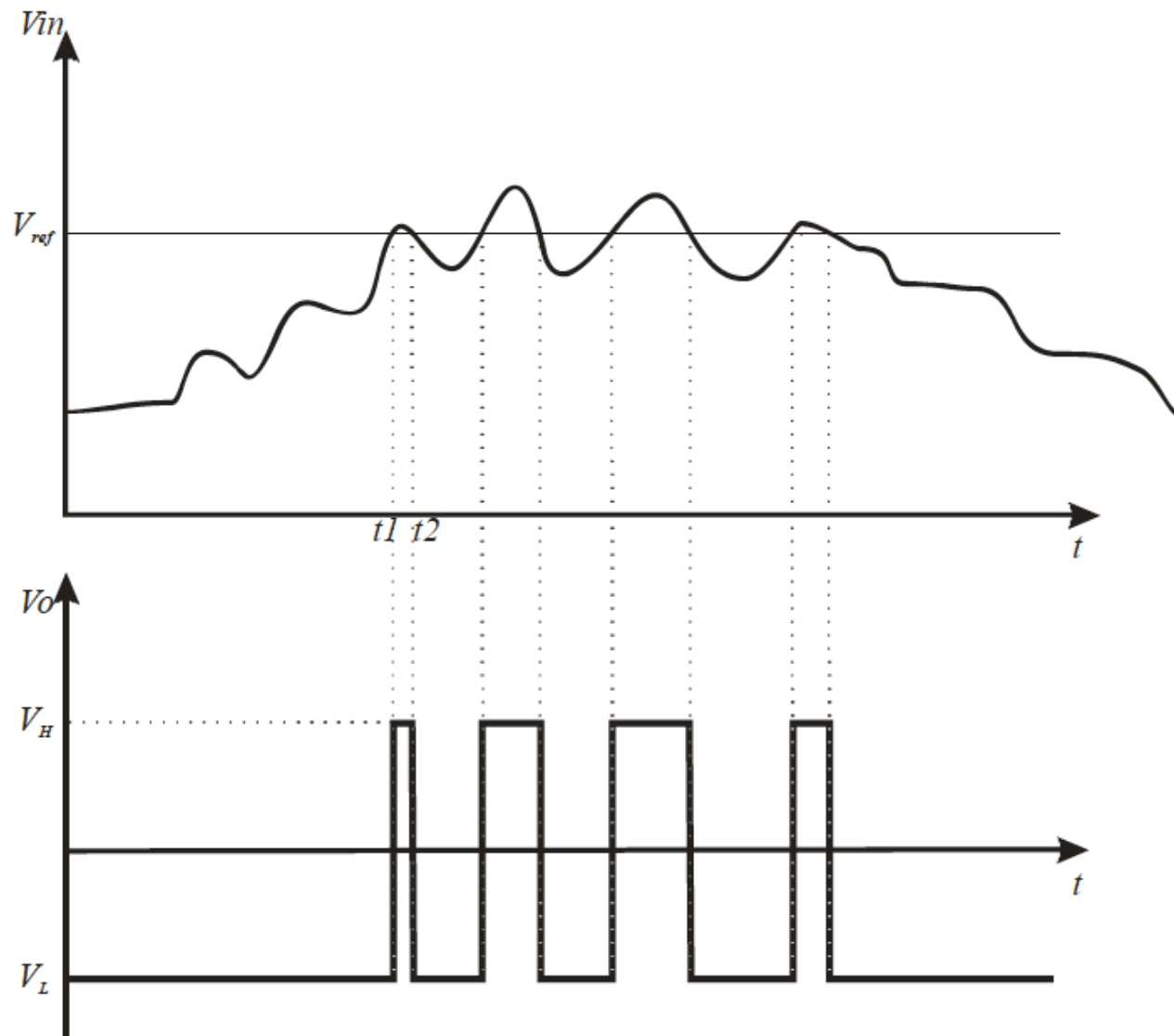
$$v_1 < v_2, v_o = +13 \text{ V}$$



If  $(v_i + v_{\text{ref}}) > 0$  then  $v_o = -13 \text{ V}$       else       $v_o = +13 \text{ V}$

$R_1$  will prevent overdriving the op-amp

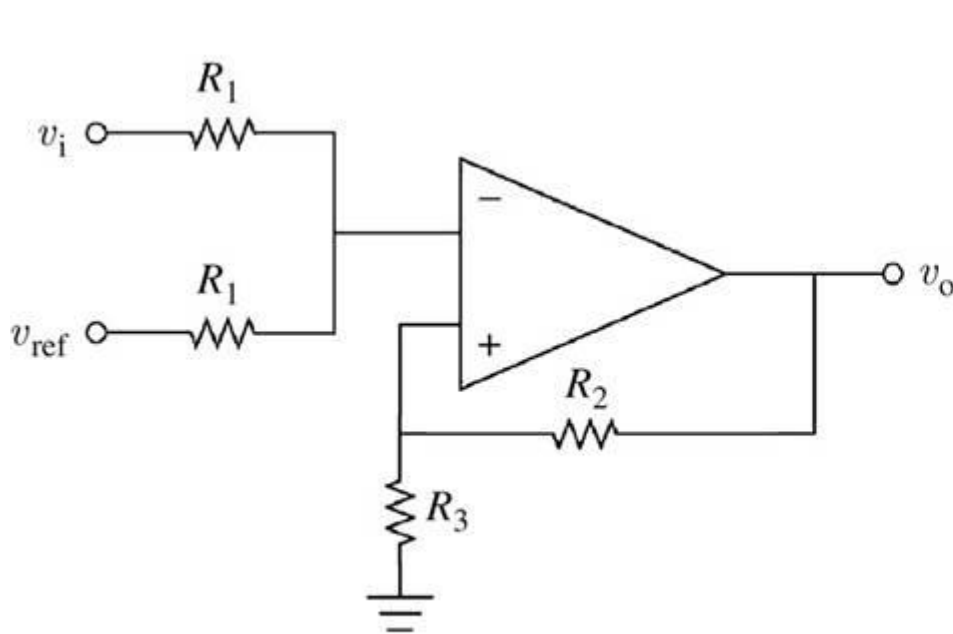




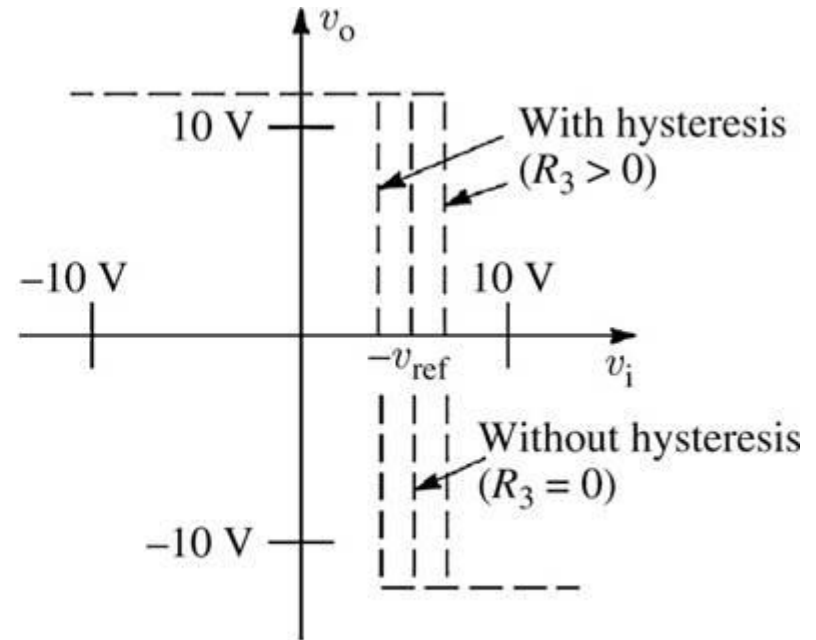
Note that as  $V_{in}$  exceeds  $V_{ref}$ , the voltage at the output of the comparator switches from  $V_L$  to  $V_H$ . Notice that sometime after  $t_1$  the voltage  $V_{in}$  begins to decrease and at time  $t_2$  it crosses  $V_{ref}$ . Now the output of the comparator switches back to  $V_L$ . This fluctuation in  $V_{in}$  might be noise in the signal.

