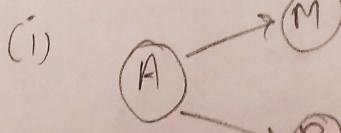


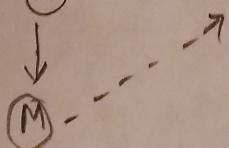
Question -1**Question : 1**

$$\begin{aligned}
 & P(\neg J, \neg M, \neg A, \neg E, \neg B) \\
 & = P(\neg B) \cdot P(\neg E) \cdot P(\neg A | \neg B, \neg E) \cdot P(\neg J | \neg A) \cdot P(\neg M | \neg A) \\
 & = 0.999 \times 0.998 \times 0.999 \times 0.95 \times 0.99 \\
 & = 0.936743
 \end{aligned}$$

Question -2**Question : 2**Alarm  $\rightarrow A$ Mary calls  $\rightarrow M$ Burglary  $\rightarrow B$ (ii) @ Node 1  $\rightarrow A$ (b) Node 2  $\rightarrow A \dashrightarrow M$ , parent(M) = A

$\because$  Mary agreed to call if she hears the Alarm, Mary calls or not depends on whether alarm happened or not.

$$\therefore P(M|A) \neq P(M)$$

(c) Node 3  $\rightarrow A \dashrightarrow B$  Parent(B) = A, M

$$P(B|A, M) = \frac{P(M|A, B) \cdot P(B|A)}{P(M|A)}$$

Given Alarm, Mary calls is independent of burglary. So,  $P(M|AB) = P(M|A)$

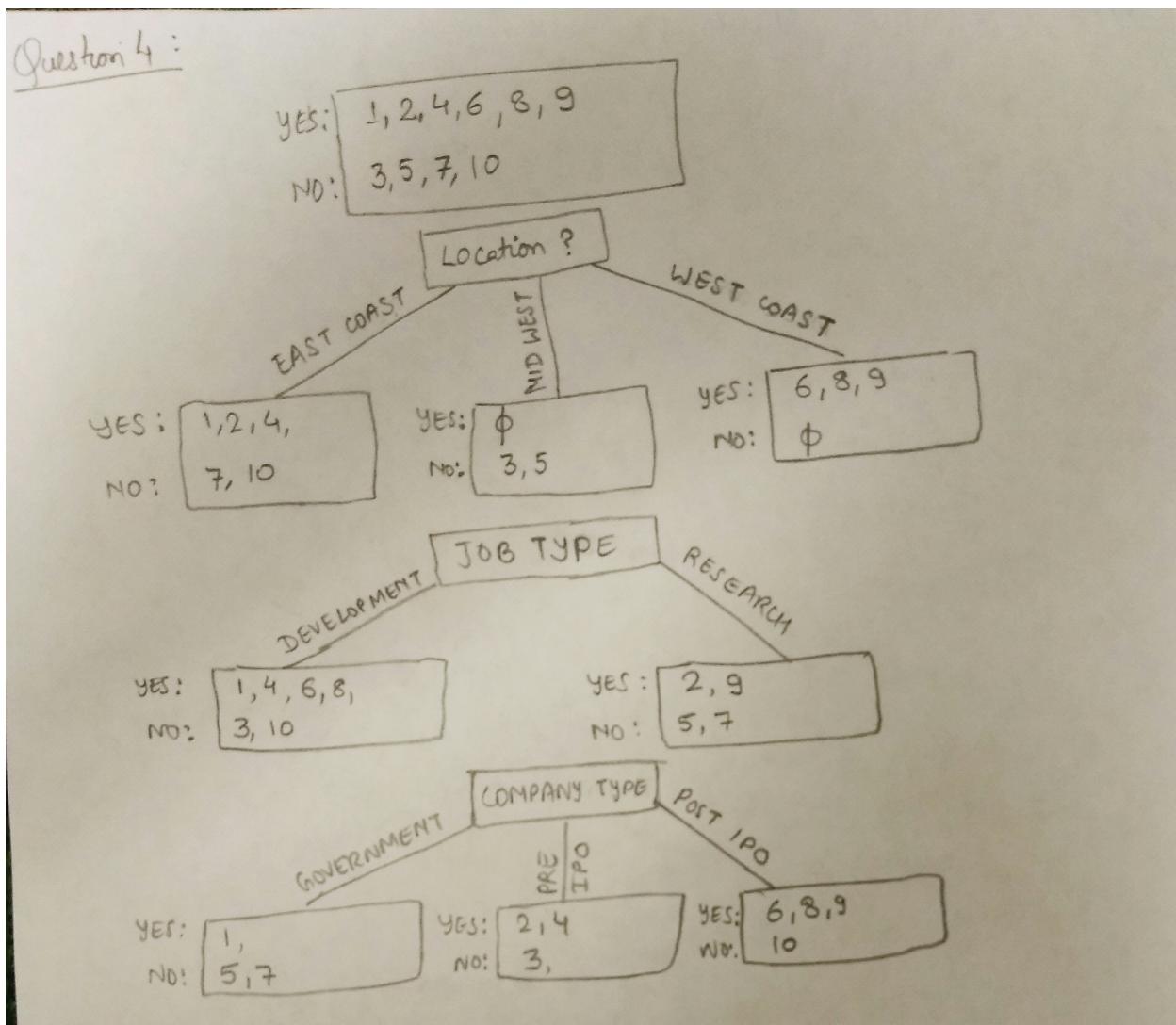
$$\Rightarrow P(B|AM) = P(B|A) \quad \therefore B \leftarrow A$$

