# TEAM SPACE COAST UNMANNED AIRSPEW CHALLENGE

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#### **OBJECTIVE**

#### Design a system that:

- 1. Attaches to a DJI Phantom 4 without permanent modification
  - Remote activation using built in DJI functionality
- 2. Plays audio output via speaker system
- 3. Ability to incorporate Software Defined Radio
  - Radio transmission in FM frequency
  - GNURadio compatible
- 4. Drops one pound of pamphlets





## SPACE COAST UNMANNED'S SOLUTION

- All in one solution allowing a single Phantom to perform all aspects the mission
  - Reduces fleet requirement from 3 simultaneous
    Phantoms to 1 Phantom
  - Significant cost savings to end user due to reduced fleet size and maintenance
- All Payloads to not interfere with the camera or avoidance sensors
- System can be separated into individual modules if desired
  - Would allow much more weight for audio speaker system



# **CONFIGURATIONS**

- Saddles can be removed and replaced for four configurations:
- 1. FM Transmitter
- 2. FM Transmitter, Audio Speakers
- 3. FM Transmitter, Pamphlet Dropper
- 4. FM Transmitter, Audio Speakers, Pamphlet Dropper











## DESIGN APPROACH

- Implement mature open source technologies where possible to minimize risk
- Design and produce as many components as possible to reduce dependencies on outside resources
  - Reduces risk for future change
  - Reduces procurement costs
- Allows greater customizability to meet customer's future needs





# 3D DESIGN

Using 3d scanners to get accurate CAD data of the Phantom 4, Space Coast Unmanned designed integrated payload modules.

3D SCAN Phantom 4 UAV



FM Transmitter/Computer



Loud Speaker



Leaflet Dropper



ALL IN ONE SOLUTION

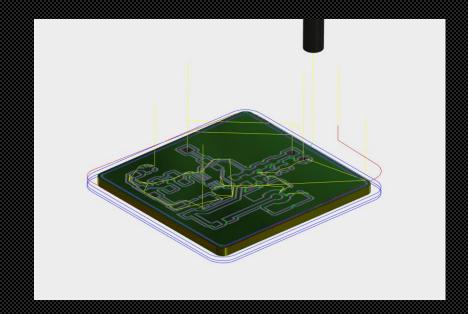




# MANUFACTURING

• All custom components were designed and manufactured by Space Coast Unmanned, saving time and cost.





## ATTACHES WITHOUT PERMANENT MODIFICATION

- Light Sensor
  - Attaches in place of friction fit clear lens cap for forward LED using velcro
- Pamphlet Dropper/Speaker module
  - Attaches to right side of Phantom landing gear using Velcro
- Raspberry Pi/FM transmitter/Audio amplifier/Battery module
  - Attach to left side of Phantom landing gear using Velcro
- Landing gear standoff attaches to landing gear using Velcro
- No permanent modifications required





## CONTROL USING DJI FUNCTIONALITY

- A light sensor module was designed that simply replaces the clear lens cap on one of the forward lights
  - Simple design using only 3 passive components, highly reliable with minimal cost
- Attaches via Velcro for quick modification





- Off the shelf audio amplifier from Adafruit was leveraged to minimize development time and risk
  - Uses Texas Instruments TPA2016D2 chip
  - Example code provided, along with schematics
  - Future versions can be made without purchasing unit from Adafruit for cost savings
- Class D operation is ~90% efficient, allowing longer battery life while maintaining higher output volume









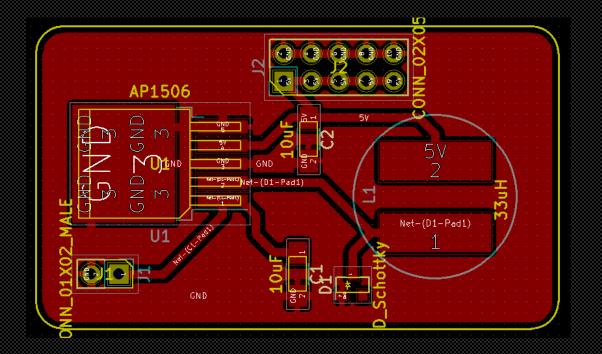
- Raspberry Pi was chosen for:
  - Processing power
  - Linux OS allows GNURadio compatibility
  - Small form factor
  - Low cost
  - Large pool of resources available online

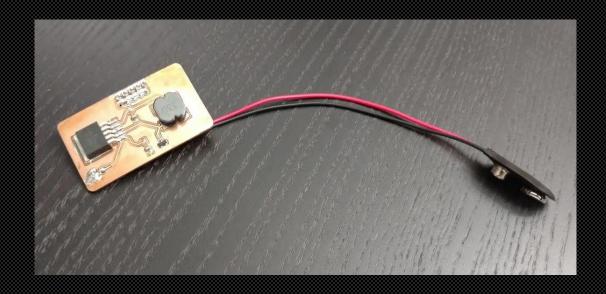


# POWER SUPPLY

- Using high efficiency
  AP1506 5V 3A DC-DC
  Switching power supply
  - $\sim$ 85% efficiency at 9V input
- Module designed, built, and tested successfully









