

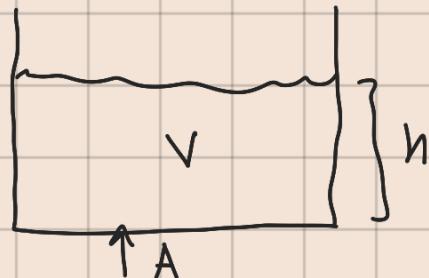
the heart AS A Pump

blood comes in the left ventricle with pressure of left atrial into LV
 the pressure in the Left Ventricle is the input pressure
 " " " " Aorta is the output pressure

$$\Delta P = P_{\text{out}} - P_{\text{input}}$$

$$\Delta P = P_{\text{AO}} - P_{\text{LA}}$$

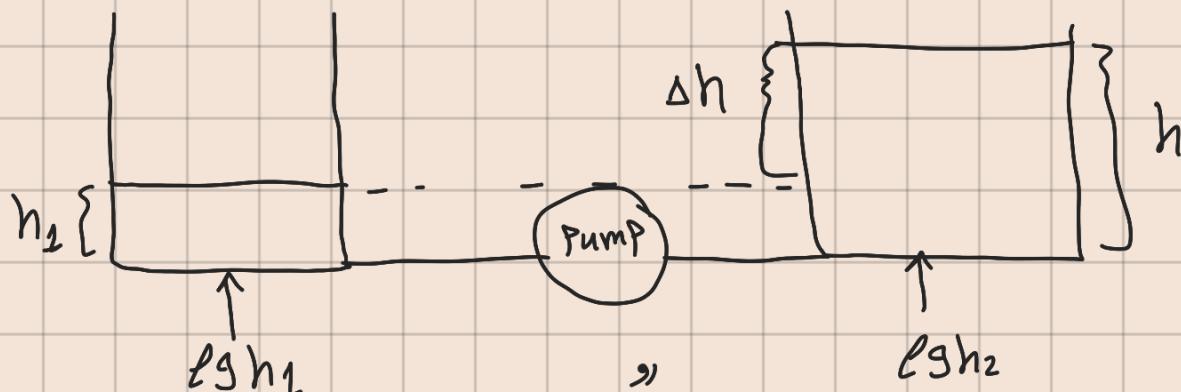
$$P = \rho g h$$



$$\Delta P = \rho g (h_0 - h_i) = \rho g \Delta h$$

Δh
↳ Pump head (Pressn head)

the unit of Pressure $\Rightarrow [Pa]$ or $[mm Hg]$



$$\Delta P = \rho g h_2 - \rho g h_1 = \rho g (h_2 - h_1) = \rho g \Delta h$$

where: Δh = Pump head

in the hydraulic system if you consider the mechanical system.

MS ES

independen variable X q charge KE m $\geq L$

Dependent " "

effort " F

V PE X $\geq \frac{1}{L}$
Voltage

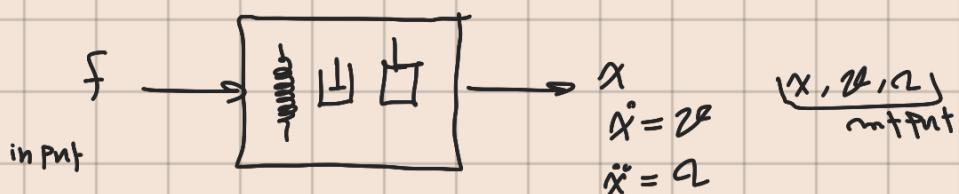
Motion

\dot{x}
velocity

I
current

HE

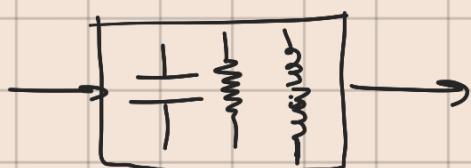
$b \rightleftharpoons R_e$



- so the effort variable the input of the system
- the motion variable the output \rightarrow independent variable

how we can model: constant variables like spring damper mass,
in mechanical system

In electrical system we have capacitance which correspond to spring and resistance which correspond to damper and the mass which is inductances



so mass is the analog of \rightarrow inductor $m \rightleftharpoons L$
the stiffness is " " " \rightarrow resistor capacitance (L)
 $K \rightleftharpoons 1/C$

the damper (b) is analog of \rightarrow resistance $b \rightleftharpoons R_e$

Now we will switch to hydraulic system.

