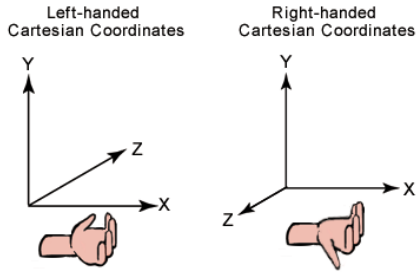


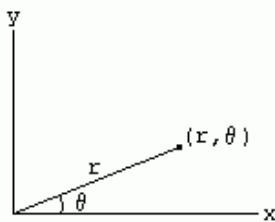
1. Coordinate systems

a) Rectangular Cartesian Coordinate Systems



In this coordinates, the vectors that span the frame are the \vec{i} , \vec{j} , \vec{k} vectors. The left-handed system is used in DirectX and the right-handed system in OpenGL. The right-handed system is the standard frame used in Math and in Physics. The frame $\{\vec{i}, \vec{j}, \vec{k}\}$ is said to be an orthonormal frame since $\vec{i} \perp \vec{j} \perp \vec{k}$ and $\|\vec{i}\| = \|\vec{j}\| = \|\vec{k}\| = 1$.

b) Polar Coordinate



In polar coordinate, a point is represented by the pair (θ, r) where r is the line between the point and the origin O , and θ is the angle between r and the x -axis in radian such that $x = r \cos(\theta)$ and $y = r \sin(\theta)$ or $\vec{p}(x, y) = (r \cos(\theta), r \sin(\theta))$. This is a conversion from polar to Cartesian coordinates. To convert back to polar coordinate we calculate

$$\tan(\theta) = \left(\frac{y}{x}\right) \text{ or } \theta = \tan^{-1}\left(\frac{y}{x}\right) \text{ and } r = \sqrt{x^2 + y^2}.$$

Converting from rectangular (cartesian) coordinate to polar coordinate

Example 1.b.1: Write the Cartesian coordinates of point $\vec{p}(1,1)$ in polar coordinate.

We need the pair (θ, r) , $r = \sqrt{x^2 + y^2} = \sqrt{1^2 + 1^2} = \sqrt{2}$, and $\theta = \tan^{-1}\left(\frac{y}{x}\right) = \tan^{-1}\left(\frac{1}{1}\right) = \tan^{-1}(1) = \frac{\pi}{4}$

So $\vec{p}(1,1)$ is $\left(\frac{\pi}{4}, \sqrt{2}\right)$

TODO: Go to Activity and solve question 1

Converting from Polar coordinate to rectangular (cartesian) coordinate

Example 1.b.2 : Write the polar point $\vec{p}(\pi, 2)$ in Cartesian coordinates.

Answer : using $\vec{p}(x, y) = (r \cos(\theta), r \sin(\theta))$ in Cartesian coordinates with $\theta = \pi$ and $r = 2$ we get :

$$\vec{p}(x, y) = (2 \cos(\pi), 2 \sin(\pi)) = (-2, 0)$$

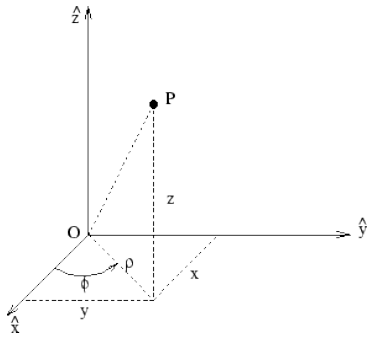
Example 1.b.3: Write the polar point $\vec{p}\left(\frac{\pi}{4}, 4\right)$ in Cartesian coordinates.

using $\vec{p}(x, y) = (r \cos(\theta), r \sin(\theta))$ in Cartesian coordinates with $\theta = \frac{\pi}{4}$ and $r = 4$ we get :

$$\vec{p}(x, y) = \left(4 \cos\left(\frac{\pi}{4}\right), 4 \sin\left(\frac{\pi}{4}\right)\right) = \left(4 \frac{\sqrt{2}}{2}, 4 \frac{\sqrt{2}}{2}\right) = (2\sqrt{2}, 2\sqrt{2}).$$

TODO: Go to Activity and solve question 2

c) Cylindrical Coordinate Systems



In cylindrical coordinate , a point is represented by the triple (ρ, ϕ, z) such that

$$\begin{cases} x = \rho \cos \phi \\ y = \rho \sin \phi \\ z = z \end{cases} \quad \text{where} \quad 0 \leq \phi \leq 2\pi, \quad \rho > 0, \quad -\infty < z < +\infty. \text{ This is a conversion}$$

from cylindrical to Cartesian coordinates. To convert from Cartesian to cylindrical coordinate we calculate

$$\rho = \sqrt{x^2 + y^2} \quad \phi = \tan^{-1}\left(\frac{y}{x}\right) \quad \text{and} \quad z = z \quad \phi \text{ reads phi}$$

Example 1.c.1: change $\left(3, \frac{\pi}{2}, 1\right)$ from cylindrical to Cartesian coordinates.

Answer: using $\begin{cases} x = \rho \cos \phi \\ y = \rho \sin \phi \\ z = z \end{cases}$ with $(\rho, \phi, z) = \left(3, \frac{\pi}{2}, 1\right) \Rightarrow \rho = 3, \phi = \frac{\pi}{2}$ and $z = 1$ we have

$$\begin{cases} x = 3 \cos\left(\frac{\pi}{2}\right) = 3(0) = 0 \\ y = 3 \sin\left(\frac{\pi}{2}\right) = 3(1) = 3 \\ z = 1 \end{cases} \Rightarrow \left(3, \frac{\pi}{2}, 1\right) \text{ in Cartesian coordinates is } (0, 3, 1)$$

Example 1.c.2: change $\left(2, \frac{\pi}{6}, 5\right)$ from cylindrical to Cartesian coordinates.

Answer: using $\begin{cases} x = \rho \cos \phi \\ y = \rho \sin \phi \\ z = z \end{cases}$ with $(\rho, \phi, z) = \left(2, \frac{\pi}{6}, 5\right) \Rightarrow \rho = 2, \phi = \frac{\pi}{6}$ and $z = 5$ we have

$$\begin{cases} x = 2 \cos\left(\frac{\pi}{6}\right) = 2\left(\frac{\sqrt{3}}{2}\right) = \sqrt{3} \\ y = 2 \sin\left(\frac{\pi}{6}\right) = 2\left(\frac{1}{2}\right) = 1 \\ z = 5 \end{cases} \Rightarrow \left(2, \frac{\pi}{6}, 5\right) \text{ in Cartesian coordinates is } (\sqrt{3}, 1, 5)$$

TODO: Go to Activity and solve question 3

Example 1.c.3: Change $(1, 1, 2)$ from Cartesian to cylindrical coordinates.

Answer: use $\rho = \sqrt{x^2 + y^2} \quad \phi = \tan^{-1}\left(\frac{y}{x}\right) \quad \text{and} \quad z = z$

From $(1, 1, 2)$, $x = 1$, $y = 1$, and $z = 2 \Rightarrow \rho = \sqrt{x^2 + y^2} = \sqrt{1^2 + 1^2} = \sqrt{2}$,

$$\phi = \tan^{-1}\left(\frac{y}{x}\right) = \tan^{-1}\left(\frac{1}{1}\right) = \tan^{-1}(1) = \frac{\pi}{4} \quad (45^\circ)$$

So $(1, 1, 2)$ is $(\rho, \phi, z) = \left(\sqrt{2}, \frac{\pi}{4}, 2\right)$ in cylindrical coordinates

Example 1.c.4: Change $(0, 4, 12)$ from Cartesian to cylindrical coordinates.

Answer : use $\rho = \sqrt{x^2 + y^2}$ $\phi = \tan^{-1}\left(\frac{y}{x}\right)$ and $z = z$

From $(0, 4, 12)$, $x = 0$, $y = 4$, and $z = 12 \rightarrow \rho = \sqrt{0^2 + 4^2} = \sqrt{16} = 4$,

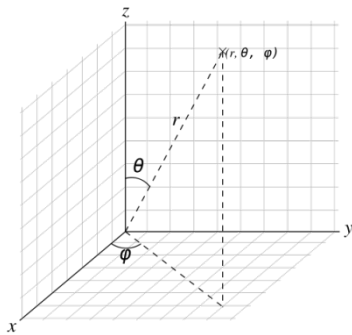
We cannot use $\phi = \tan^{-1}\left(\frac{y}{x}\right)$ because $x = 0$. From $\begin{cases} x = \rho \cos \phi \\ y = \rho \sin \phi \\ z = z \end{cases}$ we use $x = \rho \cos \phi \rightarrow$

$$\cos \phi = \frac{x}{\rho} = \frac{0}{4} = 0 \quad \text{and} \quad \phi = \cos^{-1}(0) = \frac{\pi}{2} \quad (90^\circ)$$

So $(0, 4, 12)$ is $(\rho, \phi, z) = \left(4, \frac{\pi}{2}, 12\right)$ in cylindrical coordinates

TODO: Go to Activity and solve question 4

d) Spherical Coordinate Systems



In spherical coordinate, a point is represented by the triple (r, θ, ϕ) such that

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases} \quad \text{where} \quad 0 \leq \theta \leq \pi, \quad 0 \leq \phi \leq 2\pi, \quad r > 0.$$

This is a conversion from spherical to Cartesian coordinates. To convert back to spherical coordinate we calculate

$$r = \sqrt{x^2 + y^2 + z^2} \quad \phi = \tan^{-1}\left(\frac{y}{x}\right) \quad \theta = \cos^{-1}\left(\frac{z}{\sqrt{x^2 + y^2 + z^2}}\right)$$

Example 1.d.1 : change $\left(3, \frac{\pi}{2}, \frac{\pi}{4}\right)$ from spherical to Cartesian coordinates.