# Comparator – With Hysteresis

Reduces multiple transitions due to mV noise levels by moving the threshold value after each transition.

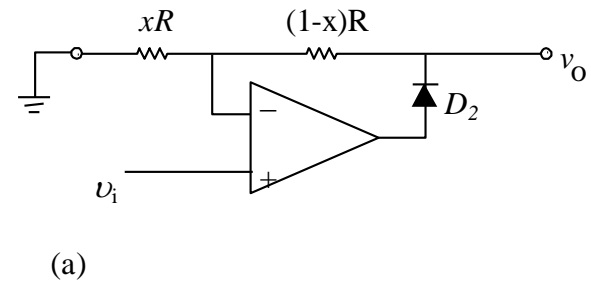
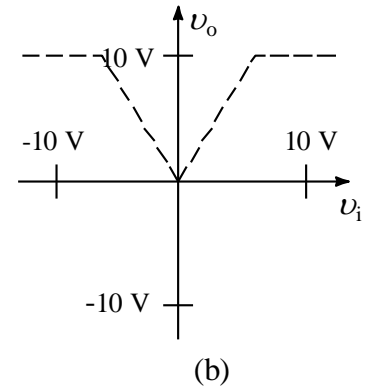
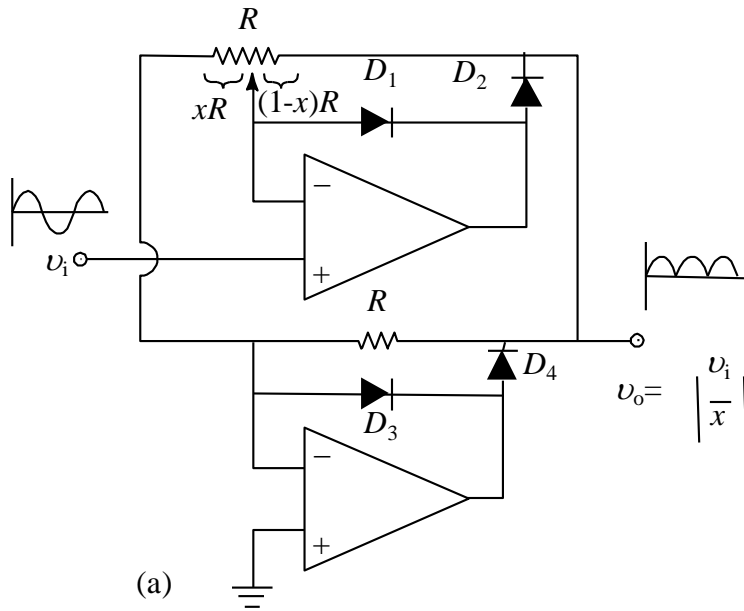


(a)



(b)

# Rectifier



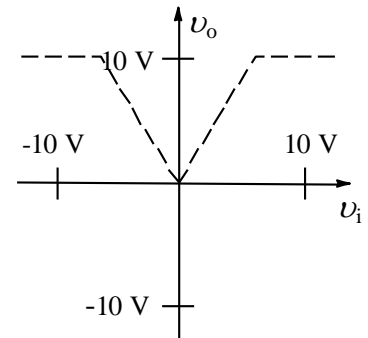
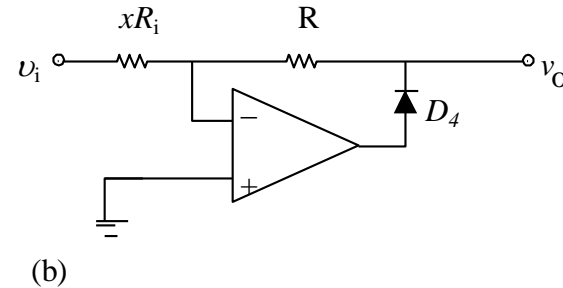
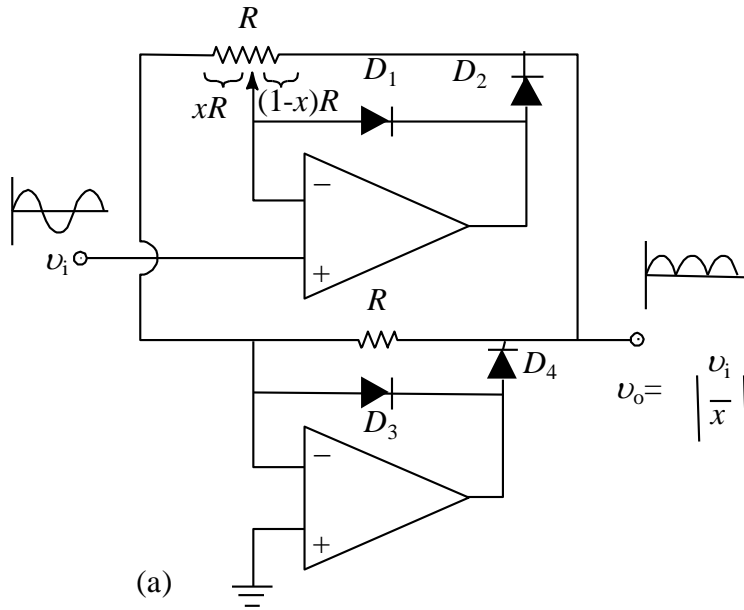
## Full-wave precision rectifier:

a) For  $v_i > 0$ ,

$D_2$  and  $D_3$  conduct, whereas  $D_1$  and  $D_4$  are reverse-biased.

Noninverting amplifier at the top is active

# Rectifier



(b)

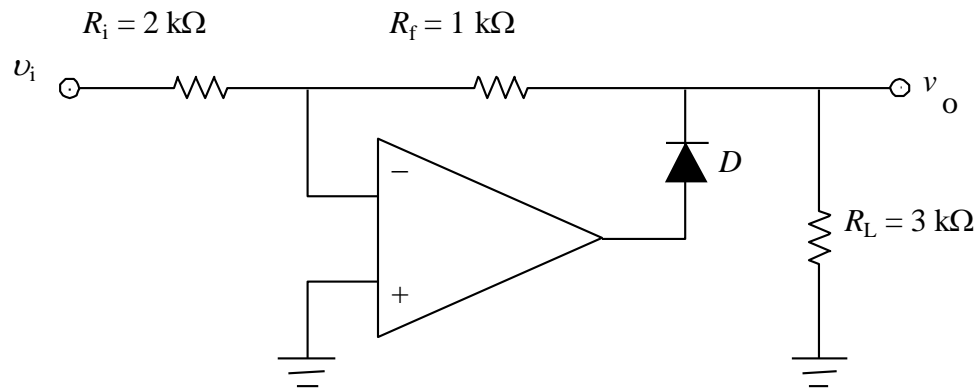
## Full-wave precision rectifier:

b) For  $v_i < 0$ ,

$D_1$  and  $D_4$  conduct, whereas  $D_2$  and  $D_3$  are reverse-biased.

