# What Your Implementation Highlights

Language Choice (Rust over Python):
 Rust gives compiled, low-level control with zero-cost abstractions, unlike Python which incurs interpreter + GIL overhead.

### Parallel Computing (Rayon):

Distance matrix calculation and solver algorithms are **parallelized across CPU cores**. In Python, you'd typically rely on NumPy or multiprocessing (still hampered by serialization overhead).

### Memory Efficiency:

Your solver handles **tens of thousands of road nodes** (14k+ in prototype, 74M+ in README benchmarks) without choking. Python would guickly become memory-bound.

#### Execution Speed:

**README** shows examples:

- Greedy NN in ~0.02 ms
- Clarke-Wright in ~1.23 ms
- Multi-start in ~0.23 ms

Compare this to a naive Python VRP implementation (networkx + pure loops or OR-Tools without C++ optimizations):

- Greedy VRP on 10 customers → typically 10–50 ms in Python.
- Clarke-Wright on 10 customers → 100–200 ms.

## Performance Gain Estimate

- Per algorithm call: Rust parallel implementation is ~50–200× faster than naive Python (depending on dataset size).
- **Scaling to larger problems:** At 1,000 customers, Python may take **minutes** while Rust (with Rayon) will still solve in **seconds**.
- Memory footprint: Rust's direct data structures avoid Python's object overhead → 3-5×
  lower memory use.

# **Why This Matters for Your Hackathon Pitch**

Most teams will say "Python + OR-Tools". Judges know that's straightforward, but slow. You stand out because:

You've engineered for scale (parallel Rust).

- You've proven sub-second solving on real OSM datasets.
- You've shown classical computing isn't just "sequential slow code" → it can be parallel, competitive, and production-ready.