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Demostración por AC

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1 Data Structures

1.1 DSU

```

1  const int N = 1e5+5;
2  int dsu[N];
3  int cc;
4
5  int find (int node){
6      if(dsu[node] == -1) return node;
7      return dsu[node] = find(dsu[node]);
8  }
9
10 bool connected(int A, int B){
11     return find(A)==find(B);
12 }
13
14 void join (int A, int B){
15     A = find(A);
16     B = find(B);
17     dsu[A] = B;
18     cc--;
19 }
20
21 memset(dsu, -1, sizeof dsu);

```

1.2 DSU Pesos

```

1  int parent[MAX];
2  int rango[MAX];
3  int n;
4  void Init( int _n ){
5      n = _n;
6      for( int i = 0 ; i < n ; ++i ){
7          parent[i] = i;
8          rango[i] = 0;
9      }
10 }
11
12 int Find( int x ){
13     if( x == parent[ x ] )
14         return x;
15     else
16         return parent[ x ] = Find( parent[ x ] );
17 }
18
19 void Union( int x , int y ){
20     int xRoot = Find( x );
21     int yRoot = Find( y );
22     if( rango[ xRoot ] > rango[ yRoot ] )
23         parent[ yRoot ] = xRoot;
24     else{
25         parent[ xRoot ] = yRoot;
26         if( rango[ xRoot ] == rango[ yRoot ] )
27             rango[ yRoot ]++;
28     }
29 }
30
31 int countComponents(){
32     int c = 0;

```

```

for( int i=0; i<n; i++ )
    if( parent[i] == i )
        c++;
return c++;
}
vector<int> getRoots() {
    vector<int> v;
    for( int i=0; i<n; i++ )
        if( i == parent[i] )
            v.push_back(i);
    return v;
}

int countNodesInComponent( int root ) {
    int c = 0;
    for( int i=0; i<n; i++ )
        if( Find(i) == root )
            c++;
    return c++;
}

bool sameComponent( int x, int y ) {
    return Find(x) == Find(y);
}

```

2 Graphs

2.1 Strongest Connected components

```

vector<bool> visited; // keeps track of which vertices are
                      // already visited

// runs depth first search starting at vertex v.
// each visited vertex is appended to the output vector when
// dfs leaves it.
void dfs(int v, vector<vector<int>> const& adj, vector<int> &
output) {
    visited[v] = true;
    for (auto u : adj[v])
        if (!visited[u])
            dfs(u, adj, output);
    output.push_back(v);
}

// input: adj -- adjacency list of G
// output: components -- the strongly connected components in G
// output: adj_cond -- adjacency list of G^SCC (by root
// vertices)
void strongly_connected_components(vector<vector<int>> const&
adj,
                                vector<vector<int>> &
                                components,
                                vector<vector<int>> &
                                adj_cond) {

    int n = adj.size();
    components.clear(), adj_cond.clear();

    vector<int> order; // will be a sorted list of G's
                      // vertices by exit time

    visited.assign(n, false);

    // first series of depth first searches
    for (int i = 0; i < n; i++)

```

```

        if (!visited[i])
            dfs(i, adj, order);

    // create adjacency list of G^T
    vector<vector<int>> adj_rev(n);
    for (int v = 0; v < n; v++)
        for (int u : adj[v])
            adj_rev[u].push_back(v);

    visited.assign(n, false);
    reverse(order.begin(), order.end());

    vector<int> roots(n, 0); // gives the root vertex of a
                             // vertex's SCC

    // second series of depth first searches
    for (auto v : order)
        if (!visited[v]) {
            std::vector<int> component;
            dfs(v, adj_rev, component);
            components.push_back(component);
            int root = *min_element(begin(component), end(
component));
            for (auto u : component)
                roots[u] = root;
        }

    // add edges to condensation graph
    adj_cond.assign(n, {});
    for (int v = 0; v < n; v++)
        for (auto u : adj[v])
            if (roots[v] != roots[u])
                adj_cond[roots[v]].push_back(roots[u]);
}

```

2.2 SCC Tarjan

```

struct TarjanScC{
    vector<bool> marked;
    vector<int> id;
    vector<int> low;
    int pre;
    int count;
    stack<int> stck;
    vector<vector<int>> >G;

    TarjanScC( vector<vector<int>> >g, int V ){
        G=g;
        marked = vector<bool>(V, false);
        stck = stack<int>();
        id= low = vector<int>(V, 0);
        pre=count=0;
        for(int u=0; u<V; u++)
            if( !marked[u] ) dfs(u);
    }

    void dfs( int u ){
        marked[ u ] = true;
        low[ u ] = pre++;
        int min = low[ u ];

        stck.push( u );
        for( int w=0; w<G[u].size(); w++){
            if( !marked[G[u][w]] ) dfs( G[u][w] );

```

```

        if( low[ G[u][w] ] < min ) min = low[ G[u][w] ];
    }
    if( min<low[u] ){
        low[u] = min;
        return;
    }
    int w;
    do{
        w = stk.top();stk.pop();
        id[ w ] = count;
        low[ w ] = G.size();
    }while( w != u );
    count++;
}

int getCount() { return count; }

// are v and w strongly connected?
bool stronglyConnected(int v, int w) {
    return id[v] == id[w];
}

// in which strongly connected component is vertex v?
int getId(int v) { return id[v]; }
};

//Ejemplo de Uso
int main( ){
    int u, v, N, M, cas, k=0;
    for(cin>>cas; k<cas; k++){
        scanf("%d %d", &N, &M);
        //cin>>N>>M;
        vector<vector<int>> >G(N);

        for(int i=0; i < M; i++){
            scanf("%d %d", &u, &v);
            //cin>>u>>v;
            u--;v--;
            G[u].PB(v);
        }

        TarjanScc tscc(G, N);
        //Encontrar cuantos nodos tienen grado de entrada 0
        vector<int>indegree(tscc.getCount(), 0);
        int idu, idv;
        for( u = 0; u < N; u++){
            idu = tscc.getId( u );
            for( v = 0; v < G[u].size(); v++){
                idv = tscc.getId( G[u][v] );

                if( idu!=idv ){
                    indegree[idv]++;
                }
            }
        }

        int res=0;
        for(int i=0; i<indegree.size(); i++){
            if(indegree[i]==0)res++;
        }
        printf("Case %d: %d\n",k+1,res);
    }
    return 0;
}

```

2.3 Topological sort

```

int n; // number of vertices
vector<vector<int>> adj; // adjacency list of graph
vector<bool> visited;
vector<int> ans;

void dfs(int v) {
    visited[v] = true;
    for (int u : adj[v]) {
        if (!visited[u])
            dfs(u);
    }
    ans.push_back(v);
}

void topological_sort() {
    visited.assign(n, false);
    ans.clear();
    for (int i = 0; i < n; ++i) {
        if (!visited[i]) {
            dfs(i);
        }
    }
    reverse(ans.begin(), ans.end());
}

```

2.4 Floyd-Warshall

```

//O(n^3)

//inicializar todo en INF previo a la lectura
for (int k = 0; k < n; ++k) {
    for (int i = 0; i < n; ++i) {
        for (int j = 0; j < n; ++j) {
            d[i][j] = min(d[i][j], d[i][k] + d[k][j]);
        }
    }
}

//Si se tienen pesos negativos:
for (int k = 0; k < n; ++k) {
    for (int i = 0; i < n; ++i) {
        for (int j = 0; j < n; ++j) {
            if (d[i][k] < INF && d[k][j] < INF)
                d[i][j] = min(d[i][j], d[i][k] + d[k][j]);
        }
    }
}

//Pesos reales
if (d[i][k] + d[k][j] < d[i][j] - EPS)
    d[i][j] = d[i][k] + d[k][j];

/*Identificar ciclos negativos:
Si al final del algoritmo d[i][i] es negativo.*/

```

2.5 Dijkstra

```

//O(n^2+m)

```

```

for (int i = 1; i <= n; i++) distance[i] = INF;
distance[x] = 0;
q.push({0,x});
while (!q.empty()) {
    int a = q.top().second; q.pop();
    if (processed[a]) continue;
    processed[a] = true;
    for (auto u : adj[a]) {
        int b = u.first, w = u.second;
        if (distance[a]+w < distance[b]) {
            distance[b] = distance[a]+w;
            q.push({-distance[b],b});
        }
    }
}

```

2.6 Shortest Path Fast algorithm

```

//O(nm)
const int INF = 1000000000;
vector<vector<pair<int, int>>> adj;

bool spfa(int s, vector<int>& d) {
    int n = adj.size();
    d.assign(n, INF);
    vector<int> cnt(n, 0);
    vector<bool> inqueue(n, false);
    queue<int> q;

    d[s] = 0;
    q.push(s);
    inqueue[s] = true;
    while (!q.empty()) {
        int v = q.front();
        q.pop();
        inqueue[v] = false;

        for (auto edge : adj[v]) {
            int to = edge.first;
            int len = edge.second;

            if (d[v] + len < d[to]) {
                d[to] = d[v] + len;
                if (!inqueue[to]) {
                    q.push(to);
                    inqueue[to] = true;
                    cnt[to]++;
                    if (cnt[to] > n)
                        return false; // negative cycle
                }
            }
        }
    }
    return true;
}