MS

ES HS

$X [m]$

$\dot{q} [\text{canl}]$

F

V

$v̄ = \dot{x} \left[\frac{m}{s} \right]$

$I = \dot{q} \left[\frac{\text{canl}}{\text{sec}} \right]$

f_s : force in spring $K \rightarrow f_s = Kx$

C: $V_C = \frac{1}{C} q$ the volt through the capacitance

Force in the damper $b \rightarrow F_d = b\dot{x}$

b: $V_R = R_e I$ ohm equation

" " " mass $m \rightarrow f_m = m\ddot{x}$

m: $V_I = L I$

$$\dot{q} = I \quad q = CV$$

HS

Volume

V

Pressure

P

mation variable

$$Q \left[\frac{m}{s} \right]$$

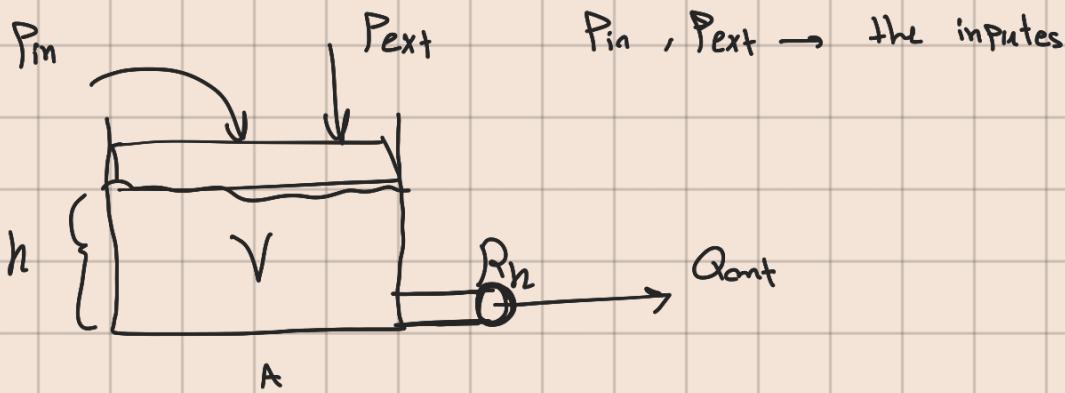
↓
flow

$$C = \frac{A}{\rho g}$$

$$P = R_h Q$$

For now we will ignore the mass it is completed

we are modeling the hydrolic system



the flinde from the input is going to discharge from this open

Q_{out}

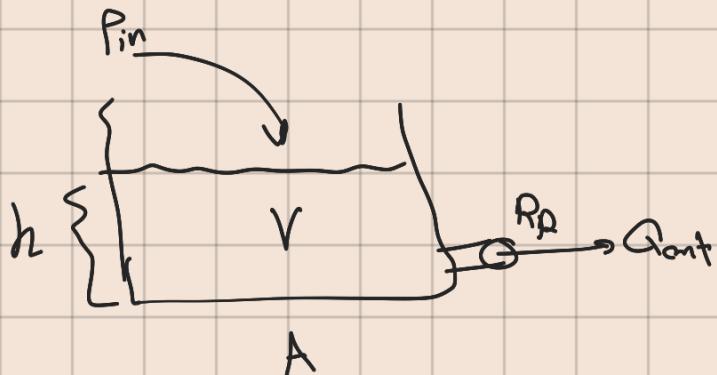
- now we will try to express the dynamic of hydronical system

$$b \dot{x} + Kx = F_{ext} \rightarrow M.S$$

$$R \dot{q}_1 + \frac{1}{C} q_1 = V_{in} \rightarrow E.S$$

First lets assume that there is not external pressure $P_{ext}=0$ we just have an input flow and output flow and the Volume accumulated in the riser
 Gi chigil also

riser
Gi chigil also



So when we see accumulate first thing come to mind integrate
 accumulate \rightarrow integrate

what does it integrate \rightarrow it is integrate volume

Ex:

MS \rightarrow  spring what does it integral distance

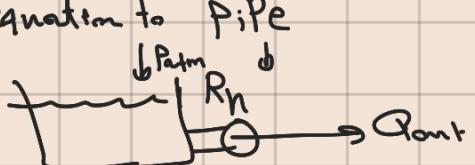
ES \rightarrow $\frac{1}{T} \int q$ capacitance integrate charges

so firstful

1-using ohm's equation

$$\Delta P = R_h Q$$

$\underbrace{\qquad\qquad\qquad}_{\text{we can apply this equation to the pipe}}$ $P_i - P_e$



$$\Delta P = P_{in} - P_{out} = \rho g h_1 + P_{atm} - \rho g h_2 - P_{atm}$$

$$P = \rho g h + P_{atm}$$

$$\Delta P = \rho g \Delta h$$

$$P = \rho g h + P_{atm}$$

so because of that we can ignore the atmosphere pressure

when we calculate the changing in the pressure



$$\text{Since: } V = A h \Rightarrow h = \frac{V}{A}$$

$$P_{in} = \rho g h = \rho g \frac{V}{A} = \frac{\rho g}{A} V$$

inverse of the capacitance

$$P = \frac{1}{C} V$$

$$V = \frac{1}{C} q$$

$$q = C V$$

$$\frac{1}{C} = \frac{\rho g}{A}$$

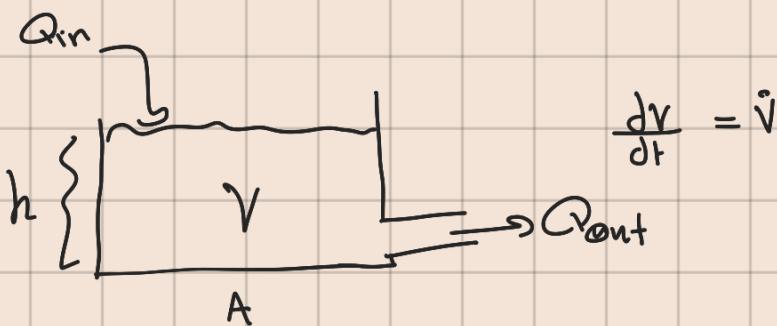
$$\Delta P = R_h Q_{out}$$

$$\frac{\rho g}{A} V = R_h Q_{out}$$

→ ① first equation

which comes from ohm's relationship

2- apply KCL



$$Q_{in} - Q_{out} = \dot{V}$$

continuity equation hydrostatic

since:

KCL equation

$$\rho g \frac{V}{A} = R_h Q_{out}$$

$$\therefore Q_{out} = Q_{in} - \dot{V}$$

$$\Rightarrow \rho g \frac{V}{A} = R_h (Q_{in} - \dot{V}) \rightarrow \text{we have now differential eq. in terms } V$$

dividing every think with R

$$\frac{\rho g}{R_h} \frac{V}{A} = \frac{R_h}{R_h} (Q_{in} - \dot{V}) \quad \text{since } \frac{\rho g}{A} = \frac{1}{C}$$

$$\frac{1}{R_h C_h} V = Q_{in} - \dot{V} \Rightarrow \dot{V} = -\frac{1}{R_h C_h} V + Q_{in}$$

as we know the most generic form for $-\frac{1}{R_h C_h}$ is \rightarrow

$$\dot{y} = -ay + b \quad \text{∴ pole the system} = \frac{1}{C_h} = \frac{1}{RC}$$