### Question 3:

$$P(\text{Burglary} | \text{MaryCalls}) > P(\text{Burglary} | \text{MaryCalls, Earthquake})$$

Here, Burglary and Earthquake are causes and Marycalls is the effect. Although Earthquake and Burglary are independent of each other, the presence of one cause (Earthquake) makes the other (Burglary) unlikely. This phenomenon is called "explaining away" or Inter-causal inference. MaryCalls event depends on whether Alarm happened or not which in turn, depends on Burglary or Earthquake. So when it is known that Earthquake (cause II) and Marycalls (Effect) have happened, it is less likely that Burglary (cause I) has happened. However, when there is no detail on the occurrence of Earthquake, likelihood of Burglary given Marycalls is greater.

### Question 4:



**Question 5:**

Question 5.

$$\begin{aligned}
 P(\text{Yes}) &= 6/10 = 0.6 \\
 P(\text{No}) &= 4/10 = 0.4 \\
 \text{Entropy} &= -(0.6) \log(0.6) - (0.4) \log(0.4) \\
 &= 0.971 \\
 \text{Gain}(E, \text{Location}) &= 0.971 - \frac{5}{10} \left\{ -0.6 \log(0.6) - 0.4 \log(0.4) \right\} = 0 \\
 &= \frac{0.971}{2} = 0.4855 \\
 \text{Gain}(E, \text{Job type}) &= 0.971 - \frac{6}{10} \left\{ -\frac{4}{6} \log\left(\frac{4}{6}\right) - \frac{2}{6} \log\left(\frac{2}{6}\right) \right\} \\
 &\quad - \frac{4}{10} \left\{ -\frac{2}{4} \log\left(\frac{2}{4}\right) - \frac{2}{4} \log\left(\frac{2}{4}\right) \right\} \\
 &= 0.971 - 0.6 \times 0.918 - 0.4 \times 1 \\
 &= 0.0202 \\
 \text{Gain}(E, \text{Company type}) &= 0.971 - \frac{3}{10} \left\{ -\frac{1}{3} \log\left(\frac{1}{3}\right) - \frac{2}{3} \log\left(\frac{2}{3}\right) \right\} \\
 &\quad - \frac{3}{10} \left\{ -\frac{2}{3} \log\left(\frac{2}{3}\right) - \frac{1}{3} \log\left(\frac{1}{3}\right) \right\} - \frac{4}{10} \left\{ -\frac{3}{4} \log\left(\frac{3}{4}\right) - \frac{1}{4} \log\left(\frac{1}{4}\right) \right\} \\
 &= 0.971 - 0.3 \times 0.918 - 0.3 \times 0.918 - 0.4 \times 0.811 \\
 &= 0.0358
 \end{aligned}$$

**Question 6:**

'Location' attribute should be chosen first.

$$\text{Information Gain}(E, \text{attribute}) = \text{Entropy}(E) - \text{Entropy}(E/\text{attribute})$$

Information gain value is the mutual information of 'E' and 'attribute', i.e. the reduction in the entropy of 'E' achieved by learning the state of the random variable 'attribute'.

At each depth, we choose the attribute which most rapidly narrow down the state of 'E'. And so, attribute with highest mutual information is chosen first. In the above case, 'Location' has the highest entropy reduction (information gain) and so it will be chosen over 'Job Type' and 'Company Type'.

**Question 7:**

### Code:

```
from __future__ import division
import math

def calculate_entropy(sample):
    total = sample[0] + sample[1]
    result = 0
    for s in sample:
        val = s/total
        if val == 0: continue
        result += - (val)*math.log(val,2)

    return result

def information_gain(sample, sampleRes):
    total_entropy = calculate_entropy(sample)
    total = sample[0] + sample[1]

    result = 0
    gain = total_entropy

    for s in sampleRes:
        val = (s[0]+s[1])/total
        gain -= val*calculate_entropy(s)

    return gain

print('{:20s}'.format("Attribute") + "Information Gain")
print("=====")
print('{:20s}'.format("Location") + str(information_gain([6,4], [[3,2], [0,2], [3,0]])))
print('{:20s}'.format("Job Type") + str(information_gain([6,4], [[4,2], [2,2]])))
print('{:20s}'.format("Company Type") + str(information_gain([6,4], [[1,2], [5,2]])))
print
print ("Slide 07, Page 09")
print('{:20s}'.format("Attribute") + "Information Gain")
print("=====")
print('{:20s}'.format("Alternate") + str(information_gain([6,6], [[3,3], [3,3]])))
print('{:20s}'.format("Bar") + str(information_gain([6,6], [[3,3], [3,3]])))
print('{:20s}'.format("Fri/Sat") + str(information_gain([6,6], [[2,3], [4,3]])))
print('{:20s}'.format("Hungry") + str(information_gain([6,6], [[5,2], [1,4]])))
print('{:20s}'.format("Patrons") + str(information_gain([6,6], [[0,2], [4,0], [2,4]])))
print('{:20s}'.format("Price") + str(information_gain([6,6], [[3,4], [2,0], [1,2]])))
print('{:20s}'.format("Rain") + str(information_gain([6,6], [[2,2], [4,4]])))
print('{:20s}'.format("Reservation") + str(information_gain([6,6], [[3,2], [3,4]])))
print('{:20s}'.format("Type") +
str(information_gain([6,6], [[1,1], [1,1], [2,2], [2,2]])))
print('{:20s}'.format("Wait Estimate") +
str(information_gain([6,6], [[4,2], [1,1], [1,1], [0,2]])))
```

