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ESERCIZIO 1.1
i) \{x \in \mathbb{R}^3 : d(x, A) = 3d(x, B)\} dove A = (1, 4/2, 4) \in B = (1, -2, 1)
                                                                                                                 d(x,A) = \sqrt{(x_1-a_1)^2 + ... + (x_n-a_n)^2}
      · d(x,A) + 9d(x,B)
                                                                                                                  d(x,A) = ad(x,B) => d(x,A) = a (x,B)2
     · (x1-4)2+(x1-2)2+(x3-1)2= 4(x1-1)2+4(x1+2)2+4(x1-1)2
                                                                                                                 (X_1 - a_1)^2 + ... + (X_n - a_n)^2 = (X_1 - b_1)^2 + ...
      8(X_1^2-4X_1+1)+9(X_1^2+4X_1+4)+8(X_3^2-4X_3+1)-X_1^2+X_2-1/4=0
     - 8x1 + 8x2 + 8x2 - 16x, + 37x2 - 16x3 + 199/4 = 0
     - X, + X1+ X1 - 2x, + 37/8 x2 - 2x3 + 199/36 =0
                                                                                                                  d(x,\pi) = \frac{1ax_1 + \dots + 2x_n + \dots + 2x_n}{\sqrt{a^2 + \dots + 2^2}}
ii) {xeR3: d(x,A) = 2d(x, T)} dove A= (0,1,1) e T: x-y+1=0
     -d(x,A)2 = 4d(x,π)2
     -(X_1-0)^2+(X_2-1)^2+(X_3-1)^2=4\left(\frac{|X_1-X_2+1|}{\sqrt{-2}+(-1)^2}\right)^2
     X_1^2 + X_2^2 - 2X_2 + 1 + X_2^2 - 2X_2 + 1 = 4 \frac{(X_1 - X_2 + 1)^2}{2}
      X_1^1 + X_2^2 + X_2^2 - 2X_2 - 2X_2 + 2 = 2 (X_2^2 - X_1 X_2 + X_1 - X_1 X_2 + X_2^2 - X_2 + X_1 - X_2 + 1)
      · X1+ X2+ X3- 2×2- 2×3+2 = 2×2+2×2-4x, x2+4x1-4x2+2
     - X1 + X2 - X3 - 4 X, X, + 4 X, - 2 X2 + 2 X = 0
i(i) {xe/λ3: 2d(x,π)=2d(x,r)} dore π:x-y=0 e r:(1,0,0,1+t(0,1,0)
      · 4d(x, T) = 4d(x, T)2
     = 4 ( \frac{1 \times_1 - \times_2 1}{\sqrt{2} + (-1)^2} \right)^2 = 4 ( \times_1^2 + \times_2^2 - 2) \times_1 + 1 \frac{1}{2}
                                                                                                     d(x,r):
      - & (X, - X2) = 4X2+4X3-8X,+4
                                                                                                      · Q=(1,0,0) e ==(0,1,0)
                                                                                                      · PQ = (x,-1, x,-0, x3-0) = (x,-1, x, x3)
      - &X1+ 2x2 - 4x, x3 =4X1+4X2-8X,+4
                                                                                                      Pà·V = xi-1 x. x3 → determinante
      · 2x2 - 2x2 +4x3 +4x, x2 - 8x, +4 =0
     -X_1^2 - X_2^2 + 2X_3^2 + 2X_1X_2 - 4X_1 + 2 = 0
                                                                                                             = \hat{i}(-x_3) - \hat{i}(0) + \hat{\epsilon}(x_1 - i) \rightarrow (-x_3, 0, x_1 - i)
                                                                                                      . 11 PQ · V 11 = √(X-1+(X-1))
                                                                                                      · 11 1 11 = \(\frac{1}{12}\) = $
                                                                                                      - d(x,r) = (\frac{||\vec{pq} \cdot \vec{v}||}{||\vec{q}||})^2 \times x_3^2 + x_4^2 - x_4x_1 + 1
ESERCIZIO 1.1
i) {xeR: 3x2+ 2xy+ 3y2+ 2x+2y+1=0}
       A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \rightarrow AY = -b \rightarrow \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \end{pmatrix} \rightarrow \begin{pmatrix} 3x + y \\ x + 3y \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \end{pmatrix} \rightarrow V_0 = \begin{pmatrix} 1/4 & 1/4 \end{pmatrix} 
      · Hetrica:
            - \chi_{s}(t) = \det \left(\frac{3-t}{s}, \frac{1}{s-t}\right) = 0 \rightarrow (3-t)^{\frac{1}{s-1}} = 0 \rightarrow (3-t-1)(3-t+1) = 0 \rightarrow (3-t)(4-t) = 0 \quad \lambda_{s} = 1, \lambda_{s} = 1
            - 221+421+c'=0 -> c'= c+b1 10=++(-1,-1)(1/4)=1-2/4=1/2 -> 22+421+1/2=0 -> ellisse
      · Affine
            - segnatura (2,0,0)
            - dividere per 1c'1 → 21+221+1=0 → w1+ w1+1=0 → circonferenza
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(i) | Xe R2 : X2 + 6xy +y2 - 3 = 0}
        A = \begin{pmatrix} 4 & 3 \\ 3 & 1 \end{pmatrix} \rightarrow A = -b \rightarrow \begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} y + 3x = 0 \\ 3x + y = 0 \end{pmatrix} \rightarrow \begin{cases} 0 \\ 0 \end{pmatrix} 
              - \chi_{1}(t) = det \begin{pmatrix} 1-t & 3 \\ 3 & 1-t \end{pmatrix} = 0 \rightarrow (1-t)^{2} - 3^{2} = 0 \rightarrow (1-t-3)(1-t+3) = 0 \rightarrow (-2-t)(4-t) = 0 \quad \lambda_{1} = 2
              - -2 ≥3 + 4 ≥3 + C' = 0 → C' = -3 + [0,0](8) = -3 → -2 ≥3 + 4 ≥3 - 3 = 0 → iperbole
       · Affine
                     segnatura (1,0,1)
             - -2/3 2, +12, -1=0 → w, -w, -1=0 → iperbole
(ii) { xeR3: 8x2+242+2x2+322-4=0}
       • A = \begin{pmatrix} 3 & 4 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} \rightarrow AV = -b \rightarrow \begin{pmatrix} 3 & 4 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{cases} 3x + y = 0 \\ x + 2y = 0 \end{cases} \rightarrow \begin{cases} 0 \\ x + 2y = 0 \end{cases}
              \rightarrow (3-t)(t^2-5t+5)=0 \lambda_1=\frac{5-\sqrt{5}}{3}, \lambda_2=\frac{5+\sqrt{5}}{3}, \lambda_3=\frac{5+\sqrt{5}}{3}
              - 2 - 4 - 5 - 15 - 4 - 0 -> C'= -4 + (0,0,0) (3) = -4 -> ellissoide
       · Affine:
              - segnatura: (3,0,0)