Inverting amplifier at the bottom is active

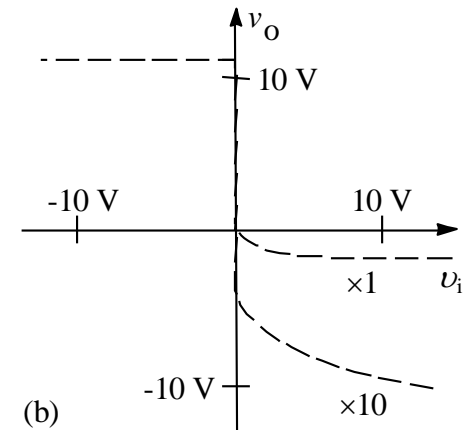
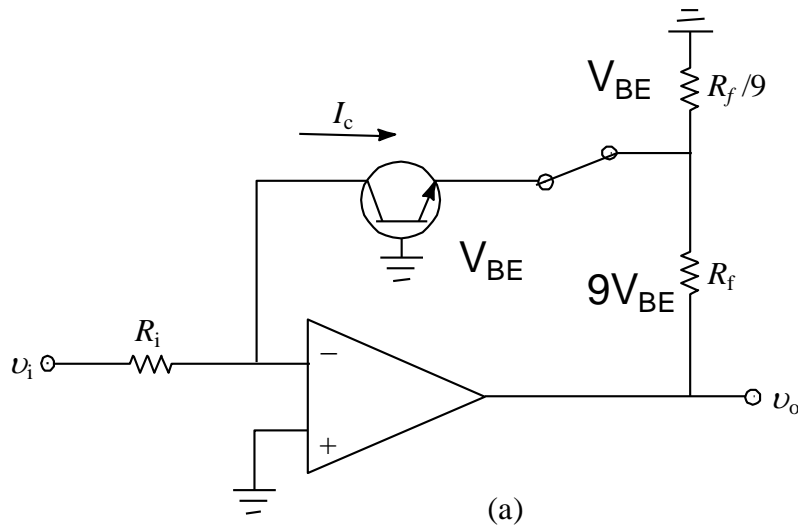
# One-Op-Amp Full Wave Rectifier



(c)

For  $v_i < 0$ , the circuit behaves like the inverting amplifier rectifier with a gain of  $+0.5$ . For  $v_i > 0$ , the op amp disconnects and the passive resistor chain yields a gain of  $+0.5$ .

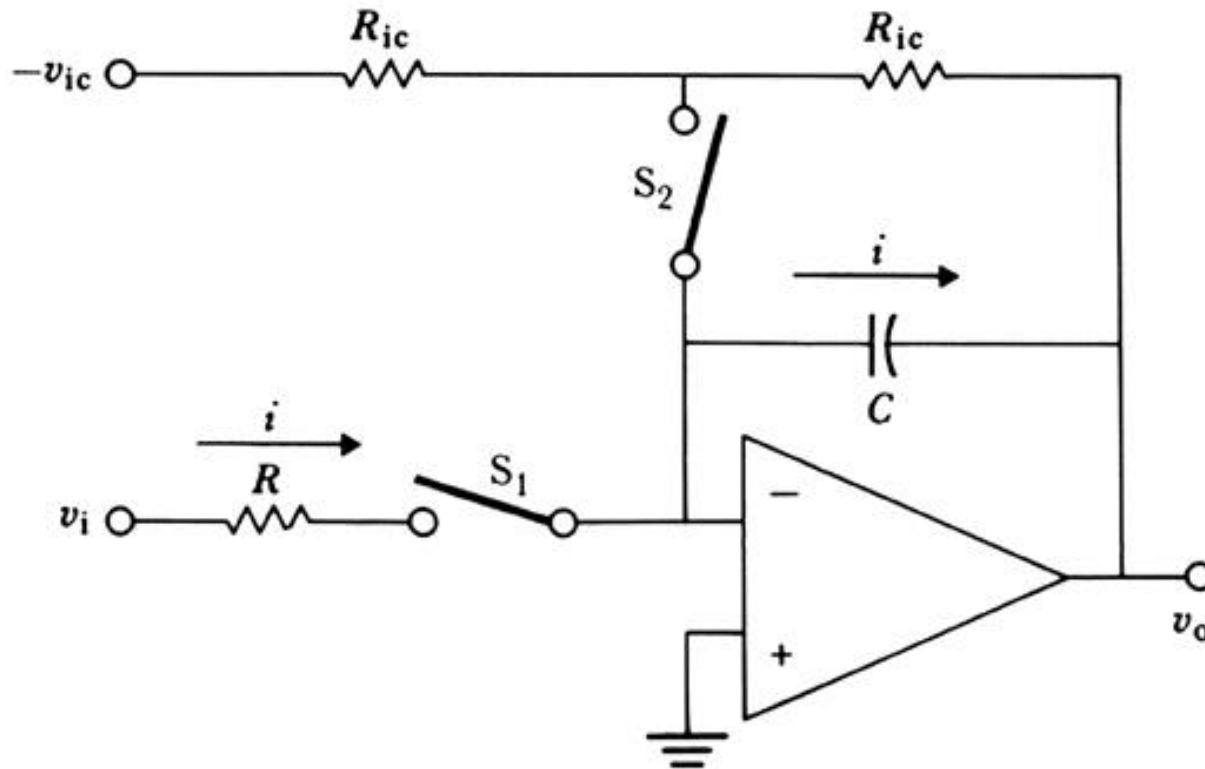
# Logarithmic Amplifiers



**Figure 3.8** (a) With the switch thrown in the alternate position, the circuit gain is increased by 10. (b) Input-output characteristics show that the logarithmic relation is obtained for only one polarity;  $\times 1$  and  $\times 10$  gains are indicated.

# Integrators

what if we were to change the purely resistive ( $R_f$ ) feedback element of an inverting amplifier to that of a frequency dependent impedance such as a Capacitor,  $C$ . What would be the effect on the op-amps output voltage over its frequency range?



**Figure 3.9 A three-mode integrator** With  $S_1$  open and  $S_2$  closed, the dc circuit behaves as an inverting amplifier. Thus  $v_o = v_{ic}$  and  $v_o$  can be set to any desired initial conduction. With  $S_1$  closed and  $S_2$  open, the circuit integrates. With both switches open, the circuit holds  $v_o$  constant, making possible a leisurely readout.

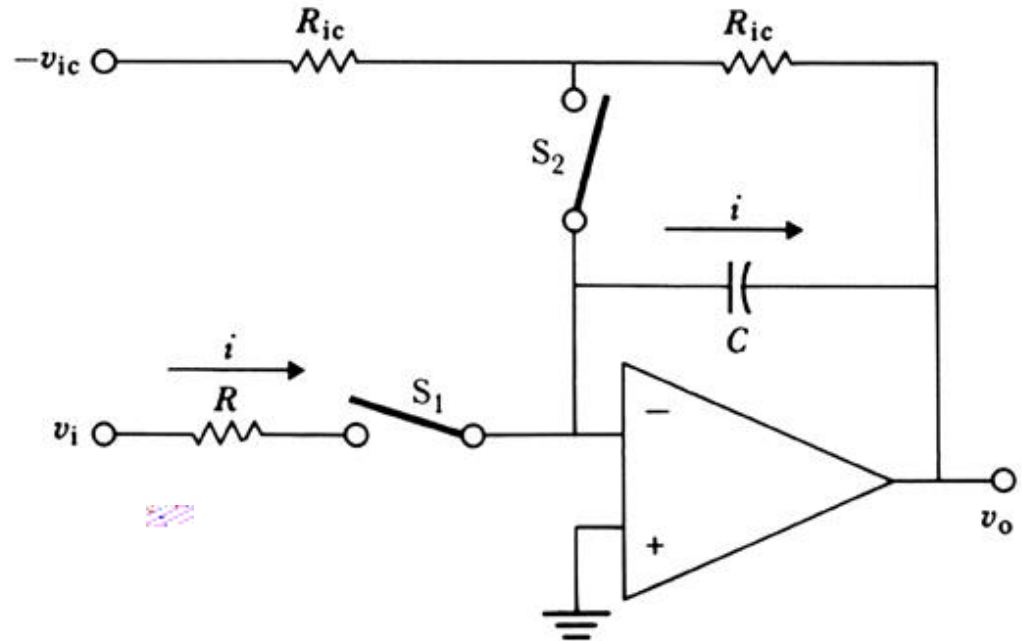
# Integrators– (cont.)