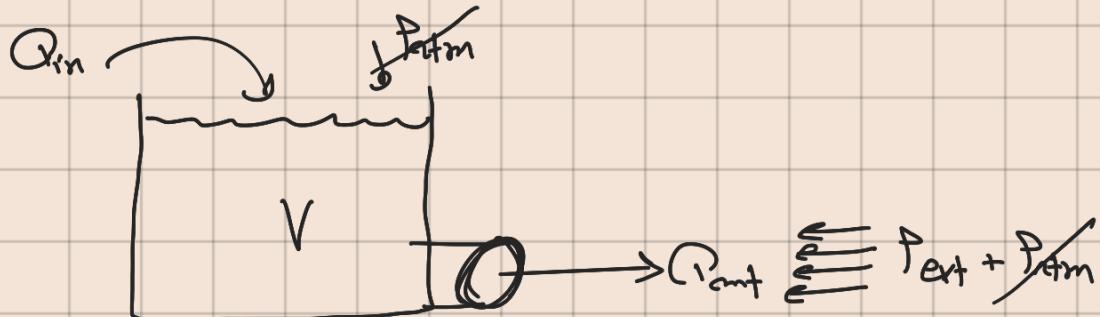
so this is RC circuit with time constant $\frac{1}{RC}$

$$\tau = RC$$

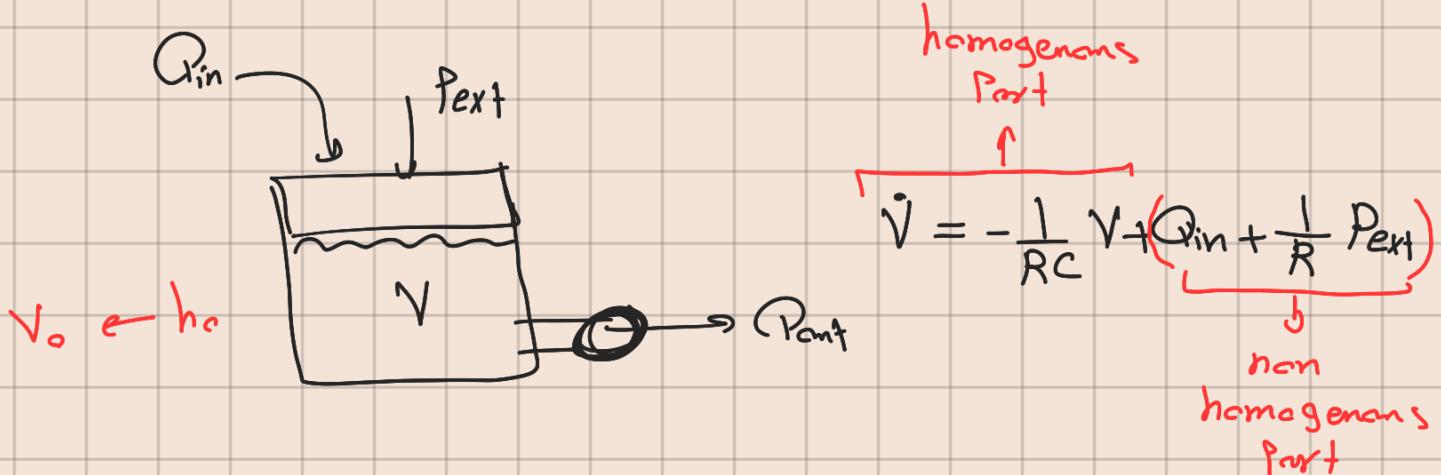
$$\dot{V} = -\frac{1}{RC} V + Q_{in}$$

If now I want to add the pressure it exerts on it P_{ext}
so it will be in terms $Q \Rightarrow$ since $P = RQ$
 $\frac{P}{R} = Q$

$$\Rightarrow \dot{V} = -\frac{1}{RC}V + Q_{in} + \frac{1}{R}P_{ext}$$



If you measure P over P_{atm} \Rightarrow called as gauge pressure



You have to start from initial high V_0 initial volume V_0

$$V(t) = \left(V_0 - \frac{b}{a} \right) e^{-\frac{t}{RC}} + \frac{b}{a}$$

general solution
to resivore
Value

$$\dot{V} = -aV + b$$

$$y(t) = \left(y_0 - \frac{b}{a} \right) e^{-\frac{t}{RC}} + \frac{b}{a}$$

$$so \Rightarrow b = Q_{in} - \frac{1}{R}P_{ext}$$

$$a = \frac{1}{RC}$$

$$\frac{b}{a} = \frac{Q_{in} - \frac{1}{R}P_{ext}}{1/RC}$$

$$\frac{b}{a} = R C Q_{in} - C P_{ext}$$

Homework: \Rightarrow you are going to use matlab
Create reservoir (A) \rightarrow the one we interested

$$C = \frac{A}{eg}$$

determine Q_{in}

Calculate Q_{out}

" "

γ

$R_h \rightarrow$ calculate
the resistance
of the pump

model cardiac vascular system

each pump in the heart fail in Volume

the flow that comes in from the LA to LV

the volume in distolic go up
and in the systol phase $Q_{in} \rightarrow$
the volume go down

if $Q_{in} > Q_{out}$ the volume will increase

$$Q_{in} - Q_{out} = q$$

in some point when blood goes to fail the LV $Q_{out} = 0$

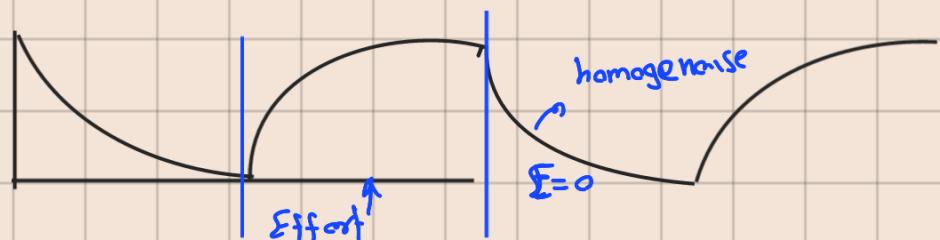
if $Q_{out} < Q_{in}$ the volume will decrease