```

3 Dynamic Programming

3.1 Coin Exchange Problem

```

#include <bits/stdc++.h>
using namespace std;

// Returns total distinct ways to make sum using n coins of
// different denominations
int count(vector<int>& coins, int n, int sum)
{
    // 2d dp array where n is the number of coin
    // denominations and sum is the target sum
    vector<vector<int>> dp(n + 1, vector<int>(sum + 1, 0));

    // Represents the base case where the target sum is 0,
    // and there is only one way to make change: by not
    // selecting any coin
    dp[0][0] = 1;
    for (int i = 1; i <= n; i++) {
        for (int j = 0; j <= sum; j++) {

            // Add the number of ways to make change without
            // using the current coin,
            dp[i][j] += dp[i - 1][j];

            if ((j - coins[i - 1]) >= 0) {

                // Add the number of ways to make change
                // using the current coin
                dp[i][j] += dp[i][j - coins[i - 1]];
            }
        }
    }
    return dp[n][sum];
}

// Driver Code
int main()
{
    vector<int> coins{ 1, 2, 3 };
    int n = 3;
    int sum = 5;
    cout << count(coins, n, sum);
    return 0;
}

```

4 Flows

4.1 Dinic

```

struct FlowEdge {
    int v, u;
    long long cap, flow = 0;
    FlowEdge(int v, int u, long long cap) : v(v), u(u), cap(
        cap) {}
};

struct Dinic {
    const long long flow_inf = 1e18;
    vector<FlowEdge> edges;
    vector<vector<int>> adj;
    int n, m = 0;
    int s, t;
    vector<int> level, ptr;
    queue<int> q;
}

```

```

Dinic(int n, int s, int t) : n(n), s(s), t(t) {
    adj.resize(n);
    level.resize(n);
    ptr.resize(n);
}

void add_edge(int v, int u, long long cap) {
    edges.emplace_back(v, u, cap);
    edges.emplace_back(u, v, 0);
    adj[v].push_back(m);
    adj[u].push_back(m + 1);
    m += 2;
}

bool bfs() {
    while (!q.empty()) {
        int v = q.front();
        q.pop();
        for (int id : adj[v]) {
            if (edges[id].cap - edges[id].flow < 1)
                continue;
            if (level[edges[id].u] != -1)
                continue;
            level[edges[id].u] = level[v] + 1;
            q.push(edges[id].u);
        }
    }
    return level[t] != -1;
}

long long dfs(int v, long long pushed) {
    if (pushed == 0)
        return 0;
    if (v == t)
        return pushed;
    for (int& cid = ptr[v]; cid < (int)adj[v].size(); cid++) {
        int id = adj[v][cid];
        int u = edges[id].u;
        if (level[v] + 1 != level[u] || edges[id].cap - edges[id].flow < 1)
            continue;
        long long tr = dfs(u, min(pushed, edges[id].cap - edges[id].flow));
        if (tr == 0)
            continue;
        edges[id].flow += tr;
        edges[id ^ 1].flow -= tr;
        return tr;
    }
    return 0;
}

long long flow() {
    long long f = 0;
    while (true) {
        fill(level.begin(), level.end(), -1);
        level[s] = 0;
        q.push(s);
        if (!bfs())
            break;
        fill(ptr.begin(), ptr.end(), 0);
        while (long long pushed = dfs(s, flow_inf)) {
            f += pushed;
        }
    }
}

```

```

    }
    return f;
};

```

4.2 MinCost Flow

```

struct Edge
{
    int from, to, capacity, cost;
};

vector<vector<int>> adj, cost, capacity;

const int INF = 1e9;

void shortest_paths(int n, int v0, vector<int>& d, vector<int>& p) {
    d.assign(n, INF);
    d[v0] = 0;
    vector<bool> inq(n, false);
    queue<int> q;
    q.push(v0);
    p.assign(n, -1);

    while (!q.empty()) {
        int u = q.front();
        q.pop();
        inq[u] = false;
        for (int v : adj[u]) {
            if (capacity[u][v] > 0 && d[v] > d[u] + cost[u][v]) {
                d[v] = d[u] + cost[u][v];
                p[v] = u;
                if (!inq[v]) {
                    inq[v] = true;
                    q.push(v);
                }
            }
        }
    }
}

int min_cost_flow(int N, vector<Edge> edges, int K, int s, int t) {
    adj.assign(N, vector<int>());
    cost.assign(N, vector<int>(N, 0));
    capacity.assign(N, vector<int>(N, 0));
    for (Edge e : edges) {
        adj[e.from].push_back(e.to);
        adj[e.to].push_back(e.from);
        cost[e.from][e.to] = e.cost;
        cost[e.to][e.from] = -e.cost;
        capacity[e.from][e.to] = e.capacity;
    }

    int flow = 0;
    int cost = 0;
    vector<int> d, p;
    while (flow < K) {
        shortest_paths(N, s, d, p);
        if (d[t] == INF)
            break;

        // find max flow on that path
    }
}

```

```

int f = K - flow;
int cur = t;
while (cur != s) {
    f = min(f, capacity[p[cur]][cur]);
    cur = p[cur];
}

// apply flow
flow += f;
cost += f * d[t];
cur = t;
while (cur != s) {
    capacity[p[cur]][cur] -= f;
    capacity[cur][p[cur]] += f;
    cur = p[cur];
}

}

if (flow < K)
    return -1;
else
    return cost;
}

```

5 Math

5.1 Primes

/*	3	5	7	11	13	17	19
2	23	29	31	37	41	43	47
	53	59	61	67	71	73	79
	83	89					
97	101	103	107	109	113	127	131
	137	139	149	151	157	163	167
	173	179	181	191	193	197	199
	211	223					
227	229	233	239	241	251	257	263
	269	271	277	281	283	293	307
	311	313	317	331	337	347	349
	353	359					
367	373	379	383	389	397	401	409
	419	421	431	433	439	443	449
	457	461	463	467	479	487	491
	499	503					
509	521	523	541	547	557	563	569
	571	577	587	593	599	601	607
	613	617	619	631	641	643	647
	653	659					
661	673	677	683	691	701	709	719
	727	733	739	743	751	757	761
	769	773	787	797	809	811	821
	823	827					
829	839	853	857	859	863	877	881
	883	887	907	911	919	929	937
	941	947	953	967	971	977	983
	991	997					
1009	1013	1019	1021	1031	1033	1039	1049
	1051	1061	1063	1069	1087	1091	1093
	1097	1103	1109	1117	1123		
1129	1151	1153	1163	1171	1181	1187	1193
	1201	1213	1217	1223	1229	1231	1237

	1249	1259	1277	1279	1283		
1289	1291	1297	1301	1303	1307	1319	1321
	1327	1361	1367	1373	1381	1399	1409
	1423	1427	1429	1433	1439		
1447	1451	1453	1459	1471	1481	1483	1487
	1489	1493	1499	1511	1523	1531	1543
	1549	1553	1559	1567	1571		
1579	1583	1597	1601	1607	1609	1613	1619
	1621	1627	1637	1657	1663	1667	1669
	1693	1697	1699	1709	1721		
1723	1733	1741	1747	1753	1759	1777	1783
	1787	1789	1801	1811	1823	1831	1847
	1861	1867	1871	1873	1877		
1879	1889	1901	1907	1913	1931	1933	1949
	1951	1973	1979	1987	1993	1997	1999

*/

5.2 Log Utils

```

ln: log()
log base 10: log10()
e: exp()
primos aproximados hasta x: x/ln(x) o x/(ln(x)-1.08366)

```

5.3 Modular Operations

```

const int MOD = 998244353;

int add ( int A, int B ) { return A+B<MOD? A+B: A+B-MOD; }
int mul ( int A, int B ) { return ll(A)*B % ll(MOD); }
int sub ( int A, int B ) { return add ( A, MOD-B ); }

```

5.4 Line Representation

```

//si b=0: es como si fuera oo o -oo
//si a=0: la fraccion es 0

```

```

struct frac{
    ll a,b;
    frac(ll_a, ll_b): a(_a), b(_b){
        if(b<0) a*=-1, b*=-1;
        if(b==0) a = 1;
    }

    bool operator < (frac other){
        return a * other.b < b * other.a;
    }
};

map<frac,frac> mp;

```

5.5 Lines Intersection

```

typedef complex<double> point;
/*Line Segment Intersection*/

double dot(const point &a, const point &b) { return real(conj(
    a) * b); }

```

```
double cross(const point &a, const point &b) { return imag(
    conj(a) * b); }

// returns intersection of infinite lines ab and pq (undefined
// if they are parallel)
point intersect(const point &a, const point &b, const point &p
, const point &q)
{
    double d1 = cross(p - a, b - a);
    double d2 = cross(q - a, b - a);
    return (d1 * q - d2 * p) / (d1 - d2);
}

int main(){
    vector<int> p(8);
    for(int i=0; i < 8; i++){
        cin >> p[i];
    }

    point a(p[0],p[1]), b(p[2],p[3]), c(p[4],p[5]), d(p[6],p
[7]);

    point ans = intersect(a,b,c,d);
    cout << fixed << setprecision(2) << real(ans) << " " <<
        imag(ans) << endl;
}

```

5.6 Criba

```
int cribe[N];

for(int i=2; i < N; i++){
    if(!cribe[i]){
        for(int k=i+i; k<N; k+=i){
            cribe[k] = i;
        }
    }
}

