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EE 559

HW #5

- Q.2)
- $\{0, 1, -1, 2\} \in S_1$
 - $\{(1, 1, 1, 1), (2, 1, 1, 1)\} \in S_2$
 - $\{(-1, 1, 0, -1)\} \in S_3$

Using augmented space,

Given weights $w^{(1)}(0) = -1$

$$w^{(2)}(0) = 1$$

$$w^{(3)}(0) = 0$$

$\therefore w_1(0) = (-1, -1, -1, -1, -1)$

$w_2(0) = (1, 1, 1, 1, 1)$

$w_3(0) = (0, 0, 0, 0, 0)$

Decision Rule:

$x \in S_1 \text{ iff } g_1(x) > g_2(x) \text{ & } g_1(x) > g_3(x)$

$x \in S_2 \text{ iff } g_2(x) > g_1(x) \text{ & } g_2(x) > g_3(x)$

$x \in S_3 \text{ iff } g_3(x) > g_1(x) \text{ & } g_3(x) > g_2(x)$

$$g_k(x) = \omega_k^T x$$

$$x_1 = (1, 0, 1, -1, 2)$$

$$g_1(x) = -3$$

$$\omega_1(1) = \omega_1(0) + x_1$$

$$g_2(x) = 3$$

$$= (0, -1, 0, -2, 1)$$

$$g_3(x) = 0$$

$$\omega_2(2) = \omega_2(0) - x_1$$

$$= (0, 1, 0, 2, -1)$$

$$\omega_3(1) = \omega_3(0)$$

$$= (0, 0, 0, 0, 0)$$

$$x_2 = (1, 1, 1, 1, 1)$$

$$g_1(x) = -2$$

$$\omega_1(2) = \omega_1(1)$$

$$g_2(x) = 2$$

$$= (0, -1, 0, -2, 1)$$

$$g_3(x) = 0$$

$$\omega_2(2) = \omega_2(1)$$

$$= (0, 1, 0, 2, -1)$$

$$\omega_3(2) = (0, 0, 0, 0, 0)$$

$$x_3 = (1, 2, 1, 1, 1)$$

$$g_1(x) = -3$$

$$\omega_1(3) = \omega_1(2)$$

$$g_2(x) = 3$$

$$= (0, -1, 0, -2, 1)$$

$$g_3(x) = 0$$

$$\omega_2(3) = \omega_2(2)$$

$$= (0, 1, 0, 2, -1)$$

$$\omega_3(3) = \omega_3(2) = (0, 0, 0, 0, 0)$$

$$x_3 = (1, -1, 1, 0, -1)$$

$$g_1(x) = 0$$

$$w_3(3) = w_3(2) + y_3$$

$$g_2(x) = 0$$

$$= (1, -1, 1, 0, -1)$$

$$g_3(x) = 0$$

$$w_2(4) = w_2(3) - y_3$$

$$= (-1, 2, -1, 2, 0)$$

$$w_3(4) = (0, -1, 0, -2, 1)$$

Discriminant func"

