

MAT1320-Linear Algebra Lecture Notes

Matrices

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A matrix A over a field K or, simply, a matrix A (when K is implicit) is a rectangular array of scalars usually presented in the following form:

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$$

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The rows of such a matrix A are the m horizontal lists of scalars:

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and the columns of A are the n vertical lists of scalars:

$$\begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{pmatrix}, \dots, \begin{pmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{pmatrix}$$

Note that the element a_{ij} , called the ij-entry or ij-element, appears in row i and column j. We frequently denote such a matrix by simply writing $A = [a_{ij}]$.

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- A matrix with m rows and n columns is called an m by n matrix, written m × n. The pair of numbers m and n is called the size of the matrix.
- Two matrices A and B are equal, written A = B, if they have the same size and if corresponding elements are equal. Thus, the equality of two $m \times n$ matrices is equivalent to a system of mn equalities, one for each corresponding pair of elements.

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- Matrices whose entries are all real numbers are called real matrices and are said to be matrices over R.
- Analogously, matrices whose entries are all complex numbers are called complex matrices and are said to be matrices over
 C. This text will be mainly concerned with such real matrices.

Example

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$$\begin{pmatrix}1\\3\end{pmatrix},\begin{pmatrix}2\\1\end{pmatrix},\begin{pmatrix}3\\2\end{pmatrix}.$$

Example

The 2 × 4 zero matrix is the matrix $0 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$.

Find
$$x, y, z, t$$
 such that $\begin{pmatrix} x+y & 3z+t \\ x-y & z-t \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}$.

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Solving the above system of equations yields

$$x = 3$$
, $y = -1$, $z = 1$ and $t = -2$.

Matrix Addition and Scalar

Multiplication

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$$A + B = \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{pmatrix}.$$

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- Observe that A + B and kA are also $m \times n$ matrices.
- We also define -A = (-1) A and A B = A + (-1) B. The matrix -A is called the negative of the matrix A, and the matrix A B is called the difference of A and B.

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- We also define -A = (-1)A and A B = A + (-1)B. The matrix -A is called the negative of the matrix A, and the matrix A B is called the difference of A and B.
- The sum of matrices with different sizes is not defined.

Let
$$A = \begin{pmatrix} 1 & -2 & 3 \\ 0 & 4 & 5 \end{pmatrix}$$
 and $B = \begin{pmatrix} 4 & 6 & 8 \\ 1 & -3 & -7 \end{pmatrix}$.

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Example

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$$3A = \begin{pmatrix} 3(1) & 3(-2) & 3(3) \\ 3(0) & 3(4) & 3(5) \end{pmatrix}$$

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$$= \begin{pmatrix} -10 & -22 & -18 \\ -3 & 17 & 31 \end{pmatrix}$$

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$$\bullet \quad 1 \cdot A = A$$

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$$\sum_{k=1}^{n} f(k) = f(1) + f(2) + \ldots + f(n).$$

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- The letter *k* is called the index, and 1 and *n* are called, respectively, the lower and upper limits.
- We also generalize our definition by allowing the sum to range from any integer n_1 to any integer n_2 . That is, we define

$$\sum_{k=n_1}^{n_2} f(k) = f(n_1) + f(n_1+1) + f(n_1+2) + \dots + f(n_2)$$

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5.
$$\sum_{k=1}^{p} a_{ik} b_{kj} = a_{i1} b_{1j} + a_{i2} b_{2j} + a_{i3} b_{3j} + \dots + a_{ip} b_{pj}$$

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- The product AB of a row matrix $A = [a_i]$ and a column matrix $B = [b_i]$ with the same number of elements is defined to be the scalar (or 1×1 matrix) obtained by multiplying corresponding entries and adding; that is,

$$AB = \begin{pmatrix} a_1 & a_2 & \dots & a_n \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

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■ The product *AB* is not defined when *A* and *B* have different numbers of elements.

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2.
$$\begin{pmatrix} 6 & -1 & 8 & 3 \end{pmatrix} \begin{pmatrix} 4 \\ -9 \\ -2 \\ 5 \end{pmatrix} = 24 + 9 - 16 + 15 = 32.$$

Example

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 $\begin{pmatrix} 3 \\ 2 \\ -1 \end{pmatrix} = 7(3) + (-4)(2) + 5(-1) = 21 - 8 - 5 = 8.$

2.
$$\begin{pmatrix} 6 & -1 & 8 & 3 \end{pmatrix} \begin{pmatrix} 4 \\ -9 \\ -2 \\ 5 \end{pmatrix} = 24 + 9 - 16 + 15 = 32.$$

We are now ready to define matrix multiplication in general.