$$v_o = -\frac{1}{R_i C_f} \int_0^{t_1} v_i dt + v_{ic}$$

$$\frac{V_o(j\omega)}{V_i(j\omega)} = -\frac{Z_f}{Z_i}$$

$$\frac{V_o(j\omega)}{V_i(j\omega)} = \frac{-1/j\omega C}{R_i}$$

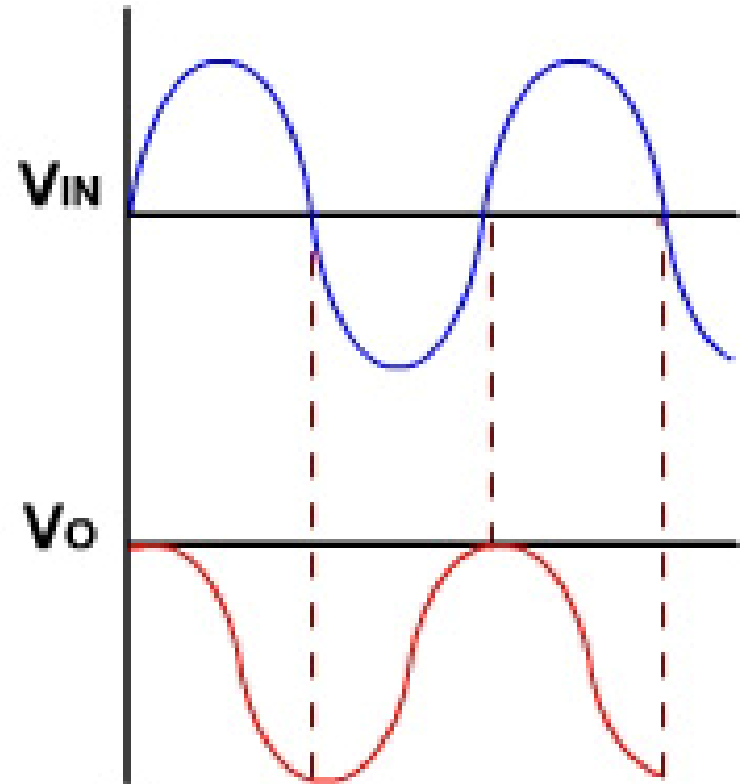
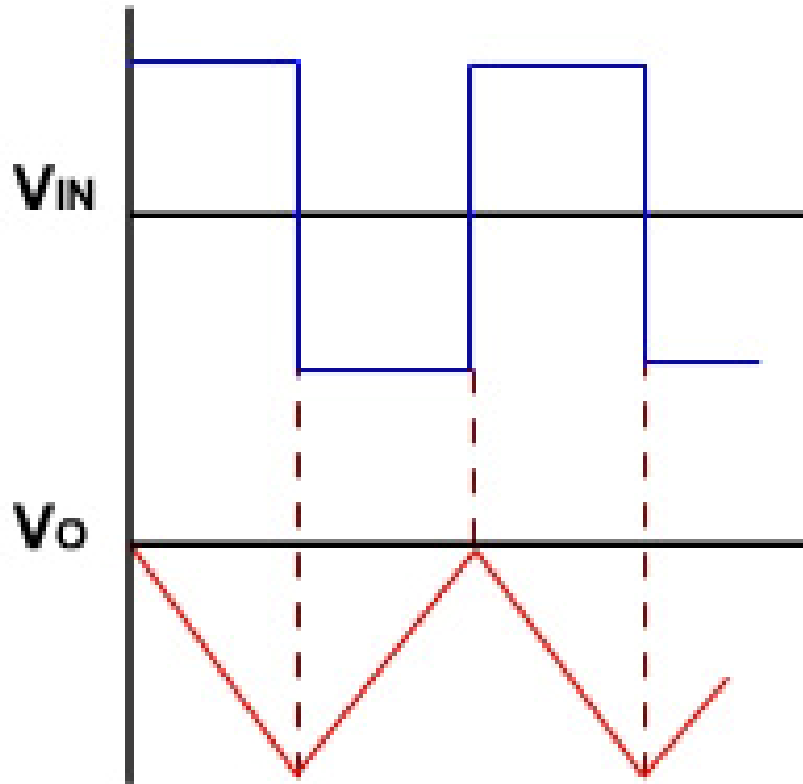
$$\frac{V_o(j\omega)}{V_i(j\omega)} = \frac{-1}{j\omega R_i C} = \frac{-1}{j\omega t}$$



- circuit gain decreases as  $R$  increases
- circuit gain is 1 when  $\omega\tau = 1$



- The output voltage is directly proportional to the negative integral of the input voltage and inversely proportional to the time constant  $RC$ .
- If the input is a sine wave the output will be cosine wave. If the input is a square wave, the output will be a triangular wave.



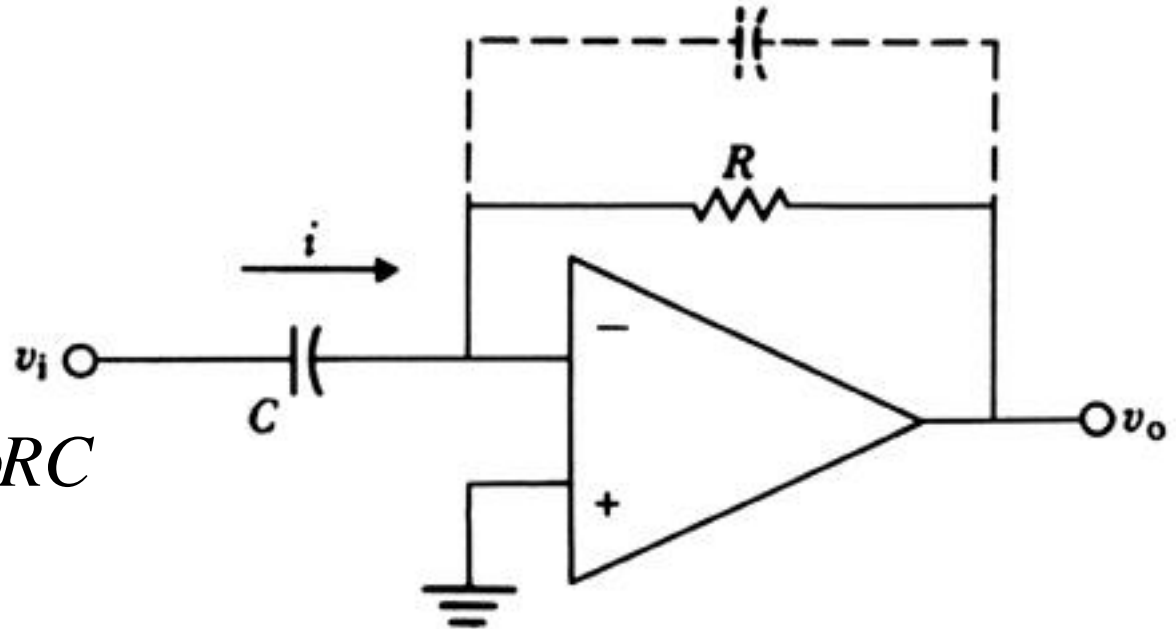
- An integrator circuit produces a steadily changing output voltage for a constant input voltage.

# Differentiators

- produces a voltage output which is directly proportional to the input voltage's rate-of-change with respect to time

