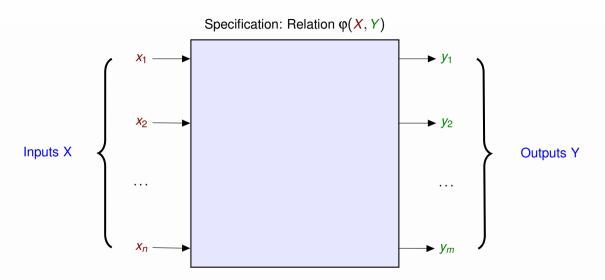
Engineering an Efficient Boolean Functional Synthesis Engine

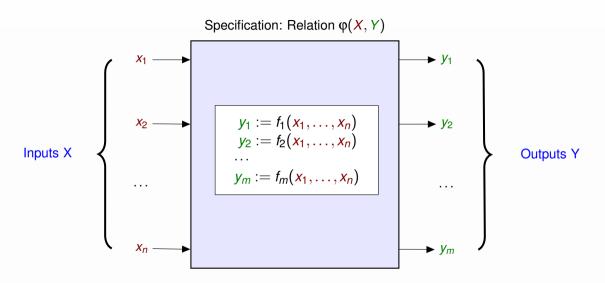
Priyanka Golia 1,2

Joint work with: Friedrich Slivovsky³, Subhajit Roy ¹, and Kuldeep S. Meel ²

¹ Indian Institute of Technology Kanpur ²National University of Singapore ³TU Wien

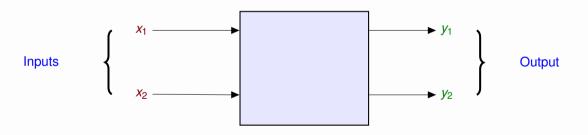
Corresponding Paper at ICCAD 2021





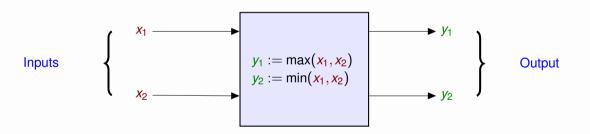
Synthesis – Example(I)

$$\phi(X,Y) = (y_1 \ge x_1) \land (y_1 \ge x_2) \land ((y_1 = x_1) \lor (y_1 = x_2)) \land (y_2 \le x_1) \land (y_2 \le x_2) \land ((y_2 = x_1) \lor (y_2 = x_2))$$



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Functional Synthesis

Given
$$\varphi(X, Y)$$
 over inputs $X = \{x_1, x_2, \dots, x_n\}$ and outputs $Y = \{y_1, y_2, \dots, y_m\}$.
Synthesize A function vector $F = \{f_1, f_2, \dots, f_m\}$, such that $y_i := f_i(x_1, \dots, x_n)$ such that:
$$\exists Y \varphi(X, Y) \equiv \varphi(X, F(X))$$

Each f_i is called Skolem function and F is called Skolem function vector.

Let
$$X = \{x_1, x_2\}, Y = \{y_1\}$$
 and $\varphi(X, Y) = x_1 \lor x_2 \lor y_1$

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Possible Skolem function: $f(x_1, x_2) := \neg(x_1 \lor x_2)$

$$\varphi(X,F(X))=x_1\vee x_2\vee (\neg(x_1\vee x_2))$$

| Χ | ∃ Y φ() | X , Y) | $\varphi(X, F(X))$ |
|--------------------|----------------|-----------------------|--------------------|
| $x_1 = 0, x_2 = 0$ | $y_1 = 1$ | True | True |
| $x_1 = 0, x_2 = 1$ | $y_1 = 1$ | True | True |
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| $x_1 = 1, x_2 = 1$ | $y_1 = 1$ | True | True |