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$$\begin{pmatrix} a_{11} & \dots & a_{1p} \\ \vdots & \ddots & \vdots \\ a_{i1} & \dots & a_{ip} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mp} \end{pmatrix} \begin{pmatrix} b_{11} & \dots & b_{1j} & \dots & b_{1n} \\ \vdots & \dots & \vdots & \dots & \vdots \\ \vdots & \dots & \vdots & \dots & \vdots \\ b_{p1} & \dots & b_{pj} & \dots & b_{pn} \end{pmatrix} = \begin{pmatrix} c_{11} & \dots & c_{1n} \\ \vdots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & \dots & c_{mn} \end{pmatrix}$$

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The product AB is not defined if A is an $m \times p$ matrix and B is a $q \times p$ matrix, where $p \neq q$.

Find
$$AB$$
 where $A=\begin{pmatrix}1&3\\2&-1\end{pmatrix}$ and $B=\begin{pmatrix}2&0&-4\\5&-2&6\end{pmatrix}$.

Find
$$AB$$
 where $A = \begin{pmatrix} 1 & 3 \\ 2 & -1 \end{pmatrix}$ and $B = \begin{pmatrix} 2 & 0 & -4 \\ 5 & -2 & 6 \end{pmatrix}$.

Because A is 2×2 and B is 2×3 , the product AB is defined and AB is a 2×3 matrix.

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$$\begin{pmatrix} 2 \\ 5 \end{pmatrix}$$
, $\begin{pmatrix} 0 \\ -2 \end{pmatrix}$, $\begin{pmatrix} -4 \\ 6 \end{pmatrix}$ respectively.

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$$AB = \begin{pmatrix} 2+15 & 0-6 & -4+18 \\ . & . & . \end{pmatrix} = \begin{pmatrix} 17 & -6 & 14 \\ . & . & . \end{pmatrix}$$

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$$AB = \begin{pmatrix} 17 & -6 & 14 \\ 4-5 & 0+2 & -8-6 \end{pmatrix} = \begin{pmatrix} 17 & -6 & 14 \\ -1 & 2 & -14 \end{pmatrix}$$

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Note: The above example shows that matrix multiplication is not commutative that is, in general, $AB \neq BA$. However, matrix multiplication does satisfy the following properties.

Mehmet F. KÖROĞLU

Theorem

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- 3. (B+C)A = BA + CA (right distributive law),
- 4. k(AB) = (kA)B = A(kB), where k is a scalar.
- 5. We note that 0A = 0 and B0 = 0, where 0 is the zero matrix.

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- The next theorem lists basic properties of the transpose operation.

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Theorem

Let A and B be matrices and let k be a scalar. Then, whenever the sum and product are defined,

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- 2. $(kA)^T = kA^T$
- $3. \left(A^T\right)^T = A$
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We emphasize that, by (4), the transpose of a product is the product of the transposes, but in the reverse order.

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- Recall that not every two matrices can be added or multiplied.
 However, if we only consider square matrices of some given order n, then this inconvenience disappears.
- Specifically, the operations of addition, multiplication, scalar multiplication, and transpose can be performed on any $n \times n$ matrices, and the result is again an $n \times n$ matrix.

Example The following are square matrices of order 3:

Example

$$A = \begin{pmatrix} 1 & 2 & 3 \\ -4 & -4 & -4 \\ 5 & 6 & 7 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & -5 & 1 \\ 0 & 3 & -2 \\ 1 & 2 & -4 \end{pmatrix}$$

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The following theorem applies.

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Then diagonal of $A = \{1, -4, 7\}$ and Tr(A) = 1 - 4 + 7 = 4 diagonal of $B = \{2, 3, -4\}$ and Tr(B) = 2 + 3 - 4 = 1

$$Tr(A+B) = 3-1+3=5$$
, $Tr(2A) = 2-8+14=8$, $Tr(A^T) = 4$
 $Tr(AB) = 5+0-35=-30$, $Tr(BA) = 27-24-33=-30$

As expected from previous Theorem,

$$Tr(A+B) = Tr(A) + Tr(B), Tr(A^T) = Tr(A), Tr(2A) = 2Tr(A)$$

Furthermore, although $AB \neq BA$, the traces are equal.

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The n-square identity or unit matrix, denoted by I_n , or simply I, is the n-square matrix with 1 's on the diagonal and 0's elsewhere. The identity matrix I is similar to the scalar 1 in that, for any n-square matrix A

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For any scalar k, the matrix k I that contains k 's on the diagonal and 0 's elsewhere is called the scalar matrix corresponding to the scalar k. Observe that

$$(kI)A = k(IA) = kA$$

That is, multiplying a matrix A by the scalar matrix kI is equivalent to multiplying A by the scalar k