Answer : we have $(r, \theta, \phi) = \left(3, \frac{\pi}{2}, \frac{\pi}{4}\right) \rightarrow r = 3, \theta = \frac{\pi}{2}, \text{ and } \phi = \frac{\pi}{4}$ plugged in

$$\begin{cases} x = r \sin \theta \cos \phi = 3 \sin \frac{\pi}{2} \cos \frac{\pi}{4} = 3(1) \left(\frac{\sqrt{2}}{2}\right) = \frac{3\sqrt{2}}{2} \\ y = r \sin \theta \sin \phi = 3 \sin \frac{\pi}{2} \sin \frac{\pi}{4} = 3(1) \left(\frac{\sqrt{2}}{2}\right) = \frac{3\sqrt{2}}{2} \\ z = r \cos \theta = 3 \cos \frac{\pi}{2} = 3(0) = 0 \end{cases} \rightarrow \begin{cases} x = \frac{3\sqrt{2}}{2} \\ y = \frac{3\sqrt{2}}{2} \\ z = 0 \end{cases}$$

So $\left(3, \frac{\pi}{2}, \frac{\pi}{4}\right)$ is $\left(\frac{3\sqrt{2}}{2}, \frac{3\sqrt{2}}{2}, 0\right)$ in Cartesian coordinates.

Example 1.d.2 : change $\left(2, \pi, \frac{\pi}{3}\right)$ from spherical to Cartesian coordinates.

Answer : we have $(r, \theta, \phi) = \left(2, \pi, \frac{\pi}{3}\right) \rightarrow r = 2, \theta = \pi, \text{ and } \phi = \frac{\pi}{3}$ plugged in

$$\begin{cases} x = r \sin \theta \cos \phi = 2 \sin \pi \cos \frac{\pi}{3} = 2(0) \left(\frac{\sqrt{3}}{2}\right) = 0 \\ y = r \sin \theta \sin \phi = 2 \sin \pi \sin \frac{\pi}{3} = 2(0) \left(\frac{1}{2}\right) = 0 \\ z = r \cos \theta = 2 \cos \pi = 2(-1) = -2 \end{cases} \rightarrow \begin{cases} x = 0 \\ y = 0 \\ z = -2 \end{cases}$$

So $\left(2, \pi, \frac{\pi}{3}\right)$ is $(0, 0, -2)$ in Cartesian coordinates.

TODO: Go to Activity and solve question 5

Example 1.d.3 : change $(1, 1, 0)$ from Cartesian to spherical coordinates.

Answer: $(1, 1, 0) \rightarrow x=1, y=1, z=0$ we need to find r, θ and ϕ

Using $r = \sqrt{x^2 + y^2 + z^2} = \sqrt{1^2 + 1^2 + 0} = \sqrt{2}$ $\phi = \tan^{-1}\left(\frac{y}{x}\right) = \tan^{-1}\left(\frac{1}{1}\right) = \frac{\pi}{4}$

and $\theta = \cos^{-1}\left(\frac{z}{\sqrt{x^2 + y^2 + z^2}}\right) = \cos^{-1}\left(\frac{0}{\sqrt{1^2 + 1^2 + 0^2}}\right) = \cos^{-1}(0) = \frac{\pi}{2}$

so $(1, 1, 0)$ is $(r, \theta, \phi) = \left(\sqrt{2}, \frac{\pi}{2}, \frac{\pi}{4}\right)$ in spherical coordinates

Example 1.d.4 : change $(2\sqrt{3}, 6, 4)$ from Cartesian to spherical coordinates.

Answer: $(2\sqrt{3}, 6, 4) \rightarrow x = 2\sqrt{3}, y = 6, z = 4$ we need to find r, θ and ϕ

Using $r = \sqrt{(2\sqrt{3})^2 + 6^2 + 4^2} = \sqrt{12 + 36 + 16} = \sqrt{64} = 8$ $\phi = \tan^{-1}\left(\frac{y}{x}\right) = \tan^{-1}\left(\frac{6}{2\sqrt{3}}\right) = \tan^{-1}(\sqrt{3}) = \frac{\pi}{3}$

and $\theta = \cos^{-1}\left(\frac{4}{\sqrt{(2\sqrt{3})^2 + 6^2 + 4^2}}\right) = \cos^{-1}\left(\frac{4}{8}\right) = \cos^{-1}(0.5) = \frac{\pi}{3}$

so $(2\sqrt{3}, 6, 4)$ is $(r, \theta, \phi) = \left(8, \frac{\pi}{3}, \frac{\pi}{3}\right)$ in spherical coordinates

TODO: Go to Activity and solve question 6

Example 1.d.5:

Example 1.d.6

Example 1.d.7

Example 1.d.8

2. Vector Differentiation

Given a vector $\vec{u}(x, y, z) = (x(t), y(t), z(t)) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$, the derivation of \vec{u} with respect to t is a vector

$$\frac{d\vec{u}}{dt} = \dot{x}(t)\vec{i} + \dot{y}(t)\vec{j} + \dot{z}(t)\vec{k}.$$

If \vec{a} and \vec{b} are differentiable vectors, then

$$a) \quad \frac{d}{dt}(\vec{a} \pm \vec{b}) = \frac{d\vec{a}}{dt} \pm \frac{d\vec{b}}{dt}$$

$$b) \quad \frac{d}{dt}(\vec{a} \cdot \vec{b}) = \frac{d\vec{a}}{dt} \cdot \vec{b} + \vec{a} \cdot \frac{d\vec{b}}{dt}$$

$$c) \quad \frac{d}{dt}(\vec{a} \times \vec{b}) = \frac{d\vec{a}}{dt} \times \vec{b} + \vec{a} \times \frac{d\vec{b}}{dt}$$

Example: Given $\vec{u} = 3t^2\vec{i} + t^3\vec{j} - 2t^5\vec{k}$

$$\frac{d\vec{u}}{dt} = \frac{d(3t^2)}{dt}\vec{i} + \frac{d(t^3)}{dt}\vec{j} - \frac{d(2t^5)}{dt}\vec{k} = (6t)\vec{i} + (3t^2)\vec{j} - (10t^4)\vec{k} = (6t, 3t^2, -10t^4).$$

3. Time-Derivative of a vector on a Rotating Frame (Optional)

Let $\vec{u}(t)$ and $\vec{u}_0(t)$ be the vectors respectively in world and in a rotating body frame coordinates, such that $\vec{u}(t) = R(t) \cdot \vec{u}_0(t)$. If the body frame coordinate rotates with angular velocity $\vec{\omega}$, then the time derivative of $\vec{u}(t)$ in a fixed coordinate system (world) is related to its time derivative in a rotating frame (body frame) by the following equation:

$$\left(\frac{d\vec{u}}{dt} \right)_{\text{world}} = \left(\frac{d\vec{u}}{dt} \right)_{\text{rot}} + \vec{\omega} \times \vec{u} = \frac{D\vec{u}}{Dt} + \vec{\omega} \times \vec{u}, \quad \text{where } \left(\frac{d\vec{u}}{dt} \right)_{\text{rot}} = \text{time derivative of } \vec{u}(t) \text{ in}$$

the rotating frame (rigidbody space), $\left(\frac{d\vec{u}}{dt} \right)_{\text{rot}} = \left(\frac{d\vec{u}}{dt} \right)_{\text{body}} = \frac{D\vec{u}}{Dt} = R \frac{d\vec{u}_0(t)}{dt}$, $R = R(t)$ is body space world orientation.

If $\vec{u}_0(t)$ is constant vector with respect to the time in body space, then $\left(\frac{d\vec{u}}{dt} \right)_{\text{rot}} = \vec{0}$ and the above equation

becomes $\left(\frac{d\vec{u}}{dt} \right)_{\text{world}} = \vec{\omega} \times \vec{u}$. note that $\left(\frac{d\vec{u}}{dt} \right)_{\text{rot}} = \left(\frac{d\vec{u}}{dt} \right)_{\text{body}}$

Example 3.1 : A vector \vec{u} with world coordinate $\vec{u} = (1, 0, 1)$ is on a rotating disk with $\vec{\omega} = (0, 1, 0)$ rad/s

a) Find $\frac{d\vec{u}}{dt}$ if its coordinates are constant in body space (disk frame)

$$\left(\frac{d\vec{u}}{dt} \right)_{\text{world}} = \vec{\omega} \times \vec{u} = \vec{j} \times (\vec{i} + \vec{k}) = \vec{i} - \vec{k} = (1, 0, -1) \quad \text{since } \left(\frac{d\vec{u}}{dt} \right)_{\text{rot}} = \vec{0} \text{ from } \vec{u} \text{ in body frame.}$$

b) Find \vec{u} (world coordinate) and $\frac{d\vec{u}}{dt}$ if its coordinates are $\vec{u}_0 = (t^2, t, 3)$ in body space (disk frame)

whose orientation is $R_z(\pi/2)$.

$$\vec{u} = R_z(\pi/2)\vec{u}_0 = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} t^2 \\ t \\ 3 \end{pmatrix} = \begin{pmatrix} -t \\ t^2 \\ 3 \end{pmatrix}$$

$$\frac{D\vec{u}}{Dt} = R \frac{d\vec{u}_0(t)}{dt} = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \frac{d}{dt} \begin{pmatrix} t^2 \\ t \\ 3 \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 2t \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ 2t \\ 0 \end{pmatrix}, \quad \vec{\omega} \times \vec{u} = (3, 0, t)$$

$$\left(\frac{d\vec{u}}{dt} \right)_{\text{world}} = \frac{D\vec{u}}{Dt} + \vec{\omega} \times \vec{u} = \vec{\omega} \times \vec{u} = (-1, 2t, 0) + (3, 0, t) = (2, 2t, t).$$

4. Partial Differentiation

let $f(x,y)$ be a function of 2 variables, then the partial derivative with respect to x is

$$\frac{\partial f}{\partial x} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x, y) - f(x, y)}{\Delta x} = f_x, \text{ similarly a partial derivative with respect to y is}$$

$$\frac{\partial f}{\partial y} = \lim_{\Delta y \rightarrow 0} \frac{f(x, y + \Delta y) - f(x, y)}{\Delta y} = f_y$$

For higher order and mixed derivatives we have .