### Output:

Attribute	Information Gain
Location	0.485475297227
Job Type	0.019973094022
Company Type	0.0912774462417

Slide 07, Page 09

Attribute	Information Gain
-----------	------------------

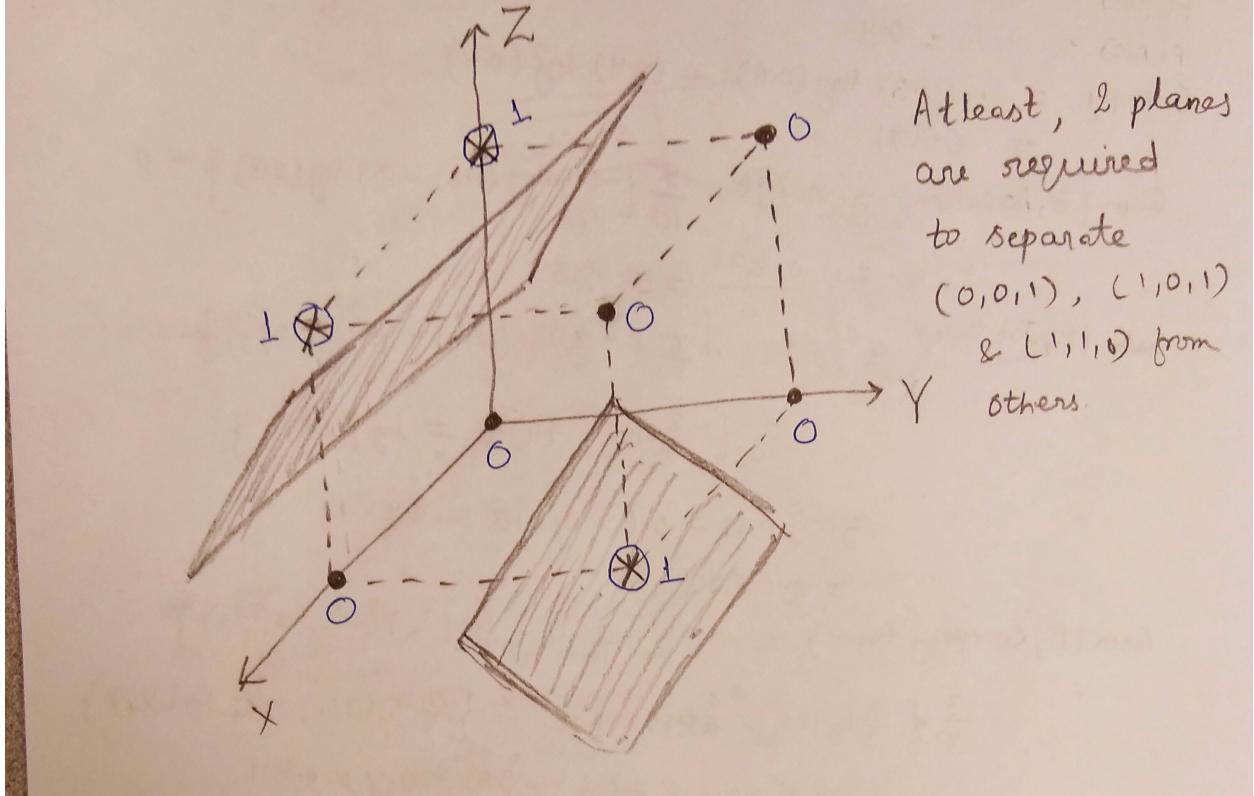
=====

Alternate	0.0
Bar	0.0
Fri/Sat	0.0207208396239
Hungry	0.1957096288
Patrons	0.540852082973
Price	0.1957096288
Rain	1.11022302463e-16
Reservation	0.0207208396239
Type	1.11022302463e-16
Wait Estimate	0.207518749639

**Question 8:**

- (1) No, a single perceptron unit cannot solve the following Classification problem.
- (2) As illustrated in the figure below, no single plane can be used to separate points  $\{(0,0,1), (1,0,1), (1,1,0)\}$  from points  $\{(0,0,0), (0,1,0), (0,1,1), (1,0,0), (1,1,1)\}$ .

Question 8:



- (3) As shown in figure above, no single plane exists which can separate points  $\{(0,0,1), (1,0,1), (1,1,0)\}$  from points  $\{(0,0,0), (0,1,0), (0,1,1), (1,0,0), (1,1,1)\}$ . We need atleast two planes to perform this classification.

The best single plane that can be found in this case will have 1 False Negative (top plane) i.e. point  $(1,1,0)$  will be misclassified.

