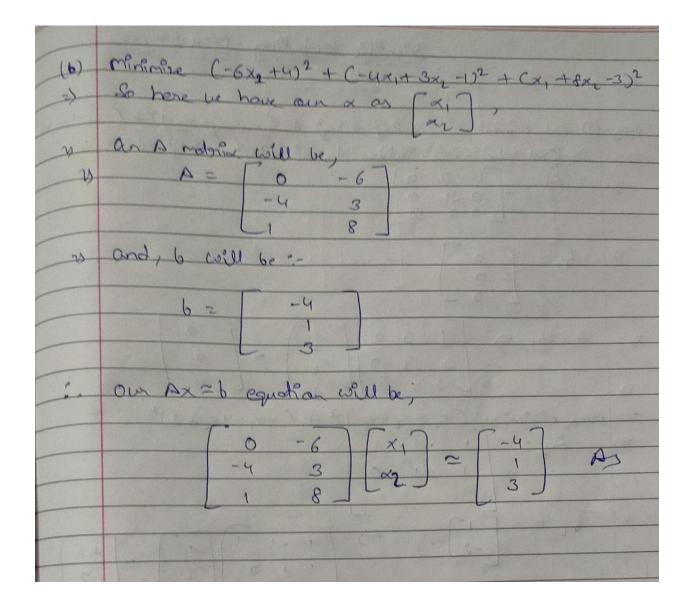
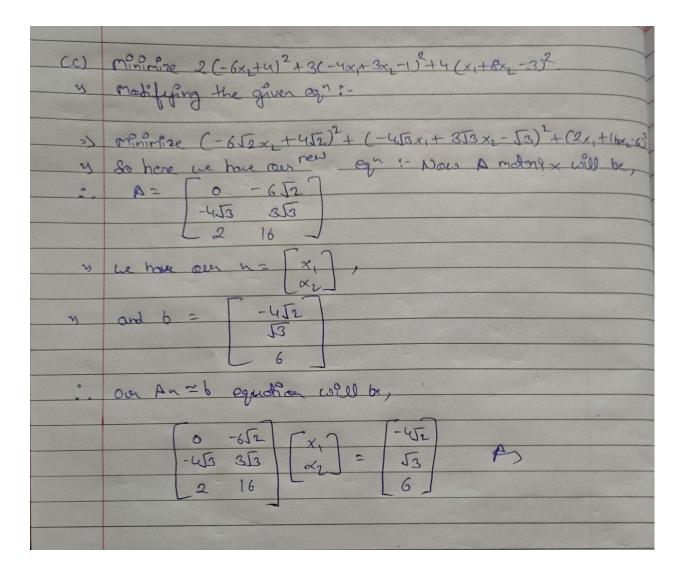
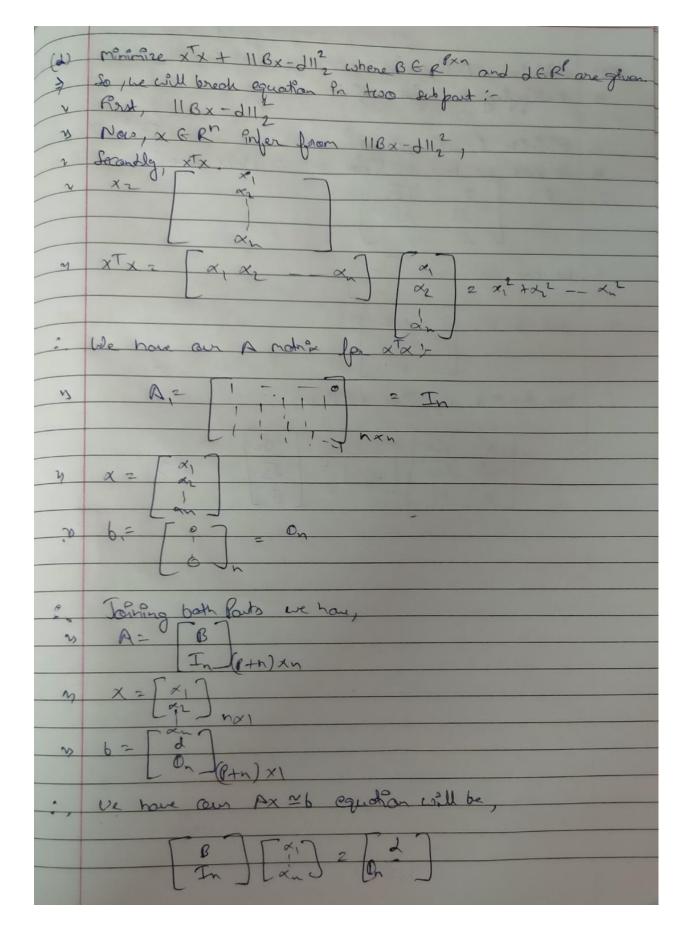
HOMEWORK-2 MTH373/573 - Scientific Computing Sourav Goyal 2020341