Example

The following are the identity matrices of orders 3 and 4 and the corresponding scalar matrices for k=5:

$$\left(\begin{array}{cccc}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right), \quad \left(\begin{array}{cccc}
1 & & & \\
& 1 & & \\
& & 1 & \\
& & & 1
\end{array}\right), \quad \left(\begin{array}{ccccc}
5 & 0 & 0 \\
0 & 5 & 0 \\
0 & 0 & 5
\end{array}\right), \quad \left(\begin{array}{ccccc}
5 & & & \\
& 5 & & \\
& & 5 & \\
& & & 5
\end{array}\right)$$

Powers of Matrices, Polynomials in

Matrices

Let A be an n -square matrix over a field K. Powers of A are defined as follows:

$$A^{2} = AA$$
, $A^{3} = A^{2}A$, ..., $A^{n+1} = A^{n}A$, ..., and $A^{0} = I$

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Polynomials in the matrix \boldsymbol{A} are also defined. Specifically, for any polynomial

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where the a_i are scalars in K, f(A) is defined to be the following matrix:

$$f(A) = a_0I + a_1A + a_2A^2 + \cdots + a_nA^n$$

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, $A^{3} = A^{2}A$, ..., $A^{n+1} = A^{n}A$, ..., and $A^{0} = I$

Polynomials in the matrix \boldsymbol{A} are also defined. Specifically, for any polynomial

$$f(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$$

where the a_i are scalars in K, f(A) is defined to be the following matrix:

$$f(A) = a_0I + a_1A + a_2A^2 + \cdots + a_nA^n$$

Note that f(A) is obtained from f(x) by substituting the matrix A for the variable x and substituting the scalar matrix a_0I for the scalar a_0 .

Let A be an n -square matrix over a field K. Powers of A are defined as follows:

$$A^{2} = AA$$
, $A^{3} = A^{2}A$, ..., $A^{n+1} = A^{n}A$, ..., and $A^{0} = I$

Polynomials in the matrix \boldsymbol{A} are also defined. Specifically, for any polynomial

$$f(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$$

where the a_i are scalars in K, f(A) is defined to be the following matrix:

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Note that f(A) is obtained from f(x) by substituting the matrix A for the variable x and substituting the scalar matrix a_0I for the scalar a_0 . If f(A) is the zero matrix, then A is called a zero or root

Example

Suppose
$$A = \begin{pmatrix} 1 & 2 \\ 3 & -4 \end{pmatrix}$$
. Then
$$A^2 = \begin{pmatrix} 1 & 2 \\ 3 & -4 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & -4 \end{pmatrix} = \begin{pmatrix} 7 & -6 \\ -9 & 22 \end{pmatrix} \text{ and }$$

$$A^3 = A^2 A = \begin{pmatrix} 7 & -6 \\ -9 & 22 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & -4 \end{pmatrix} = \begin{pmatrix} -11 & 38 \\ 57 & -106 \end{pmatrix}$$
 Suppose $f(x) = 2x^2 - 3x + 5$ and $g(x) = x^2 + 3x - 10$. Then

$$f(A) = 2\begin{pmatrix} 7 & -6 \\ -9 & 22 \end{pmatrix} - 3\begin{pmatrix} 1 & 2 \\ 3 & -4 \end{pmatrix} + 5\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 16 & -18 \\ -27 & 61 \end{pmatrix}$$
$$g(A) = \begin{pmatrix} 7 & -6 \\ -9 & 22 \end{pmatrix} + 3\begin{pmatrix} 1 & 2 \\ 3 & -4 \end{pmatrix} - 10\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Thus, A is a zero of the polynomial g(x)

A square matrix A is said to be invertible or nonsingular if there exists a matrix B such that

$$AB = BA = I$$

where I is the identity matrix. Such a matrix B is unique. That is, if $AB_1 = B_1A = I$ and $AB_2 = B_2A = I$ then

$$B_1 = B_1 I = B_1 (AB_2) = (B_1 A) B_2 = IB_2 = B_2$$

We call such a matrix B the inverse of A and denote it by A^{-1} . Observe that the above relation is symmetric; that is, if B is the inverse of A, then A is the inverse of B.

Example

Suppose that
$$A = \begin{pmatrix} 2 & 5 \\ 1 & 3 \end{pmatrix}$$
 and $B = \begin{pmatrix} 3 & -5 \\ -1 & 2 \end{pmatrix}$. Then
$$AB = \begin{pmatrix} 6-5 & -10+10 \\ 3-3 & -5+6 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
$$BA = \begin{pmatrix} 6-5 & 15-15 \\ -2+2 & -5+6 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Thus, A and B are inverses. It is known that AB = I if and only if BA = I. Thus, it is necessary to test only one product to determine whether or not two given matrices are inverses.

Now suppose A and B are invertible. Then AB is invertible and $(AB)^{-1}=B^{-1}A^{-1}$. More generally, if A_1,A_2,\ldots,A_k are invertible, then their product is invertible and

$$(A_1A_2...A_k)^{-1} = A_k^{-1}...A_2^{-1}A_1^{-1}$$

the product of the inverses in the reverse order.

?