$$Q_{in} - Q_{out} = q \Rightarrow q < 0$$

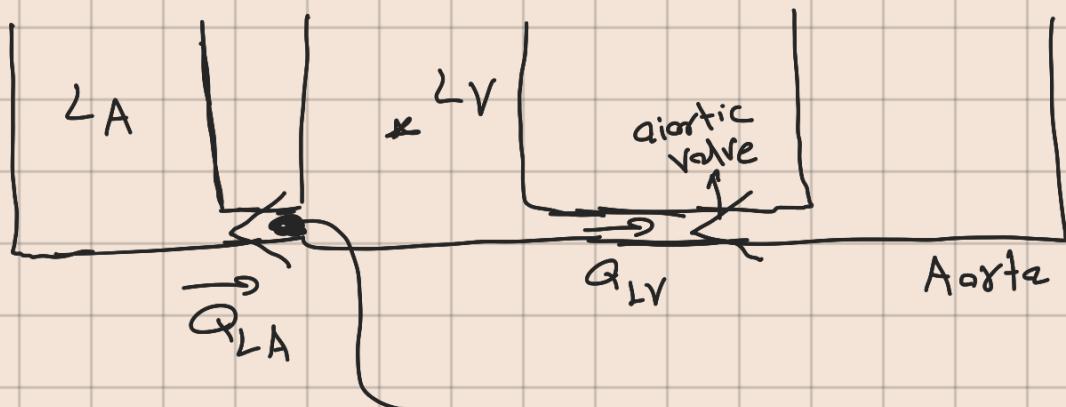
Since $q = \dot{V} > 0$

$q = \dot{V} < 0$ and we know that expression is first order

system and we know such that system the volume increase exponentially and decrease exponentially



when it increase it is you apply external effort and the external effort or force is applied is from the muscle and the force that the muscle creates we can represented as piston acting on the top vinterical



in here we have mitral valve in one direction and that mean if flow from the LA and go in if the pressure in LA is higher than the pressure here \leftarrow LV but until it reach to the pressure in LV higher than the pressure in LA and then the valve ~~is~~ will be closed and there is no blood to flow we can represent this situation as diode



electrical equivalent

and the same think in the aortic valve when the pressure in Aorta higher than the pressure in the LV then the valve aortic will close to prevent the flowing of the blood.

So during the pressure higher in LA and blood flowing into the LV the pressure in the Aorta in this time is higher the LV and the aortic valve is closed and thus no flowing blood from $LV \rightarrow$ Aorta and during this period the volume in LV increases



the equation that represent this case is \Rightarrow

$$V = \left(V_0 - \frac{b}{a} \right) e^{-\frac{t}{RC}} + \frac{b}{a}$$

since $Q = \frac{V}{t} \Rightarrow V = Qt$
 $P = \frac{Q}{A} V$

$tQ = V$ we can represent time by RC

$$\frac{b}{a} = RC Q_{in} + \frac{A}{eg} P$$

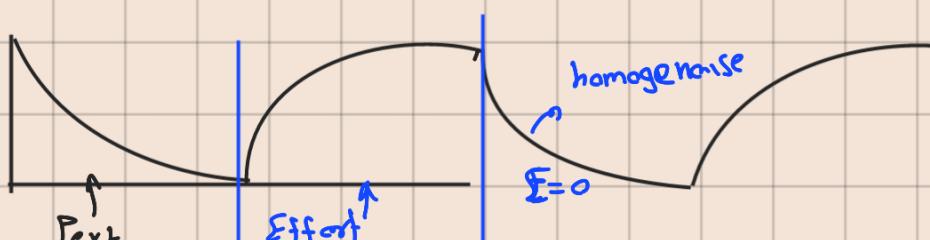
↑
during diastolic

during systole $Q_{in}=0$ and $P = P_{ext}$

$$\frac{b}{a} = RC Q_{in} + \frac{A}{eg} P_{ext} \rightarrow \text{during systole}$$

↑
during diastolic

so in two phases there is force I will explain



force acting through the pressure it will press on the ventricle here the $\Sigma F_{effort} = P_{ext}$ and this for the flow coming in and increase in the volume so in here $\bar{F}_{effort} = RQ$

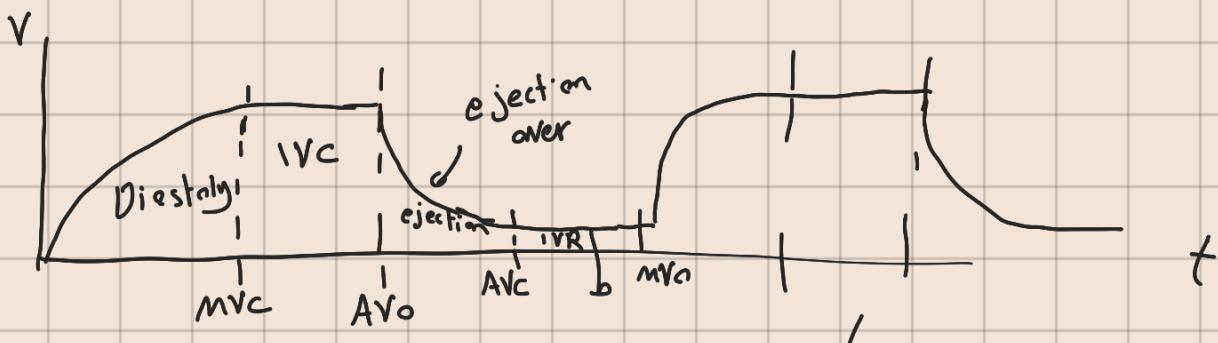
so our equation will have two form during diastolic and systolic

$$V = \begin{cases} RQ_{in} & \text{diastolic} \\ CP & \text{systolic} \end{cases}$$