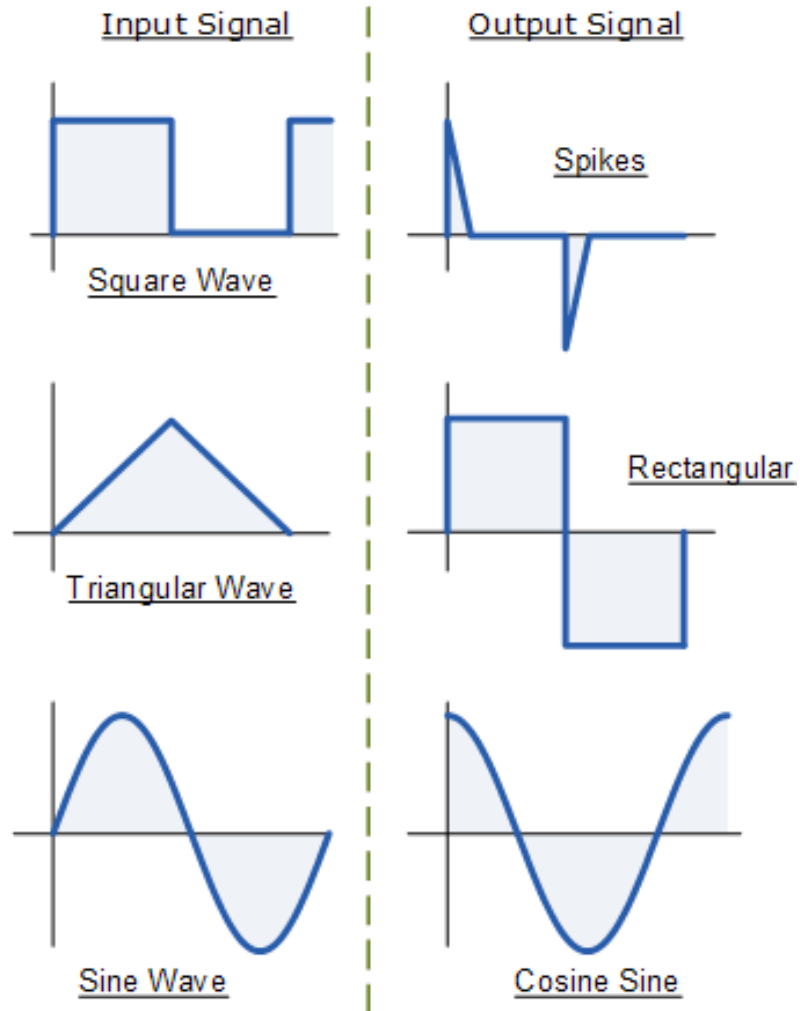
$$v_o = -RC \frac{dv_i}{dt}$$

$$\frac{V_o(j\omega)}{V_i(j\omega)} = -\frac{Z_f}{Z_i} = -j\omega RC$$



**Figure 3.11 A differentiator** The dashed lines indicate that a small capacitor must usually be added across the feedback resistor to prevent oscillation.

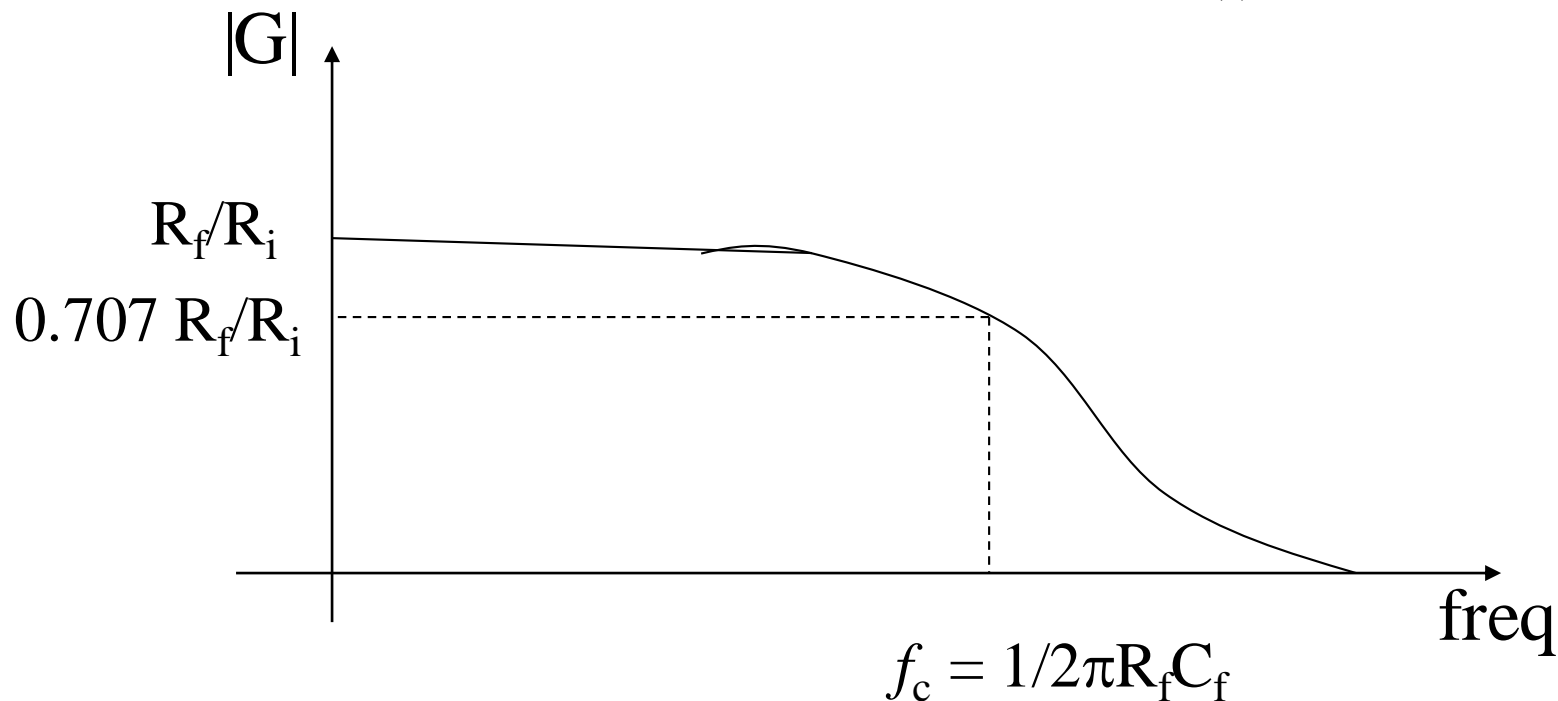
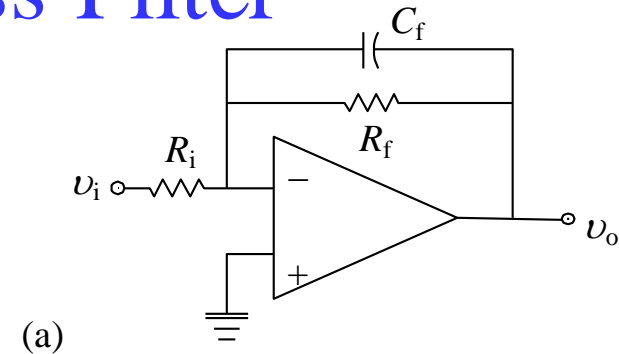
# Op-amp Differentiator Waveforms



- A differentiator circuit produces a constant output voltage for a steadily changing input voltage.

# Active Filters- Low-Pass Filter

$$\text{Gain} = G = \frac{V_o(j\omega)}{V_i(j\omega)} = \frac{-R_f}{R_i} \frac{1}{1 + j\omega R_f C_f}$$