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| X | ∃ <i>Y</i> φ(<i>)</i> | (, Y) | $\varphi(X, F(X))$ | |
|---|------------------------|------------------------------|------------------------------|---|
| $x_1 = 0, x_2 = 0$ $x_1 = 0, x_2 = 1$ $x_1 = 1, x_2 = 0$ $x_1 = 1, x_2 = 1$ | $y_1 = 1$ $y_1 = 1$ | True True True True | True True True True | $ \exists Y \varphi(X,Y) \equiv \varphi(X,F(X)) $ |

Other possible Skolem functions: $f_1(x_1, x_2) = \neg x_1$ $f_1(x_1, x_2) = \neg x_2$ $f_1(x_1, x_2) = 1$

Diverse Approaches

• From the proof of validity of $\forall X \exists Y \varphi(X, Y)$

```
(Bendetti et al., 2005)
(Jussilla et al., 2007)
(Heule et al., 2014)
```

Quantifier instantiation in SMT solvers

```
(Barrett et al., 2015)
(Bierre et al., 2017)
```

Input-Output Separation

```
(Chakraborty et al., 2018)
```

Knowledge representation

```
(Kukula et al., 2000)
(Trivedi et al., 2003)
(Jiang, 2009)
(Kuncak et al., 2010)
(Balabanov and Jiang, 2011)
(John et al., 2015)
(Fried, Tabajara, Vardi, 2016,2017)
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```

Incremental determinization

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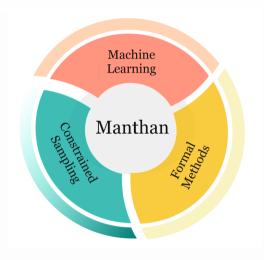
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Incremental determinization

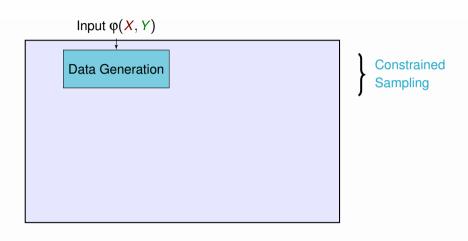
```
(Rabe et al., 2015, 2018, 2019)
```

Data-Driven Approach (Golia, Roy, Meel, 2020)

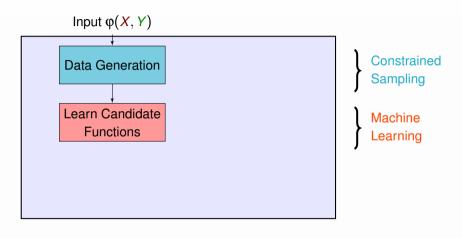
A Data-Driven Approach for Boolean Functional Synthesis

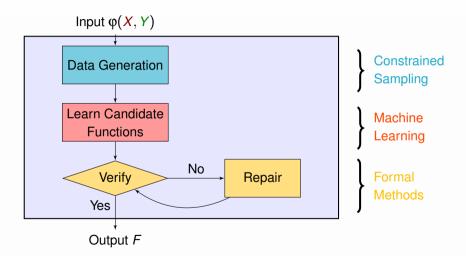


Manthan

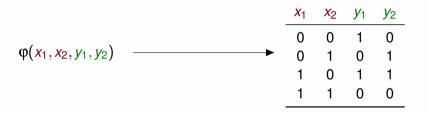


Manthan

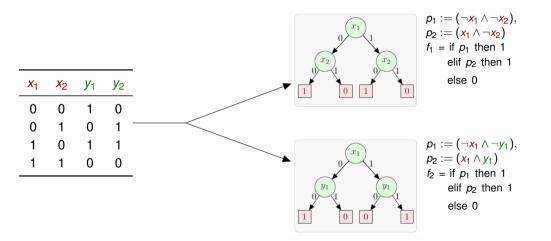




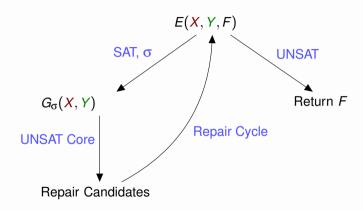
Data Generation



Learn Candidate Functions



Repair of Approximations



Manthan to Manthan2

Address scalability barriers faced by Manthan.

- Unique function extraction.
- Retention of Determined features.
- Clustering-based Multi-Classification.

Let
$$X = \{x_1, x_2\}, Y = \{y_1\} \text{ and } \phi(X, Y) = x_1 \lor x_2 \lor y_1$$

| <i>X</i> ₁ | <i>X</i> ₂ | <i>y</i> ₁ |
|-----------------------|-----------------------|-----------------------|
| 0 | 0 | 1 |
| 0 | 1 | 0/1 |
| 1 | 0 | 0/1 |
| 1 | 1 | 0/1 |

Let
$$X = \{x_1, x_2\}$$
, $Y = \{y_1\}$ and $\varphi(X, Y) = x_1 \lor x_2 \lor y_1$

| <i>x</i> ₁ | <i>X</i> ₂ | <i>y</i> ₁ |
|-----------------------|-----------------------|-----------------------|
| 0 | 0 | 1 |
| 0 | 1 | 0/1 |
| 1 | 0 | 0/1 |
| 1 | 1 | 0/1 |

 y_1 is not uniquely defined.

Let