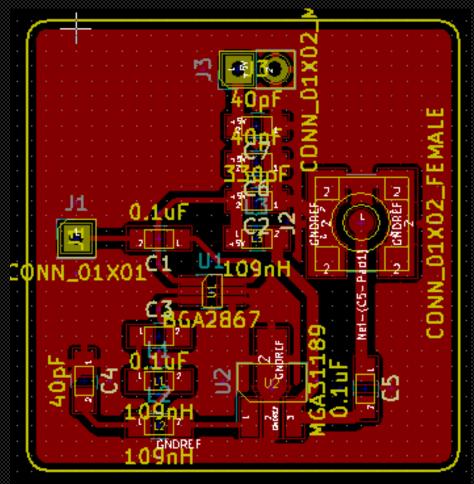
#### FM TRANSMITTER

- Off the shelf FM transmitter from Adafruit was leveraged to minimize development time and risk
  - Uses Silicon Labs SI4713 chip
  - Example code provided, along with schematics
  - Future versions can be made without purchasing unit from Adafruit for cost savings
- SI4713 does not meet Airspew challenge output power requirements
  - Requirement of 24dBm (250mW) exceeds FCC regulation maximum of 0.01µW
  - <a href="https://www.fcc.gov/media/radio/low-power-radio-general-information">https://www.fcc.gov/media/radio/low-power-radio-general-information</a>
  - https://apps.fcc.gov/edocs\_public/attachmatch/DOC-297510A1.pdf
- Space Coast Unmanned has designed but not built a high power RF amplifier that will meet desired power output



## RF AMPLIFIER DESIGN

- A two stage amplifier was designed using SPICE simulation
  - Schematics available at Space Coast Unmanned's Github repository
- Accounting for losses, theoretical output is user adjustable between 14dbm and 41dbm
  - WARNING: Significant distortion will occur at output levels over 24dbm and damage is likely over 28dBm

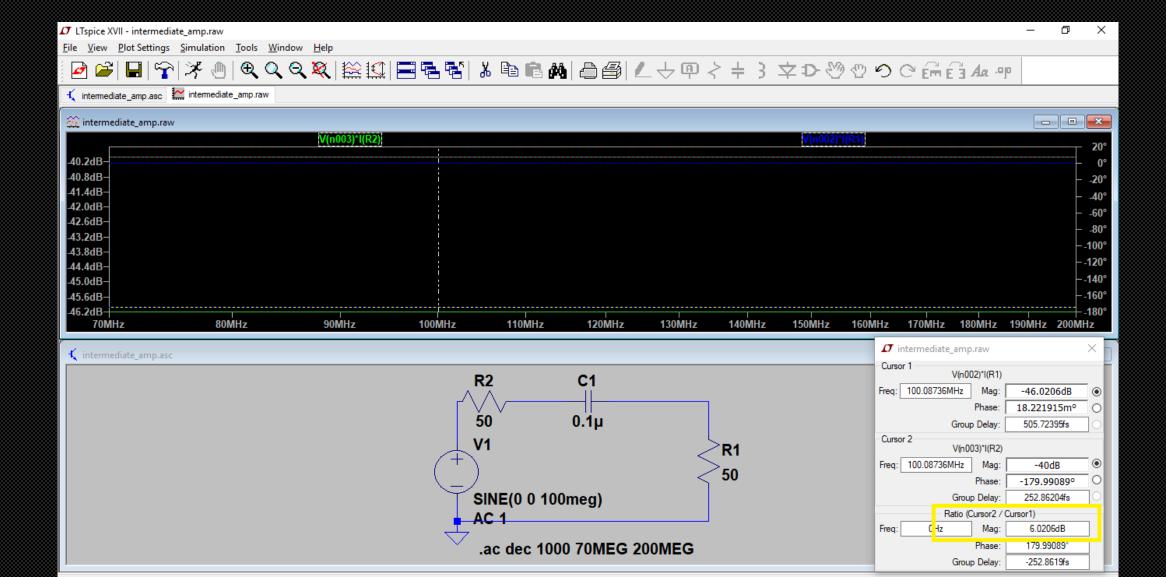


#### RF AMPLIFIER STAGE 1

- Using BGA2867 small signal amplifier with internal 50ohm matching. Spice circuit and simulation shows roughly 6dB loss in coupling circuit
  - SI4713 max output of 115dBm is 8dbm
  - Gain of amplifier is 24dB, with 6dB loss max output of first stage is  $\sim$ 26dBm, but chip is only rated to 5dBm without significant distortion
  - Recommend not exceeding 94 dBµV setting in Si4713 Power parameter



