### Source code - simplex.c

```
#include <stdio.h>
#include <math.h>
int next_iteration_index(double *ptr, int m, int n)
  int i,index=0;
  for(i=1;i< n-1;i++)
     if(*(ptr+(m-1)*n+i) < *(ptr+(m-1)*n+index))
       index = i;
  if(*(ptr+(m-1)*n+index) > 0)
     return -1;
  }
  else
     if(*(ptr+(m-1)*n+index) == 0)
       return -2;
  return index;
int pivot_index(double *ptr, int m, int n)
  int i,j=next_iteration_index(ptr,m,n),index=j;
  double vi = *(ptr+j), vn = *(ptr+n-1), min = vn/vi;
  for(i=1;i<m-1;i++)
     vi = *(ptr+i*n+j);
     vn = *(ptr+i*n+n-1);
     if(vi>0 && (vn/vi)<min)
       min = vn/vi;
       index = i*n+j;
     }
  return index;
double * convert_pivot(double *ptr, int m, int n, int p_index)
  double p = *(ptr+p_index);
  p = 1/p;
  *(ptr+p_index) = p;
  return ptr;
```

```
}
double * convert_row(double *ptr, int m, int n, int p_index)
  double p = *(ptr+p_index),r;
  int p_row = p_index/n,p_col=p_index%n,i;
  for(i=0;i<n;i++)
  {
     if(i!=p_col)
       r = *(ptr+p_row*n+i);
       r = r*p;
       *(ptr+p_row*n+i) = r;
     }
  }
  return ptr;
double * convert_column(double *ptr, int m, int n, int p_index)
  double p = *(ptr+p_index),c;
  int p_row = p_index/n,p_col = p_index%n,i;
  for(i=0;i \le m;i++)
  {
     if(i!=p_row)
       c = *(ptr+i*n+p\_col);
       c = (-1)*c*p;
       *(ptr+i*n+p\_col) = c;
     }
  return ptr;
}
double * convert_others(double *ptr, int m, int n, int p_index)
  double p = *(ptr+p_index),c,r,s;
  int p_row = p_index/n,p_col = p_index%n,i,j;
  for(i=0;i<m;i++)
  {
     for(j=0;j\leq n;j++)
       if(i!=p_row && j!=p_col)
         r = *(ptr+p_row*n+j);
         c = *(ptr+i*n+p\_col);
         s = *(ptr+i*n+j);
         s += (c*r/p);
          *(ptr+i*n+j) = s;
     }
  }
```

```
return ptr;
}
void print_array(double *ptr, int m, int n)
  int i,j;
  for(i=0;i \le m;i++)
     printf("\n");
     for(j=0;j\leq n;j++)
       printf(" %lf ",*(ptr+i*n+j));
  }
}
void print_solution(double *ptr, int *ptr2, int m, int n)
{
  int i;
  for(i=0;i<n;i++)
     if(*(ptr2+i) != -1)
       printf("x\%d = \%lf",*(ptr2+i)+1,*(ptr+i*n+n-1));
  printf("\n Other variables are non-basic, i.e, 0.");
  printf("\n Optimal solution z = %lf ",*(ptr+m*n-1));
  if (next_iteration_index(ptr,m,n)==-2)
     printf("\n Alternate solution exists.");
  }
  else
  {
     printf("\n Unique optimal solution - no alternate solution.");
}
int * swap_variables(int *ptr2, int m, int n, int p)
  int p_row = p/n, p_col = p%n;
  *(ptr2+p_col) = p_row;
  return ptr2;
}
double * simplex_solve(double *ptr, int *ptr2, int m, int n)
  printf("\n\n Tableu from iteration %d \n",i++);
  print_array(ptr,m,n);
  printf("\n\n");
  while(next_iteration_index(ptr,m,n)!=-1)
```

```
{
     printf(" Tableu from iteration %d \n",i++);
     p = pivot_index(ptr,m,n);
     ptr2 = swap_variables(ptr2,m,n,p);
     ptr = convert_pivot(ptr,m,n,p);
     ptr = convert_row(ptr,m,n,p);
     ptr = convert_column(ptr,m,n,p);
     ptr = convert_others(ptr,m,n,p);
     print_array(ptr,m,n);
     printf("\n\n");
  print_solution(ptr,ptr2,m,n);
  return ptr;
}
void main()
  int m,n,i,j;
  printf("\n Enter number of unknowns (n) : ");
  scanf("%d",&n);
  printf(" Enter number of equations (m) : ");
  scanf("%d",&m);
  m++;
  n++;
  double arr[m*n];
  printf("\n");
  for(i=0;i< m-1;i++)
     for(j=0;j< n-1;j++)
       printf(" Input for marix A's equation %d coefficient of x%d: ",(i+1),(j+1));
       scanf("%lf",&arr[n*i+j]);
     }
  }
  printf("\n");
  for(i=0;i < m-1;i++)
     printf(" Input for matrix B's - constant for equation %d: ",(i+1));
     scanf("%lf",&arr[n*(i+1)-1]);
  printf("\n");
  for(i=0;i<n-1;i++)
     printf(" Input for objective function's coefficient of x\%d: ",(i+1));
     scanf("%lf",&arr[(m-1)*n+i]);
  for(i=0;i< n-1;i++)
  {
     arr[(m-1)*n+i] *= (-1);
  arr[m*n-1] = 0.0;
```

```
double *ptr;
int arr2[100], *ptr2;
for(i=0;i<n;i++)
{
    arr2[i] = -1;
}
ptr = arr;
ptr2 = arr2;
ptr = simplex_solve(ptr,ptr2,m,n);
}</pre>
```