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = f_{xx}, \quad \frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) = f_{yy}$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = (f_y)_x, \quad \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = (f_x)_y,$$

$$f_{xyz} = (f_{xy})_z = ((f_x)_y)_z = \frac{\partial}{\partial z} \left(\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) \right) = \frac{\partial^3 f}{\partial z \partial y \partial x}$$

Note that $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$ if $f(x,y)$ has continuous second partial derivatives.

Example: if $f(x,y) = 4x^3y^2 - 3x^2 + y + 5$, $\frac{\partial f}{\partial x} = 12x^2y^2 - 6x$ and $\frac{\partial f}{\partial y} = 8x^3y + 1$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial x} (8x^3y + 1) = 24x^2y$$

Theorem: let $f=f(x,y,z,t)$ be a scalar function that depends on the variables $x=x(t), y=y(t), z=z(t)$

and the parameter t ; then the derivative of f with respect to t is

$$\boxed{\frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} + \frac{\partial f}{\partial t}}$$

And the differential of f is
$$\Delta f = \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y + \frac{\partial f}{\partial z} \Delta z + \frac{\partial f}{\partial t} \Delta t$$

Example: find $\frac{df}{dt}$ if $f(x,y,z,t) = x^2 + y^3 + z^2 + t^3$ where $x(t) = t^2 + 1$ $y(t) = t - 2t^2$ $z(t) = t$

$$\frac{\partial f}{\partial x} = 2x, \quad \frac{\partial f}{\partial y} = 3y^2, \quad \frac{\partial f}{\partial z} = 2z, \quad \frac{\partial f}{\partial t} = 3t^2 \quad \frac{dx}{dt} = 2t, \quad \frac{dy}{dt} = 1 - 4t, \quad \frac{dz}{dt} = 1$$

$$\frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} + \frac{\partial f}{\partial t} = 2x(2t) + 3y^2(1-4t) + 2z(1) + 3t^2$$

$$= 4xt + 3y^2(1-4t) + 2z + 3t^2$$

5. The Gradient of a Scalar Field

Given a scalar field $f(x, y, z)$ with existing and continuous partial derivatives, we define the gradient

of $f(x, y, z)$ as
$$\overrightarrow{\text{grad}}(f) = \frac{\partial f}{\partial x} \vec{i} + \frac{\partial f}{\partial y} \vec{j} + \frac{\partial f}{\partial z} \vec{k} = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right).$$
 We can also write

$$\overrightarrow{\text{grad}}(f) = \vec{\nabla} f = \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) f \quad \text{where} \quad \vec{\nabla} = \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \quad \text{is called the "del" or}$$

"gradient" or vector "nabla" operator.

Physical interpretation: The gradient of a scalar field is a vector field that points in the direction of the greatest rate of increase. The gradient can also be used to measure how a scalar field changes in a given direction \hat{v} by taking a dot product

$$(\vec{\nabla} \cdot f) \cdot \hat{v} = \overrightarrow{\text{grad}}(f) \cdot \hat{v}$$

Example 5.1 : Calculate $\overrightarrow{\text{grad}}(f) = \vec{\nabla} f$ if $f(x, y, z) = x^2 y + y^3 + z^2$

Answer : $\frac{\partial f}{\partial x} = 2xy$; $\frac{\partial f}{\partial y} = x^2 + 3y^2$; $\frac{\partial f}{\partial z} = 2z$ therefore

$$\overrightarrow{\text{grad}}(f) = \vec{\nabla} f = \frac{\partial f}{\partial x} \vec{i} + \frac{\partial f}{\partial y} \vec{j} + \frac{\partial f}{\partial z} \vec{k} = 2xy\vec{i} + (x^2 + 3y^2)\vec{j} + 2z\vec{k}$$

$$\text{or } \overrightarrow{\text{grad}}(f) = (2xy, x^2 + 3y^2, 2z).$$

Example 5.2 : Calculate $\overrightarrow{\text{grad}}(f) = \vec{\nabla} f$ if $f(x, y, z) = xy + z$

Answer : $\frac{\partial f}{\partial x} = y$; $\frac{\partial f}{\partial y} = x$; $\frac{\partial f}{\partial z} = 1$ therefore

$$\overrightarrow{\text{grad}}(f) = \vec{\nabla} f = \frac{\partial f}{\partial x} \vec{i} + \frac{\partial f}{\partial y} \vec{j} + \frac{\partial f}{\partial z} \vec{k} = y\vec{i} + x\vec{j} + \vec{k}$$

$$\text{or } \overrightarrow{\text{grad}}(f) = (y, x, 1).$$

TODO: Go to Activity and solve question 7

In Engineering and Physics , gradient vector is used in many physical laws such as :

- Force field $\vec{f}(x, y, z)$ and potential energy $u(x, y, z)$: $\vec{f}(x, y, z) = -\vec{\nabla}u(x, y, z)$
- Electric field $\vec{E}(x, y, z)$ and electric potential $V(x, y, z)$: $\vec{E}(x, y, z) = -\vec{\nabla}V(x, y, z)$
- Heat flow $\vec{H}(x, y, z)$ and temperature $T(x, y, z)$: $\vec{H} = -k\nabla T$,
 $k = \text{thermal conductivity}$

Example 5.3: Calculate the force field $\vec{f} = -\vec{\nabla}u$ if the potential energy field

$$\text{is } u(x, y, z) = x^2 + y^2 + z^2$$

Answer:

$$\frac{\partial u}{\partial x} = 2x ; \quad \frac{\partial u}{\partial y} = 2y ; \quad \frac{\partial u}{\partial z} = 2z \quad \text{therefore}$$

$$\vec{\nabla}u = \frac{\partial u}{\partial x}\vec{i} + \frac{\partial u}{\partial y}\vec{j} + \frac{\partial u}{\partial z}\vec{k} = 2x\vec{i} + 2y\vec{j} + 2z\vec{k}$$

$$\text{So } \vec{f} = -\vec{\nabla}u = -2x\vec{i} - 2y\vec{j} - 2z\vec{k}$$

Example 5.4: Calculate the force field $\vec{E} = -\vec{\nabla}V$ if the potential energy field

$$\text{is } V(x, y, z) = 2x - y$$

Answer:

$$\frac{\partial V}{\partial x} = 2 ; \quad \frac{\partial V}{\partial y} = -1 ; \quad \frac{\partial V}{\partial z} = 0 \quad \text{therefore}$$

$$\vec{\nabla}V = \frac{\partial V}{\partial x}\vec{i} + \frac{\partial V}{\partial y}\vec{j} + \frac{\partial V}{\partial z}\vec{k} = 2\vec{i} - \vec{j}$$

$$\text{So } \vec{E} = -\vec{\nabla}V = -2\vec{i} + \vec{j}$$

Example 5.5 Calculate the heat flow $\vec{H} = -k\nabla T$ if the temperature field

$$\text{is } T(x, y, z) = 5 + xyz, \quad k = 10$$

Answer:

$$\frac{\partial T}{\partial x} = yz ; \quad \frac{\partial T}{\partial y} = xz ; \quad \frac{\partial T}{\partial z} = xy \quad \text{therefore}$$

$$\vec{\nabla}T = \frac{\partial T}{\partial x}\vec{i} + \frac{\partial T}{\partial y}\vec{j} + \frac{\partial T}{\partial z}\vec{k} = yz\vec{i} + xz\vec{j} + xy\vec{k}$$

$$\text{So } \vec{H} = -k\vec{\nabla}T = -10(yz\vec{i} + xz\vec{j} + xy\vec{k})$$

TODO: Go to Activity and solve question 8

Convective operator $\vec{u} \cdot \vec{\nabla}$ and Convective Derivative

Another important operator from the gradient operator is the convective operator $(\vec{u} \cdot \vec{\nabla})$

$$\vec{u} \cdot \vec{\nabla} = u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z}, \text{ or } \vec{u} \cdot \vec{\nabla} = u_x \frac{\partial(\quad)}{\partial x} + u_y \frac{\partial(\quad)}{\partial y} + u_z \frac{\partial(\quad)}{\partial z} \text{ where } \vec{u} = (u_x, u_y, u_z) \text{ is the velocity field.}$$

The convective derivative, denoted $\frac{D}{Dt}$, also called material derivative is the derivative with respect to a moving coordinate system of a physical entity (temperature, pressure, density) of a material (fluid) subject to a space-time dependent velocity field $\vec{u} = (\vec{x}, t)$. We write $\frac{D}{Dt}(\quad) = \frac{\partial}{\partial t}(\quad) + (\vec{u} \cdot \vec{\nabla})(\quad)$

Some interesting physical entities are : Temperature $T = T(\vec{x}, t)$ with $\frac{DT}{Dt} = \frac{\partial T}{\partial t} + (\vec{u} \cdot \vec{\nabla})T$,

pressure $p = p(\vec{x}, t)$ with $\frac{Dp}{Dt} = \frac{\partial p}{\partial t} + (\vec{u} \cdot \vec{\nabla})p$, mass density with $\rho = \rho(\vec{x}, t)$ $\frac{D\rho}{Dt} = \frac{\partial \rho}{\partial t} + (\vec{u} \cdot \vec{\nabla})\rho$

▪ Convective Derivative of a Time-independent Scalar Field $f = f(\vec{x})$:

Given a scalar field $f = f(\vec{x}) = f(x, y, z)$, its convective derivative is

$$\frac{Df}{Dt} = \frac{\partial f}{\partial t} + (\vec{u} \cdot \vec{\nabla})f = (\vec{u} \cdot \vec{\nabla})f = \left(u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z} \right) f = u_x \cdot \frac{\partial f}{\partial x} + u_y \cdot \frac{\partial f}{\partial y} + u_z \cdot \frac{\partial f}{\partial z}$$

Since $f = f(\vec{x}) = f(x, y, z)$ is not time-dependent, we have $\frac{\partial f}{\partial t} = 0$

Example 5.6: Calculate the convective derivative of the scalar field $f(x, y, z) = x^2 + y^2 + xz$ if the velocity field is $\vec{u}(1, 2y, 2)$.