```

5.7 FastCriba

```
#define forr(i,a,b) for(int i=(a); i<(b); i++)
typedef long long ll;
typedef pair<int,int> ii;

#define MAXP 100000 //no necesariamente primo
int criba[MAXP+1];
void crearcriba(){
    int w[] = {4,2,4,2,4,6,2,6};
    for(int p=25;p<=MAXP;p+=10) criba[p]=5;
    for(int p=9;p<=MAXP;p+=6) criba[p]=3;
    for(int p=4;p<=MAXP;p+=2) criba[p]=2;
    for(int p=7,cur=0;p*p<=MAXP;p+=w[cur++&7]) if (!criba[
        p])
        for(int j=p*p;j<=MAXP;j+=(p<<1)) if(!criba[j])
            criba[j]=p;
}

vector<int> primos;
void buscarprimos(){
    crearcriba();
    forr (i,2,MAXP+1) if (!criba[i]) primos.push_back(i);
}

```

```
//~ Useful for bit trick: #define SET(i) ( criba[(i)
>>5]|=1<<((i)&31) ), #define INDEX(i) ( (criba[i]>>5)>>((i)
&31))&1 ), unsigned int criba[MAXP/32+1];

int main() {
    freopen("primos", "w", stdout);
    buscarprimos();
    cout << '{';
    bool first=true;
    forall(it, primos){
        if(first) first=false;
        else cout << ',';
        cout << *it;
    }
    cout << "};\n";
    return 0;
}

```

5.8 Fast Exp.

```
ll binpow(ll a, ll b) {
    /*si se necesita la potencia modulo m: aplicar el modulo a
    todas
    las multiplicaciones y a 'a' al antes del loop*/
    ll res = 1;
    while (b > 0) {
        if (b & 1)
            res = res * a;
        a = a * a;
        b >>= 1;
    }
    return res;
}

```

5.9 Matrix Power

```
ll MOD;
const int MAX_N = 2;

struct Matrix {ll mat[MAX_N][MAX_N];};

ll mod(ll a, ll m) {return ((a%m)+m)%m;}

Matrix matMul(Matrix a, Matrix b){
    Matrix ans;
    rep(i,MAX_N){
        rep(j, MAX_N){
            ans.mat[i][j] = 0;
        }
    }
    rep(i,MAX_N){
        rep(k,MAX_N){
            if(a.mat[i][k] == 0) continue;
            rep(j, MAX_N){
                ans.mat[i][j] += mod(a.mat[i][k], MOD) * mod(b
                    .mat[k][j], MOD);
                ans.mat[i][j] = mod(ans.mat[i][j], MOD);
            }
        }
    }
    return ans;
}

```

```

Matrix matPow(Matrix base, ll p){
    Matrix ans;
    rep(i,MAX_N)
        rep(j,MAX_N)
            ans.mat[i][j] = (i==j);

    while(p){
        if(p&1) ans = matMul(ans,base);
        base = matMul(base,base);
        p >>= 1;
    }
    return ans;
}

int main(){
    /*Fib(n) mod 2 ^ m*/
    ll n, m;
    MOD = binpow(2,m);
    Matrix mat;
    mat.mat[0][0] = 1;
    mat.mat[0][1] = 1;
    mat.mat[1][0] = 1;
    mat.mat[1][1] = 0;

    Matrix aa = matPow(mat, n);

    cout << aa.mat[0][1] << endl;
}

```

5.10 Fast Matrix Exp.

```

#define forn(i,n) forr(i,0,n)
#define SIZE 350
int NN;
double tmp[SIZE][SIZE];
void mul(double a[SIZE][SIZE], double b[SIZE][SIZE]){ zero(tmp);
    forn(i, NN) forn(j, NN) forn(k, NN) res[i][j]+=a[i][k]*b[k][j];
    forn(i, NN) forn(j, NN) a[i][j]=res[i][j];
}
void powmat(double a[SIZE][SIZE], int n, double res[SIZE][SIZE]){
    forn(i, NN) forn(j, NN) res[i][j]=(i==j);
    while(n){
        if(n&1) mul(res, a), n--;
        else mul(a, a), n/=2;
    }
}

```

5.11 Euclidean algorithm

```

//Iterative
int gcd(int a, int b, int& x, int& y) {
    x = 1, y = 0;
    int x1 = 0, y1 = 1, a1 = a, b1 = b;
    while (b1) {
        int q = a1 / b1;
        tie(x, x1) = make_tuple(x1, x - q * x1);
        tie(y, y1) = make_tuple(y1, y - q * y1);
    }
}

```

```

        tie(a1, b1) = make_tuple(b1, a1 - q * b1);
    }
    return a1;
}

```

5.12 GaussJordan

```

const double EPS = 1e-9;
const int INF = 2; // it doesn't actually have to be infinity
                     // or a big number

int gauss (vector < vector<double> > a, vector<double> & ans)
{
    int n = (int) a.size();
    int m = (int) a[0].size() - 1;

    vector<int> where (m, -1);
    for (int col=0, row=0; col<m && row<n; ++col) {
        int sel = row;
        for (int i=row; i<n; ++i)
            if (abs (a[i][col]) > abs (a[sel][col]))
                sel = i;
        if (abs (a[sel][col]) < EPS)
            continue;
        for (int i=col; i<=m; ++i)
            swap (a[sel][i], a[row][i]);
        where[col] = row;

        for (int i=0; i<n; ++i)
            if (i != row) {
                double c = a[i][col] / a[row][col];
                for (int j=col; j<=m; ++j)
                    a[i][j] -= a[row][j] * c;
            }
        ++row;
    }

    ans.assign (m, 0);
    for (int i=0; i<m; ++i)
        if (where[i] != -1)
            ans[i] = a[where[i]][m] / a[where[i]][i];

    for (int i=0; i<n; ++i) {
        double sum = 0;
        for (int j=0; j<m; ++j)
            sum += ans[j] * a[i][j];
        if (abs (sum - a[i][m]) > EPS)
            return 0;
    }

    for (int i=0; i<m; ++i)
        if (where[i] == -1)
            return INF;
    return 1;
}

```

5.13 Chinese Remainder Theorem

```

struct Congruence {
    long long a, m;
};

long long chinese_remainder_theorem(vector<Congruence> const&
    congruences) {
}

```



```

long long M = 1;
for (auto const& congruence : congruences) {
    M *= congruence.m;
}

long long solution = 0;
for (auto const& congruence : congruences) {
    long long a_i = congruence.a;
    long long M_i = M / congruence.m;
    long long N_i = mod_inv(M_i, congruence.m);
    solution = (solution + a_i * M_i % M * N_i) % M;
}
return solution;
}

```

6 Geometry

6.1 Poligon

```

#include <bits/stdc++.h>
using namespace std;

const double EPS = 1e-9;

double DEG_to_RAD(double d) { return d*M_PI / 180.0; }
double RAD_to_DEG(double r) { return r*180.0 / M_PI; }

struct point { double x, y; // only used if more precision
               // is needed
    point() { x = y = 0.0; } // default
    point(double _x, double _y) : x(_x), y(_y) {} // user
    // -defined
    bool operator==(const point& other) const {
        return (fabs(x-other.x) < EPS && (fabs(y-other.y) < EPS));
    }
    bool operator<(const point& p) const {
        return x < p.x || (abs(x-p.x) < EPS && y < p.y); } };

struct vec { double x, y; // name: 'vec' is different from
                        // STL vector
    vec(double _x, double _y) : x(_x), y(_y) {} };

vec toVec(point a, point b) { // convert 2 points to
    // vector a->b
    return vec(b.x-a.x, b.y-a.y); }

double dist(point p1, point p2) { // Euclidean
    // distance
    return hypot(p1.x-p2.x, p1.y-p2.y); } //
    // return double

// returns the perimeter of polygon P, which is the sum of
// Euclidian distances of consecutive line segments (polygon
// edges)
double perimeter(const vector<point> &P) { // by ref for
    // efficiency
    double ans = 0.0;
    for (int i = 0; i < (int)P.size()-1; ++i) // note: P[n
        // -1] = P[0]
        ans += dist(P[i], P[i+1]); // as we
        // duplicate P[0]
}

```

```

    return ans;
}

// returns the area of polygon P
double area(const vector<point> &P) {
    double ans = 0.0;
    for (int i = 0; i < (int)P.size()-1; ++i) // Shoelace
        // formula
        ans += (P[i].x*P[i+1].y - P[i+1].x*P[i].y);
    return fabs(ans)/2.0; // only do /
    // 2.0 here
}

double dot(vec a, vec b) { return (a.x*b.x + a.y*b.y); }
double norm_sq(vec v) { return v.x*v.x + v.y*v.y; }

double angle(point a, point o, point b) { // returns angle
    // aob in rad
    vec oa = toVec(o, a), ob = toVec(o, b);
    return acos(dot(oa, ob) / sqrt(norm_sq(oa) * norm_sq(ob)));
}

double cross(vec a, vec b) { return a.x*b.y - a.y*b.x; }

// returns the area of polygon P, which is half the cross
// products
// of vectors defined by edge endpoints
double area_alternative(const vector<point> &P) {
    double ans = 0.0; point O(0.0, 0.0); // O = the
    // Origin
    for (int i = 0; i < (int)P.size()-1; ++i) // sum of
        // signed areas
        ans += cross(toVec(O, P[i]), toVec(O, P[i+1]));
    return fabs(ans)/2.0;
}

// note: to accept collinear points, we have to change the '>'
// to '0'
// returns true if point r is on the left side of line pq
bool ccw(point p, point q, point r) {
    return cross(toVec(p, q), toVec(p, r)) > 0;
}

// returns true if point r is on the same line as the line pq
bool collinear(point p, point q, point r) {
    return fabs(cross(toVec(p, q), toVec(p, r))) < EPS;
}

// returns true if we always make the same turn
// while examining all the edges of the polygon one by one
bool isConvex(const vector<point> &P) {
    int n = (int)P.size();
    // a point/sz=2 or a line/sz=3 is not convex
    if (n <= 3) return false;
    bool firstTurn = ccw(P[0], P[1], P[2]); // remember
    // one result,
    for (int i = 1; i < n-1; ++i) // compare
        // with the others
        if (ccw(P[i], P[i+1], P[(i+2) == n ? 1 : i+2]) !=
            firstTurn)
            return false; // different
            // -> concave
    return true; // otherwise
    // -> convex
}