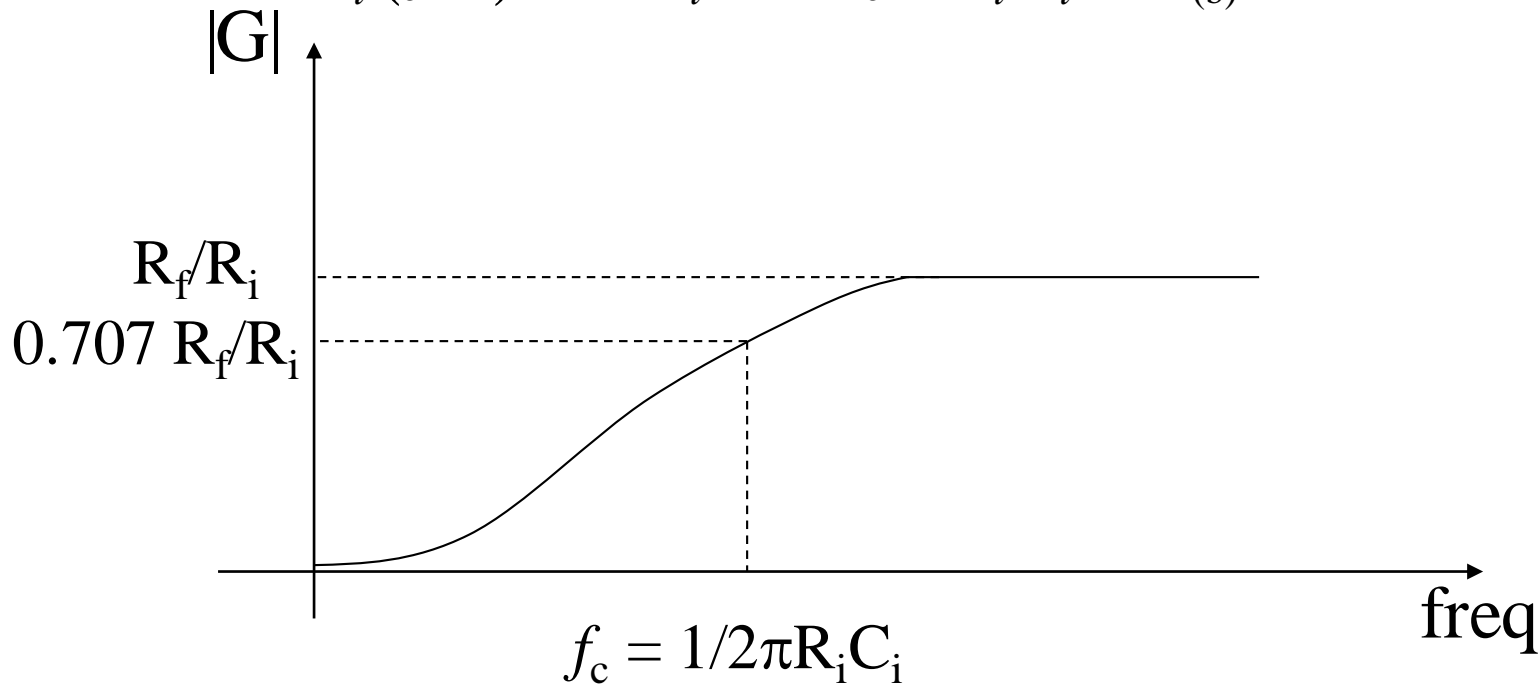
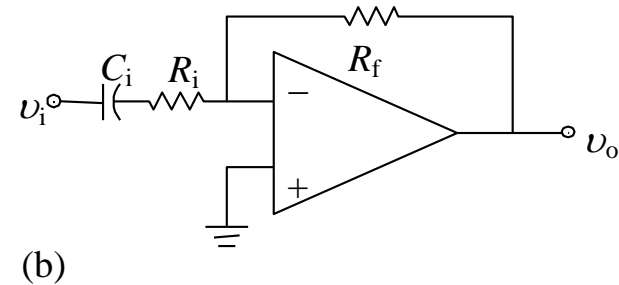


## Active filters

(a) A low-pass filter attenuates high frequencies

# Active Filters (High-Pass Filter)

$$\text{Gain} = G = \frac{V_o(j\omega)}{V_i(j\omega)} = \frac{-R_f}{R_i} \frac{j\omega R_i C_i}{1 + j\omega R_i C_i}$$

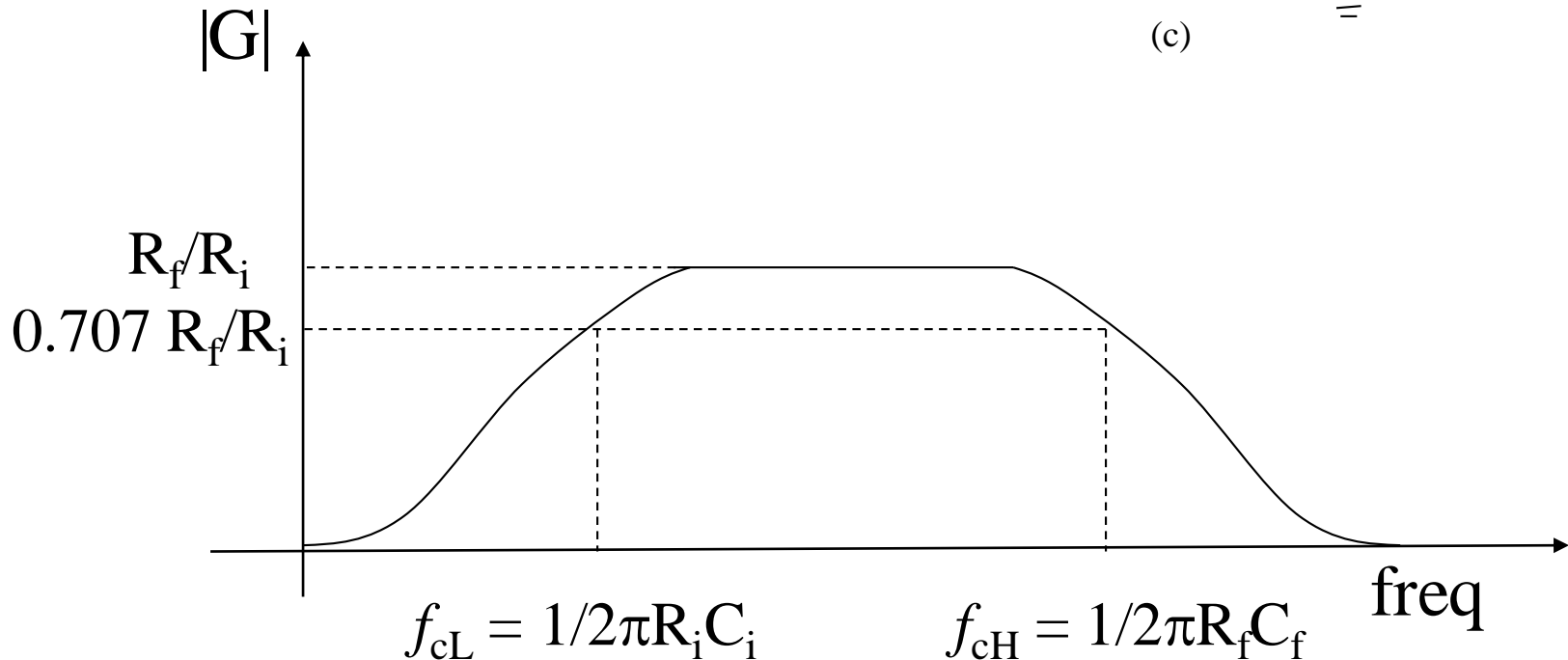
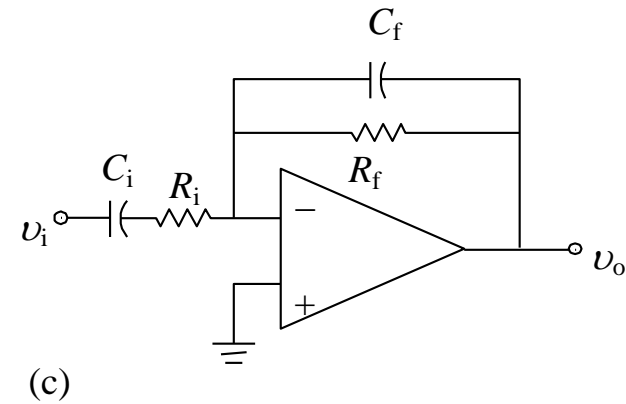


## Active filters

(b) A high-pass filter attenuates low frequencies and blocks dc.

# Active Filters (Band-Pass Filter)

$$\frac{V_o(j\omega)}{V_i(j\omega)} = \frac{-j\omega R_f C_i}{(1 + j\omega R_f C_f)(1 + j\omega R_i C_i)}$$



## Active filters

(c) A bandpass filter attenuates both low and high frequencies.