## RF AMPLIFIER STAGE 1 SPICE SIMULATION

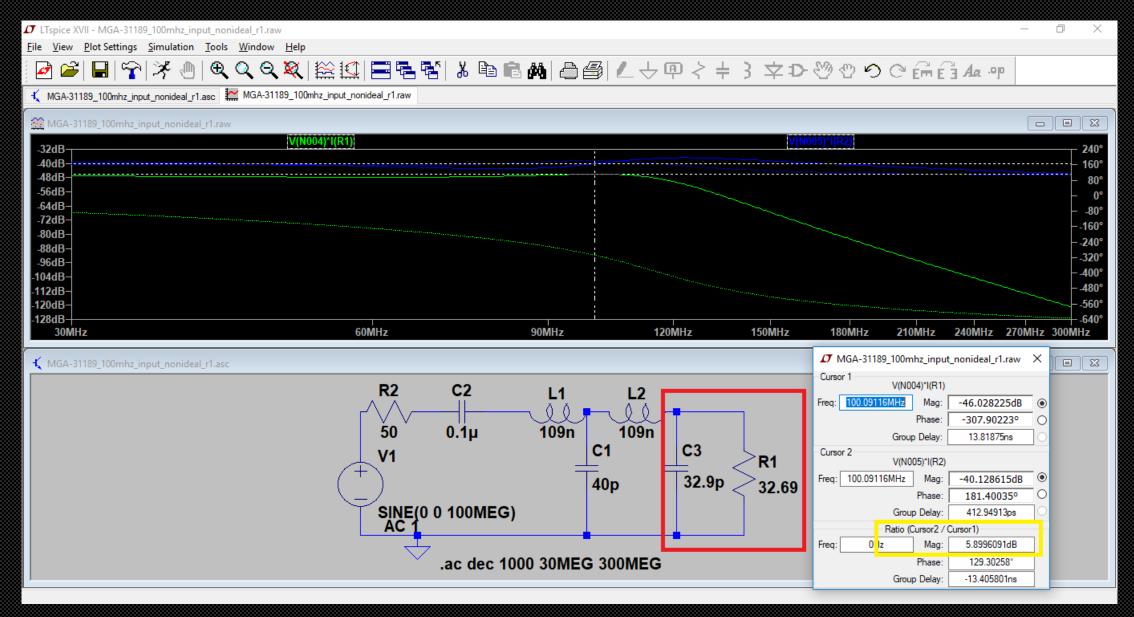


#### RF AMPLIFIER STAGE 2

- Using MGA-31189 chip that is rated to 24dBm output without significant distortion
  - Component is not internally matched, and needs matching circuit
  - 21dB of gain, 5.8dB loss from matching circuit. Theoretical max output of total FM Transmitter is 41dBm (12.6W).
    - WARNING: This is a significant power level and will destroy components. It is not recommended to go higher than 26dBm output.

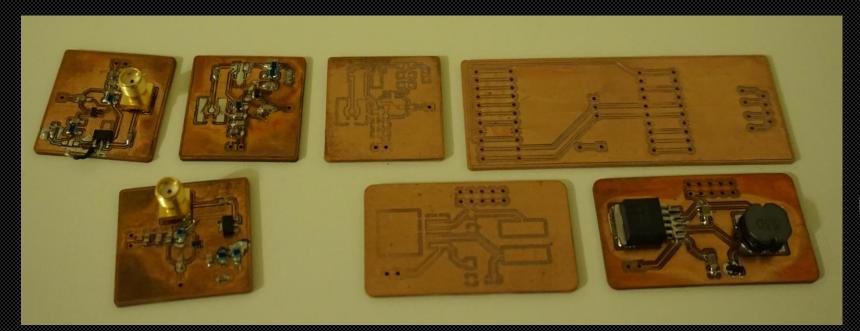


## RF AMPLIFIER STAGE 2 SPICE SIMULATION



# RF AMPLIFIER FABRICATION

- Several boards were fabricated, populated, and soldered
- Due to extremely small tolerances, we were unable to produce an electrically correct completed assembly









- Tested to 1 pound pamphlet capacity
- Single servo control
- Releases all pamphlets at once in accordance with clarification provided during Q&A session
- Attaches using Velcro for non-permanent mounting
- Does not interfere with side, forward, aft and even the downward facing sensors



# COST

- The development of all the components for the three modules keeps the cost to a minimum.
- Purpose built components ensure the end product is highly efficient at the lowest cost possible.



## SPACE COAST UNMANNED'S SOLUTION

## Offers a system that:

- ✓ Attaches to a DJI Phantom 4 without permanent modification
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- SWAP(Size, Weight and Power): Space Coast Unmanned would do further research and development to lower the weight of modules.
- Audio Volume: develop a speaker module that produce louder sound.
- Space Coast Unmanned would like to discuss developing a purpose built UAV platform that can utilize all three payloads in an integrated package with higher endurance and greater control functionality.

# RESOURCES

- This presentation, along with the User Manual and circuit schematics can be found at our Github repository:
- <a href="https://github.com/Space-Coast-Unmanned/AirSpew">https://github.com/Space-Coast-Unmanned/AirSpew</a>