# <u>Output – simplex.c</u>

```
Enter number of unknowns (n): 4
Enter number of equations (m): 3
```

```
Input for marix A's equation 1 coefficient of x1:1 Input for marix A's equation 1 coefficient of x2:3 Input for marix A's equation 1 coefficient of x3:0 Input for marix A's equation 1 coefficient of x4:1 Input for marix A's equation 2 coefficient of x1:2 Input for marix A's equation 2 coefficient of x1:2 Input for marix A's equation 2 coefficient of x1:0 Input for marix A's equation 2 coefficient of x1:0 Input for marix A's equation 3 coefficient of x1:0 Input for marix A's equation 3 coefficient of x1:0 Input for marix A's equation 3 coefficient of x1:0 Input for marix A's equation 3 coefficient of x1:0 Input for marix A's equation 3 coefficient of x1:0 Input for marix A's equation 3 coefficient of x1:0 Input for marix A's equation 3 coefficient of x1:0
```

```
Input for matrix B's - constant for equation 1 : 4
Input for matrix B's - constant for equation 2 : 3
Input for matrix B's - constant for equation 3 : 3
```

Input for objective function's coefficient of x1:2 Input for objective function's coefficient of x2:4 Input for objective function's coefficient of x3:1 Input for objective function's coefficient of x4:1

#### Tableu from iteration 0

```
1.000000 3.000000 0.000000 1.000000 4.000000 2.000000 1.000000 0.000000 0.000000 3.000000 0.000000 1.000000 4.000000 1.000000 3.000000 -2.000000 -4.000000 -1.000000 -1.000000 0.000000
```

### Tableu from iteration 1

### Tableu from iteration 2

# Tableu from iteration 3

-0.200000 0.400000 0.000000 0.400000 1.000000 0.600000 -0.200000 -0.000000 -0.200000 1.000000 0.050000 -0.100000 0.250000 0.150000 0.500000 0.450000 1.100000 0.250000 0.350000 6.500000

 $x2 = 1.000000 \quad x1 = 1.000000 \quad x3 = 0.500000$ Other variables are non-basic, i.e, 0. Optimal solution z = 6.500000Unique optimal solution - no alternate solution.