- 5-13

- 8 2; + 6+05

- 2 2; + 3423-(=0 → ω²+ω±+ω;-1=0 → sfera
-\chi_{A}(t) = \det\begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{pmatrix} = 0 \rightarrow (1-t)(1-t)(-1-t) - (-1-t) = 0 \rightarrow \lambda_{1} = -1, \lambda_{2} = 0, \lambda_{3} = 2
              - -2^{1}_{1}+2^{3}_{2}+1=0 \Rightarrow c^{1}=0+(-1,-1,-1) \begin{pmatrix} -1\\-1 \end{pmatrix}=1 \Rightarrow cilindro iperbolico
       · Affine:
              - segnatura (1,1,1)
              - wi - wi +1 =0 → cilindro iperbolico
ESERCIZIO 1.3
i) Q, {x ∈ R2 , x++ 2x,x, +x++x, +2x,=0}
            A = \begin{pmatrix} 4 & 1 \\ 1 & 1 \end{pmatrix} \longrightarrow A \times = -b \longrightarrow \begin{pmatrix} 4 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \chi \\ \chi \end{pmatrix} = \begin{pmatrix} \chi_1 \\ 1 \end{pmatrix} \longrightarrow \begin{pmatrix} \chi_1 \chi_2 & \chi_2 \\ \chi_1 \chi_2 & 1 \end{pmatrix} \neq centro
       • \chi_{A}(t) = \det \left( \begin{smallmatrix} 1-t \\ 1 \end{smallmatrix} \right) = 0 \rightarrow (1-t)^{2} - 1 = 0 \rightarrow (1-t-1)(1-t+1) = 0 \rightarrow (-t)(1-t) = 0 \rightarrow \lambda_{1} = 0, \lambda_{2} = 2

    segnatora : (1,0,1)

       · Affine
              - t2+st=0 -> parabola
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    Metrica

                                                         - autospazi: (1 1)(v1) = 0 → V1+V2=0 V1=(-1)
                                                                                                                                                                                \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = 0 \rightarrow V_1 - V_2 = 0 \qquad V_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}
                           - t_1 = X_1 - X_2, t_2 = X_1 + X_2 \rightarrow \lambda_1 t_1^2 + \lambda_2 t_2^2 = 2 t_2^2 = 0 relta?