# Frequency Response of op-amp and Amplifier

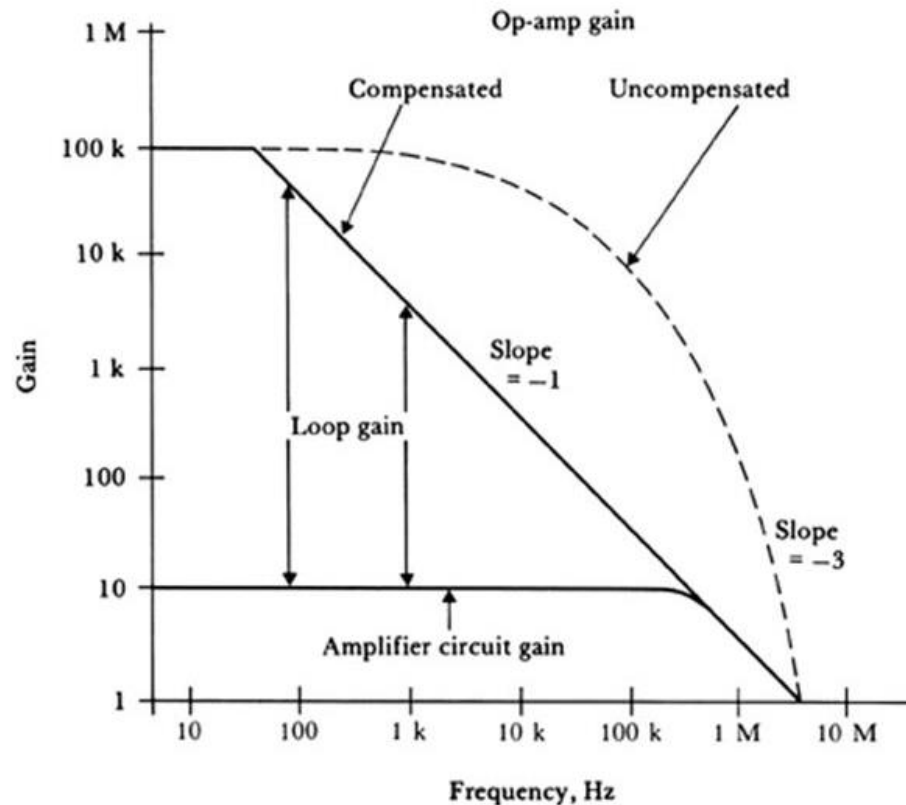
Open-Loop Gain

Compensation

Closed-Loop Gain

Gain Bandwidth Product

Slew Rate



**Figure 3.13 Op-amp frequency characteristics**  
early op amps (such as the 709) were uncompensated, had a gain greater than 1 when the phase shift was equal to  $-180^\circ$ , and therefore oscillated unless compensation was added externally. A popular op amp, the 411, is compensated internally, so for a gain greater than 1, the phase shift is limited to  $-90^\circ$ . When feedback resistors are added to build an amplifier circuit, the loop gain on this log-log plot is the difference between the op-amp gain and the amplifier-circuit gain.

# Offset Voltage and Bias Current

Read section 3.12 (**OFFSET VOLTAGE**)

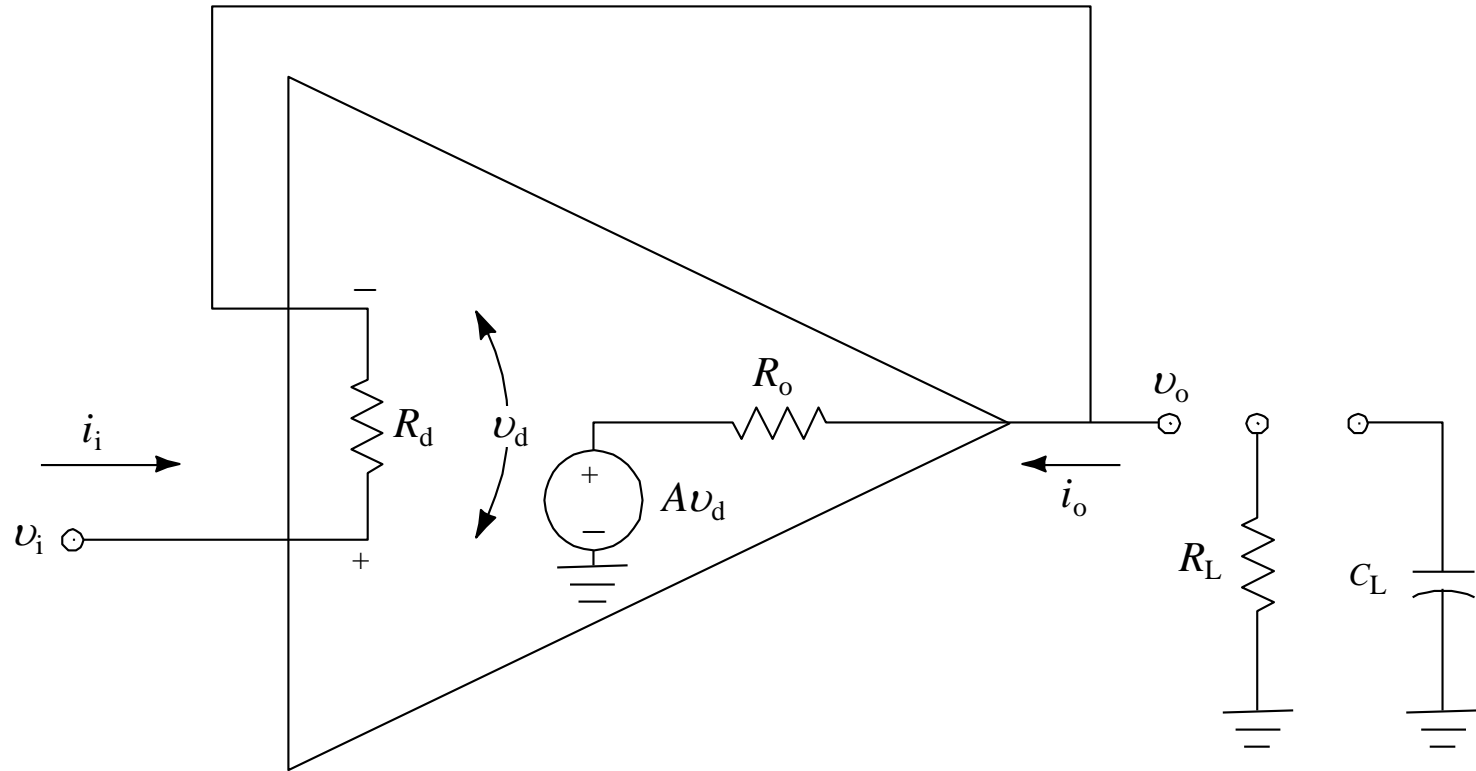
Nulling, Drift, Noise

Read section and 3.13 (**BIAS CURRENT**)

Differential bias current, Drift, Noise



# Input and Output Resistance



$$R_{ai} = \frac{\Delta v_i}{\Delta i_i} = (A + 1)R_d$$

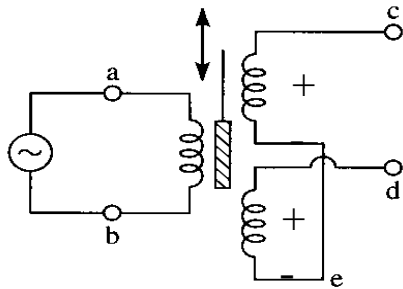
$$R_{ao} = \frac{\Delta v_o}{\Delta i_o} = \frac{R_o}{A + 1}$$

Typical value of  $R_d = 2$  to  $20 \text{ M}\Omega$

Typical value of  $R_o = 40 \text{ }\Omega$

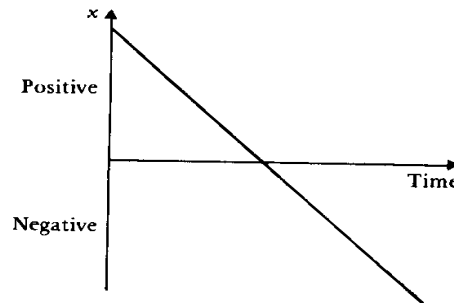
# Phase Modulator for Linear variable differential transformer LVDT

- This device works on the principle that alterations in the self-inductance of a coil may be produced by changing the geometric form factor or the movement of a magnetic core within the coil.