Answer:

$$\begin{aligned} \frac{Df}{Dt} &= (\vec{u} \cdot \vec{\nabla})f = \left(u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z} \right) f = u_x \cdot \frac{\partial f}{\partial x} + u_y \cdot \frac{\partial f}{\partial y} + u_z \cdot \frac{\partial f}{\partial z} \\ &= u_x \cdot \frac{\partial}{\partial x}(x^2 + y^2 + xz) + u_y \cdot \frac{\partial}{\partial y}(x^2 + y^2 + xz) + u_z \cdot \frac{\partial}{\partial z}(x^2 + y^2 + xz) \\ &= u_x(2x + z) + u_y(2y) + u_z(x) = (1)(2x + z) + (2y)(2y) + (2)(x) \\ &= 2x + z + 4y^2 + 2x = 4x + 4y^2 + z \end{aligned}$$

Example 5.7: Calculate the convective derivative of the temperature field $T(x, y, z) = x^2 + y^2 + z^2$ if the velocity field is $\vec{u} = (1, 2, 1)$.

Answer:

$$\begin{aligned} \frac{DT}{Dt} &= (\vec{u} \cdot \vec{\nabla})T = \left(u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z} \right) T = u_x \cdot \frac{\partial T}{\partial x} + u_y \cdot \frac{\partial T}{\partial y} + u_z \cdot \frac{\partial T}{\partial z} \\ &= u_x \cdot \frac{\partial}{\partial x}(x^2 + y^2 + z^2) + u_y \cdot \frac{\partial}{\partial y}(x^2 + y^2 + z^2) + u_z \cdot \frac{\partial}{\partial z}(x^2 + y^2 + z^2) \\ &= u_x(2x) + u_y(2y) + u_z(2z) = (1)(2x) + (2)(2y) + (1)(2z) = 2x + 4y + 2z \end{aligned}$$

TODO: Go to Activity and solve question 9

▪ **Convective Derivative of a Time-Dependent Scalar Field** $f = f(\vec{x}, t)$

Example 5.6: Calculate the convective derivative of $f(\vec{x}, t) = f(x, y, z, t) = x^2 + y^2 + xz + 2t$ if the velocity field is $\vec{u}(1, 2y, 2)$.

Answer:

$$\begin{aligned}\frac{Df}{Dt} &= \frac{\partial f}{\partial t} + (\vec{u} \cdot \vec{\nabla})f = 2 + \left(u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z} \right) f = 2 + u_x \cdot \frac{\partial f}{\partial x} + u_y \cdot \frac{\partial f}{\partial y} + u_z \cdot \frac{\partial f}{\partial z} \\ &= 2 + u_x \cdot \frac{\partial}{\partial x} (x^2 + y^2 + xz + 2t) + u_y \cdot \frac{\partial}{\partial y} (x^2 + y^2 + xz + 2t) + u_z \cdot \frac{\partial}{\partial z} (x^2 + y^2 + xz + 2t) \\ &= 2 + 2x + z + 4y^2 + 2x = 2 + 4x + 4y^2 + z\end{aligned}$$

▪ **Convective Derivative of a Time-Independent Vector field** \vec{F}

Given a vector field \vec{F} , its convective derivative is

$$\frac{D\vec{F}}{Dt} = \frac{\partial \vec{F}}{\partial t} + (\vec{u} \cdot \vec{\nabla})\vec{F} = (\vec{u} \cdot \vec{\nabla})\vec{F} = u_x \cdot \frac{\partial \vec{F}}{\partial x} + u_y \cdot \frac{\partial \vec{F}}{\partial y} + u_z \cdot \frac{\partial \vec{F}}{\partial z}$$

where $\vec{u} \cdot \vec{\nabla} = u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z}$ is our convective derivative operator, and $\frac{\partial \vec{F}}{\partial t} = \vec{0}$ since \vec{F} is not time t dependent.

Example 5.8: Let $\vec{F} = (x + y^2, y, xz)$, calculate $\frac{D\vec{F}}{Dt}$ if the velocity field is $\vec{u}(x^2, y, 5z)$

Answer: with $\frac{\partial \vec{F}}{\partial t} = \vec{0}$ $\frac{D\vec{F}}{Dt} = \frac{\partial \vec{F}}{\partial t} + (\vec{u} \cdot \vec{\nabla})\vec{F} = (\vec{u} \cdot \vec{\nabla})\vec{F}$

$$\begin{aligned}\frac{D\vec{F}}{Dt} &= (\vec{u} \cdot \vec{\nabla})\vec{F} = \left(u_x \cdot \frac{\partial}{\partial x} + u_y \cdot \frac{\partial}{\partial y} + u_z \cdot \frac{\partial}{\partial z} \right) \vec{F} = u_x \cdot \frac{\partial \vec{F}}{\partial x} + u_y \cdot \frac{\partial \vec{F}}{\partial y} + u_z \cdot \frac{\partial \vec{F}}{\partial z} \\ &= x^2 \cdot \frac{\partial}{\partial x} (x + y^2, y, xz) + y \cdot \frac{\partial}{\partial y} (x + y^2, y, xz) + 5z \cdot \frac{\partial}{\partial z} (x + y^2, y, xz) \\ &= x^2 \cdot (1, 0, z) + y \cdot (2y, 1, 0) + 5z \cdot (0, 0, x) = (x^2, 0, x^2z) + (2y^2, y, 0) + (0, 0, 5xz) \\ &= (x^2 + 2y^2, y, x^2z + 5xz)\end{aligned}$$

Example 5.9: Let $\vec{a} = (x^2, y, 5z)$, find $\frac{D\vec{a}}{Dt} = (\vec{u} \cdot \vec{\nabla})\vec{a}$ if the velocity field is $\vec{u} = (x, 3, y)$

Answer: $\frac{D\vec{a}}{Dt} = (\vec{u} \cdot \vec{\nabla})\vec{a} = \left(u_x \cdot \frac{\partial}{\partial x} + u_y \cdot \frac{\partial}{\partial y} + u_z \cdot \frac{\partial}{\partial z} \right) \vec{a} = u_x \cdot \frac{\partial \vec{a}}{\partial x} + u_y \cdot \frac{\partial \vec{a}}{\partial y} + u_z \cdot \frac{\partial \vec{a}}{\partial z}$

$$\begin{aligned}&= x \cdot \frac{\partial}{\partial x} (x^2, y, 5z) + 3 \cdot \frac{\partial}{\partial y} (x^2, y, 5z) + y \cdot \frac{\partial}{\partial z} (x^2, y, 5z) \\ &= x \cdot (2x, 0, 0) + 3 \cdot (0, 1, 0) + y \cdot (0, 0, 5) = (2x^2, 0, 0) + (0, 3, 0) + (0, 0, 5y) = (2x^2, 3, 5y)\end{aligned}$$

▪ **Convective Derivative of a Time-Dependent Vector field \vec{F} .**

If a vector field $\vec{F} = \vec{F}(\vec{x}, t)$ is time-dependent then $\frac{D\vec{F}}{Dt} = \frac{\partial \vec{F}}{\partial t} + (\vec{u} \cdot \vec{\nabla})\vec{F}$

Example 5.10: Let $\vec{a} = (x^2, y, 5z + t^2)$, find $\frac{D\vec{a}}{Dt}$ if the velocity field is $\vec{u} = (x, 3, y)$

Answer :

$$\begin{aligned}\frac{D\vec{a}}{Dt} &= \frac{\partial \vec{a}}{\partial t} + (\vec{u} \cdot \vec{\nabla})\vec{a} = \frac{\partial \vec{a}}{\partial t} + \left(u_x \cdot \frac{\partial}{\partial x} + u_y \cdot \frac{\partial}{\partial y} + u_z \cdot \frac{\partial}{\partial z} \right) \vec{a} = \frac{\partial \vec{a}}{\partial t} + u_x \cdot \frac{\partial \vec{a}}{\partial x} + u_y \cdot \frac{\partial \vec{a}}{\partial y} + u_z \cdot \frac{\partial \vec{a}}{\partial z} \\ &= (0, 0, 2t) + x \cdot \frac{\partial}{\partial x} (x^2, y, 5z + t^2) + 3 \cdot \frac{\partial}{\partial y} (x^2, y, 5z + t^2) + y \cdot \frac{\partial}{\partial z} (x^2, y, 5z + t^2) \\ &= (0, 0, 2t) + x \cdot (2x, 0, 0) + 3 \cdot (0, 1, 0) + y \cdot (0, 0, 5) \\ &= (0, 0, 2t) + (2x^2, 0, 0) + (0, 3, 0) + (0, 0, 5y) = (2x^2, 3, 5y + 2t)\end{aligned}$$

6. The Curl of a Vector Field

If $\vec{u} = (u_x, u_y, u_z) = u_x \vec{i} + u_y \vec{j} + u_z \vec{k}$ then the Curl of \vec{u} is

$$\text{Curl } \vec{u} = \vec{\nabla} \times \vec{u} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u_x & u_y & u_z \end{vmatrix} \quad \text{with } \vec{\nabla} = \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k}$$

Physical interpretation: if \vec{u} represents the velocity field of a flowing fluid at a point $\vec{p}(x, y, z)$, then $\text{Curl } \vec{u}$ represents the measure of the fluid tendency to rotate about an axis that has the same direction as $\text{Curl } \vec{u}$.