**Question 9:**

**Code:**

```
import numpy as np
import random
import os, subprocess
import matplotlib.pyplot as plt
from matplotlib import animation

images = []

class Perceptron:
    def __init__(self, N):
        # Random linearly separated data
        xA,yA,xB,yB = [random.uniform(-1, 1) for i in range(4)]
        self.V = np.array([xB*yA-xA*yB, yB-yA, xA-xB])
```

```

        self.X = self.generate_points(N)

    def trainingDataAnd(self):
        t = 1.5
        self.V = np.array([t,1,1])
        X = []
        N = len(self.X)
        for i in range(N):
            x1, x2 = [random.uniform(-1, 1) for i in range(2)]
            x = np.array([1, x1, x2])
            if self.V.T.dot(x) >= 0:
                s = 1
            else:
                s = -1
            X.append((x, s))
        self.X = X

    def trainingDataOr(self):
        t = 0.5
        self.V = np.array([t,1,1])
        X = []
        N = len(self.X)
        for i in range(N):
            x1, x2 = [random.uniform(-1, 1) for i in range(2)]
            x = np.array([1, x1, x2])
            if self.V.T.dot(x) >= 0:
                s = 1
            else:
                s = -1
            X.append((x, s))
        self.X = X

    def trainingDataNot(self):
        t = -0.5
        self.V = np.array([t,-1,0])
        X = []
        N = len(self.X)
        for i in range(N):
            x1, x2 = [random.uniform(-1, 1) for i in range(2)]
            x = np.array([1, x1, x2])
            if self.V.T.dot(x) >= 0:
                s = 1
            else:
                s = -1
            X.append((x, s))
        self.X = X

    def DataXor(self):
        t = 0
        # self.V = np.array([t,-1,0])
        X = []
        N = len(self.X)
        for i in range(N):
            x1, x2 = [random.uniform(-1, 1) for i in range(2)]
            x = np.array([1, x1, x2])
            if (x1 >= 0 and x2 >= 0) or (x1 < 0 and x2 < 0):
                s = -1
            else:
                s = 1
            X.append((x, s))
        self.X = X

```

```

def generate_points(self, N):
    X = []
    for i in range(N):
        x1,x2 = [random.uniform(-1, 1) for i in range(2)]
        x = np.array([1,x1,x2])
        s = int(np.sign(self.V.T.dot(x)))
        X.append((x, s))
    return X

def plot(self, mispts=None, vec=None, save=False):
    fig = plt.figure(figsize=(5,5))
    plt.xlim(-1,1)
    plt.ylim(-1,1)
    V = self.V
    a, b = -V[1]/V[2], -V[0]/V[2]
    l = np.linspace(-1,1)
    plt.plot(l, a*l+b, 'k-')
    cols = {1: 'r', -1: 'b'}
    for x,s in self.X:
        plt.plot(x[1], x[2], cols[s] + 'o')
    if mispts:
        for x,s in mispts:
            plt.plot(x[1], x[2], cols[s] + '.')
    if vec != None:
        aa, bb = -vec[1]/vec[2], -vec[0]/vec[2]
        plt.plot(l, aa*l+bb, 'g-', lw=2)
    if save:
        if not mispts:
            plt.title('N = %s' % (str(len(self.X))))
        else:
            plt.title('N = %s with %s test points' \
                      % (str(len(self.X)),str(len(mispts))))
        plt.savefig('p_N%s' % (str(len(self.X))), \
                    dpi=200, bbox_inches='tight')
    # plt.show()

def classification_error(self, vec, pts=None):
    # Error defined as fraction of misclassified points
    if not pts:
        pts = self.X
    M = len(pts)
    n_mispts = 0
    for x,s in pts:
        if int(np.sign(vec.T.dot(x))) != s:
            n_mispts += 1
    error = n_mispts / float(M)
    return error

def choose_miscl_point(self, vec):
    # Choose a random point among the misclassified
    pts = self.X
    mispts = []
    for x,s in pts:
        if int(np.sign(vec.T.dot(x))) != s:
            mispts.append((x, s))
    return mispts[random.randrange(0, len(mispts))]

def pla(self, save=False):
    # Initialize the weights to zeros
    w = np.zeros(3)