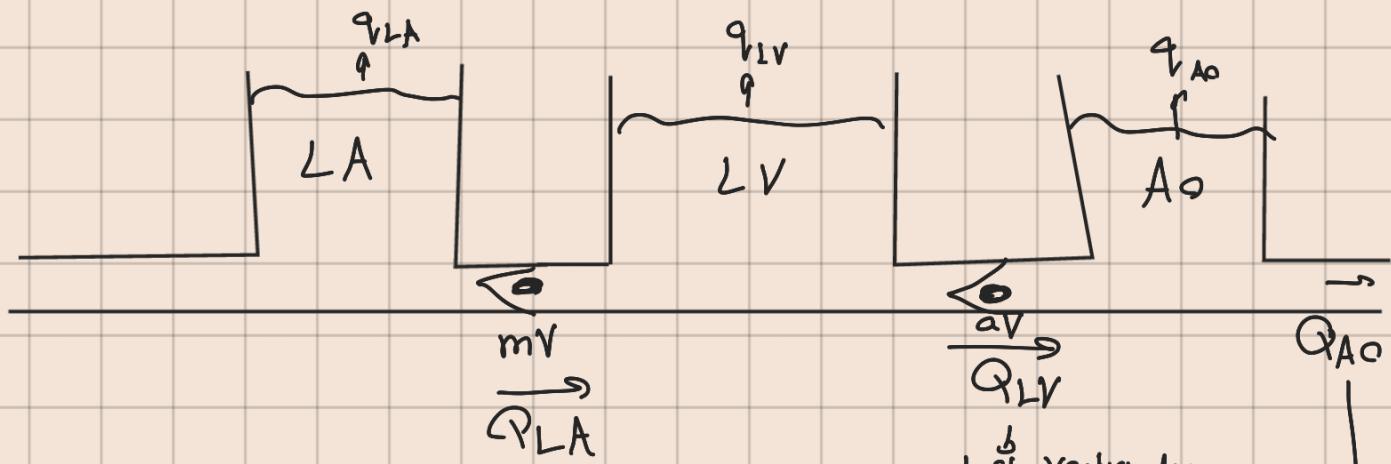
and the volume during two is

$\frac{b}{a} = 0$

represented in graph



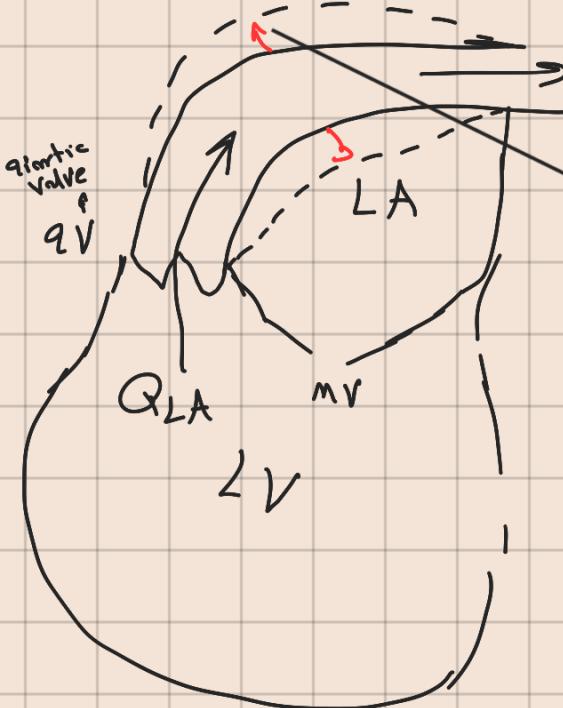
Homework



\downarrow
left ventricular
blood during
ejection
going to aorta
and rising the
volume blood
and then flowing
to the body

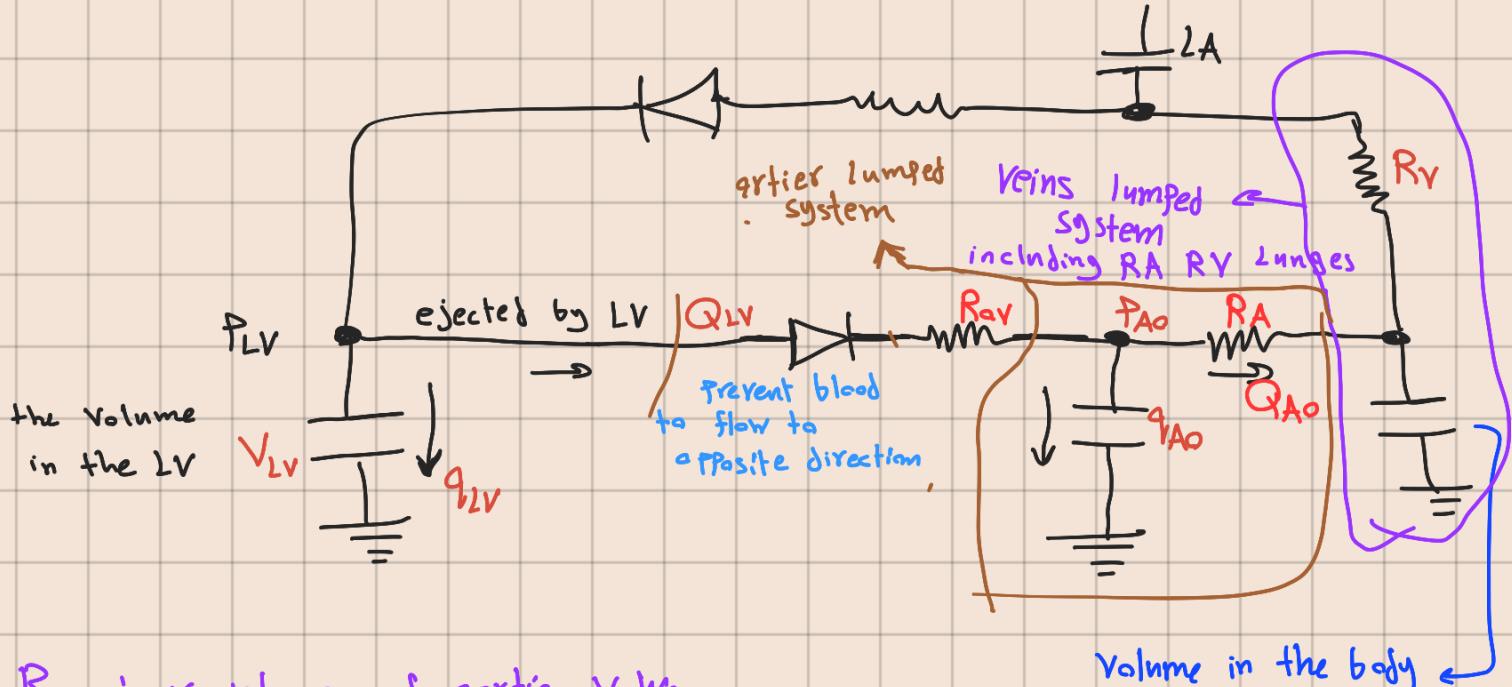
during ejection in LV the aorta inside the aorta increases

$$q_{Ao} \uparrow$$



Some of it goes to the rest
of body and some of stay
in the aorta enlarge the
flow with ventricular contraction
all the artiers in the body
So what we see up and down
movement of aorta inside
the body