Example 6.1: Given $\vec{u}(u_x, u_y, u_z) = 3x^2y \cdot \vec{i} + xy \cdot \vec{j} + z^3 \vec{k}$, compute $\text{curl } \vec{u} = \vec{\nabla} \times \vec{u}$.

$$\begin{aligned}\Rightarrow \text{Curl } \vec{u} &= \vec{\nabla} \times \vec{u} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u_x & u_y & u_z \end{vmatrix} = \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u_y & u_z \end{vmatrix} \vec{i} - \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ u_x & u_z \end{vmatrix} \vec{j} + \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ u_x & u_y \end{vmatrix} \vec{k} \\ &= \left(\frac{\partial u_z}{\partial y} - \frac{\partial u_y}{\partial z} \right) \vec{i} - \left(\frac{\partial u_z}{\partial x} - \frac{\partial u_x}{\partial z} \right) \vec{j} + \left(\frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y} \right) \vec{k} \quad , \text{ with } u_x = 3x^2y, \quad u_y = xy, \quad \text{and } u_z = z^3 \\ &= \left(\frac{\partial(z^3)}{\partial y} - \frac{\partial(xy)}{\partial z} \right) \vec{i} - \left(\frac{\partial(z^3)}{\partial x} - \frac{\partial(3x^2y)}{\partial z} \right) \vec{j} + \left(\frac{\partial(xy)}{\partial x} - \frac{\partial(3x^2y)}{\partial y} \right) \vec{k} \\ &= (0 - 0) \vec{i} - (0 - 0) \vec{j} + (y - 3x^2) \vec{k} = (y - 3x^2) \vec{k} = (0, 0, y - 3x^2)\end{aligned}$$

Example 6.2: Given $\vec{u} = xz\vec{i} + 5y\vec{j} + xz^2\vec{k}$, compute $\text{curl } \vec{u} = \vec{\nabla} \times \vec{u}$.

Answer: $\vec{u} = xz\vec{i} + 5y\vec{j} + xz^2\vec{k} \rightarrow u_x = xz, u_y = 5y \text{ and } u_z = xz^2$

$$\begin{aligned} \text{Curl } \vec{u} = \vec{\nabla} \times \vec{u} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u_x & u_y & u_z \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xz & 5y & xz^2 \end{vmatrix} = \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 5y & xz^2 \end{vmatrix} \vec{i} - \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ xz & xz^2 \end{vmatrix} \vec{j} + \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ xz & 5y \end{vmatrix} \vec{k} \\ &= \left(\frac{\partial(xz^2)}{\partial y} - \frac{\partial(5y)}{\partial z} \right) \vec{i} - \left(\frac{\partial(xz^2)}{\partial x} - \frac{\partial(xz)}{\partial z} \right) \vec{j} + \left(\frac{\partial(5y)}{\partial x} - \frac{\partial(xz)}{\partial y} \right) \vec{k} \\ &= (0-0)\vec{i} - (z^2-x)\vec{j} + (0-0)\vec{k} = (x-z^2)\vec{j} = (0, x-z^2, 0) \end{aligned}$$

Example 6.3: Given $\vec{u} = x^2z\vec{i} + 3xy\vec{j} + yz\vec{k}$, compute $\text{curl } \vec{u} = \vec{\nabla} \times \vec{u}$.

Answer: $\vec{u} = x^2z\vec{i} + 3xy\vec{j} + yz\vec{k} \rightarrow u_x = x^2z, u_y = 3xy \text{ and } u_z = yz$

$$\begin{aligned} \text{Curl } \vec{u} = \vec{\nabla} \times \vec{u} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u_x & u_y & u_z \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2z & 3xy & yz \end{vmatrix} = \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3xy & yz \end{vmatrix} \vec{i} - \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ x^2z & yz \end{vmatrix} \vec{j} + \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ x^2z & 3xy \end{vmatrix} \vec{k} \\ &= \left(\frac{\partial(yz)}{\partial y} - \frac{\partial(3xy)}{\partial z} \right) \vec{i} - \left(\frac{\partial(yz)}{\partial x} - \frac{\partial(x^2z)}{\partial z} \right) \vec{j} + \left(\frac{\partial(3xy)}{\partial x} - \frac{\partial(x^2z)}{\partial y} \right) \vec{k} \\ &= (z-0)\vec{i} - (0-x^2)\vec{j} + (3y-0)\vec{k} = z\vec{i} + x^2\vec{j} + 3y\vec{k} = (z, x^2, 3y) \end{aligned}$$

Example 6.4: Given $\vec{u} = y\vec{i} + z\vec{j} + x\vec{k}$, compute $\text{curl } \vec{u} = \vec{\nabla} \times \vec{u}$.

Answer: $\vec{u} = y\vec{i} + z\vec{j} + x\vec{k} \rightarrow u_x = y, u_y = z \text{ and } u_z = x$

$$\begin{aligned} \text{Curl } \vec{u} = \vec{\nabla} \times \vec{u} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u_x & u_y & u_z \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & z & x \end{vmatrix} = \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ z & x \end{vmatrix} \vec{i} - \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ y & x \end{vmatrix} \vec{j} + \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ y & z \end{vmatrix} \vec{k} \\ &= \left(\frac{\partial(x)}{\partial y} - \frac{\partial(z)}{\partial z} \right) \vec{i} - \left(\frac{\partial(x)}{\partial x} - \frac{\partial(y)}{\partial z} \right) \vec{j} + \left(\frac{\partial(z)}{\partial x} - \frac{\partial(y)}{\partial y} \right) \vec{k} \\ &= (0-1)\vec{i} - (1-0)\vec{j} + (0-1)\vec{k} = -\vec{i} - \vec{j} - \vec{k} = (-1, -1, -1) \end{aligned}$$

TODO: Go to Activity and solve question 10

TODO: Go to Activity and solve question 11

7. The Divergence of a Vector Field

The divergence of a vector field is defined as the dot product of the del $\vec{\nabla}$ operator and the vector field $\vec{u} = (u_x, u_y, u_z) = u_x \vec{i} + u_y \vec{j} + u_z \vec{k}$, that is

$$\vec{\nabla} \cdot \vec{u} = \text{div} \vec{u} = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}$$

Physical interpretation: if \vec{u} represents the velocity field of a flowing fluid, then $\text{div} \vec{u}$ represents the net rate of change of the fluid mass flowing out ($\text{div} \vec{u}(\mathbf{p}) > 0$) or sinking in ($\text{div} \vec{u}(\mathbf{p}) < 0$) at a point $\mathbf{p}(x, y, z)$. It's the measure of the fluid compressibility (measure of relative fluid volume change as a response to pressure change).
If $\text{div} \vec{u} = 0 \Rightarrow$ fluid is said to be incompressible.

Example 7.1: Calculate $\text{div} \vec{u}$ if the velocity field is $\vec{u} = 2z\vec{i} + y\vec{j} + x^2\vec{k} = (2z, y, x^2)$

Answer:
$$\vec{\nabla} \cdot \vec{u} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (u_x, u_y, u_z) = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = \frac{\partial(2z)}{\partial x} + \frac{\partial(y)}{\partial y} + \frac{\partial(x^2)}{\partial z} = 1$$

 $\text{div} \vec{u} > 0 \Rightarrow$ fluid mass flowing out at constant rate

Example 7.2: Calculate $\text{div} \vec{u}$ if the velocity field is $\vec{u} = y\vec{i} + z\vec{j} + x\vec{k}$

Answer:
$$\vec{\nabla} \cdot \vec{u} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (y, z, x) = \frac{\partial(y)}{\partial x} + \frac{\partial(z)}{\partial y} + \frac{\partial(x)}{\partial z} = 0$$

 $\text{div} \vec{u} = 0 \Rightarrow$ fluid is incompressible

Example 7.3: Calculate $\text{div} \vec{u}$ if the velocity field is $\vec{u} = xz\vec{i} + 5y\vec{j} + xz^2\vec{k}$.

Is the flow a source or a sink at the point at the point $\vec{p} = (1, -2, -5)$

Answer:
$$\vec{\nabla} \cdot \vec{u} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (xz, 5y, xz^2) = \frac{\partial(xz)}{\partial x} + \frac{\partial(5y)}{\partial y} + \frac{\partial(xz^2)}{\partial z} = z + 5 + 2xz$$

 $\vec{\nabla} \cdot \vec{u}(\vec{p}) = \vec{\nabla} \cdot \vec{u}(1, -2, -5) = (-5) + 5 + 2(1)(-5) = -10 < 0 \Rightarrow$ we have a sink at $\vec{p}(1, -2, -5)$

TODO: Go to Activity and solve question 12

TODO: Go to Activity and solve question 13

8. The Laplacian of a Scalar or Vector Field

Given a scalar field $f(x, y, z)$ with existing and continuous partial derivatives, we define

the Laplacian of f by $\vec{\nabla}^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$. From the previous formula, one can see that

the Laplacian operator is $\vec{\nabla}^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$

For a vector field $\vec{u} = (u_x, u_y, u_z) = u_x \vec{i} + u_y \vec{j} + u_z \vec{k}$ we define the Laplacian of \vec{u} by

$$\vec{\nabla}^2 \vec{u} = \vec{\nabla} (\vec{\nabla} \cdot \vec{u}) = (\vec{\nabla}^2 u_x) \cdot \vec{i} + (\vec{\nabla}^2 u_y) \cdot \vec{j} + (\vec{\nabla}^2 u_z) \cdot \vec{k} \quad \text{that is a vector. } \vec{\nabla}^2 \vec{u} = \vec{\nabla} (\vec{\nabla} \cdot \vec{u}) = \overline{\text{grad}}(\text{div} \vec{u})$$

Example 8.1: Given the scalar field $f(x, y, z) = x^2y + y^3 + z^2$ find Laplacian of $f(x, y, z)$

Answer: $\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial x} (2xy) = 2y$, $\frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial y} (x^2 + 3y^2) = 6y$,

$$\frac{\partial^2 f}{\partial z^2} = \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right) = \frac{\partial}{\partial z} (2z) = 2$$

So the Laplacian is $\bar{\nabla}^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 2y + 6y + 2 = 8y + 2$

Example 8.2: Given the scalar field $f(x, y, z) = x^2 + 3y^2 - z^2$ find Laplacian of $f(x, y, z)$

Answer: $\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial x} (2x) = 2$, $\frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial y} (6y) = 6$,

$$\frac{\partial^2 f}{\partial z^2} = \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right) = \frac{\partial}{\partial z} (-2z) = -2$$

So the Laplacian is $\bar{\nabla}^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 2 + 6 - 2 = 6$

TODO: Go to Activity and solve question 14

TODO: Go to Activity and solve question 15

Example 8.3: Given the vector field $\vec{u}(u_x, u_y, u_z) = (3x^2y, xy, z^3)$ find Laplacian of \vec{u} , $\bar{\nabla}^2 \vec{u}$.