```

```

X, N = self.X, len(self.X)
it = 0
# Iterate until all points are correctly classified
while self.classification_error(w) != 0 and it <= 100:
    it += 1
    # Pick random misclassified point
    x, s = self.choose_miscl_point(w)
    # Update weights
    w += s*x
    if save:
        self.plot(vec=w)
        plt.title('N = %s, Iteration %s\n' \
                  % (str(N), str(it)))
        plt.savefig('p_N%s_it%s' % (str(N), str(it)), \
                    dpi=200, bbox_inches='tight')
        # images.append(plt)
    self.w = w

def check_error(self, M, vec):
    check_pts = self.generate_points(M)
    return self.classification_error(vec, pts=check_pts)

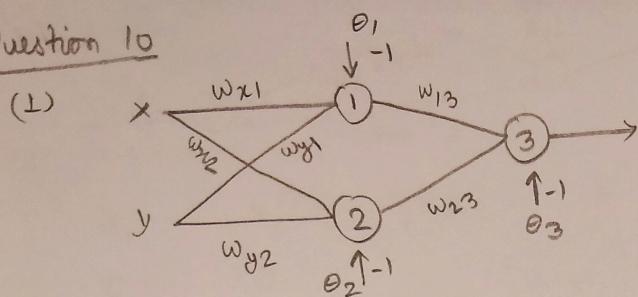
def plotXOR(pAnd, pNot, pOr, mispts=None, vec=None, save=False,):
    fig = plt.figure(figsize=(5, 5))
    plt.xlim(-1, 1)
    plt.ylim(-1, 1)
    if mispts:
        for x,s in mispts:
            val1 = np.sign(pNot.w[1] * (pAnd.w[1] * x[1] + pAnd.w[2] * x[2]))
            val2 = np.sign(pOr.w[1] * x[1] + pOr.w[2]*x[2])
            val3 = np.sign(pAnd.w[1]*val1 + pAnd.w[2]*val2)
            if val3 == s:
                plt.plot(x[1], x[2], 'ob')
            else:
                plt.plot(x[1], x[2], 'or')
    plt.title('N = %s, Iteration %s\n' \
              % (str(10), str(5)))
    plt.savefig('p_N%s_it%s' % (str(10), str(5)), \
                dpi=200, bbox_inches='tight')
    plt.show()

p = Perceptron(100)
p.trainingDataAnd()
p.pla(save=True)
p1 = Perceptron(100)
p1.trainingDataNot()
p1.pla(save=False)
p2 = Perceptron(100)
p2.trainingDataOr()
p2.pla(save=False)
pf = Perceptron(500)
pf.DataXor()
plotXOR(p,p1,p2,pf.X)
pf.pla(save=True)
p.plot(p.generate_points(500), p.w, save=True)
err = []
for i in range(100):
    err.append(p.check_error(500, p.w))
print(np.mean(err))

```

Question 10:

Question 10



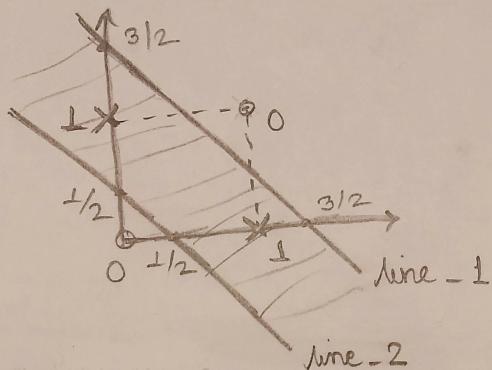
(2) Decision boundary

$$\text{line-1: } y < -x + 3/2$$

$$2x + 2y < 3$$

$$\text{line-2: } y > -x + 0.5$$

$$2x + 2y > 1$$



Question -11

$$E(w) = (w+1)(w-1)(w-3)(w-4)$$

$$= (w^2-1)(w^2-7w+12)$$

$$= w^4 - 7w^3 + 11w^2 + 7w - 12$$

$$\Delta w = -\frac{\partial E}{\partial w}$$

$$= -\alpha (4w^3 - 21w^2 + 22w + 7)$$

$$w_{t+1} = w_t + \Delta w_{t+1}$$

$$= w_t - \alpha (4w^3 - 21w^2 + 22w + 7)$$

Question 11: In image above

**Question 12:**

**Code:**

```
import matplotlib.pyplot as plt
w_old = 0
w = -2
step_size = 0.01
precision = 0.001

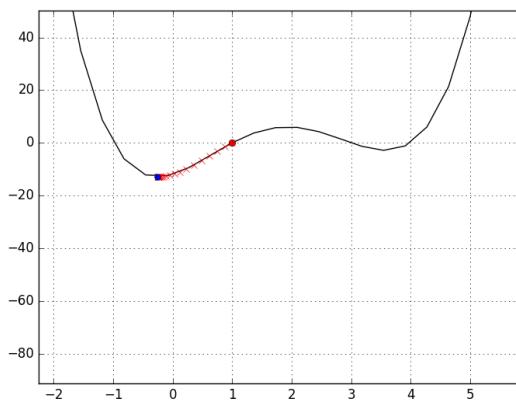
def f_derivative(x):
    return (4 * (x ** 3)) - (21 * (x ** 2)) + (22 * x) + 7

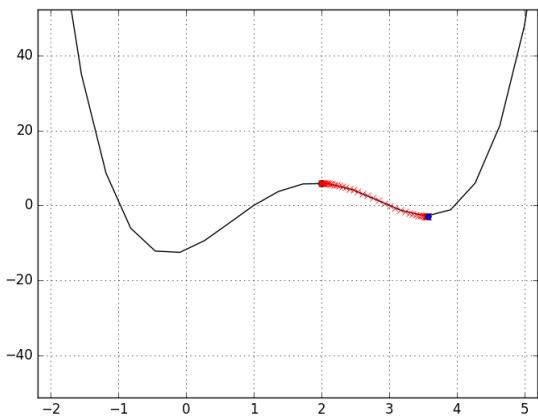
def fx(x):
    return (x+1)*(x-1)*(x-3)*(x-4)

xarr=[]
yarr=[]
while abs(w - w_old) > precision:
    w_old = w
    gradient = f_derivative(w_old)
    w_delta = gradient * step_size
    w = w_old - w_delta
    xarr.append(w_old)
    yarr.append(fx(w))
print xarr[:10]
plt.plot(xarr,yarr)
plt.ylabel('Error')
plt.xlabel('(w)')
plt.show()

print("Local minimum occurs at {}".format(round(w, 2)))
```