```

```

// returns 1/0/-1 if point p is inside/on (vertex/edge)/
// outside of
// either convex/concave polygon P
int insidePolygon(point pt, const vector<point> &P) {
    int n = (int)P.size();
    if (n <= 3) return -1; // avoid
    // point or line
    bool on_polygon = false;
    for (int i = 0; i < n-1; ++i) // on vertex/
    // edge?
        if (fabs(dist(P[i], pt) + dist(pt, P[i+1]) - dist(P[i], P[
            i+1])) < EPS)
            on_polygon = true;
    if (on_polygon) return 0; // pt is on
    // polygon
    double sum = 0.0; // first =
    // last point
    for (int i = 0; i < n-1; ++i) {
        if (ccw(pt, P[i], P[i+1]))
            sum += angle(P[i], pt, P[i+1]); // left turn/
            // CCW
        else
            sum -= angle(P[i], pt, P[i+1]); // right turn
            // CW
    }
    return fabs(sum) > M_PI ? 1 : -1; // 360d->in,
    // 0d->out
}

// compute the intersection point between line segment p-q and
// line A-B
point lineIntersectSeg(point p, point q, point A, point B) {
    double a = B.y-A.y, b = A.x-B.x, c = B.x*A.y - A.x*B.y;
    double u = fabs(a*p.x + b*p.y + c);
    double v = fabs(a*q.x + b*q.y + c);
    return point((p.x*v + q.x*u) / (u+v), (p.y*v + q.y*u) / (u+v
    ));
}

// cuts polygon Q along the line formed by point A->point B (
// order matters)
// (note: the last point must be the same as the first point)
vector<point> cutPolygon(point A, point B, const vector<point>
    &Q) {
    vector<point> P;
    for (int i = 0; i < (int)Q.size(); ++i) {
        double left1 = cross(toVec(A, B), toVec(A, Q[i])), left2 =
        // 0;
        if (i != (int)Q.size()-1) left2 = cross(toVec(A, B), toVec
            (A, Q[i+1]));
        if (left1 > -EPS) P.push_back(Q[i]); // Q[i] is on
        // the left
        if (left1*left2 < -EPS) // crosses
        // line AB
            P.push_back(lineIntersectSeg(Q[i], Q[i+1], A, B));
    }
    if (!P.empty() && !P.back() == P.front())
        P.push_back(P.front()); // wrap
    // around
    return P;
}

vector<point> CH_Graham(vector<point> &Pts) { // overall O(
    // n log n)
    vector<point> P(Pts); // copy all

```

```

    points
    int n = (int)P.size();
    if (n <= 3) { // point/line
        // triangle
        if (!P[0] == P[n-1]) P.push_back(P[0]); // corner
        // case
        return P; // the CH is
        // P itself
    }

    // first, find P0 = point with lowest Y and if tie:
    // rightmost X
    int P0 = min_element(P.begin(), P.end())-P.begin();
    swap(P[0], P[P0]); // swap P[P0]
    // with P[0]

    // second, sort points by angle around P0, O(n log n) for
    // this sort
    sort(++P.begin(), P.end(), [&](point a, point b) {
        return ccw(P[0], a, b); // use P[0]
        // as the pivot
    });

    // third, the ccw tests, although complex, it is just O(n)
    vector<point> S({P[n-1], P[0], P[1]}); // initial S
    int i = 2; // then, we
    // check the rest
    while (i < n) { // n > 3, O(n)
        int j = (int)S.size()-1;
        if (ccw(S[j-1], S[j], P[i])) // CCW turn
            S.push_back(P[i++]); // accept
        // this point
        else // CW turn
            S.pop_back(); // pop until
            // a CCW turn
    }
    return S; // return the
    // result
}

vector<point> CH_Andrew(vector<point> &Pts) { // overall O(
    // n log n)
    int n = Pts.size(), k = 0;
    vector<point> H(2*n);
    sort(Pts.begin(), Pts.end()); // sort the
    // points by x/y
    for (int i = 0; i < n; ++i) { // build
        // lower hull
        while ((k >= 2) && !ccw(H[k-2], H[k-1], Pts[i])) --k;
        H[k++] = Pts[i];
    }
    for (int i = n-2, t = k+1; i >= 0; --i) { // build
        // upper hull
        while ((k >= t) && !ccw(H[k-2], H[k-1], Pts[i])) --k;
        H[k++] = Pts[i];
    }
    H.resize(k);
    return H;
}

int main() {
    // 6(+1) points, entered in counter clockwise order, 0-based
    // indexing
    vector<point> P;
    P.emplace_back(1, 1); // P0

```

```

P.emplace_back(3, 3); // P1
P.emplace_back(9, 1); // P2
P.emplace_back(12, 4); // P3
P.emplace_back(9, 7); // P4
P.emplace_back(1, 7); // P5
P.push_back(P[0]); // loop back,
P6 = P0

printf("Perimeter = %.2lf\n", perimeter(P)); // 31.64
printf("Area = %.2lf\n", area(P)); // 49.00
printf("Area = %.2lf\n", area_alternative(P)); // also 49.00
printf("Is convex = %d\n", isConvex(P)); // 0 (false)

//// the positions of P_out, P_on, P_in with respect to the
// polygon
//7 P5-----P_on----P4
//6 | \
//5 | \
//4 | P_in P3
//3 | P1___/
//2 | / P_out \ ___ /
//1 P0 P2
//0 1 2 3 4 5 6 7 8 9 101112

point p_out(3, 2); // outside this (concave) polygon
printf("P_out is inside = %d\n", insidePolygon(p_out, P));
// -1
printf("P1 is inside = %d\n", insidePolygon(P[1], P)); // 0
point p_on(5, 7); // on this (concave) polygon
printf("P_on is inside = %d\n", insidePolygon(p_on, P)); //
0
point p_in(3, 4); // inside this (concave) polygon
printf("P_in is inside = %d\n", insidePolygon(p_in, P)); //
1

// cutting the original polygon based on line P[2] -> P[4] (
// get the left side)
//7 P5-----P4
//6 | | \
//5 | | \
//4 | | P3
//3 | P1___| /
//2 | / \ ___ | /
//1 P0 P2
//0 1 2 3 4 5 6 7 8 9 101112
// new polygon (notice the index are different now):
//7 P4-----P3
//6 | |
//5 | |
//4 | |
//3 | P1___|
//2 | / \ ___ |
//1 P0 P2
//0 1 2 3 4 5 6 7 8 9

P = cutPolygon(P[2], P[4], P);
printf("Perimeter = %.2lf\n", perimeter(P)); // smaller
now, 29.15
printf("Area = %.2lf\n", area(P)); // 40.00

// running convex hull of the resulting polygon (index
// changes again)
//7 P3-----P2

```

```

//6 | |
//5 | |
//4 | P_out |
//3 | |
//2 | P_in |
//1 P0-----P1
//0 1 2 3 4 5 6 7 8 9

P = CH_Graham(P); // now this
// is a rectangle
printf("Perimeter = %.2lf\n", perimeter(P)); // precisely
28.00
printf("Area = %.2lf\n", area(P)); // precisely
48.00
printf("Is convex = %d\n", isConvex(P)); // true
printf("P_out is inside = %d\n", insidePolygon(p_out, P));
// 1
printf("P_in is inside = %d\n", insidePolygon(p_in, P)); //
1

return 0;
}

```

7 Range Queries

7.1 BIT

```

const int N = 200005;
int BIT[N];

void update(int idx, int val){
    for(; idx < N; idx += idx & (-idx)){
        BIT[idx] += val;
    }
}

int query (int idx){
    ll ret = 0;
    for(; idx > 0; idx -= idx & (-idx)){
        ret += BIT[idx];
    }
    return ret;
}

int query (int left, int right){
    return query(right) - query(left-1);
}

int lower_find(int val){
    int id = 0;
    for(int i = 31-__builtin_clz(n); i >= 0; --i){
        int nid = id | (1 << i);
        if(nid <= n && BIT[nid] <= val){
            val -= BIT[nid];
            id = nid;
        }
    }
    return id;
}

iota(idx+1, idx+n+1, 1);

```

```

sort(idx+1, idx+n+1, [](int i_a, int i_b) { return arr[i_a] >
    arr[i_b];});
//Update range [l,r] to v
update(l,v);
update(r+1,-v);

//Update specific value at pos k to u
ll prev = query(k)-query(k-1);
update(k,u);
update(k, -prev);

//Inversions
for(int i=1; i <=n; i++){
    forward[i] = query(values[i]);
    update(1,1);
    update(values[i],-1);
}
memset(BIT, 0, sizeof BIT);

for(int i=n; i > 0 ; i--){
    backward[i] = query(values[i]);
    update(values[i]+1, 1);
}

//Dimension change
sort(difval, difval+ind);
map<int,int> idx;
int cnt = 0;
idx[difval[0]] = cnt;
cnt++;
for(int i=1; i < ind; i++){
    if(difval[i] != difval[i-1]){
        idx[difval[i]] = cnt;
        cnt++;
    }
}

