

Polygon Colorization using Conditional UNet: Report and Insights

1 Hyperparameters

What was tried

- Learning rates: 1e-3, 5e-4, 1e-4 (best).
- Optimizers: Adam, AdamW (Adam yielded smoother convergence).
- Loss weights: L1-only, MSE-only, combo (L1: 1.0, MSE: 0.5 worked best).
- Dropout values: 0.0, 0.1, 0.25.
- Schedulers: ReduceLROnPlateau (chosen), CosineAnnealing.

Final Settings

Image Size:	256x256
Embedding Dim:	64
Batch Size:	16
Learning Rate:	1e-4
Loss:	L1 + 0.5 * MSE
Dropout:	0.1
Optimizer:	Adam
Scheduler:	ReduceLROnPlateau
Early Stopping:	15 epochs

Rationale: Final settings were chosen based on validation loss trends and visual outputs, considering sharpness, saturation, and boundary quality.

2 Architecture and Conditioning

Design Overview

- **Backbone:** A standard 4-level UNet with symmetric encoder-decoder pathways and skip connections. Each block is composed of two convolutional layers with batch normalization and ReLU activations (via a **DoubleConv** module).
- **Condition Injection:** The color label is passed through an `nn.Embedding` layer to obtain a 64-dimensional vector. This vector is broadcast spatially (to 64xHxW) and concatenated with the 1-channel grayscale input along the channel dimension, forming a 65-channel tensor.
- **Encoder Path:** The concatenated tensor is passed through:
 - Initial DoubleConv block (1 + 64 → 64 channels).
 - Downsampling layers with max pooling followed by DoubleConv blocks, with increasing channels: 64→128→256→512→1024.
- **Decoder Path:** Uses bilinear upsampling and skip connections from encoder. Each Up block merges feature maps from encoder and decoder before applying DoubleConv.
- **Output Layer:** A 1x1 convolution projects the final feature map (64 channels) to 3 output channels (RGB), followed by a sigmoid activation to constrain output values to [0, 1].
- **Dropout:** Applied in DoubleConv blocks to prevent overfitting, set at 0.1.

Ablations Explored

- **No conditioning:** Model always predicted the same color regardless of input, confirming the importance of label injection.
- **FiLM vs. Concatenation:** FiLM-based conditioning (Feature-wise Linear Modulation) was tested but underperformed compared to simple channel-wise concatenation of the embedding.
- **Upsampling methods:** Transposed convolution vs. bilinear interpolation showed no significant difference; bilinear was chosen for simplicity and parameter efficiency.

Ablations Explored

- **No conditioning:** Output lacked diversity; same input always produced one color.
- **Concat vs. FiLM:** Concatenation of embedding as spatial channel gave better results.
- **Bilinear vs. TransposeConv:** Both were similar; bilinear was used for simplicity.

3 Training Dynamics

Loss Curves

Both training and validation losses steadily decreased over epochs. Mild overfitting appeared after epoch 60 and was addressed using early stopping.

Qualitative Trends

- Early epochs: Output images were desaturated or patchy.
- Mid training: Colors became more vivid and edges more defined.
- Final model: Accurately filled polygons with correct colors.

Failure Modes and Fixes

- **Blurry edges:** Resolved using L1 loss.
- **Wrong colors:** Occurred when conditioning was not injected early enough in the model.
- **Output artifacts:** Reduced using dropout and data augmentation.

4 Key Learnings

- Conditional embeddings are effective; the model learned distinct outputs for the same shape with different input colors.
- UNet architecture is suitable for structured image generation and preserved polygon boundaries well.
- Embedding injection should occur early (in the first convolutional layer) to provide strong conditioning.
- Combining L1 and MSE loss yielded better visual fidelity than using either one alone.
- Data augmentation was essential for generalization, especially on rotated or flipped polygon shapes.

Conclusion

This project demonstrates that a Conditional UNet, when combined with simple color conditioning and a stable training setup, can produce high-quality polygon colorizations that generalize well across shapes and classes.