$$X = \{x_1, x_2\}, Y = \{y_1\} \text{ and } \phi(X, Y) = ((x_1 \lor x_2) \leftrightarrow y_1))$$

| <i>x</i> ₁ | <i>X</i> ₂ | <i>y</i> ₁ |
|-----------------------|-----------------------|-----------------------|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

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|-----------------------|-----------------------|-----------------------|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

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| <i>X</i> ₁ | <i>X</i> ₂ | <i>y</i> ₁ |
|-----------------------|-----------------------|-----------------------|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

 y_1 is uniquely defined.

 y_i is uniquely defined: for a fixed valuation of X, valuation of y_i is fixed.

• Extract the Skolem function f_i using interpolation-based method.

Unique function extraction reduces the number of candidate functions to learn.

Determined features: Set of uniquely defined Y variables.

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Let
$$X = \{x_1, x_2\}, Y = \{y_1, y_2\}$$
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Determined features: Set of uniquely defined Y variables.

Let
$$X = \{x_1, x_2\}, Y = \{y_1, y_2\}$$
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• y_1 has unique function. $f_1 = (x_1 \lor x_2)$.

Determined features: Set of uniquely defined Y variables.

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- y_1 has unique function. $f_1 = (x_1 \lor x_2)$.
- Variable Elimination (suggested in Akshay et al., 2017,2018) $\phi(X,Y) = ((x_1 \lor x_2) \leftrightarrow (x_1 \lor x_2)) \land ((x_1 \lor x_2) \lor y_2)$

$$\varphi(X,Y)=((x_1\vee x_2)\vee y_2)$$

• Possible Skolem function $f_2 = \neg(x_1 \lor x_2)$.

Determined features: Set of uniquely defined Y variables.

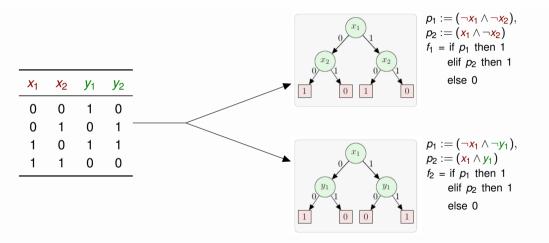
Let
$$X = \{x_1, x_2\}, Y = \{y_1, y_2\}$$
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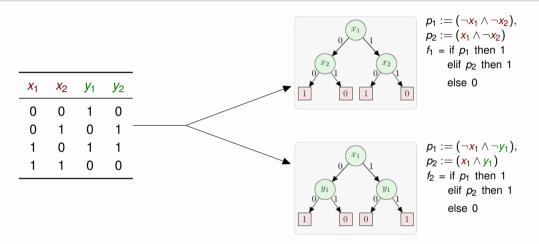
- y_1 has unique function. $f_1 = (x_1 \lor x_2)$.
- Variable Retention

$$\varphi(X,Y) = ((x_1 \vee x_2) \leftrightarrow y_1) \wedge (y_1 \vee y_2)$$

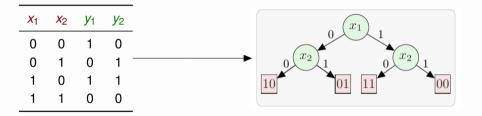
• Possible Skolem function $f_2 = \neg(y_1)$.

Retention of determined features helps to learn simpler candidate functions.





Can we learn functions for y_1 and y_2 together to save candidate learning time?



$$\begin{array}{ll} p_1 := (\neg x_1 \wedge \neg x_2), & p_1 := (\neg x_1 \wedge x_2), \\ p_2 := (x_1 \wedge \neg x_2) & p_2 := (x_1 \wedge \neg x_2), \\ f_1 = \text{if } p_1 \text{ then 1} & elif \ p_2 \text{ then 1} \\ & else \ 0 & else \ 0 \end{array}$$