Answer : here we have $u_x = 3x^2y$, $u_y = xy$ and $u_z = z^3$, $\bar{\nabla}^2 \vec{u} = (\bar{\nabla}^2 u_x) \cdot \vec{i} + (\bar{\nabla}^2 u_y) \cdot \vec{j} + (\bar{\nabla}^2 u_z) \cdot \vec{k}$

With $u_x = 3x^2y$

$$\begin{aligned} \bar{\nabla}^2 u_x &= \frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} + \frac{\partial^2 u_x}{\partial z^2} = \frac{\partial}{\partial x} \left(\frac{\partial u_x}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u_x}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial u_x}{\partial z} \right) = \frac{\partial}{\partial x} (6xy) + \frac{\partial}{\partial y} (3x^2) + \frac{\partial}{\partial z} (0) \\ &= 6y + 0 + 0 = 6y \end{aligned}$$

With $u_y = xy$

$$\begin{aligned} \bar{\nabla}^2 u_y &= \frac{\partial^2 u_y}{\partial x^2} + \frac{\partial^2 u_y}{\partial y^2} + \frac{\partial^2 u_y}{\partial z^2} = \frac{\partial}{\partial x} \left(\frac{\partial u_y}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u_y}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial u_y}{\partial z} \right) = \frac{\partial}{\partial x} (y) + \frac{\partial}{\partial y} (x) + \frac{\partial}{\partial z} (0) \\ &= 0 + 0 + 0 = 0 \end{aligned}$$

$u_z = z^3$

$$\begin{aligned} \bar{\nabla}^2 u_z &= \frac{\partial^2 u_z}{\partial x^2} + \frac{\partial^2 u_z}{\partial y^2} + \frac{\partial^2 u_z}{\partial z^2} = \frac{\partial}{\partial x} \left(\frac{\partial u_z}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u_z}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial u_z}{\partial z} \right) = \frac{\partial}{\partial x} (0) + \frac{\partial}{\partial y} (0) + \frac{\partial}{\partial z} (3z^2) \\ &= 0 + 0 + 6z = 6z \end{aligned}$$

So the Laplacian of vector field \vec{u} is $\bar{\nabla}^2 \vec{u} = (\bar{\nabla}^2 u_x) \cdot \vec{i} + (\bar{\nabla}^2 u_y) \cdot \vec{j} + (\bar{\nabla}^2 u_z) \cdot \vec{k} = 6y\vec{i} + 6z\vec{k}$

$$\bar{\nabla}^2 \vec{u} = (6y, 0, 6z) .$$

Example 8.4: Given the vector field $\vec{u} = x^2\vec{i} + xy\vec{j} - 3xz\vec{k} = (x^2, xy, -3xz)$ find Laplacian of \vec{u} , $\vec{\nabla}^2\vec{u}$.

Answer :

here we have $u_x = x^2$, $u_y = xy$ and $u_z = -3xz$, $\vec{\nabla}^2\vec{u} = (\vec{\nabla}^2u_x)\cdot\vec{i} + (\vec{\nabla}^2u_y)\cdot\vec{j} + (\vec{\nabla}^2u_z)\cdot\vec{k}$

With $u_x = x^2$

$$\begin{aligned}\vec{\nabla}^2u_x &= \frac{\partial^2u_x}{\partial x^2} + \frac{\partial^2u_x}{\partial y^2} + \frac{\partial^2u_x}{\partial z^2} = \frac{\partial}{\partial x}\left(\frac{\partial u_x}{\partial x}\right) + \frac{\partial}{\partial y}\left(\frac{\partial u_x}{\partial y}\right) + \frac{\partial}{\partial z}\left(\frac{\partial u_x}{\partial z}\right) = \frac{\partial}{\partial x}(2x) + \frac{\partial}{\partial y}(0) + \frac{\partial}{\partial z}(0) \\ &= 2 + 0 + 0 = 2\end{aligned}$$

With $u_y = xy$

$$\begin{aligned}\vec{\nabla}^2u_y &= \frac{\partial^2u_y}{\partial x^2} + \frac{\partial^2u_y}{\partial y^2} + \frac{\partial^2u_y}{\partial z^2} = \frac{\partial}{\partial x}\left(\frac{\partial u_y}{\partial x}\right) + \frac{\partial}{\partial y}\left(\frac{\partial u_y}{\partial y}\right) + \frac{\partial}{\partial z}\left(\frac{\partial u_y}{\partial z}\right) = \frac{\partial}{\partial x}(y) + \frac{\partial}{\partial y}(x) + \frac{\partial}{\partial z}(0) \\ &= 0 + 0 + 0 = 0\end{aligned}$$

With $u_z = -3xz$

$$\begin{aligned}\vec{\nabla}^2u_z &= \frac{\partial^2u_z}{\partial x^2} + \frac{\partial^2u_z}{\partial y^2} + \frac{\partial^2u_z}{\partial z^2} = \frac{\partial}{\partial x}\left(\frac{\partial u_z}{\partial x}\right) + \frac{\partial}{\partial y}\left(\frac{\partial u_z}{\partial y}\right) + \frac{\partial}{\partial z}\left(\frac{\partial u_z}{\partial z}\right) = \frac{\partial}{\partial x}(-3z) + \frac{\partial}{\partial y}(0) + \frac{\partial}{\partial z}(-6xz) \\ &= 0 + 0 - 6x = -6x\end{aligned}$$

So the Laplacian of vector field \vec{u} is $\vec{\nabla}^2\vec{u} = (\vec{\nabla}^2u_x)\cdot\vec{i} + (\vec{\nabla}^2u_y)\cdot\vec{j} + (\vec{\nabla}^2u_z)\cdot\vec{k} = -6x\vec{k} = (0, 0, -6x)$

$$\vec{\nabla}^2\vec{u} = (0, 0, -6x)$$

TODO: Go to Activity and solve question 16

TODO: Go to Activity and solve question 17

Useful Gradient, Divergent and Curl Properties

- $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{u}) = 0$, $\text{div}(\text{curl } \vec{u}) = 0$
- $\vec{\nabla} \times \vec{\nabla} f = \vec{0}$, $\text{curl}(\text{grad } f) = \vec{0}$
- $\vec{\nabla} \cdot \vec{\nabla} f = \vec{\nabla}^2 f$, $\text{div}(\text{grad } f) = \text{Laplacian } f$
- $\vec{\nabla} \times (f \cdot \vec{u}) = f \cdot (\vec{\nabla} \times \vec{u}) + (\vec{\nabla} f) \times \vec{u}$
- $\vec{\nabla} \cdot (\vec{u} \cdot \vec{v}') = \vec{v} \cdot (\vec{\nabla} \cdot \vec{u}) + (\vec{u} \cdot \vec{\nabla}) \vec{v}$
- $\vec{\nabla} \cdot (f \cdot \vec{u}) = f \cdot \vec{\nabla} \cdot \vec{u} + \vec{u} \cdot \vec{\nabla} f$
- $\vec{\nabla} (f \cdot g) = g \cdot \vec{\nabla} f + f \cdot \vec{\nabla} g$
- $(\vec{u} \cdot \vec{\nabla}) \vec{u} = (\vec{\nabla} \times \vec{u}) \times \vec{u} + \frac{1}{2} \vec{\nabla} (\vec{u} \cdot \vec{u})$

9. Vector Functions

$$\text{Let } \vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix} \text{ a } n \times 1 \text{ column vector and } \vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_m \end{pmatrix} \text{ } m \times 1 \text{ column vector,}$$

we define the vector function \vec{y} as function \vec{x} to be $\vec{y} = \vec{y}(\vec{x})$.

Example 9.1:

$$\vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} \text{ where } \begin{cases} y_1 = x_1 + 2x_2 \\ y_2 = x_1^2 - x_2 \\ y_3 = x_2 \\ y_4 = x_1 x_2 \end{cases} \text{ with } \vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

In this note we will use a numerator layout; that is a layout according to \vec{y} and \vec{x}^T (transpose of \vec{x}) also known as the

Jacobian formulation . That is vectors are defined as column vectors like $\vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix}$ and

$$\frac{\partial \vec{y}}{\partial \vec{x}} = \frac{\partial \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}}{\partial \begin{bmatrix} x_1 & x_2 \end{bmatrix}} = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} \\ \frac{\partial y_3}{\partial x_1} & \frac{\partial y_3}{\partial x_2} \\ \frac{\partial y_4}{\partial x_1} & \frac{\partial y_4}{\partial x_2} \end{pmatrix}, \text{ the order of the resulting matrix in general is :}$$

order of (\vec{y}) by order of $(\vec{x}^T) = (m \times 1)$ by $(1 \times n) = m \times n$.

So from the above example , the matrix obtained has order $(4 \times 1) \times (1 \times 2) = 4 \times 2$.

10. Derivative of a vector with respect to a vector.

The derivative of a $m \times 1$ vector $\vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$ with respect to a $n \times 1$ vector $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$ is

the $m \times n$ matrix $\frac{\partial \vec{y}}{\partial \vec{x}} = \frac{\partial \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}}{\partial \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix}} = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} & \dots & \frac{\partial y_1}{\partial x_n} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} & \dots & \frac{\partial y_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial y_m}{\partial x_1} & \frac{\partial y_m}{\partial x_2} & \dots & \frac{\partial y_m}{\partial x_n} \end{pmatrix}$ known as the matrix Jacobian.

Example 10.1: if $\vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix}$ where $\begin{cases} y_1 = x_1 + 2x_2 \\ y_2 = x_1^2 - x_2 \\ y_3 = x_2 \\ y_4 = x_1 x_2 \end{cases}$ with $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$, calculate $\frac{\partial \vec{y}}{\partial \vec{x}}$.