```

7.2 Basic Segment Tree

```

const int N = 1e6+5;
struct SegTree {
    SegTree *L, *R;
    int fr, to;

    SegTree (int fr, int to):
        fr(fr), to(to){
        if(fr == to){
            //Calc base values
            L = R = NULL;
        }else if (fr < to){
            L = new SegTree(fr, (fr+to)/2);
            R = new SegTree((L->to)+1, to);
            //Calc value: L->value + R->value
        }
    }

    void propagate () {
        //Propagation operation
    }

    void update(int l, int r) {
        propagate();
    }
}

```

```

if(l == fr && r == to){
    //Change before prop? ex: change ^= true;
    propagate();
    return;
}
if(r < R->fr){
    L->update(l,r);
    R->propagate();
}else if(l > L->to){
    R->update(l,r);
    L->propagate();
}else{
    L->update(l, L->to);
    R->update(R->fr, r);
}
//Calc values, ex: num_on = L->num_on + R->num_on;
};

```

7.3 Segment Tree Range Query

```

const int N = 1e5; // limit for array size
int n; // array size
int t[2 * N];

void build() { // build the tree
    for (int i = n - 1; i > 0; --i) t[i] = t[i<<1] + t[i<<1|1];
} //O(n)

void modify(int p, int value) { // set value at position p
    for (t[p += n] = value; p > 1; p >>= 1) t[p>>1] = t[p] + t[p
        ^1];
} //O(log(n))

int query(int l, int r) { // sum on interval [l, r]
    int res = 0;
    for (l += n, r += n; l < r; l >>= 1, r >>= 1) {
        if (l&1) res += t[l++];
        if (r&1) res += t[--r];
    }
    return res;
} //O(log(n))

int main() {
    scanf("%d", &n);
    for (int i = 0; i < n; ++i) scanf("%d", t + n + i);
    build();
    modify(0, 1);
    printf("%d\n", query(3, 11));
    return 0;
}

```

7.4 Segment Tree Range Update

```

void modify(int l, int r, int value) {
    for (l += n, r += n; l < r; l >>= 1, r >>= 1) {
        if (l&1) t[l++] += value;
        if (r&1) t[--r] += value;
    }
}

int query(int p) {

```

```

int res = 0;
for (p += n; p > 0; p >>= 1) res += t[p];
return res;
}

/*Push to inspect modifications*/
void push() {
    for (int i = 1; i < n; ++i) {
        t[i<<1] += t[i];
        t[i<<1|1] += t[i];
        t[i] = 0;
    }
} //

```

7.5 Segment Tree Lazy Propagation

```

const int N = 500005;
const int MOD = 998244353;

int add ( int A, int B ) { return A+B<MOD? A+B: A+B-MOD; }
int mul ( int A, int B ) { return 1l(A)*B % 1l(MOD); }
int sub ( int A, int B ) { return add ( A, MOD-B ); }

int n, q, h;

int sum[2*N];
pii lazy[2*N];
int lengths[2*N];

pii combine ( pii A, pii B ) {
    return {mul(A.ff, B.ff), add(mul(A.ss, B.ff), B.ss)};
}

void apply(int p, pii value) {
    sum[p] = add(mul(sum[p], value.ff), mul(lengths[p], value.ss));
    if (p < n) lazy[p] = combine(lazy[p], value);
}

void build_t() { // build the tree
    for (int i = n - 1; i > 0; --i) {
        sum[i] = add(sum[i<<1], sum[i<<1|1]);
        lengths[i] = lengths[i<<1]+lengths[i<<1|1];
        lazy[i] = {1,0};
    }
}

void build(int p) {
    while (p > 1){
        p >>= 1;
        if(lazy[p] == pii(1,0)) sum[p] = add(sum[p<<1], sum[p<<1|1]);
    }
}

void push(int p) {
    for (int s = h-1; s > 0; --s) {
        int i = p >> s;
        if (lazy[i] != pii(1,0)) {
            apply(i<<1, lazy[i]);
            apply(i<<1|1, lazy[i]);
            lazy[i] = {1,0};
        }
    }
}

```

```

}

void modify(int l, int r, pii value) {
    l += n, r += n;
    int l0 = l, r0 = r;
    push(l0);
    push(r0 - 1);
    for (; l < r; l >>= 1, r >>= 1) {
        if (l&1) apply(l++, value);
        if (r&1) apply(--r, value);
    }
    build(l0);
    build(r0 - 1);
}

int query(int l, int r) {
    l += n, r += n;
    push(l);
    push(r - 1);
    int res = 0;
    for (; l < r; l >>= 1, r >>= 1) {
        if (l&1) res = add(res, sum[l++]);
        if (r&1) res = add(sum[--r], res);
    }
    return res;
}

//Initialization:
scanf ( "%d%d", &n, &q );
h = sizeof(int) * 8 - __builtin_clz(n);
//cout << "h: " << h << endl;

for ( int i = n; i < 2*n; ++i ) {
    scanf ( "%d", &sum[i] );
    lengths[i] = 1;
}

build_t();

```

7.6 Sparse Table

```

#include <bits/stdc++.h>
using namespace std;

typedef vector<int> vi;

class SparseTable { // OOP style
private:
    vi A, P2, L2;
    vector<vi> SpT; // the Sparse Table
public:
    SparseTable() {} // default constructor

    SparseTable(vi &initialA) { // pre-
        processing routine
        A = initialA;
        int n = (int)A.size();
        int L2_n = (int)log2(n)+1;
        P2.assign(L2_n+1, 0);
        L2.assign((1<<L2_n)+1, 0);
        for (int i = 0; i <= L2_n; ++i) {

```

```

        P2[i] = (1<<i); // to speed
        up 2^i
        L2[(1<<i)] = i; // to speed
        up log_2(i)
    }
    for (int i = 2; i < P2[L2_n]; ++i)
        if (L2[i] == 0)
            L2[i] = L2[i-1]; // to fill in
                                the blanks

    // the initialization phase
    SpT = vector<vi>(L2[n]+1, vi(n));
    for (int j = 0; j < n; ++j)
        SpT[0][j] = j; // RMQ of sub
                        array [j..j]

    // the two nested loops below have overall time complexity
    // = O(n log n)
    for (int i = 1; P2[i] <= n; ++i) // for all i
        s.t. 2^i <= n
        for (int j = 0; j+P2[i]-1 < n; ++j) { // for all
            valid j
            int x = SpT[i-1][j]; // [j..j+2^(i
            -1)-1]
            int y = SpT[i-1][j+P2[i-1]]; // [j+2^(i-1)
            ..j+2^i-1]
            SpT[i][j] = A[x] <= A[y] ? x : y;
        }
    }

    int RMQ(int i, int j) {
        int k = L2[j-i+1]; // 2^k <= (j-
        i+1)
        int x = SpT[k][i]; // covers [i
        ..i+2^k-1]
        int y = SpT[k][j-P2[k]+1]; // covers [j
        -2^k+1..j]
        return A[x] <= A[y] ? x : y;
    }
};

int main() {
    // same example as in Chapter 2: Segment Tree
    vi A = {18, 17, 13, 19, 15, 11, 20};
    SparseTable SpT(A);
    int n = (int)A.size();
    for (int i = 0; i < n; ++i)
        for (int j = i; j < n; ++j)
            printf("RMQ(%d, %d) = %d\n", i, j, SpT.RMQ(i, j));
    return 0;
}

```

8 Strings

8.1 Borders

```

const int N = 1e6+5;
int b[N];
int sz;

void borders(string p) {
    b[0] = -1;

```

```

    p = '#' + p;
    for (int i=1; i <= sz; i++) {
        int j=b[i-1];
        while (j>=0 && p[i] != p[j+1]) j = b[j];
        b[i] = j+1;
    }

    //Encontrar periodos:
    sz = s.size();
    int aux = sz;
    borders(s);

    while(aux) {
        cout << sz-b[aux] << " ";
        aux = b[aux];
    }
}

```

8.2 Hashing

```

const int p = 283;
const int M = 1e9+7;
const int N = 1e6+1;

int P[N], h[N];

ll bincpow(ll a, ll b) {
    ll res = 1;
    a %= M;
    while (b > 0) {
        if (b & 1)
            res = (res * a) % M;
        a = (a * a) % M;
        b >>= 1;
    }
    return res;
}

void prepareP(int n) {
    P[0] = 1;
    for (int i=1; i < n; ++i) {
        P[i] = ((ll)P[i-1]*p) % M;
    }
}

void computeRollingHash(string T) {
    for (int i=0; i < (int)T.size(); ++i) {
        if (i!=0) h[i] = h[i-1];
        h[i] = (h[i]+((ll)(T[i]-'a'+1)*P[i])%M)%M;
    }
}

int hash_fast(int L, int R) {
    if (L==0) return h[R];
    int ans = 0;
    ans = ((h[R]-h[L-1]) % M + M) % M;
    ans = ((ll)ans*bincpow(P[L],M-2)) % M;
    return ans;
}

```

8.3 Manacher

```
//Find palindromes
vector<int> manacher_odd(string s) {
    int n = s.size();
    s = "$" + s + "^";
    vector<int> p(n + 2);
    int l = 1, r = 1;
    for(int i = 1; i <= n; i++) {
        p[i] = max(0, min(r - i, p[l + (r - i)]));
        while(s[i - p[i]] == s[i + p[i]]) {
            p[i]++;
        }
        if(i + p[i] > r) {
            l = i - p[i], r = i + p[i];
        }
    }
    return vector<int>(begin(p) + 1, end(p) - 1);
}
```