Ans-1

4	Scientific Computing - MTH 373/573 Homowork - 2
=)	O (a) Principle $h_1^2 + 2x_1^2 + 3x_2^2 + (h_1 - x_2 + x_3 - 1)^2 + (-x_1 - 4x_2 + 2)^2$ So first take 1 Minimization of $x_1^2 + 2x_2^2 + 3x_3^2$ which is, $A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{bmatrix}$
7)	b,= [0]
25	$A_{1} \times 2b_{1} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 52 & 0 & 0 \\ 0 & 0 & 53 & 0 \\ 0 & 0 & 53 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \approx \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 &$
	Now minimize! (x, -x2+x3-1)2+ (-x,-4x2+2)2
Ŋ	A2 = 1 -1 1
	1 4 0
7	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
	-2 3 1-1 1 1 1 +1
	L 1 4 0 1 2 1 -2
	Joining A, and Az and b, and be, we have,
2)	BZ AI and b= bi
=>	Ax=b
25	
	[100]
	0 52 0 21 = 0
	0 0 53 1 02 0
	1 - T 1 [X ₃] 1
	L-2_





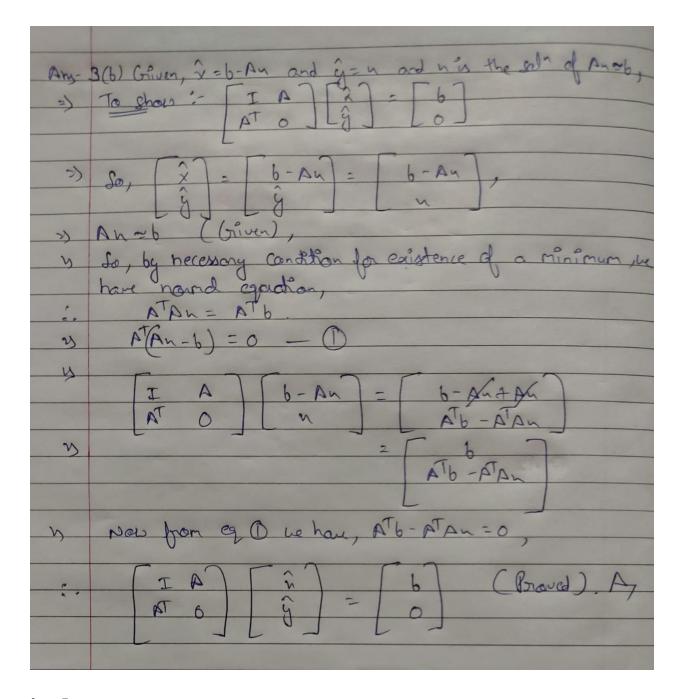


(e)	Winimize XTOX + 11BX-J113 where DER is a flagand reduced with possible flagand clements, BEREN and def are flag
	with positive Lagand clements, BEREN and def are fine
y	So, we have n = [xi]
	Lar 141
23	Agon brook given on in two parts,
3	Agon brock grun og in too parts,
24	
	[x, -dn] [0, 0, 0] = 0x,2+0xx2-0xx
	L Pul man
n	So, ue have B, robre for xTDX,
y	A = Di
	A1 2 01 = 0
IA Cura	x b1 = 0 2 0
9	2 1
	l o Jn
n	Com-10, 118-11)
,	Secondly, 11Bx-211.
	0: [0]
- 13	Our Rind A motion will be, A: [D]
V	our b matrix will be,
	6 2 On d
	0 ~1 ~ 012
	be how our Ax = 6 equation that by
	Carrier Carrie
	B Landrai On
	CPANXN (PAN)XI
	Manager Control of the Control of th