Answer:

$$\text{With } \begin{cases} y_1 = x_1 + 2x_2 \\ y_2 = x_1^2 - x_2 \\ y_3 = x_2 \\ y_4 = x_1 x_2 \end{cases}, \quad \frac{\partial \vec{y}}{\partial \vec{x}} = \frac{\partial \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix}}{\partial \begin{bmatrix} x_1 & x_2 \end{bmatrix}} = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} \\ \frac{\partial y_3}{\partial x_1} & \frac{\partial y_3}{\partial x_2} \\ \frac{\partial y_4}{\partial x_1} & \frac{\partial y_4}{\partial x_2} \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 2x_1 & -1 \\ 0 & 1 \\ x_2 & x_1 \end{pmatrix}$$

Example 10.2: Calculate $\frac{\partial \vec{w}}{\partial \vec{u}}$, if $\vec{w} = \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}$ where $\begin{cases} w_1 = xy + z \\ w_2 = x^2 + y^2 + z \\ w_3 = 2x + y + z^3 \end{cases}$ with $\vec{u} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

Answer:

This will result into a 3x1 by 1x3=3x3 matrix

$$\frac{\partial \vec{w}}{\partial \vec{u}} = \frac{\partial \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}}{\partial \begin{bmatrix} x & y & z \end{bmatrix}} = \begin{pmatrix} \frac{\partial w_1}{\partial x} & \frac{\partial w_1}{\partial y} & \frac{\partial w_1}{\partial z} \\ \frac{\partial w_2}{\partial x} & \frac{\partial w_2}{\partial y} & \frac{\partial w_2}{\partial z} \\ \frac{\partial w_3}{\partial x} & \frac{\partial w_3}{\partial y} & \frac{\partial w_3}{\partial z} \end{pmatrix} = \begin{pmatrix} y & x & 1 \\ 2x & 2y & 1 \\ 2 & 1 & 3z^2 \end{pmatrix}$$

Example 10.3: Calculate $\frac{\partial \vec{w}}{\partial \vec{u}}$, if $\vec{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$ where $\begin{cases} w_1 = 3x - y + z \\ w_2 = x + y + 5z \end{cases}$ with $\vec{u} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

Answer:

This will result into a 2x1 by 1x3=2x3 matrix

$$\frac{\partial \vec{w}}{\partial \vec{u}} = \frac{\partial \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}}{\partial \begin{bmatrix} x & y & z \end{bmatrix}} = \begin{pmatrix} \frac{\partial w_1}{\partial x} & \frac{\partial w_1}{\partial y} & \frac{\partial w_1}{\partial z} \\ \frac{\partial w_2}{\partial x} & \frac{\partial w_2}{\partial y} & \frac{\partial w_2}{\partial z} \end{pmatrix} = \begin{pmatrix} 3 & -1 & 1 \\ 1 & 1 & 5 \end{pmatrix}$$

TODO: Go to Activity and solve question 18

TODO: Go to Activity and solve question 19

TODO: Go to Activity and solve question 20

11. Derivative of a scalar s with respect to a vector.

The derivative of scalar value $s = s(\vec{x})$ with respect to a $n \times 1$ vector \vec{x} is the $1 \times n$ row vector

$$\frac{\partial s}{\partial \vec{x}} = \begin{bmatrix} \frac{\partial s}{\partial x_1} & \frac{\partial s}{\partial x_2} & \dots & \frac{\partial s}{\partial x_n} \end{bmatrix}$$

Example 11.1: if $s = s(\vec{x}) = (x_1 - a)^2 + (x_2 - b)^2 + (x_3 - c)^2 - 4$ where $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$, calculate $\frac{\partial s}{\partial \vec{x}}$.

Answer: This will result into a 1x1 by 1x3= 1x3 row vector

$$\frac{\partial s}{\partial \vec{x}} = \begin{bmatrix} \frac{\partial s}{\partial x_1} & \frac{\partial s}{\partial x_2} & \frac{\partial s}{\partial x_3} \end{bmatrix} = [2(x_1 - a) \quad 2(x_2 - b) \quad 2(x_3 - c)]$$

Example 11.2: if $s = s(\vec{u}) = x + xy + y^2 + z^2$ where $\vec{u} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$, calculate $\frac{\partial s}{\partial \vec{x}}$.

Answer:

This will result into a 1x1 by 1x3= 1x3 row vector

$$\frac{\partial s}{\partial \vec{u}} = \begin{bmatrix} \frac{\partial s}{\partial x} & \frac{\partial s}{\partial y} & \frac{\partial s}{\partial z} \end{bmatrix} = [1+y \quad x+2y \quad 2z]$$

Example 11.3: if $s = s(\vec{u}) = x + 2y + z$ where $\vec{u} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$, calculate $\frac{\partial s}{\partial \vec{x}}$.

Answer:

This will result into a 1x1 by 1x3= 1x3 row vector

$$\frac{\partial s}{\partial \vec{u}} = \begin{bmatrix} \frac{\partial s}{\partial x} & \frac{\partial s}{\partial y} & \frac{\partial s}{\partial z} \end{bmatrix} = [1 \quad 2 \quad 1]$$

TODO: Go to Activity and solve question 21

TODO: Go to Activity and solve question 22

TODO: Go to Activity and solve question 23

12. Vector Gradient or Jacobian

Let $f(\vec{x})$ be a differentiable scalar function of n variables with

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix}, \text{ then the vector gradient of } f(\vec{x}) \text{ with respect to } \vec{x} \text{ is } \frac{\partial f}{\partial \vec{x}} = \vec{\nabla} f = \overrightarrow{\nabla_{\vec{x}} f} = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \dots & \frac{\partial f}{\partial x_n} \end{bmatrix}$$

It is a 1xn row vector (important!), also called the Jacobian.

Example 12.1: : Calculate $\frac{\partial f}{\partial \vec{x}} = \vec{\nabla} f = \overrightarrow{\nabla_{\vec{x}} f}$, if $f(\vec{x}) = f(x_1, x_2, x_3) = \frac{x_1^2}{4} + \frac{x_2^2}{9} + \frac{x_3^2}{25} - 1$

Answer : $\frac{\partial f}{\partial \vec{x}} = \vec{\nabla} f = \overrightarrow{\nabla_{\vec{x}} f} = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \end{bmatrix} = \begin{bmatrix} \frac{x_1}{2} & \frac{2x_2}{9} & \frac{2x_3}{25} \end{bmatrix}$ or $\frac{x_1}{2} \hat{i} + \frac{2x_2}{9} \hat{j} + \frac{2x_3}{25} \hat{k}$

Example 12.2: Calculate $\frac{\partial f}{\partial \vec{v}} = \vec{\nabla} f = \overrightarrow{\nabla_{\vec{v}} f}$ if $f(\vec{v}) = xyz$ with $\vec{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

Answer: $\frac{\partial f}{\partial \vec{v}} = \vec{\nabla} f = \overrightarrow{\nabla_{\vec{v}} f} = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{bmatrix} = [yz \quad xz \quad xy]$ or $yz\hat{i} + xz\hat{j} + xy\hat{k}$

Example 12.3: Calculate $\frac{\partial f}{\partial \vec{x}} = \vec{\nabla} f = \overrightarrow{\nabla_x} f$ if $f(\vec{x}) = x_1 + 5x_2 - 7x_3$ with $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$

Answer: $\frac{\partial f}{\partial \vec{x}} = \vec{\nabla} f = \overrightarrow{\nabla_x} f = \left[\frac{\partial f}{\partial x_1} \quad \frac{\partial f}{\partial x_2} \quad \frac{\partial f}{\partial x_3} \right] = [1 \quad 5 \quad -7]$ or $\hat{i} + 5\hat{j} - 7\hat{k}$

13. Derivative of a vector with respect to a scalar s

Given $\vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{pmatrix}$, $\frac{\partial \vec{y}}{\partial s} = \begin{bmatrix} \frac{\partial y_1}{\partial s} \\ \frac{\partial y_2}{\partial s} \\ \vdots \\ \frac{\partial y_m}{\partial s} \end{bmatrix}$

Example: if $\vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix}$ where $\begin{cases} y_1 = x_1 + 2x_2 \\ y_2 = x_1^2 - x_2 \\ y_3 = x_2 \\ y_4 = x_1 x_2 \end{cases}$

Then $\frac{\partial \vec{y}}{\partial x_1} = \begin{bmatrix} \frac{\partial y_1}{\partial x_1} \\ \frac{\partial y_2}{\partial x_1} \\ \frac{\partial y_3}{\partial x_1} \\ \frac{\partial y_4}{\partial x_1} \end{bmatrix} = \begin{bmatrix} 1 \\ 2x_2 \\ 0 \\ x_2 \end{bmatrix}$

14. Matrix formulation:

Let $\vec{a} = (a_1, a_2, a_3)$ and $\vec{b} = (b_1, b_2, b_3)$, in matrix form they will be column vectors $\vec{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$ and $\vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$

We want here to define the matrix expression of both the vector product and cross product in matrix form.

Dot product: $\vec{a} \cdot \vec{b} = \vec{a}' \vec{b} = (a_1 \ a_2 \ a_3) \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ in matrix form

Example 14.1: if $f(x, y, z) = 2x + y + 3z$ with $\vec{c} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$ and $\vec{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ then in matrix form we

$$\text{have } f = f(\vec{v}) = \vec{c}' \vec{v} = (2 \ 1 \ 3) \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 2x + y + 3z$$

Cross product: $\vec{a} \times \vec{b} = \psi(\vec{a}) \vec{b}$ in matrix form where $\psi(\vec{a}) = \text{skew}(\vec{a}) = \begin{pmatrix} 0 & -a_3 & a_2 \\ a_3 & 0 & -a_1 \\ -a_2 & a_1 & 0 \end{pmatrix}$

Quadric form: Let $f(x, y) = ax^2 + 2bxy + cy^2$ then the matrix expression of the quadric form is

$$f(x, y) = ax^2 + 2bxy + cy^2 = (x \ y) \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}. \text{ If } \vec{x} = \begin{pmatrix} x \\ y \end{pmatrix} \text{ and } A = \begin{pmatrix} a & b \\ b & c \end{pmatrix} \text{ then}$$

$$f(x, y) = f(\vec{x}) = \vec{x}' \cdot A \cdot \vec{x}$$

Example 14.2 : Express the quadric forms in matrix form .

