

## **Image Processing - I**

### **(AY: 2022 - 2023)**

#### **References:**

- A. R. C. Gonzalez and R. E. Woods: Digital Image Processing, Prentice Hall, 2018.
- B. Maria Petrou and Costas Petrou: Image Processing: The Fundamentals, John Wiley & Sons, Ltd, 2010.
- C. B. Chanda and D. Dutta Majumder: Digital Image Processing and Analysis, Prentice Hall of India, New Delhi, 2000.
- D. A. Rosenfeld and A. C. Kak; Digital Picture Processing, 2nd ed., (Vol. 1 and 2), Academic Press, New York, 1982.
- E. Maria Petrou and Sei-ichiro Kamata: Image Processing: Dealing with Texture, John Wiley & Sons, Ltd, 2021.

<b>Topics</b>	<b>Sub-topics</b>	<b>References</b>	<b>Lectures</b>
Introduction	Definition of an image Image processing to computer vision History of digital image processing Applications of digital image processing Key stages in digital image processing	A, Ch. 1	2
Image formation	Digital image acquisition Image formation model Digitization - sampling and quantization Three way representation of digital images Dynamic range and image contrast	A, Ch. 2	2
	Resolution of an image Spatial and intensity resolution Isopreference curve	A, Ch. 2	1
	Operator for image processing Point spread function and its properties Stacking operator Separable transform	B, Ch. 1	1
Enhancement	Basics of intensity transformation and spatial filtering Neighbours of a pixel Enhancement - basics transformation functions Contrast stretching, intensity-level slicing, bit-plane slicing	A, Ch. 3	2
	Histogram, histogram equalisation	A, Ch. 3	2

	Histogram specification, local contrast enhancement	A, Ch. 3	2
	Noise in image Fundamental of spatial filtering Order-statistic / rank order filter - median, max, min, mid-point, mode, $\alpha$ -trimmed. Weighted versus unweighted filter	A B, Ch. 4.2	2
	Low-pass filtering High-pass filtering Linear spatial filtering Convolution and correlation Separable kernels	A	2
	Smoothing - box filter, Gaussian filter Weights of Gaussian filter	A, Ch. B, Ch. 4.2	2
	Sharpening Derivatives of a digital function Second-order derivative - Laplacian First-order derivative - Prewitt, Sobel	A, Ch.	2
Edge detection	Fundamental of segmentation Adjacency, connectivity, regions, boundaries Point and line detection	A, Ch. 10	2
	Edge detection Derivation of Sobel operators Non-maxima suppression	B, Ch. 6.2	2
	Linking edge points Local processing Global processing - Hough transform	A, Ch. 10	2
	Laplacian of Gaussian Marr-Hildreth algorithm for edge detection Difference of Gaussians	A, Ch. 10	2
	Canny edge detection algorithm Three criteria Derivative of Gaussians Hysteresis edge linking	A, Ch. 10 B, Ch. 6.2	2
Segmentation	Pixel classification Grey level thresholding Global/local thresholding Optimum thresholding - Bayes analysis	A, Ch. 10.3 B, Ch. 6.1	2
	Otsu thresholding Multiple thresholds	B, Ch. 6.1 A, Ch. 10.3	1

	Region growing, homogeneity property Region splitting and merging Quad tree, quad regions/images Top-down and bottom-up approaches	C	1
Compression	Image compression Predictive versus transform compression Lossy versus lossless compression RMSE, PSNR, error image Block truncation compression Huffman coding, transformed coding, run-length coding	C, Ch. 8	2
Color image processing	Primary and secondary colors Radiance, luminance, brightness Hue, saturation, intensity Chromaticity diagram, color gamut Color model: RGB, CMY, CMYK, HSI Conversion of one model to another	A, Ch. 6	2
	Information content of an image Multispectral images Principal component analysis Pseudo color, intensity slicing, smoothing, sharpening, segmentation	B, Ch. 7 A, Ch. 6	2
Registration	Image registration Monomodal, multimodal, modality to model Feature space, search space, search strategy Extrinsic versus intrinsic feature-based versus intensity-based Local versus global Local registration: tie points, transformation, interpolation Global registration: translation, scaling, rotation	D, Ch. 9	2
	Moments, central moments, principal axis Interpolation - bilinear Similarity metric: cross-correlation, sum of absolute differences, mutual information	D, Ch. 12	2
Image features	Texture - stationary versus non-stationary Rolling bins in histogram Gradient magnitude histogram Orientation histogram Run-length matrix	E	2
	Grey level co-occurrence matrix Haralick's textural features		2

	Local binary patterns, rotation invariant LBP Connected component labeling		
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### **Class Assignment [5]:**

Regular class assignments are available at [PDF Assignments.pdf](#)

### **Programming Assignment [10]:**

You may use any programming language to implement the following:

- Generate a histogram equalised image from a grayscale image.
- Perform 2-D convolution between a grayscale image and a 2-D kernel (such as box-filter, Gaussian filter, Laplacian, Prewitt and Sobel).
- Generate a two-tone image from a grayscale image using Otsu thresholding approach.
- For a color image, convert RGB to HSI and HSI to RGB.

### **Project Assignment [15]:**

Any paper related to image processing and published in IEEE-TIP, IEEE-TMI, IEEE-TPAMI or similar venue during the last 5-10 years may be considered for the project. The presentation of the project must highlight the following:

- Definition of the problem
- Objective of the work
- Algorithm(s)
- Implementation details
- Performance on benchmark data
- Conclusion and future direction

### **Important Dates:**

- ❖ The date of presentation of the project assignment is **April 27, 2023**.
- ❖ The deadline for the submission of all assignments is **April 28, 2023**.
- ❖ Please submit your assignment to **ipcourse.assignments@gmail.com**