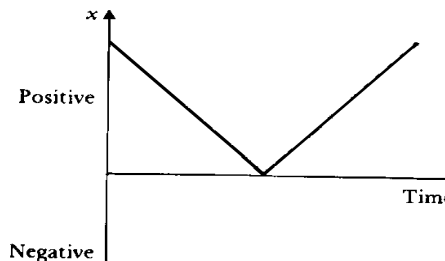
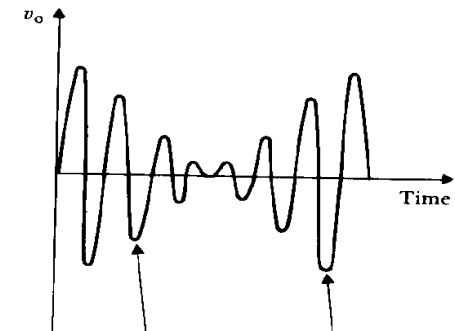


(c)

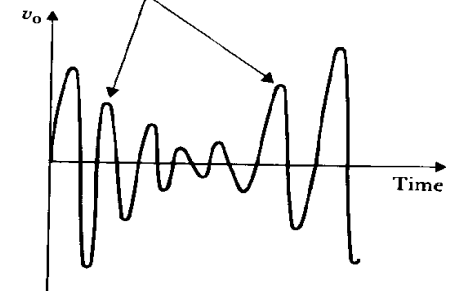
- the same magnitude of output voltage results from two very different input displacements.



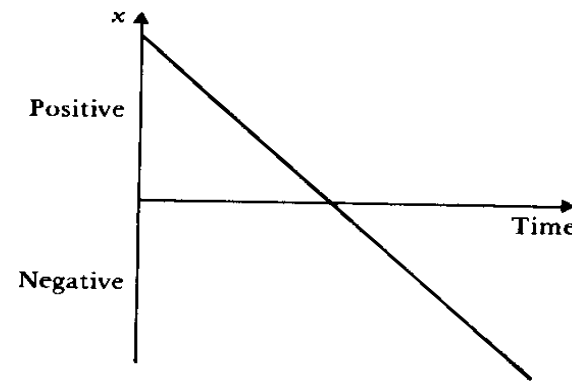
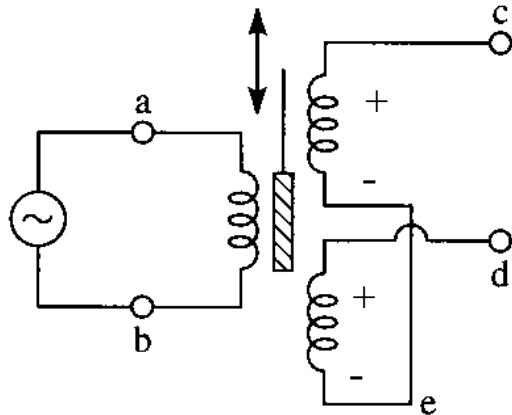
(a)



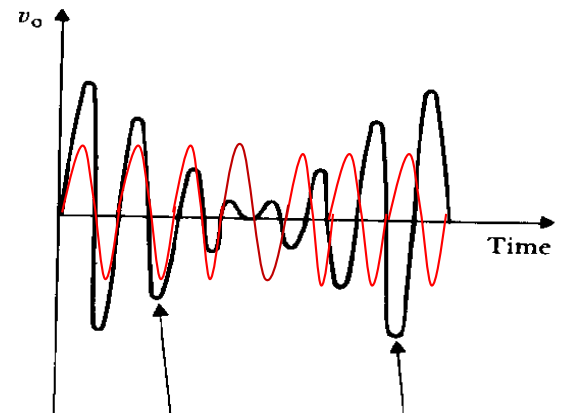
(b)



# Phase Modulator for Linear variable differential transformer LVDT

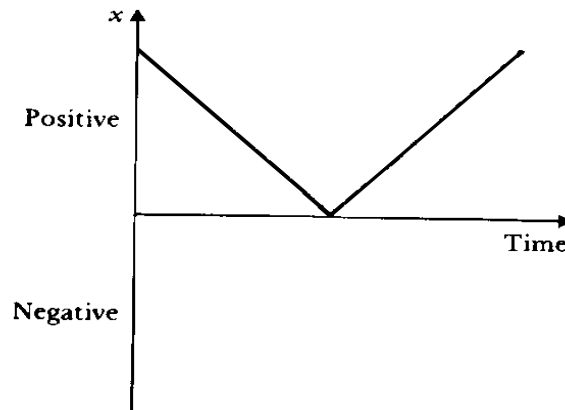


(a)

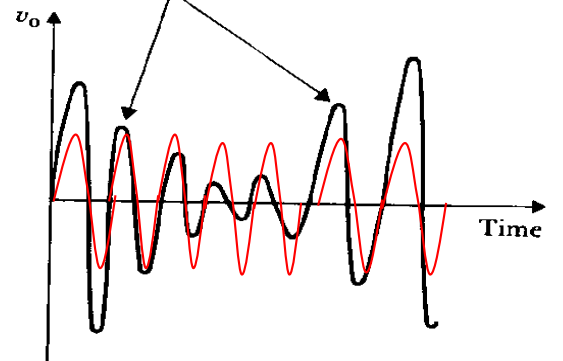


Phase angle = 0°

Phase angle = 180°



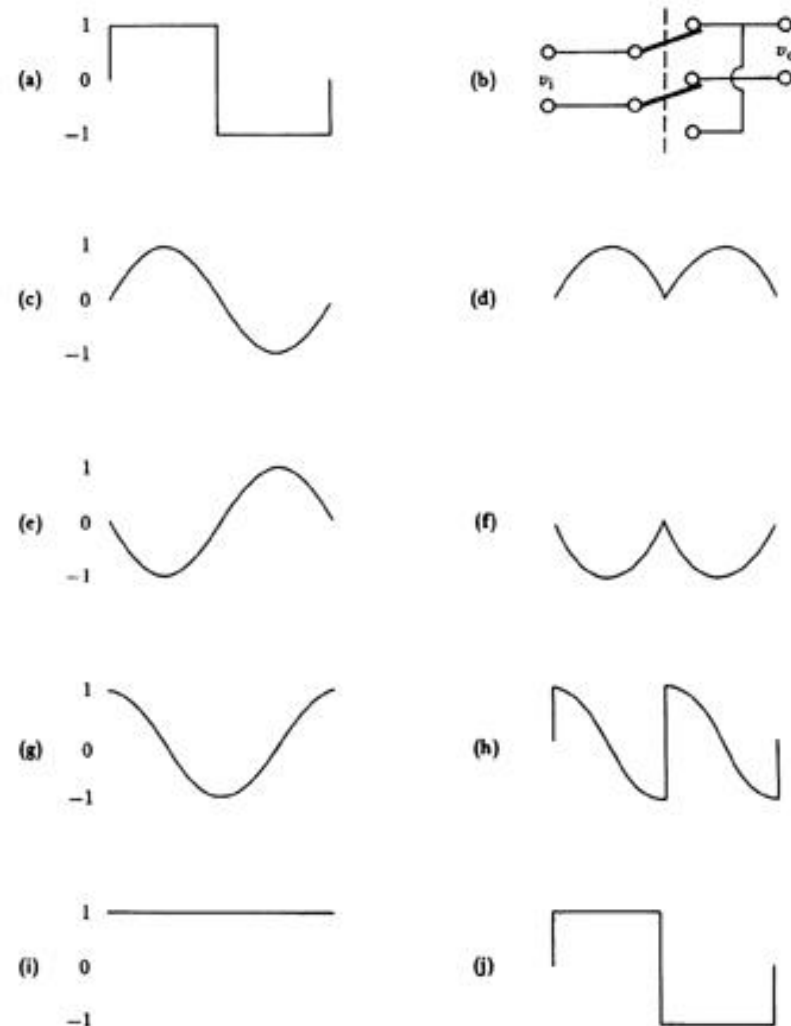
(b)



- The direction of displacement may be determined by using the fact that there is a 180° phase shift when the core passes through the null position

# Phase-Sensitive Demodulator

- A phase-sensitive demodulator yields a full-wave-rectified output of the in-phase component of a sine wave. Its output is proportional to the amplitude of the input, but it changes sign when the phase shifts by  $180^\circ$ .



**Figure 3.16 Functional operation of a phase-sensitive demodulator** (a) Switching function. (b) Switch. (c), (e), (g), (i) Several input voltages. (d), (f), (h), (j) Corresponding output voltages.

Used in many medical instruments for signal detection, averaging, and Noise rejection