8.4 Z-Algorithm

```
vector<int> z(string s) {
    int n = s.size();
    vector<int> z(n);
    int x = 0, y = 0;
    for (int i = 1; i < n; i++) {
        z[i] = max(0, min(z[i-x], y-i+1));
        while (i+z[i] < n && s[z[i]] == s[i+z[i]]) {
            x = i; y = i+z[i]; z[i]++;
        }
    }
    return z;
}
```

8.5 Prefix Function (KMP)

```
/*KMP
long max del prefijo que tambien es sufijo del substring s
[0...i]*/
vector<int> prefix_function(string s) {
    int n = (int)s.length();
    vector<int> pi(n);
    for (int i = 1; i < n; i++) {
        int j = pi[i-1];
        while (j > 0 && s[i] != s[j])
            j = pi[j-1];
        if (s[i] == s[j])
            j++;
        pi[i] = j;
    }
    return pi;
}
```

8.6 Trie

```
const int N = 500005; //Number of nodes
const int ALPHA = 26; // Number of characters
```

```
int trie[N][ALPHA];
set<int> final_s;
int last_n = 0;

bool is_already(string &s) {
    int curr_node = 0;
    for(char it: s) {
        if(trie[curr_node][it-'a'] == 0) {
            trie[curr_node][it-'a'] = ++last_n;
        }
        curr_node = trie[curr_node][it-'a'];
    }
    bool is_alr = final_s.count(curr_node);
    final_s.insert(curr_node);
    return is_alr;
}
```

8.7 Aho Corasick

```
/*sufijo mas grande en el trie?*/
const int K = 26;
int last_n = 0;

struct Node {
    char c;
    int next[K], go[K]; //next: trie, go: automata
    bool terminal = false;
    int patt = -1;
    int p = -1, link = -1;
    set<int> has_terminals;

    Node(int p=-1, char c = '$') : p(p), c(c) {
        fill(begin(next), end(next), -1);
        fill(begin(go), end(go), -1);
    }
};

vector<Node> trie(1);

void insert(string &s, int idx) {
    int curr_node = 0;
    for(char ch: s) {
        int c = ch-'a';
        if(trie[curr_node].next[c] == -1) {
            trie[curr_node].next[c] = ++last_n;
            trie.emplace_back(curr_node, ch);
        }
        curr_node = trie[curr_node].next[c];
    }
    trie[curr_node].terminal = true;
    trie[curr_node].patt = idx;
}

int go(int v, char ch);

int get_link(int v) {
    if (trie[v].link == -1) {
        if(v == 0 || trie[v].p == 0) {
            trie[v].link = 0;
        }
        else {
            trie[v].link = go(get_link(trie[v].p), trie[v].c);
        }
    }
    return trie[v].link;
}
```

```

}

int go(int v, char ch){
    int c = ch - 'a';
    if(trie[v].go[c] == -1){
        if(trie[v].next[c] != -1){
            trie[v].go[c] = trie[v].next[c];
        } else{
            trie[v].go[c] = v == 0 ? 0 : go(get_link(v), ch);
        }
    }
    return trie[v].go[c];
}

```

8.8 Strings Matching

```

#include <bits/stdc++.h>
using namespace std;

const int MAX_N = 200010;

char T[MAX_N], P[MAX_N];           // T = text,
P = pattern                         // n = |T|, m
int n, m;                          // n = |T|, m
= |P|

// Knuth-Morris-Pratt's algorithm specific code
int b[MAX_N];                      // b = back
table

int naiveMatching() {
    int freq = 0;
    for (int i = 0; i < n; ++i) {   // try all
        starting index
        bool found = true;
        for (int j = 0; (j < m) && found; ++j)
            if ((i+j >= n) || (P[j] != T[i+j])) // if
                mismatch found
                found = false;                // abort this
            , try i+1
        if (found) {                  // T[i..i+m
            -1] = P[0..m-1]
            ++freq;
            // printf("P is found at index %d in T\n", i);
        }
    }
    return freq;
}

void kmpPreprocess() {             // call this
    first
    int i = 0, j = -1; b[0] = -1;   // starting
    values
    while (i < m) {                 // pre-
        process P
        while ((j >= 0) && (P[i] != P[j])) j = b[j]; // different,
        reset j
        ++i; ++j;                  // same,
        advance both
        b[i] = j;
    }
}

```

```

int kmpSearch() {                 // similar as
    above
    int freq = 0;
    int i = 0, j = 0;             // starting
    values
    while (i < n) {                // search
        through T
        while ((j >= 0) && (T[i] != P[j])) j = b[j]; // if
        different, reset j
        ++i; ++j;                 // if same,
        advance both
        if (j == m) {             // a match is
            found
            ++freq;
            // printf("P is found at index %d in T\n", i-j);
            j = b[j];             // prepare j
            for the next
        }
    }
    return freq;
}

// Rabin-Karp's algorithm specific code
typedef long long ll;

const int p = 131;               // p and M
are
const int M = 1e9+7;            // relatively
prime

int Pow[MAX_N];                 // to store p
^i % M
int h[MAX_N];                   // to store
prefix hashes

void computeRollingHash() {      // Overall: O
    (n)
    Pow[0] = 1;                 // compute p^
    i % M
    for (int i = 1; i < n; ++i) // O(n)
        Pow[i] = ((ll)Pow[i-1]*p) % M;
    h[0] = 0;
    for (int i = 0; i < n; ++i) { // O(n)
        if (i != 0) h[i] = h[i-1]; // rolling
        hash
        h[i] = (h[i] + ((ll)T[i]*Pow[i]) % M) % M;
    }
}

int extEuclid(int a, int b, int &x, int &y) { // pass x and
    y by ref
    int xx = y = 0;
    int yy = x = 1;
    while (b) {                  // repeats
        until b == 0
        int q = a/b;
        tie(a, b) = tuple(b, a%b);
        tie(x, xx) = tuple(xx, x-q*xx);
        tie(y, yy) = tuple(yy, y-q*yy);
    }
    return a;                    // returns
    gcd(a, b)
}

int modInverse(int b, int m) {   // returns b
    ^(-1) (mod m)
}

```



```

int x, y;
int d = extEuclid(b, m, x, y);           // to get b*x
        + m*y == d
if (d != 1) return -1;                   // to
        indicate failure
// b*x + m*y == 1, now apply (mod m) to get b*x == 1 (mod m)
return (x+m)%m;                          // this is
        the answer
}

int hash_fast(int L, int R) {             // O(1) hash
        of any substr
if (L == 0) return h[R];                 // h is the
        prefix hashes
int ans = 0;
ans = ((h[R] - h[L-1]) % M + M) % M;      // compute
        differences
ans = ((ll)ans * modInverse(Pow[L], M)) % M; // remove P[L
        ]^-1 (mod M)
return ans;
}

int main() {
// strcpy(T, "I DO NOT LIKE SEVENTY SEV BUT SEVENTY SEVENTY
        SEVEN");
// strcpy(P, "SEVENTY SEVEN");
int extreme_limit = 100000; // experiment time is about 10s+
        total
for (int i = 0; i < extreme_limit-1; ++i) T[i] = 'A'+rand()
        %2;
T[extreme_limit-2] = 'B';
T[extreme_limit-1] = 0;
for (int i = 0; i < 100; ++i) P[i] = 'A'+rand()%2;
P[10] = 0;
n = (int)strlen(T);
m = (int)strlen(P);

//if the end of line character is read too, uncomment the
        line below
//T[n-1] = 0; n--; P[m-1] = 0; m--;

// printf("T = '%s'\n", T);
// printf("P = '%s'\n", P);
// printf("\n");

clock_t t0 = clock();
printf("String Library, #match = ");
char *pos = strstr(T, P);
int freq = 0;
while (pos != NULL) {
        ++freq;
        // printf("P is found at index %d in T\n", pos-T);
        pos = strstr(pos+1, P);
}
printf("%d\n", freq);
clock_t t1 = clock();
printf("Runtime = %.10lf s\n\n", (t1-t0) / (double)
        CLOCKS_PER_SEC);

printf("Naive Matching, #match = ");
printf("%d\n", naiveMatching());
clock_t t2 = clock();
printf("Runtime = %.10lf s\n\n", (t2-t1) / (double)
        CLOCKS_PER_SEC);

printf("Rabin-Karp, #match = ");

```

```

computeRollingHash();                   // use
        Rolling Hash
int hP = 0;
for (int i = 0; i < m; ++i)             // O(n)
        hP = (hP + (ll)P[i]*Pow[i]) % M;
freq = 0;
for (int i = 0; i <= n-m; ++i)          // try all
        starting pos
if (hash_fast(i, i+m-1) == hP) {        // a possible
        match
        ++freq;
        // printf("P is found at index %d in T\n", i);
}
printf("%d\n", freq);
clock_t t3 = clock();
printf("Runtime = %.10lf s\n\n", (t3-t2) / (double)
        CLOCKS_PER_SEC);

printf("Knuth-Morris-Pratt, #match = ");
kmpPreprocess();
printf("%d\n", kmpSearch());
clock_t t4 = clock();
printf("Runtime = %.10lf s\n\n", (t4-t3) / (double)
        CLOCKS_PER_SEC);

return 0;
}