- $f(x, y) = 3x^2 + 4xy + 5y^2$
- $f(x, y) = 4x^2 + 3xy + y^2$
- $f(x, y, z) = x^2 + 6xy + 4xz + 3y^2 + 2yz + 2z^2$
- $f(x, y, z) = 5x^2 - 2xy + 8xz + 3y^2 + 6yz + 7z^2$

Answer:

$$\text{a) } f(x, y) = 3x^2 + 4xy + 5y^2 = (x \ y) \begin{pmatrix} 3 & 2 \\ 2 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \text{ or } f(x, y) = f(\vec{x}) = \vec{x}' \cdot A \cdot \vec{x} \text{ with}$$

$$\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix} \text{ and } A = \begin{pmatrix} 3 & 2 \\ 2 & 5 \end{pmatrix}$$

$$\text{b) } f(x, y) = 4x^2 + 3xy + y^2 = (x \ y) \begin{pmatrix} 4 & \frac{3}{2} \\ \frac{3}{2} & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \text{ or } f(x, y) = f(\vec{x}) = \vec{x}' \cdot A \cdot \vec{x} \text{ with}$$

$$\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix} \text{ and } A = \begin{pmatrix} 4 & \frac{3}{2} \\ \frac{3}{2} & 1 \end{pmatrix}$$

$$c) \quad f(x, y, z) = x^2 + 6xy + 4xz + 3y^2 + 2yz + 2z^2 = (x \ y \ z) \begin{pmatrix} 1 & 3 & 2 \\ 3 & 3 & 1 \\ 2 & 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\text{or } f(x, y, z) = f(\vec{x}) = \vec{x}' \cdot A \cdot \vec{x} \text{ with } \vec{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \text{ and } A = \begin{pmatrix} 1 & 3 & 2 \\ 3 & 3 & 1 \\ 2 & 1 & 2 \end{pmatrix}$$

$$d) \quad f(x, y, z) = 5x^2 - 2xy + 8xz + 3y^2 + 6yz + 7z^2 = (x \ y \ z) \begin{pmatrix} 5 & -1 & 4 \\ -1 & 3 & 3 \\ 4 & 3 & 7 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\text{or } f(x, y, z) = f(\vec{x}) = \vec{x}' \cdot A \cdot \vec{x} \text{ with } \vec{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \text{ and } A = \begin{pmatrix} 5 & -1 & 4 \\ -1 & 3 & 3 \\ 4 & 3 & 7 \end{pmatrix}$$

15. Identities

- If \vec{u} is not a function of \vec{x} then $\frac{\partial \vec{u}}{\partial \vec{x}} = 0_{m \times n}$ (zero matrix)

Example 15.1: if $\vec{u} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$, and $\vec{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ then $\frac{\partial \vec{u}}{\partial \vec{x}} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

- $\frac{\partial \vec{x}}{\partial \vec{x}} = I_{n \times n}$ (identity matrix)

Example 15.2: if $\vec{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ $\frac{\partial \vec{x}}{\partial \vec{x}} = \frac{\partial \begin{pmatrix} x \\ y \\ z \end{pmatrix}}{\partial [x \ y \ z]} = \begin{pmatrix} \frac{\partial x}{\partial x} & \frac{\partial x}{\partial y} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} & \frac{\partial z}{\partial z} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

Given a matrix A that is not a function of \vec{x} ,

- $\frac{\partial}{\partial \vec{x}} (A\vec{x}) = A$

Example 15.3: Given $\begin{cases} w_1 = 2x + 8y \\ w_2 = 5x + 3y \end{cases} \Rightarrow \vec{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 2 & 8 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = A\vec{x}$

$$\frac{\partial}{\partial \vec{x}} (A\vec{x}) = A \frac{\partial \vec{x}}{\partial \vec{x}} = A \cdot I = A = \begin{pmatrix} 2 & 8 \\ 5 & 3 \end{pmatrix}$$

- $\frac{\partial}{\partial \vec{x}} (\vec{x}^T A) = A^T$
- $\frac{\partial}{\partial \vec{x}} (c\vec{y}) = c \frac{\partial \vec{y}}{\partial \vec{x}}$ c is a scalar not function of \vec{x} but $\vec{y} = \vec{y}(\vec{x})$
- $\frac{\partial}{\partial \vec{x}} (\vec{a} \cdot \vec{y}) = \frac{\partial}{\partial \vec{x}} (\vec{a}' \vec{y}) = \vec{a}' \frac{\partial \vec{y}}{\partial \vec{x}}$ \vec{a} is not function of \vec{x} but $\vec{y} = \vec{y}(\vec{x})$ and in matrix $\vec{a} \cdot \vec{y} = \vec{a}' \vec{y}$

Example 15.4: let $g(x, y, z) = 2x + 3y + 5z$, if $\vec{a} = \begin{pmatrix} 2 \\ 3 \\ 5 \end{pmatrix}$ and $\vec{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ then

$$g(x, y, z) = 2x + 3y + 5z = \begin{pmatrix} 2 & 3 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \vec{a}' \vec{x} \quad \text{or} \quad g(\vec{x}) = \vec{a}' \vec{x} \quad \text{and}$$

$$\frac{\partial}{\partial \vec{x}}(g) = \frac{\partial}{\partial \vec{x}}(\vec{a}' \vec{x}) = \vec{a}' \frac{\partial \vec{x}}{\partial \vec{x}} = \vec{a}' = \begin{pmatrix} 2 & 3 & 5 \end{pmatrix}$$

$$\bullet \quad \frac{\partial}{\partial \vec{x}}(\vec{x}^T A \vec{x}) = \vec{x}^T (A + A^T) \quad \text{or} \quad \frac{\partial}{\partial \vec{x}}(\vec{x}^T A \vec{x}) = 2\vec{x}^T A \quad \text{if } A \text{ is symmetric } (A^T = A)$$

Example 15.5 : Let $f(x, y) = 3x^2 + 4xy + 5y^2$, we want to calculate $\frac{\partial f}{\partial \vec{x}}$

$$f(x, y) = 3x^2 + 4xy + 5y^2 = \begin{pmatrix} x & y \end{pmatrix} \begin{pmatrix} 3 & 2 \\ 2 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad \text{now we express } f(x, y) \text{ in term of vector } \vec{x}, \text{ that is}$$

$$f(\vec{x}) = \vec{x}' \cdot A \cdot \vec{x} \quad \text{with } \vec{x} = \begin{pmatrix} x \\ y \end{pmatrix} \text{ and } A = \begin{pmatrix} 3 & 2 \\ 2 & 5 \end{pmatrix}.$$

$$\frac{\partial f(\vec{x})}{\partial \vec{x}} = \frac{\partial f}{\partial \vec{x}}(\vec{x}' \cdot A \cdot \vec{x}) = \vec{x}' (A + A^T) = 2\vec{x}' A \quad A \text{ is symmetric } \rightarrow A^T = A$$

$$\frac{\partial f(\vec{x})}{\partial \vec{x}} = 2\vec{x}' A = 2 \begin{pmatrix} x & y \end{pmatrix} \begin{pmatrix} 3 & 2 \\ 2 & 5 \end{pmatrix} = [6x + 4y \quad 4x + 10y]$$

TODO: Go to Activity and solve question 24

TODO: Go to Activity and solve question 25

$$\bullet \quad \frac{\partial(\vec{a} \cdot \vec{x})}{\partial \vec{x}} = \frac{\partial(\vec{a}' \vec{x})}{\partial \vec{x}} = \vec{a}' \quad \vec{a} \text{ is not function of } \vec{x} \text{ and in matrix } \vec{a} \cdot \vec{x} = \vec{a}' \vec{x}$$

$$\bullet \quad \frac{\partial \vec{x} \cdot \vec{x}}{\partial \vec{x}} = \frac{\partial \vec{x}^T \vec{x}}{\partial \vec{x}} = \frac{\partial \vec{x}^T \cdot I \cdot \vec{x}}{\partial \vec{x}} = \vec{x}^T (I + I^T) = \vec{x}^T (2I) = 2\vec{x}^T$$

$$\bullet \quad \frac{\partial(\vec{u} \cdot \vec{v})}{\partial \vec{x}} = \frac{\partial(\vec{u}^T \vec{v})}{\partial \vec{x}} = \vec{v}^T \frac{\partial \vec{u}}{\partial \vec{x}} + \vec{u}^T \frac{\partial \vec{v}}{\partial \vec{x}} \quad \text{where } \vec{u} = \vec{u}(\vec{x}) \text{ and } \vec{v} = \vec{v}(\vec{x})$$

$$\bullet \quad \frac{\partial(\vec{u} + \vec{v})}{\partial \vec{x}} = \frac{\partial \vec{u}}{\partial \vec{x}} + \frac{\partial \vec{v}}{\partial \vec{x}}$$

$$\bullet \quad \frac{\partial \|\vec{x} - \vec{a}\|}{\partial \vec{x}} = \frac{(\vec{x} - \vec{a})'}{\|\vec{x} - \vec{a}\|} \quad (\text{order} = 1 \times n) \quad \vec{a} \text{ is not function of } \vec{x}$$

$$\bullet \quad \frac{\partial(\vec{u} \times \vec{v})}{\partial \vec{v}} = \frac{\partial[\psi(\vec{u}) \vec{v}]}{\partial \vec{v}} = \psi(\vec{u}) \quad \text{where } \psi(\vec{u}) = \text{skew}(\vec{u}) = \begin{pmatrix} 0 & -u_z & u_y \\ u_z & 0 & -u_x \\ -u_y & u_x & 0 \end{pmatrix} \text{ skew symmetric matrix of } u.$$

- $\frac{\partial \|\vec{u} \times \vec{v}\|}{\partial \vec{v}} = \frac{(\vec{u} \times \vec{v})^T}{\|\vec{u} \times \vec{v}\|} \psi(\vec{u})$ where $\psi(\vec{u}) = skew(\vec{u}) = \begin{pmatrix} 0 & -u_z & u_y \\ u_z & 0 & -u_x \\ -u_y & u_x & 0 \end{pmatrix}$

The rule is to convert the expressions in matrix form

16. Application to Non-linear Optimization with Lagrange Multipliers (optional)

17. ☺