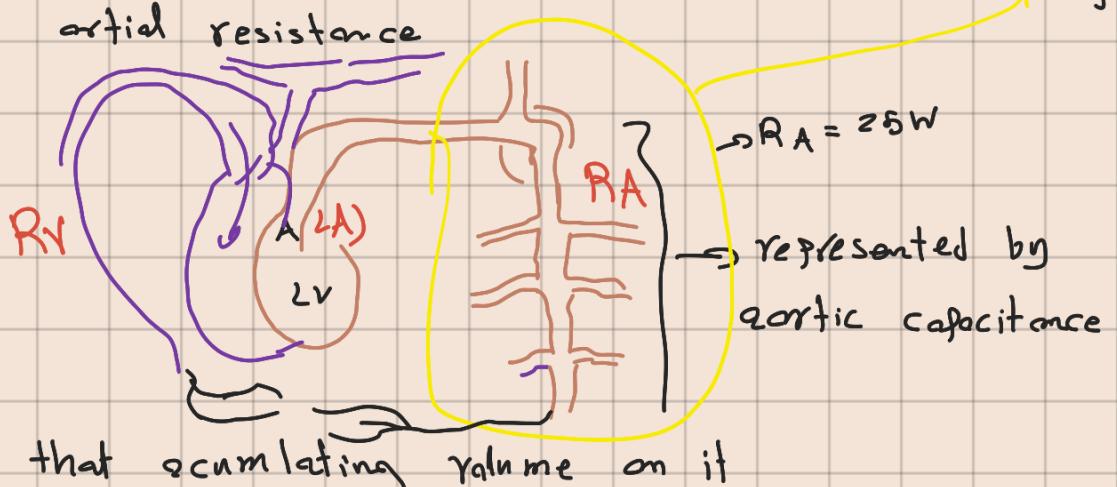
the way we are going to model this as electrical system



R_{Av} : resistance of aortic Valve

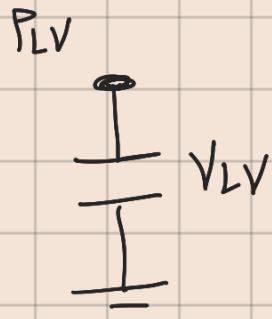
We are model the left ventricular and all these arterial resistance the aorta Lumped system

$$C = \frac{A}{\rho g}$$



the capacity that accumulating volume on it

We have 4 RC systems



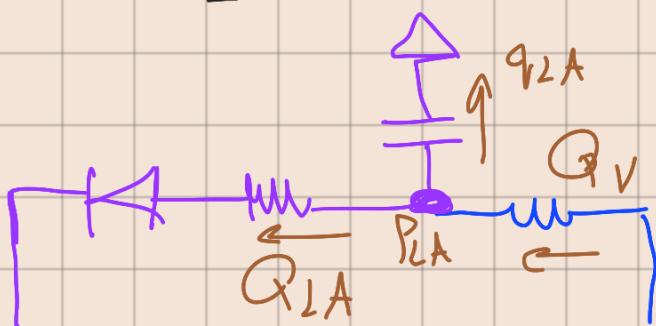
the Volume creat a pressure in electrical system

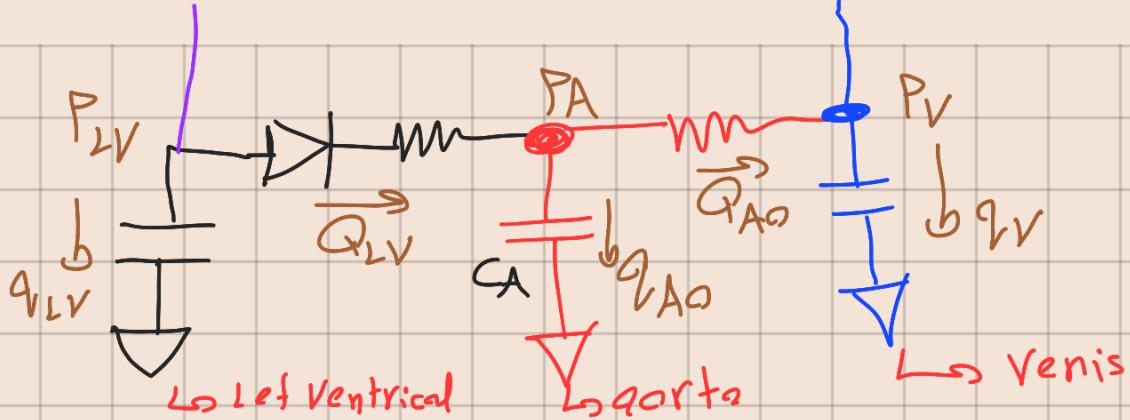
$$\gamma = C V \rightarrow \text{voltage}$$

in our system

$$V = CP \Rightarrow$$

$$P = \frac{1}{C} V$$





so for each system we have P, Q, R

note: $P, Q \Rightarrow$ unknown we have to get 3 equation
for each node

We can observe this equation by using
Ohm aort $\rightarrow R_A Q_{AO} = P_{AO} - P_V$

KCL continuity $Q_{LV} = Q_{AO} + Q_{AV}$

capacitance Since $V = cP \rightarrow \dot{V} = c\dot{P} \quad \dot{V} = Q$

$Q = c\dot{P} \rightarrow Q$ it is the volume that
 $\dot{P}_{AO} = \frac{1}{c} Q_{AO}$ creates pressure