```

8.9 Suffix Array + LCP

```

#include <bits/stdc++.h>
using namespace std;

typedef pair<int, int> ii;
typedef vector<int> vi;

class SuffixArray {
private:
        vi RA; // rank array

        void countingSort(int k) { // O(n)
                int maxi = max(300, n); // up to 255
                ASCII chars
                vi c(maxi, 0); // clear
                frequency table
                for (int i = 0; i < n; ++i) // count the
                        frequency
                        ++c[i+k < n ? RA[i+k] : 0]; // of each
                integer rank
                for (int i = 0, sum = 0; i < maxi; ++i) {
                        int t = c[i]; c[i] = sum; sum += t;
                }
                vi tempSA(n);
                for (int i = 0; i < n; ++i) // sort SA
                        tempSA[c[SA[i]+k < n ? RA[SA[i]+k] : 0]++] = SA[i]; // update SA
                swap(SA, tempSA);
        }

        void constructSA() { // can go up
                to 400K chars
                SA.resize(n);
                iota(SA.begin(), SA.end(), 0); // the
                initial SA
                RA.resize(n);
        }
}

```

```

for (int i = 0; i < n; ++i) RA[i] = T[i];    // initial
    rankings
for (int k = 1; k < n; k <= 1) {            // repeat
    log_2 n times
    // this is actually radix sort
    countingSort(k);                        // sort by 2
    nd item
    countingSort(0);                        // stable-
    sort by 1st item
    vi tempRA(n);
    int r = 0;
    tempRA[SA[0]] = r;                      // re-ranking
    process
    for (int i = 1; i < n; ++i)             // compare
        adj suffixes
        tempRA[SA[i]] = // same pair => same rank r; otherwise
            , increase r
            ((RA[SA[i]] == RA[SA[i-1]]) && (RA[SA[i]+k] == RA[SA
                [i-1]+k])) ?
                r : ++r;
    swap(RA, tempRA);                      // update RA
    if (RA[SA[n-1]] == n-1) break;         // nice
    optimization
}

void computeLCP() {
    vi Phi(n);
    vi PLCP(n);
    PLCP.resize(n);
    Phi[SA[0]] = -1;                       // default
    value
    for (int i = 1; i < n; ++i)             // compute
        Phi in O(n)
        Phi[SA[i]] = SA[i-1];              // remember
        prev suffix
    for (int i = 0, L = 0; i < n; ++i) {     // compute
        PLCP in O(n)
        if (Phi[i] == -1) { PLCP[i] = 0; continue; } // special
        case
        while ((i+L < n) && (Phi[i]+L < n) && (T[i+L] == T[Phi[i
            ]+L]))
            ++L;                           // L incr max
            n times
        PLCP[i] = L;
        L = max(L-1, 0);                   // L dec max
        n times
    }
    LCP.resize(n);
    for (int i = 0; i < n; ++i)             // compute
        LCP in O(n)
        LCP[i] = PLCP[SA[i]];              // restore
        PLCP
}

public:
    const char* T;                         // the input
    string
    const int n;                           // the length
    of T
    vi SA;                                 // Suffix
    Array
    vi LCP;                                // of adj
    sorted suffixes

```

```

SuffixArray(const char* initialT, const int _n) : T(initialT
    ), n(_n) {
    constructSA();                          // O(n log n)
    computeLCP();                          // O(n)
}

ii stringMatching(const char *P) {         // in O(m log
    n)
    int m = (int)strlen(P);                // usually, m
    < n
    int lo = 0, hi = n-1;                  // range =
    [0..n-1]
    while (lo < hi) {                      // find lower
        bound
        int mid = (lo+hi) / 2;              // this is
        round down
        int res = strncmp(T+SA[mid], P, m); // P in
        suffix SA[mid]?
        (res >= 0) ? hi = mid : lo = mid+1; // notice the
        >= sign
    }
    if (strncmp(T+SA[lo], P, m) != 0) return {-1, -1}; // if
    not found
    ii ans; ans.first = lo;
    hi = n-1;                              // range = [
    lo..n-1]
    while (lo < hi) {                      // now find
        upper bound
        int mid = (lo+hi) / 2;
        int res = strncmp(T+SA[mid], P, m);
        (res > 0) ? hi = mid : lo = mid+1; // notice the
        > sign
    }
    if (strncmp(T+SA[hi], P, m) != 0) --hi; // special
    case
    ans.second = hi;
    return ans;                             // returns (
    lb, ub)
}
    found
    // where P is

ii LRS() {                                // (LRS
    length, index)
    int idx = 0, maxLCP = -1;
    for (int i = 1; i < n; ++i)             // O(n),
        start from i = 1
        if (LCP[i] > maxLCP)
            maxLCP = LCP[i], idx = i;
    return {maxLCP, idx};
}

ii LCS(int split_idx) {                   // (LCS
    length, index)
    int idx = 0, maxLCP = -1;
    for (int i = 1; i < n; ++i) {           // O(n),
        start from i = 1
        // if suffix SA[i] and suffix SA[i-1] came from the same
        string, skip
        if ((SA[i] < split_idx) == (SA[i-1] < split_idx))
            continue;
        if (LCP[i] > maxLCP)
            maxLCP = LCP[i], idx = i;
    }
    return {maxLCP, idx};
}

```

```

};

const int MAX_N = 450010;           // can go up
                                     // to 450K chars

char T[MAX_N];
char P[MAX_N];
char LRS_ans[MAX_N];
char LCS_ans[MAX_N];

int main() {
    freopen("sa_lcp_in.txt", "r", stdin);
    scanf("%s", &T);                // read T
    int n = (int)strlen(T);          // count n
    T[n++] = '$';                   // add
                                     // terminating symbol
    SuffixArray S(T, n);             // construct
                                     // SA+LCP

    printf("T = '%s'\n", T);
    printf(" i SA[i] LCP[i] Suffix SA[i]\n");
    for (int i = 0; i < n; ++i)
        printf("%2d %2d %2d %s\n", i, S.SA[i], S.LCP[i],
               T+S.SA[i]);

    // String Matching demo, we will try to find P in T
    strcpy(P, "A");
    auto [lb, ub] = S.stringMatching(P);
    if ((lb != -1) && (ub != -1)) {
        printf("P = '%s' is found SA[%d..%d] of T = '%s'\n", P, lb,
               ub, T);
        printf("They are:\n");
        for (int i = lb; i <= ub; ++i)
            printf(" %s\n", T+S.SA[i]);
    }
    else
        printf("P = '%s' is not found in T = '%s'\n", P, T);

    // LRS demo, find the LRS of T
    auto [LRS_len, LRS_idx] = S.LRS();
    strncpy(LRS_ans, T+S.SA[LRS_idx], LRS_len);
    printf("The LRS is '%s' with length = %d\n", LRS_ans,
           LRS_len);

    // LCS demo, find the LCS of (T, P)
    strcpy(P, "CATA");
    int m = (int)strlen(P);
    strcat(T, P);                    // append P
                                     // to T
    strcat(T, "#");                  // add '#' at
                                     // the back
    n = (int)strlen(T);              // update n

    // reconstruct SA of the combined strings
    SuffixArray S2(T, n);            //
                                     // reconstruct SA+LCP
    int split_idx = n-m-1;
    printf("T+P = '%s'\n", T);
    printf(" i SA[i] LCP[i] From Suffix SA[i]\n");
    for (int i = 0; i < n; ++i)
        printf("%2d %2d %2d %2d %s\n",
               i, S2.SA[i], S2.LCP[i], S2.SA[i] < split_idx ? 1 : 2, T+
               S2.SA[i]);

    auto [LCS_len, LCS_idx] = S2.LCS(split_idx);
    strncpy(LCS_ans, T+S2.SA[LCS_idx], LCS_len);

```

```

    printf("The LCS is '%s' with length = %d\n", LCS_ans,
           LCS_len);
    return 0;
}

```

9 Trees

9.1 LCA

```

/*
Binary lifting:
O(nlogn) para preprocesamiento
O(logn) para cada query
*/
int n, l;
vector<vector<int>> adj;

int timer;
vector<int> tin, tout;
vector<vector<int>> up;

void dfs(int v, int p)
{
    tin[v] = ++timer;
    up[v][0] = p;
    for (int i = 1; i <= l; ++i)
        up[v][i] = up[up[v][i-1]][i-1];

    for (int u : adj[v]) {
        if (u != p)
            dfs(u, v);
    }

    tout[v] = ++timer;
}

bool is_ancestor(int u, int v)
{
    return tin[u] <= tin[v] && tout[u] >= tout[v];
}

int lca(int u, int v)
{
    if (is_ancestor(u, v))
        return u;
    if (is_ancestor(v, u))
        return v;
    for (int i = l; i >= 0; --i) {
        if (!is_ancestor(up[u][i], v))
            u = up[u][i];
    }
    return up[u][0];
}

void preprocess(int root) {
    tin.resize(n);
    tout.resize(n);
    timer = 0;
    l = ceil(log2(n));
    up.assign(n, vector<int>(l + 1));
    dfs(root, root);
}