$$g_1(x) = -x_1 - 2x_2 + x_3$$

$$g_2(x) = -1 + 2x_1 - x_2 + 2x_3$$

$$g_3(x) = 1 - x_1 + x_2 - x_4$$

$$b) \underline{x} = (1, x_1, x_2, 0, 0)$$

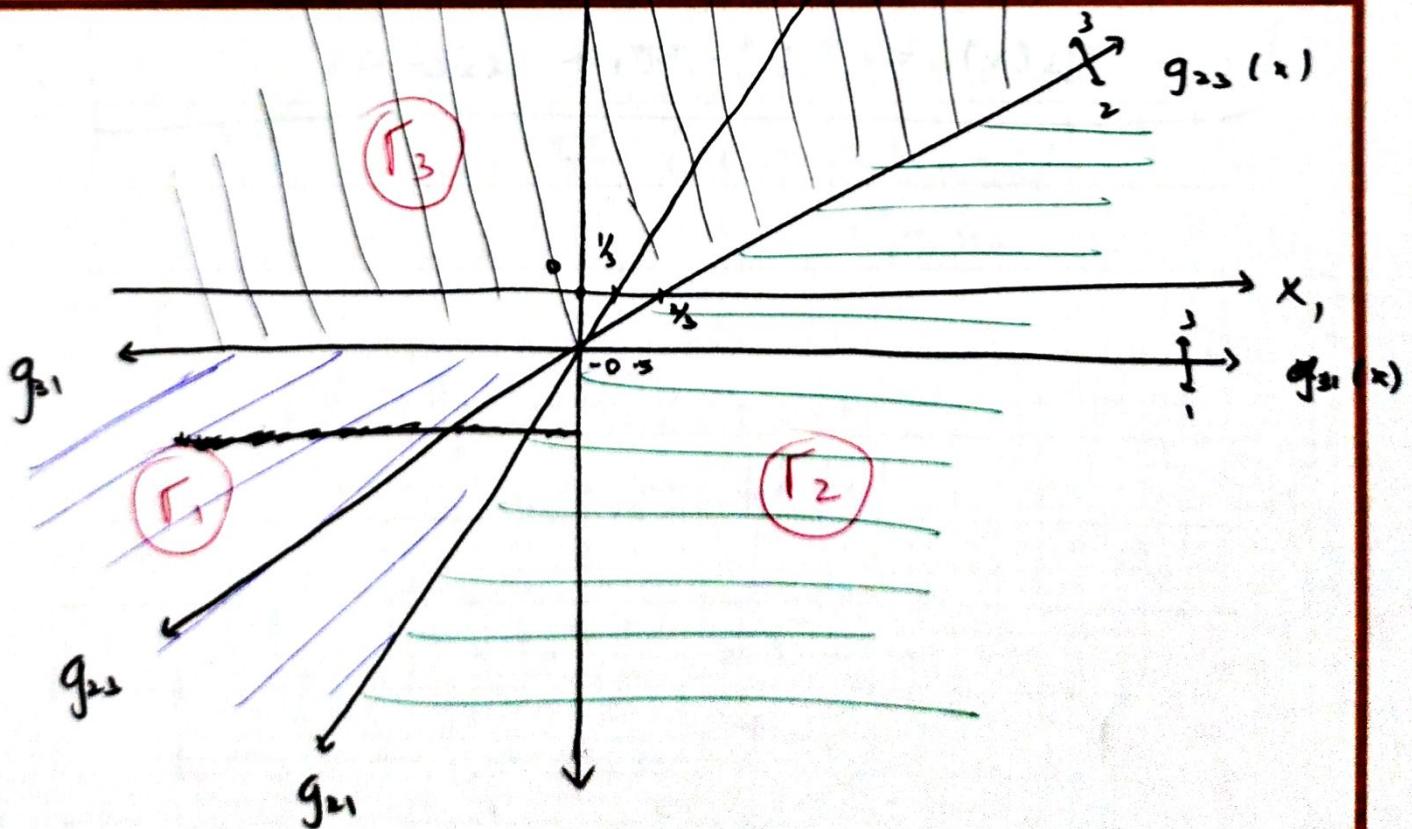
$$g_1(x) = -x_1, \quad g_2(x) = -1 + 2x_1 + -x_2$$

$$g_3(x) = -1 - x_1 + x_2$$

$$g_{4,1}(x) = 3x_1 - x_2 - 1$$

$$g_{4,2}(x) = -2 + 3x_1 - 2x_2$$

$$g_{5,1}(x) = 1 + x_2$$



~~Q.3)~~ Widrow Hoff learning

- Basic Sequential G.D.

$$a) J_n(\omega) = ?$$

$$\nabla_{\omega} J_n(\underline{\omega}) = ?$$

$$J(\underline{\omega}) = \sum_{n=1}^N (\omega^T z_n x_n - b_n)^2$$

$$\boxed{J_n(\underline{\omega}) = (\omega^T z_n x_n - b_n)^2}$$

$$\therefore \nabla_{\omega} J_n(\underline{\omega}) = \nabla_{\omega} (\omega^T z_n x_n - b_n)^2$$

$$= \nabla_{\omega} [(\omega^T z_n x_n - b_n)^T \\ (\omega^T z_n x_n - b_n)]$$

$$= \nabla_{\omega} [(z_n x_n)^T \omega \omega^T (z_n x_n) - \omega^T z_n x_n b_n^T \\ - (z_n x_n)^T \underline{\omega} b_n + b_n^T b_n]$$

$$= \nabla_{\omega} [\omega^T (z_n x_n) (z_n x_n)^T \omega - 2(z_n x_n)^T \omega b_n \\ + b_n^T b_n]$$

$$= [z(z_n x_n) (z_n x_n)^T \omega - z(z_n x_n)^T b_n]$$

$$= [z(z_n x_n) (z_n x_n)^T \omega - z b_n (z_n x_n)]$$

$$= z z_n x_n (\omega^T (z_n x_n) - b_n)$$

$$\therefore \nabla_{\omega} J_n(\omega) = z(z_n x_n) [\omega^T z_n x_n - b_n]$$

b) For Seq. G.D.
Weight updation

$$\omega(i+1) = \omega(i) - \eta(i) \nabla J_n(\underline{\omega})$$

$$= \omega(i) - \eta(i) \cdot z(z_n x_n) [\omega^T z_n x_n - b_n]$$

To converge, let

$$\eta'(i) = z \eta(i)$$

$$\therefore \omega(i+1) = \omega(i) - \eta'(i) [z_n x_n] [\omega^T z_n x_n - b_n]$$

Steps in Seq. G.D.