**Plots:**





### Question 13:

Iterations: 000,173    Learning rate: 0.03    Activation: Tanh    Regularization: None    Regularization rate: 0    Problem type: Classification

**DATA**  
Which dataset do you want to use?  
  

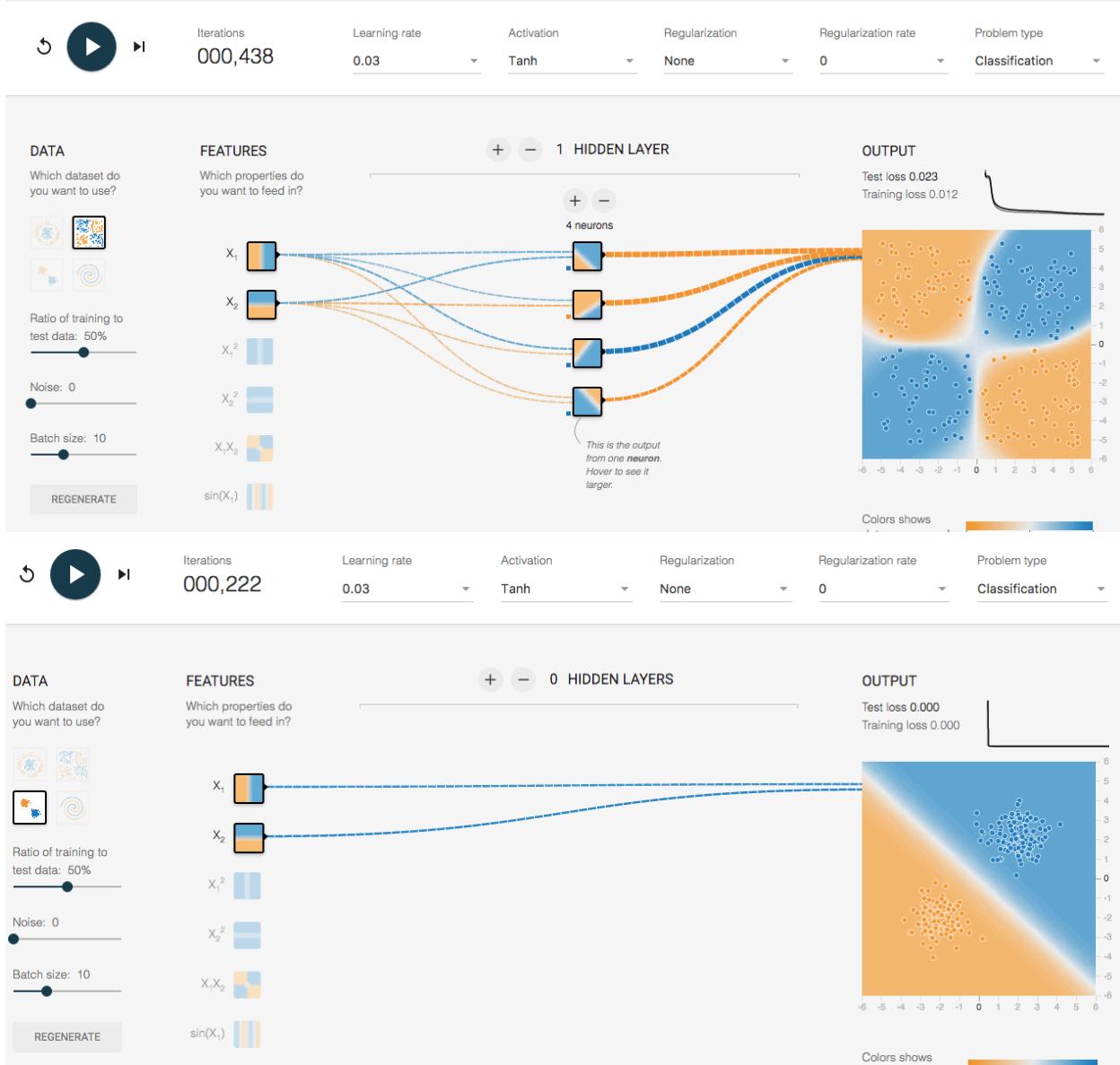
Ratio of training to test data: 50%  
Noise: 0  
Batch size: 10