Let's chose P as unknown

$$Q_{AO} = Q_{LV} - Q_{AV} \quad Q_{AO} = \frac{P_{AO} - P_V}{R_A}$$

$$\dot{P}_{AO} = \frac{1}{c} (Q_{LV} - Q_{AV})$$

$$\dot{P}_{AO} = \frac{1}{c} \left[Q_{LV} - \left(\frac{P_{AO}}{R_A} - \frac{P_V}{R_A} \right) \right]$$

$$Q_{LV} = \frac{P_{LV} - P_{AO}}{R_{AV}}$$

$$\dot{P}_{AO} = \frac{1}{C_{AO}} \left[\left(\frac{P_{LV}}{R_{AV}} - \frac{P_{AO}}{R_{AV}} \right) - \left(\frac{P_{AO}}{R_A} - \frac{P_V}{R_A} \right) \right]$$

to simplify the equation let $\frac{1}{C_{AO}} = e_{AO}$ *e: elastance steffinice*

$$R = \frac{1}{g}$$

g = adm in th

$$\dot{P}_{AO} = e_{AO} \left[(g_2 P_{LV} - g_2 P_{AO}) - (g_A P_{AO} - g_A P_V) \right]$$

$$\dot{P}_{AO} = e_{AO} \left\{ (g_2 P_{LV} - (g_a + g_A) P_{AO} + g_A P_V) \right\}$$

$$\dot{P}_{AO} = e_A g_2 P_{LV} - e_A (g_a + g_A) P_{AO} + e_A g_A P_V + \frac{Q}{P_{LA}}$$

$\dot{x} = -\alpha x + b$

if we do this equation for all node
we get

$$\dot{P}_{LV} = a_1 P_{LV} + a_2 P_{AO} + a_3 P_V + a_4 P_{LA}$$

$$\dot{P}_{AO} = b_1 P_{LV} + b_2 P_{AO} + b_3 P_V + b_4 P_{LA}$$

$$\dot{P}_V = c_1 P_{LV} + c_2 P_{AO} + c_3 P_V + c_4 P_{LA}$$

$$\dot{P}_{LA} = d_1 P_{LV} + d_2 P_{AO} + d_3 P_V + d_4 P_{LA}$$

so what we have is systemic of differential equation
and each unknown express as linear sum of 4 unknown
together this is matrix format

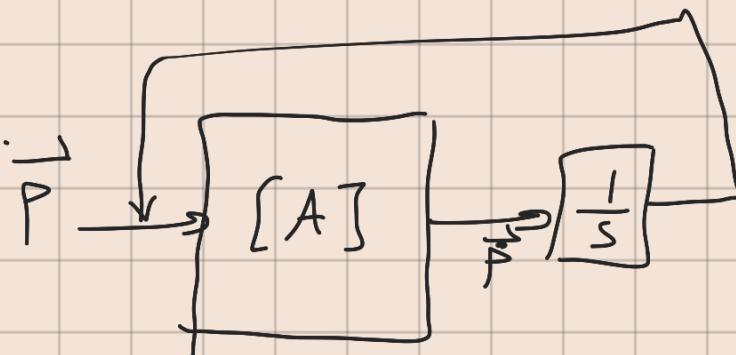
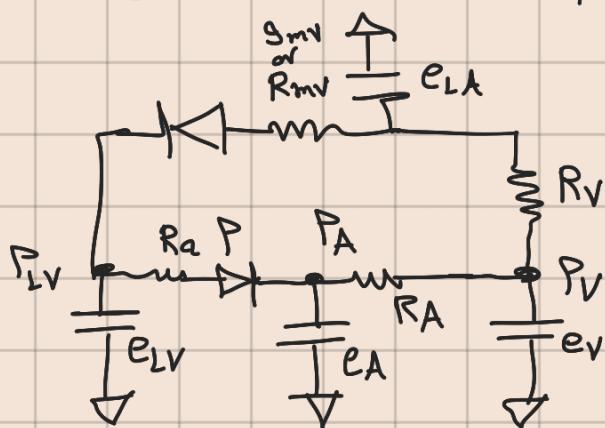
$$\begin{bmatrix} \dot{\bar{P}}_{LV} \\ \dot{\bar{P}}_{AO} \\ \dot{\bar{P}}_V \\ \dot{\bar{P}}_{LA} \end{bmatrix} = \begin{bmatrix} a_1 & a_2 & a_3 & a_u \\ b_1 & b_2 & b_3 & b_u \\ c_1 & c_2 & c_3 & c_u \\ d_1 & d_2 & d_3 & d_u \end{bmatrix} \begin{bmatrix} \bar{P}_{LV} \\ \bar{P}_{AO} \\ \bar{P}_V \\ \bar{P}_{LA} \end{bmatrix}$$

this is matrix format that can show us

$$\dot{\bar{P}} = [A] \bar{P}$$

so hole system made up by 4 unknown

and the constant one is
the resistance and the
other constant is
the elasticity e



method called state-space analysis

second order case

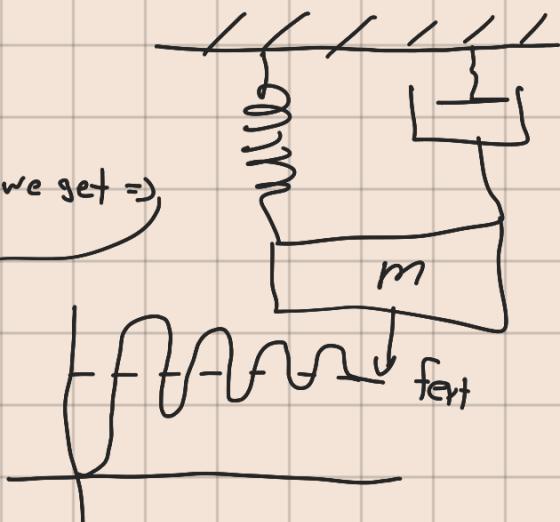
$$F_m + F_d + F_K = F_{ext}$$

for balance

$$m\ddot{x} + b\dot{x} + Kx = F_{ext} \quad \text{solving eq we get} \Rightarrow$$

$$x(t) = A e^{-\beta w_n t} \cos(\omega_n t + \theta)$$

$$w_n = \sqrt{\frac{K}{m}} \quad \beta = \frac{b}{2m} \quad \omega_n = w_n \sqrt{1 - \beta^2}$$



to solve this equation in different method go to
fundamental rule of Algebre

any n^{th} order equation is equivalent to the product of
 n 1^{st} order equation