Ans-2

177.18	
Any	Given $\begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$
•	I alving this problem using necessary another for constence
	21 A 2 [] h = [2]
7	$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
	$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 1 & 3 \end{bmatrix}$
	$\frac{1}{1}$ $\frac{1}$
	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
7	our salution is minimum by proving ATA in possitive defente,
	ATA = []
	=
	i e De have a minimum seletion.
2 2	Mars for residual vector we have, on = [2] - [0] [1] [1]
25	7 = [2] - [2]
7	
2)	Eucledson nous d'ar.
7	11211 = 102+02+12
23	1/21/21/2

Any.	(3) a) Given - A C R man, m > n with linearly independent ale
•	(mtn) x (n tn) motorix by m:
	m= I A
	LAT OJ.
	To show ?- M is non-Engelor.
=>	We will show that Idel (m) >0 for parowing mis
	(Jet CM) 1 = 1 det (IO) - Jet CATA) 1
->	[det CM)] = det (IO) - fet CA'A)
2)	= det (A A)
	How we will know that ATA is non-singular iver
	Lot's take, ATAN = 0
- 4	
4	
-	
3)	From given statement we know A motoria has Romany
2)	From given stotement we know A motorie has Rinconly Protegon tent columns go if An = 0 Inplies n = 0
	From given stotement we know A motorie has Rinconly Protespendent columns so if An = 0 Prophies n = 0. Null espace of ATA = 203,
n	Dimension of ATA = nxn
2)	Dimens Pan of PTA = nxn So, PTA is a squar motifix and null space of PTA 2501
2)	Dimension of ATA = nxn So, ATA is a square motified and null space of ATA 2501 then ATA is investible.
2)	Dimens Pan of PTA = nxn So, PTA is a squar mothis and null space of PTA 2501 Then PTA is investible. Moso, we know investible mothis are non-Engelon.
2) 2)	Dimens Pan of ATA = nxn So, ATA is a squar notified and null space of ATA 2502 Then ATA is investible matrix are non- Engelon. It co To 21 22
2) 2)	Dimension of ATA = nxn So, ATA is a flyour notified and null space of ATA 2502 Then ATA is investible More, we know investible matrice are non- Engelon Lock (ATA) 1>0 AND, by that we a fact (N) > 0
2) 2)	Dimens Pan of ATA = nxn So, ATA is a squar notified and null space of ATA 2502 Then ATA is investible matrix are non- Engelon. It co To 21 22



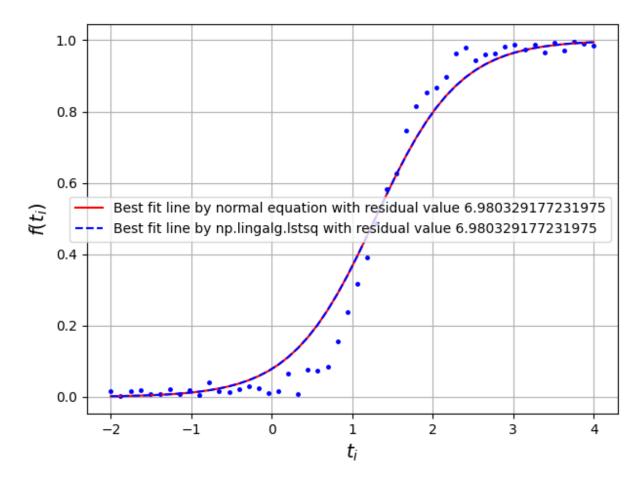
Ans-5

Ans-	5 (a) Given, $extite \approx y$, $i=1$, m , where $m=50$, $i+extite i+extite = i$
	0 < y ? < 1 for all ? = 1, , , ~.
3	Taking logarithm both site, log extits ~ logg:
3	log 1 ~ logg:
=)	log 1 - log(e-(xti+p)+1) ≈ logy; -log(e-(xti+p)+1) ≈ logy; (e-(xti+p)+1) ≈ 1
=)	
3)	estitip≈ 1 -1
>>	extits ~ 1-gi
'>	xt;+B ≈ log y:
Ŋ	Take lægge syé
	ati+B=yi A