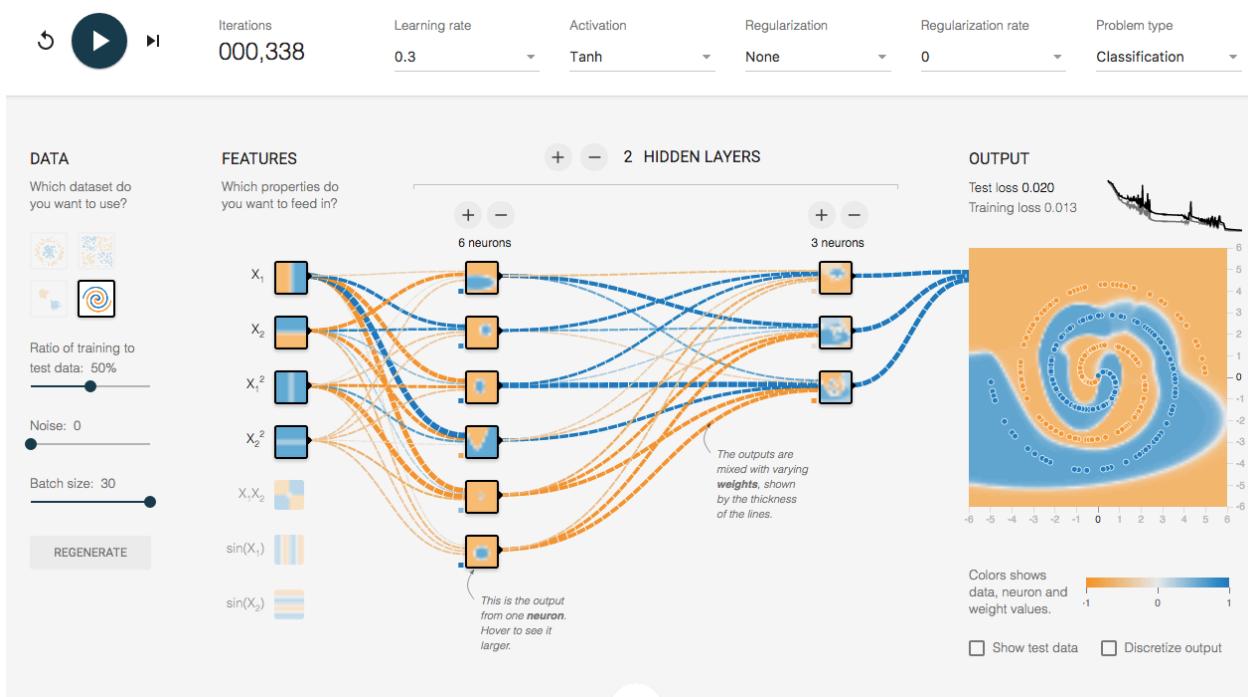
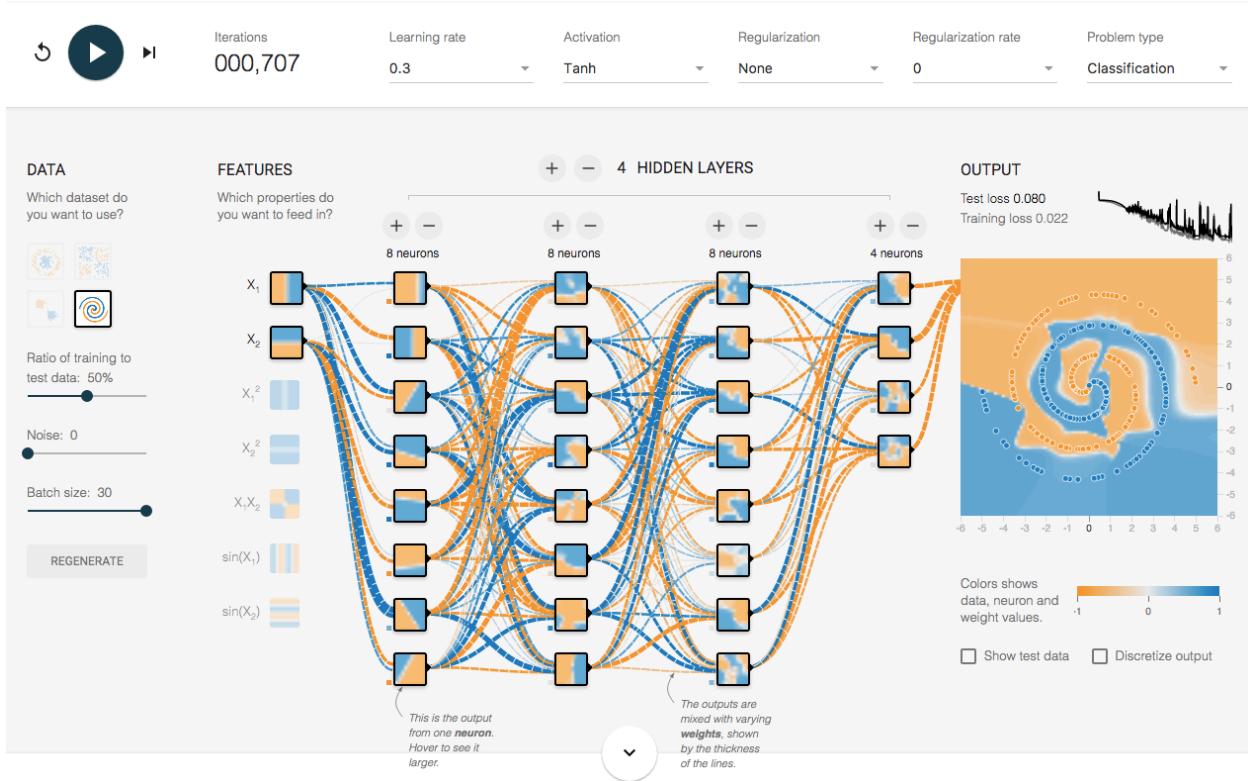
**FEATURES**  
Which properties do you want to feed in?  
 $X_1$    $X_2$    $X_1^2$    $X_2^2$    $X_1 X_2$  

**1 HIDDEN LAYER**  
+ - 3 neurons  
  
This is the output from one neuron. Hover to see it larger.