• Asse: A_2^2 = A_2^2 \rightarrow \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\
                                                                                                                                                            -> x +y = 3/4
ii) G_2: \{x \in \mathbb{R}^3 : x_1^2 - 4x_1 x_2 + x_2^2 - 4x_1 - 4x_2 - 4x_3 + 4 = 0 \}

• A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \rightarrow Ay = -b \rightarrow \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \\ y \end{pmatrix} \rightarrow \begin{pmatrix} x - y - -2 \\ y - x - 2 \end{pmatrix} centro
                              • \chi(t) = \det \begin{pmatrix} 1-t & 1-t & 0 \\ 1-t & 1-t & 0 \end{pmatrix} = 0 \rightarrow (1-t)(1-t)(-t) - (-t) = 0 \rightarrow \lambda_1 = 0 g_1 = 2, \lambda_2 = 2
                              · segnatura: (1,0,2)
                              · Affine:
                                                         - t2+2t=0 →porabola
                            · Metrica:
                                                         - autospazi: \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ 3 \\ 2 \end{pmatrix} = \left\{ \begin{pmatrix} 1 \\ 4 \\ 3 \end{pmatrix}, \begin{pmatrix} 9 \\ 9 \end{pmatrix} \right\}
                                                         - t1 = x, + x2, t2 + x3, t3 + x1 - x2 -> 2t2 ?
                            • Asse A\underline{y} : A\underline{b} \rightarrow \begin{pmatrix} 2 & -1 & 0 \\ -1 & 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rightarrow x - y = 0
 ESERCIZIO 1.4
    Q = {PER3 : d(P,P0) = d(P,π)} dore P0 = (1,0,1) e π·x-y=0
                              • d(P, P_0)^2 = d(P, \pi)^2 \rightarrow (X, -1)^2 + (X_2 - 0)^2 + (X_3 - 1)^2 = \left(\frac{1 \times 1 - \times 1}{\sqrt{4^2 + (-1)}}\right)^2 \rightarrow X_1^2 - 2 \times 1 + 1 + X_2^2 + X_3^2 - 2 \times 2 + 1 = \frac{(X_1 - X_2)^2}{2}
                            \chi_{A}(t) = \det \begin{pmatrix} \frac{1+t}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} = (1-t)(1+t)(2+t) - (2-t) = 0 \rightarrow (2-t)(2+t-t+t^{2}-1) = 0 \rightarrow (2-t)(1+t)(1+t) = 0 
                                                                                                                          -> >, -2, >,=0, >,=2
                            · segnatura: (2,0,1)
                              · Affine: ti+ti+2ti=0 -> paraboloide ellittico
                              · Metrica:
                            - e' di rotazione a=B=1 e non a sano altritermini
  ESERCIZIO 1.5
    Q: 3x_1^2 + 3x_2^2 + 2x_3^2 - 2x_1x_2 + 8x_1 + 3 = 0
                                                    A = \begin{pmatrix} 3 & 7 & 0 \\ -1 & 3 & 0 \\ 0 & 0 & 2 \end{pmatrix} \rightarrow A \underbrace{y}_{-2} = \underbrace{b}_{-3} \begin{pmatrix} 3x - y \\ -x + 3y \\ -x + 3y \end{pmatrix} = \begin{pmatrix} -4 \\ -3 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -3/2 & -3/2 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -3/2 & -3/2 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -3/2 & -3/2 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y = 0 \\ -x + 3y = 0 \end{pmatrix} \rightarrow \underbrace{y}_{0} = \begin{pmatrix} -3/2 & -4/2 \\ -x + 3y = 0 \\ -x + 3y 
                            • \chi_{a(t)} = \det \begin{pmatrix} 3-t & -1 & 0 \\ -1 & 3-t & 0 & 2-t \end{pmatrix} = (3-t)(3-t)(2-t) - (1-t) = 0 \rightarrow \lambda_{1}=2, \lambda_{2}=2, \lambda_{3}=4
                            · Metrica: 221+221+423-3=0 → ellissoide c'=3+570=3+(4,0,0)(3/2)=-3
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	Simme tr	ia:	A¹⊻	= A <u>b</u>	, (40	-640 640 640)(*; *; *;	= (]	۶) _	→ { 4	X1 - 6 X1 + 1 X3 = 0	0X2 = (<u>.</u>	<u>V</u> 4 =	(³ /4	, ½, e)					
	Rotazion	e:	α≖β	- L	non	લં ક	sono.	altri	łed	mi r	vi, S	;!											
	X 5 5 0 -	33	(2 + S	- ب _ة x	2.×.:	x. +8	¥. +	3 =0															
	_	Α=	3 - I - 1 3) →	٠ . Δ٧	-b -	• { ª	X, -X) = - V = 1	ų v	6 = 1-	3/2	1/2	0)									
	-	~ (د ۱ -	do+	13-t	-7	۱ ـ	(2-t	12		(a _+	-170	ر د است	ı) =	۔ د)	704	<u> ۱</u> ۰۰۰	د ۵		- 9	, አ፫		
																		.	^,	-2	, A <u>, T</u> 4		
	-	seg	nato	ra:	رکل	٥,٥)	→	a++;	ne:	X;+	X +	1=0	→	Circ	onte	eren-	30.						