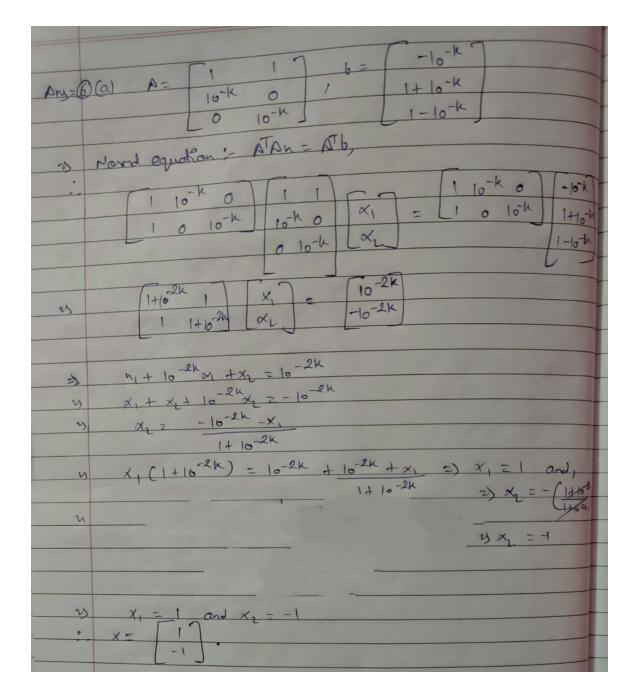
(b)

Error by normal equation : 6.980329177231975 Error by np.linalg.lstsq : 6.980329177231975

Plot :-



Ans-6



(b) Result :-

```
X for k = 6 using QR factorization : [[ 1.]
  [-1.]]
 X for k = 7 using QR factorization : [[ 1.]
  [-1.]]
 X for k = 8 using QR factorization : [[ 1.00000001]
  [-1.00000001]]
 X for k = 9 using QR factorization : [[ 1.000000005]
  [-1.000000005]]
 X for k = 10 using QR factorization : [[ 1.00000052]
  [-1.00000052]]
 X for k = 11 using QR factorization : [[ 1.00002329]
  [-1.00002329]]
 X for k = 12 using QR factorization : [[ 0.99991338]
  [-0.99991338]]
 X for k = 13 using QR factorization : [[ 0.99936385]
  [-0.99936385]]
 X for k = 14 using QR factorization : [[ 1.01270964]
  [-1.01270964]]
 X for k = 15 using QR factorization : [[ 0.86355085]
  [-0.86355085]]
(c) Result :-
```

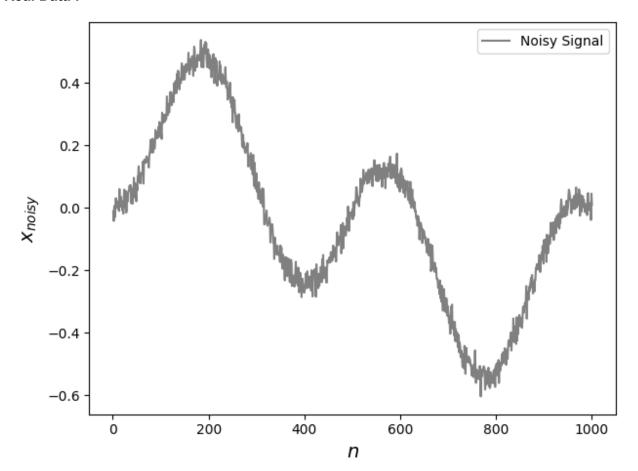
```
X for k = 6 using normal equation : [[ 0.99991111]
 [-0.99991111]]
X for k = 7 using normal equation : [[ 1.00079992]
 [-1.00079992]]
XTX becomes singular
```