$$\text{Ex: } ax^2 + bx + c = 0$$

$$(x - x_1)(x - x_2) = 0$$

$$x = x_1 \quad x = x_2$$

we can do same think to

$$\ddot{x} + 2\zeta w_n \dot{x} + w_n^2 x = 0$$

$$s^2 X(s) + 2\zeta w_n s X(s) + w_n^2 X(s) = 0$$

$$\frac{1}{X(s)}$$

$$s^2 + 2\zeta w_n s + w_n^2$$

$$(s - s_1)(s - s_2) = 0$$

in laplace domain we turn differential equation to
algebra equation

so how to solve this equation $m\ddot{x} + b\dot{x} + Kx = f_{\text{ext}}$

using fundamental algebre

$$\frac{m\ddot{x}}{m} + \frac{b\dot{x}}{m} + \frac{Kx}{m} = \frac{1}{m} f_{\text{ext}} \Rightarrow$$

$$\ddot{x} + \frac{b}{m} \dot{x} + \frac{K}{m} x = \frac{1}{m} f_{\text{ext}}$$

try to expressed as
 2^{nd} order differential
equation Product of
 2^{nd} order eq.

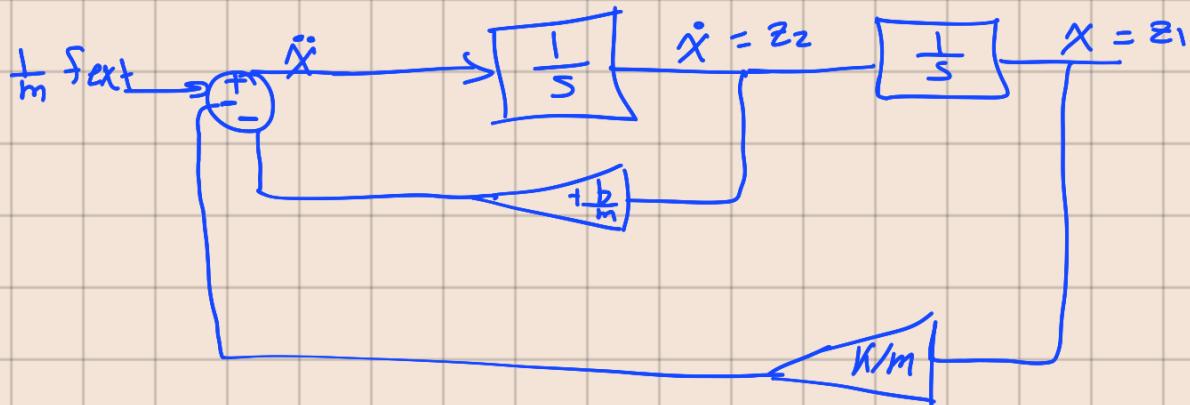
$$\frac{b}{m} = 2\zeta w_n$$

$$\frac{K}{m} = w_n^2$$

$$\ddot{x} + 2\zeta w_n \dot{x} + w_n^2 x = \frac{1}{m} f_{\text{ext}}$$

$$\ddot{x} = -\frac{k}{m}x - \frac{b}{m}\dot{x} + \frac{1}{m}f_{ext}$$

Change of Variables $\rightarrow x \rightarrow z$



$$\text{if } x = z_1 \Rightarrow \dot{x} = \dot{z}_1 \rightarrow \ddot{x} = \ddot{z}_1$$

$$\dot{x} = z_2 \rightarrow \ddot{x} = \dot{z}_2$$

$$\ddot{x} = -\frac{k}{m}x - \frac{b}{m}\dot{x} + \frac{1}{m}f_{ext}$$

$$\dot{z}_2 = -\frac{k}{m}z_1 - \frac{b}{m}z_2 + \frac{1}{m}f_{ext}$$

$$\dot{z}_1 = z_2 \quad \vec{\dot{z}} = [A] \vec{z}$$

$$\dot{z}_1 = 0z_1 + 1z_2 + 0f_{ext}$$

$$\dot{z}_2 = -\frac{k}{m}z_1 - \frac{b}{m}z_2 + \frac{1}{m}f_{ext}$$

$$\begin{bmatrix} \dot{z}_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{b}{m} \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{1}{m} \end{bmatrix} f_{ext}$$

$$\begin{bmatrix} \vec{z} \end{bmatrix} = \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} z \end{bmatrix} + \begin{bmatrix} B \end{bmatrix} f_{ext}$$

$$\vec{z} = Az + Bu$$

\uparrow
nonhomogeneous

$$y = -ay + b$$

$$\dot{P} = [A]P + [B]U$$

in order to solve the system ohm's KCL
capacity

but for the Left Ventrical the capacity will gonna
have tricke

$$\text{volume } \leftarrow V = CP$$

$$\dot{V} = C \dot{P}$$

$$q = C \dot{P}$$

$$\dot{P} = \frac{1}{C} q$$

$$q \downarrow \frac{1}{C}$$

$$c = \frac{1}{C}$$

$$\dot{P} = cq$$

so in the left ventrical you have problem

that capacitance not constant for all other nodes
the capacitance is constant but for the Left Ventrical
C will not be constant

$$\dot{P} = cq$$

$c = \frac{1}{C} \rightarrow$ remember the elasty changes

by the time



so you have $c_{LV}(t)$ for

LV

$$V_{LV}(t) = c_{LV}(t) P_{LV}(t)$$

$$\dot{V}(t) = \ddot{c}_{LV} P_{LV} + c_{LV} \dot{P}$$

so that will complicate your midirm exam

$$\dot{V} \Rightarrow q_{LV}$$

$$P_{LV} = \frac{1}{c_{LV}} V_{LV}$$

$$P_{LV} = c_{LV} V_{LV}$$

$$\dot{P}_{LV} = \ddot{c}_{LV} V_{LV} + c_{LV} \dot{V}_{LV}$$

$$\dot{P}_{LV} = \frac{\dot{c}_{LV}}{c_{LV}} P_{LV} + c_{LV} q_{LV}$$

Since $e_{LV} V_{LV} = P_{LV}$

$$V_{LV} = \frac{P_{LV}}{e_{LV}}$$