**OUTPUT**  
Test loss 0.033  
Training loss 0.019

REGENERATE    sin( $X_1$ ) 





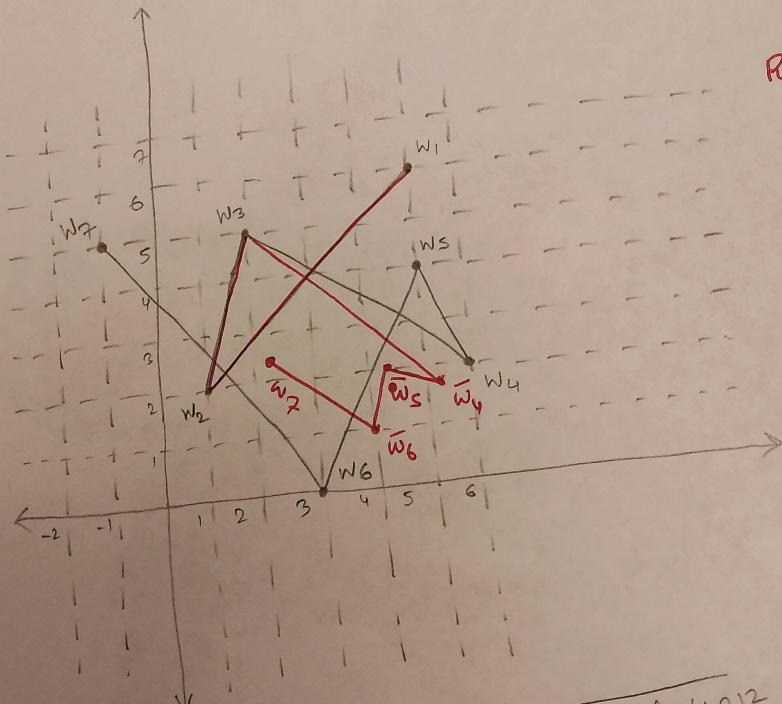
Question 15:

Question 15:  $\bar{w}_j \leftarrow \bar{w}_j + \eta h(j, i(\bar{w})) (\bar{w} - w_j)$

$$\begin{aligned} \text{(i)} \quad \eta &= 1 \\ \text{(ii)} \quad h(j, i(\bar{w})) &= 1 \quad \text{if } j = i(\bar{w}) \\ &= 2/3 \quad \text{if } j = i(\bar{w}) \pm 1 \\ &= 1/3 \quad \text{if } j = i(\bar{w}) \pm 2 \end{aligned}$$

	$\bar{w}_1$	$\bar{w}_2$	$\bar{w}_3$	$\bar{w}_4$	$\bar{w}_5$	$\bar{w}_6$	$\bar{w}_7$
$w_{i1}$	5	1	2	6	5	3	-1
$w_{i2}$	6	2	5	2	4	0	5

Red connections are new one.



$$\begin{aligned} \text{(iv)} \quad \bar{x} &= (4, 1) \\ \text{BMU} &= \arg\min \sqrt{(5-4)^2 + (6-1)^2} + \sqrt{(4-1)^2 + (1-2)^2} + \sqrt{(4-2)^2 + (5-1)^2} + \\ &\quad \sqrt{(6-4)^2 + (2-1)^2} + \sqrt{(5-4)^2 + (4-1)^2} + \sqrt{(4-3)^2 + (1-0)^2} + \sqrt{(0-1)^2 + (5-1)^2} \end{aligned}$$

$$\text{BMU} = \bar{w}_6$$

Iteration : 1  $\rightarrow$

$$\begin{aligned} \bar{w}_6 &\leftarrow (3, 0) + 1 \times 1 \times (4-3, 1-0) \\ &\Rightarrow \bar{w}_6 = (4, 1) \end{aligned}$$

$$\bar{w}_5 \leftarrow (5, 4) + 1 \times \frac{2}{3} \times (4-5, 1-4)$$

$$\Rightarrow \bar{w}_5 = \left( \frac{13}{3}, 2 \right) = (4.33, 2)$$

$$\bar{w}_7 \leftarrow (-1, 5) + 1 \times \frac{2}{3} \times (4+1, 1-5)$$

$$\Rightarrow \bar{w}_7 = \left( \frac{7}{3}, \frac{7}{3} \right) = (2.33, 2.33)$$

$$\bar{w}_4 \leftarrow (6, 2) + 1 \times \frac{1}{3} \times (4-6, 1-2)$$

$$\Rightarrow \bar{w}_4 = \left( \frac{16}{3}, \frac{5}{3} \right) = (5.33, 1.66)$$

$\bar{w}_1, \bar{w}_2$  and  $\bar{w}_3$  will not change as  $h(j, i(x)) = 0$

if  $\{j > i(n) \pm 2\}$

New weights.

	$w_1$	$w_2$	$w_3$	$w_4$	$w_5$	$w_6$	$w_7$
$w_{i1}$	5	1	2	5.33	4.33	4	2.33
$w_{i2}$	6	2	5	1.66	2	1	2.33