Compare between all three result :-

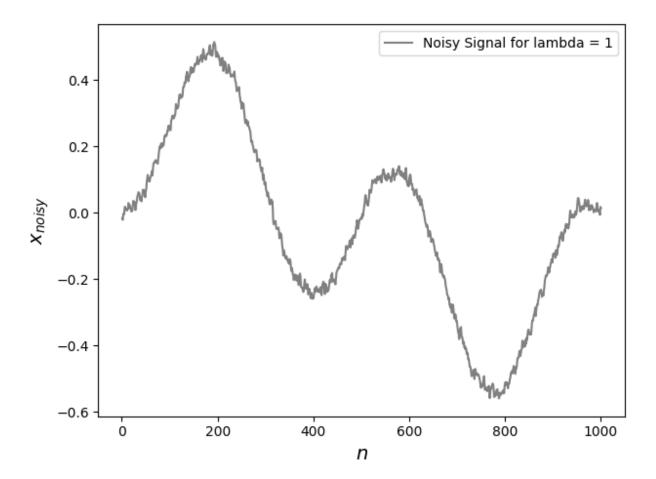
In normal equation we have x value only for k = 6 and k = 7 because of floating point at k >= 8 10^{-2k} consider as 0 which makes the ATA matrix singular and by that we haven't solution for that but according to our analytical solution we have x independent of k which equals to [[1,-1]] For k = 6 we have k = 10.99991111, -0.99991111 by normal equation but our desired solution is [[1,-1]] and this also happens due to floating point system and same as for k = 7 we get value closer to 1 and -1 but we haven't exact value for k = 7 also.

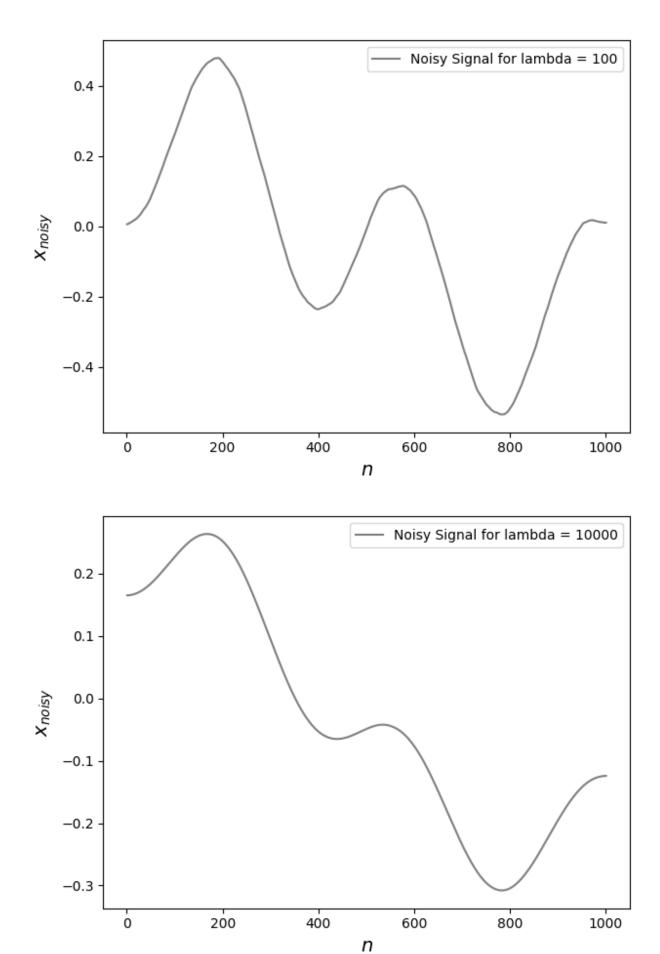
In QR decomposition we have correct result for k = 6 and 7 which is more accurate than solution we getting from normal equation computation and after $k \ge 8$ our ATA becomes singular so no solution we are getting from normal equation computation but in QR we have solution because R is an upper triangular matrix and Q is orthogonal so inverse exist for both but due to floating point system we have value closer to our solution but not accurate that much.

Ans-7 Real Data :-



Effect of λ on the quality of the estimate x:-





Observations:-

• As lambda increases :-

- The noisiness in the curve decreases.
- o The minimum value increases and maximum value decreases.
- The number of local minimum and local maximum decreases
- The curve takes the shape of a straight line or shrinking of the graph.
- So from all of the above observation we can conclude that lambda = 100 can be a
 optimal value because at lambda = 100 graph will be smoothened and not much
 deviated from original path but at lambda > 100 it's start more deviating (which we
 observe from our above observation) which increases the error.