- 1) Random Shuffling of data point.
- 2) Initialization for $\omega(0)$.
- 3) Define epoch index n as

$$n = \{1, 2, \dots, N\}$$

$$i = (n-1)N + n - 1$$

$$\omega(i+1) = \omega(i) - \eta(i) \nabla_{\omega} J_n(\omega)$$

$$\omega(i+1) = \omega(i) - \eta'(i) z_n x_n (b_n - \omega(i)^T z_n x_n)$$

$$\eta(i) > 0.$$

Need to converge ω .

Q.1) 2-class perceptron with margin algorithm.

Prove - convergence for linearly separable data.

Assumptions:

$$\eta(i) = \eta = \text{const} > 0 \quad \forall i$$

Seq. G.D.

linearly separable.

Reflected data pts $z_n x_n \quad n=1, 2, \dots, N$.

$\eta = 1$ w/o loss of generality.

$$\text{Let } z_n x_n = z_n \eta x_n \quad \eta > 0.$$

Algorithm:

$$\left\{ \begin{array}{l} \omega(0) = \text{arbitrary}, \\ \omega(i+1) = \omega(i) + z_i x_i \end{array} \right.$$

$$\left[\omega(i)^T z_i < 0 \right]$$

$$z_i x_i = i = 0, 1, 2, \dots \quad \text{cyclically ordered.}$$

Let $z_i x_i \rightarrow$ subset of training data that are misclassified.

Algorithm :

$$1) \quad \begin{cases} w(0) = \text{arbitrary} \\ w(i+1) = w(i) + z^i x^i \end{cases}$$

in which $w(i)^T z^i x^i \leq b$ ~~for~~ $\forall i$
 for margin.

If \hat{w} is a soln, then $a\hat{w}$ is also a soln.

$$\hat{w}^T z_n x_n > b \quad \text{then}$$

$$a\hat{w}^T z_n x_n - ab > 0 \quad \text{then } \underline{a > 0}.$$

For error measure,

$$E_w(i) = \|w(i) - a\hat{w}\|_2^2 - b$$

$$w(i+1) - a\hat{w} = (w(i) - a\hat{w}) + z^i x^i$$

$$\|w(i+1) - a\hat{w}\|_2^2 = \|w(i) - a\hat{w} + z^i x^i\|_2^2$$

$$\|w(i+1) - a\hat{w}\|_2^2 - b = \|w(i) - a\hat{w} + z^i x^i\|_2^2 - b.$$

$$\|\omega(i+1) - \hat{\omega}\|_2^2 = b$$

$$= \|\omega(i) - \hat{\omega} + z_i^i x_i^i\|_2^2 - 2b + b.$$

$$= \|\omega(i) - \hat{\omega}\|_2^2 + 2(\omega(i) - \hat{\omega})^T z_i^i x_i^i + \|z_i^i x_i^i\|_2^2 - 2b + b.$$

$$= (\omega(i) - \hat{\omega})^T + 2(\omega(i)^T z_i^i x_i^i - b) - 2\hat{\omega}^T z_i^i x_i^i + \|z_i^i x_i^i\|_2^2 + b$$

But, $\omega(i)^T \underbrace{z^i x^i}_{\text{misclassified pt.}} \leq 0$

$$\epsilon \omega(i+1) \leq \|\omega(i) - \hat{\omega}\|_2^2 - 2\hat{\omega}^T z_i^i x_i^i - b + \|z^i x^i\|_2^2 + b - 2ab$$

But $2ab > 0$

$-2ab < 0$ drop.

$$\epsilon \omega(i+1) \leq \|\omega(i) - \hat{\omega}\|_2^2 - 2\hat{\omega}^T z^i x^i - b + \|z^i x^i\|_2^2 + b$$

$$\text{Let } \gamma^2 x^* = \|x^*\|_2$$

$$\beta^2 = \max \|x^*\|_2$$

$$c = \min_k \{ \hat{w}^\top z_k x_k \} > 0$$

$$\epsilon w(i+1) \leq \|w(i) - a\hat{w}\|_2^2 - 2ac + \beta^2 + b$$

$$\text{Assume } a = b + \frac{\beta^2}{c}$$

$$\epsilon w(i+1) \leq \|w(i) - a\hat{w}\|_2^2 - 2b - \beta^2 + b$$

$$\leq \|w(i) - a\hat{w}\|_2^2 - 2b - \beta^2 + 2b - b$$

$$\leq \|w(i) - a\hat{w}\|_2^2 - b - \beta^2$$

Apply focusing argument :

$$b \leq \epsilon w(i+1) \leq \epsilon w(i) - \beta^2 \quad \forall i$$

For some i_0 , we would have

$$\epsilon w(i_0) < \beta^2$$

$\leq \epsilon_{\text{tol}}$

$$b < \epsilon_w(i_0 + 1) \leq \epsilon_w(i_0) - \rho^2 < b$$

→ impossible.

⇒ Iteration must cease at $i = i_0 - 1$
(or sooner)

$\epsilon_w(i_0)$ is result of $(i_0 - i)^{\text{th}}$ iteration.

⇒ Algorithm converges at a sol' weight
vector at $(i_0 - s)^{\text{th}}$ iteration.