- Partition *Y* variables with disjoint subsets.
- Use a multi-classifier to learn candidates for each partition.

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How should the variable partitioning be driven?

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How should the variable partitioning be driven?

Learn related variables together — lead to smaller decision tree.

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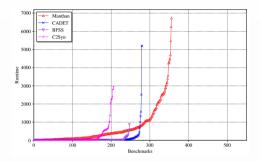
How should the variable partitioning be driven?

- Learn related variables together lead to smaller decision tree.
- Use edge(hop) distance in primal graph to cluster Y variables into disjoint subsets.

Experimental Evaluations

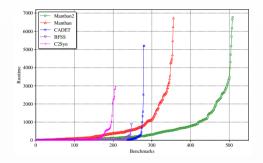
- 609 Benchmarks from:
 - QBFEval competition
 - Arithmetic
 - Disjunctive decomposition
 - Factorization
- Compared Manthan2 with State-of-the-art tools: Manthan (Golia et al., 2020), CADET (Rabe et al., 2019), BFSS (Akshay et al., 2018), C2Syn (Chakraborty et al., 2019).
- Timeout: 7200 seconds.

Experimental Evaluations



| C2Syn | BFSS | CADET | Manthan |
|-------|------|-------|---------|
| 206 | 247 | 280 | 356 |

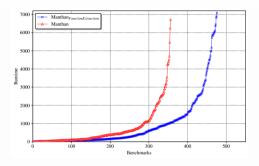
Experimental Evaluations



| C2Syn | BFSS | CADET | Manthan | Manthan2 |
|-------|------|-------|---------|----------|
| 206 | 247 | 280 | 356 | 509 |

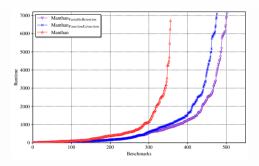
An increase of 153 benchmarks.

Impact of Individual Contribution



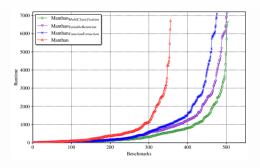
| Manthan | Manthan Function Extraction |
|---------|-----------------------------|
| 356 | 477 |
| 6374.39 | 3523.28 |

Impact of Individual Contribution



| 6374.39 3523.28 3227.11 | Manthan 356 6374.39 | Manthan _{FunctionExtraction} 477 3523.28 | Manthan _{VariableRetention} 502 3227.11 |
|--------------------------------|---------------------------|---|--|
|--------------------------------|---------------------------|---|--|

Impact of Individual Contribution



| Manthan 356 | Manthan _{FunctionExtraction} 477 | Manthan Variable Retention 502 | Manthan _{MultiClassification} 509 |
|----------------|---|--------------------------------|--|
| 6374.39 | 3523.28 | 3227.11 | 2858.61 |

Conclusion

Engineering an Efficient Boolean Functional Synthesis Engine

Vniqu

Unique function extraction

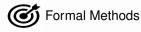
+ Variable Retention.

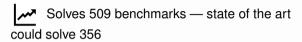


Constrained Sampling



Multi-Class Classifier







https://github.com/meelgroup/manthan