Arsh Sharma

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EDUCATION

NIT HAMIRPUR

B.Tech + M.Tech

ELECTRONICS AND COMMUNICATION Expected May 2023 | Hamirpur, IND Cum. GPA:8.52

MOUNT CARMEL SCHOOL

Grad. Mar 2018 Himachal Pradesh, IND

Cum. GPA:10

LINKS

Github:Sov-trotter LinkedIn:sov-trotter

SKILLS

PROGRAMMING

Julia • Python • C++ • Matlab • GoLang

TOOLS

Atom • LATEX • Vim • Visual Studio Code

LIBRARIES

MatPlotLib • DataFrames(Pandas)
Three.js, • JSON(RPC) • Tensorflow p5.js
• Cairo • QuantumBFS

MISCELLANEOUS

Arduino • Quantum Information Theory Processing • Blender • Genetic Algorithms • Microsoft Kinect SDK Generative Art • Webscraping

EXTRACURRICULARS

- Aug'20-Nov'20 Joint Secretary Hult Prize NITH
- Aug'18-present Secretary Team ISTE
- 2018 2019 Animator at Pixonoids

WORK EXPERIENCE

STUDENT DEVELOPER - GSOC'21 May'21 - present

Google Summer of Code

- A Cairo based 2D visualization library Javis.il for The Julia language ecosystem
- Will be working on adding higher lever abstractions for improved user experience
- Add a new layer context withing Javis.jl and Improve transformations between different shapes
- Allow livestreaming animations over a network or to platforms like Twitch.tv

STUDENT DEVELOPER - JSOC'20 May'20 - Sept'20

Julia Season of Contributions

- A GeoSpatial data handling ecosystem for the Julia language
- The project simplifies the GIS pipelines to read and view data in Julia, right from parsing it to a Tabular format and be able to plot it, all withing 4 lines of Julia code!

PRO JECTS/OPEN-SOURCE CONTRIBUTIONS

IBMQJulia.jl Oct'20

- A package written in Julia that uploads quantum circuits generated by Yao.jl to IBM-Quantum, that runs quantum circuits on real quantum computers.
- This package implements the OpenQasm specifications paper.
- For now it can login, select backends, upload the circuits and get the results from the IBMQ server made possible by two major units the REST API and the Yao IR to QObj parser.

2D RAYCASTER/RAYTRACING ENGINE Sept'19

• Built a minimal 2-D raycaster in js

MOTION CAPTURE USING KINECT April'19

- The first few steps involved interfacing with the Kinect
- The output from kinect was then stored in a .bvh file (OpenNI)
- The .bvh was imported into Blender and appiled on a model's armature thus the model imitated human movment
- In addition to it many objects were 3D scanned and their 3D models created (wavefront .obj format)

3D HUMAN - COMPUTER INTERFACE Dec'18

- Placing an object within the electric field of a capacitor affects the capacitance and the corresponding time constant.
- This gave the location of an object in a 3D space. While the Arduino
 micro-controller fetched values from the 3D space(capacitor), Processing was
 used to create a visual representation