PROJECT CODE

Program

```
#include <Wire.h>
#include < Adafruit MLX90614.h>
#define TRIG_PIN 9
#define ECHO PIN 10
#define LED_PIN 7
#define SOUND_ANALOG A0
#define SOUND_DIGITAL 2
Adafruit_MLX90614 mlx = Adafruit_MLX90614();
void setup() {
 Serial.begin(9600);
 mlx.begin();
 pinMode(TRIG_PIN, OUTPUT);
 pinMode(ECHO_PIN, INPUT);
 pinMode(LED PIN, OUTPUT);
 pinMode(SOUND DIGITAL, INPUT);
 Serial.println("Smart Sensor System Initialized");
void loop() {
 // --- Temperature ---
 float temperature = mlx.readObjectTempC();
 // --- Ultrasonic distance ---
 digitalWrite(TRIG PIN, LOW);
 delayMicroseconds(2);
 digitalWrite(TRIG_PIN, HIGH);
 delayMicroseconds(10);
 digitalWrite(TRIG_PIN, LOW);
 long duration = pulseIn(ECHO_PIN, HIGH);
 float distanceMM = duration * 0.34 / 2; // in mm
 // --- Sound ---
 int soundAnalog = analogRead(SOUND_ANALOG);
 int soundDigital = digitalRead(SOUND_DIGITAL);
 // --- LED only ON if object within 50mm ---
 if (distanceMM > 0 && distanceMM <= 50) {
```

```
digitalWrite(LED_PIN, HIGH);
    Serial.println("LED: GLOWING (Object within 50mm)");
} else {
    digitalWrite(LED_PIN, LOW);
    Serial.println("LED: OFF (No object within 50mm)");
}

// --- Other sensor status ---
    Serial.print("Temperature: ");
    Serial.print(temperature);
    Serial.print(" °C | Sound Level (Analog): ");
    Serial.print(soundAnalog);

if (soundDigital == HIGH) {
        Serial.println(" | Loud Sound Detected!");
    } else {
        Serial.println(" | No Loud Sound");
}

delay(500);
```