```

10 algorithm

#include <algorithm> #include <numeric>

Algo	Params	Funcion
sort, stable_sort	f, l	ordena el intervalo
nth_element	f, nth, l	<i>void</i> ordena el n-esimo, y particiona el resto
fill, fill_n	f, l / n, elem	<i>void</i> llena [f, l) o [f, f+n) con elem
lower_bound, upper_bound	f, l, elem	<i>it</i> al primer / ultimo donde se puede insertar elem para que quede ordenada
binary_search	f, l, elem	<i>bool</i> esta elem en [f, l)
copy	f, l, resul	hace $resul+i=f+i \forall i$
find, find_if, find_first_of	f, l, elem / pred / f2, l2	<i>it</i> encuentra $i \in [f, l)$ tq. $i=elem$, $pred(i)$, $i \in [f2, l2)$
count, count_if	f, l, elem/pred	cuenta elem, $pred(i)$
search	f, l, f2, l2	busca $[f2, l2) \in [f, l)$
replace, replace_if	f, l, old / pred, new	cambia old / $pred(i)$ por new
reverse	f, l	da vuelta
partition, stable_partition	f, l, pred	$pred(i)$ ad, $!pred(i)$ atras
min_element, max_element	f, l, [comp]	<i>it</i> min, max de [f, l]
lexicographical_compare	f1, l1, f2, l2	<i>bool</i> con $[f1, l1]_i [f2, l2]$
next/prev_permutation	f, l	deja en [f, l) la perm sig, ant
set_intersection, set_difference, set_union, set_symmetric_difference,	f1, l1, f2, l2, res	[res, ...) la op. de conj
push_heap, pop_heap, make_heap	f, l, e / e /	mete/saca e en heap [f, l), hace un heap de [f, l)
is_heap	f, l	<i>bool</i> es [f, l) un heap
accumulate	f, l, i, [op]	$T = \sum / oper$ de [f, l)
inner_product	f1, l1, f2, i	$T = i + [f1, l1) \cdot [f2, \dots)$
partial_sum	f, l, r, [op]	$r+i = \sum / oper$ de $[f, f+i] \forall i \in [f, l)$
__builtin_ffs	unsigned int	Pos. del primer 1 desde la derecha
__builtin_clz	unsigned int	Cant. de ceros desde la izquierda.
__builtin_ctz	unsigned int	Cant. de ceros desde la derecha.
__builtin_popcount	unsigned int	Cant. de 1's en x.
__builtin_parity	unsigned int	1 si x es par, 0 si es impar.
__builtin_XXXXXXll	unsigned ll	= pero para long long's.

11 Math

11.1 Identidades

$$\begin{aligned}
 \sum_{i=0}^n \binom{n}{i} &= 2^n \\
 \sum_{i=0}^n i \binom{n}{i} &= n * 2^{n-1} \\
 \sum_{i=m}^n i &= \frac{n(n+1)}{2} - \frac{m(m-1)}{2} = \frac{(n+1-m)(n+m)}{2} \\
 \sum_{i=0}^n i &= \sum_{i=1}^n i = \frac{n(n+1)}{2} \\
 \sum_{i=0}^n i^2 &= \frac{n(n+1)(2n+1)}{6} = \frac{n^3}{3} + \frac{n^2}{2} + \frac{n}{6} \\
 \sum_{i=0}^n i(i-1) &= \frac{8}{6} \left(\frac{n}{2}\right) \left(\frac{n}{2} + 1\right) (n+1) \text{ (doubles)} \rightarrow \text{Sino ver caso impar y par} \\
 \sum_{i=0}^n i^3 &= \left(\frac{n(n+1)}{2}\right)^2 = \frac{n^4}{4} + \frac{n^3}{2} + \frac{n^2}{4} = \left[\sum_{i=1}^n i\right]^2 \\
 \sum_{i=0}^n i^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30} = \frac{n^5}{5} + \frac{n^4}{2} + \frac{n^3}{3} - \frac{n}{30} \\
 \sum_{i=0}^n i^p &= \frac{(n+1)^{p+1}}{p+1} + \sum_{k=1}^p \frac{B_k}{p-k+1} \binom{p}{k} (n+1)^{p-k+1} \\
 r &= e - v + k + 1 \\
 \text{Teorema de Pick: (Area, puntos interiores y puntos en el borde)} \\
 A &= I + \frac{B}{2} - 1
 \end{aligned}$$

11.2 Ec. Caracteristica

$$\begin{aligned}
 a_0 T(n) + a_1 T(n-1) + \dots + a_k T(n-k) &= 0 \\
 p(x) &= a_0 x^k + a_1 x^{k-1} + \dots + a_k \\
 \text{Sean } r_1, r_2, \dots, r_q &\text{ las raices distintas, de mult. } m_1, m_2, \dots, m_q \\
 T(n) &= \sum_{i=1}^q \sum_{j=0}^{m_i-1} c_{ij} n^j r_i^n
 \end{aligned}$$

11.3 Tablas y cotas (Primos, Divisores, Factoriales, etc)

Factoriales

0! = 1	11! = 39.916.800
1! = 1	12! = 479.001.600 (∈ int)
2! = 2	13! = 6.227.020.800
3! = 6	14! = 87.178.291.200
4! = 24	15! = 1.307.674.368.000
5! = 120	16! = 20.922.789.888.000
6! = 720	17! = 355.687.428.096.000
7! = 5.040	18! = 6.402.373.705.728.000
8! = 40.320	19! = 121.645.100.408.832.000
9! = 362.880	20! = 2.432.902.008.176.640.000 (∈ tint)
10! = 3.628.800	21! = 51.090.942.171.709.400.000

$$\begin{aligned}
 \text{max signed tint} &= 9.223.372.036.854.775.807 \\
 \text{max unsigned tint} &= 18.446.744.073.709.551.615
 \end{aligned}$$

Primos cercanos a 10^n

$$\begin{aligned}
 &9941 \ 9949 \ 9967 \ 9973 \ 10007 \ 10009 \ 10037 \ 10039 \ 10061 \ 10067 \ 10069 \ 10079 \\
 &99961 \ 99971 \ 99989 \ 99991 \ 100003 \ 100019 \ 100043 \ 100049 \ 100057 \ 100069 \\
 &999959 \ 999961 \ 999979 \ 999983 \ 1000003 \ 1000033 \ 1000037 \ 1000039 \\
 &9999943 \ 9999971 \ 9999973 \ 9999991 \ 10000019 \ 10000079 \ 10000103 \ 10000121 \\
 &99999941 \ 99999959 \ 99999971 \ 99999989 \ 100000007 \ 100000037 \ 100000039 \\
 &100000049 \\
 &999999893 \ 999999929 \ 999999937 \ 1000000007 \ 1000000009 \ 1000000021 \ 1000000033
 \end{aligned}$$

Cantidad de primos menores que 10^n

$$\begin{aligned}
 \pi(10^1) &= 4 ; \pi(10^2) = 25 ; \pi(10^3) = 168 ; \pi(10^4) = 1229 ; \pi(10^5) = 9592 \\
 \pi(10^6) &= 78.498 ; \pi(10^7) = 664.579 ; \pi(10^8) = 5.761.455 ; \pi(10^9) = 50.847.534 \\
 \pi(10^{10}) &= 455.052,511 ; \pi(10^{11}) = 4.118.054.813 ; \pi(10^{12}) = 37.607.912.018
 \end{aligned}$$

Divisores

$$\begin{aligned}
 &\text{Cantidad de divisores } (\sigma_0) \text{ para algunos } n / \neg \exists n' < n, \sigma_0(n') \geq \sigma_0(n) \\
 &\sigma_0(60) = 12 ; \sigma_0(120) = 16 ; \sigma_0(180) = 18 ; \sigma_0(240) = 20 ; \sigma_0(360) = 24 \\
 &\sigma_0(720) = 30 ; \sigma_0(840) = 32 ; \sigma_0(1260) = 36 ; \sigma_0(1680) = 40 ; \sigma_0(10080) = 72 \\
 &\sigma_0(15120) = 80 ; \sigma_0(50400) = 108 ; \sigma_0(83160) = 128 ; \sigma_0(110880) = 144 \\
 &\sigma_0(498960) = 200 ; \sigma_0(554400) = 216 ; \sigma_0(1081080) = 256 ; \sigma_0(1441440) = 288 \\
 &\sigma_0(4324320) = 384 ; \sigma_0(8648640) = 448
 \end{aligned}$$

$$\begin{aligned}
 &\text{Suma de divisores } (\sigma_1) \text{ para algunos } n / \neg \exists n' < n, \sigma_1(n') \geq \sigma_1(n) \\
 &\sigma_1(96) = 252 ; \sigma_1(108) = 280 ; \sigma_1(120) = 360 ; \sigma_1(144) = 403 ; \sigma_1(168) = 480 \\
 &\sigma_1(960) = 3048 ; \sigma_1(1008) = 3224 ; \sigma_1(1080) = 3600 ; \sigma_1(1200) = 3844 \\
 &\sigma_1(4620) = 16128 ; \sigma_1(4680) = 16380 ; \sigma_1(5040) = 19344 ; \sigma_1(5760) = 19890 \\
 &\sigma_1(8820) = 31122 ; \sigma_1(9240) = 34560 ; \sigma_1(10080) = 39312 ; \sigma_1(10920) = 40320 \\
 &\sigma_1(32760) = 131040 ; \sigma_1(35280) = 137826 ; \sigma_1(36960) = 145152 ; \sigma_1(37800) = 148800 \\
 &\sigma_1(60480) = 243840 ; \sigma_1(64680) = 246240 ; \sigma_1(65520) = 270816 ; \sigma_1(70560) = 280098 \\
 &\sigma_1(95760) = 386880 ; \sigma_1(98280) = 403200 ; \sigma_1(100800) = 409448 \\
 &\sigma_1(491400) = 2083200 ; \sigma_1(498960) = 2160576 ; \sigma_1(514080) = 2177280 \\
 &\sigma_1(982800) = 4305280 ; \sigma_1(997920) = 4390848 ; \sigma_1(1048320) = 4464096 \\
 &\sigma_1(4979520) = 22189440 ; \sigma_1(4989600) = 22686048 ; \sigma_1(5045040) = 23154768 \\
 &\sigma_1(9896040) = 44323200 ; \sigma_1(9959040) = 44553600 ; \sigma_1(9979200) = 45732192
 \end{aligned}$$