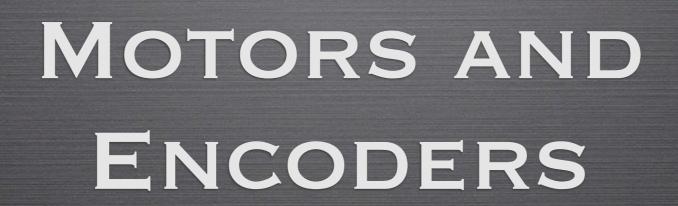
MICROMOUSE: MOTORS, ENCODERS, AND POWER, OH MY

NOVEMBER 1ST, 2012



TYPES OF MOTORS

- DC
- BLDC
- Materials
 - Graphite
 - Metallic

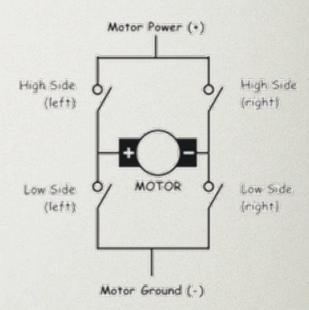


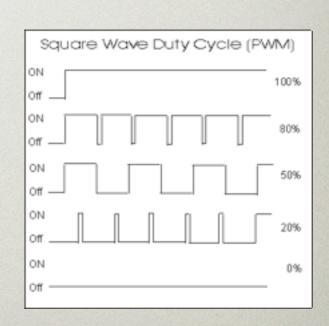
MOTOR PROPERTIES

- Power requirements
 - Nominal voltage
 - Stall current
- Gear ratio
 - Maximum RPM
- Dimensions

CONTROLLING YOUR MOTOR

- Speed proportional to voltage
- H-Bridge
 - Allows forward and reverse drive
- PWM
 - Approximation of analog output
 - Maximize applied voltage with MOSFET





WHAT IS AN ENCODER?

- Let's you figure how far you've gone
- Measures angular displacement
 - Translates to distance traveled
 - Can also be used for feedback control

ENCODER PROPERTIES

- Resolution
 - Ticks per revolution
- Methods of measurement
 - Optical
 - Magnetic
- Power requirements



ENCODER LOGIC

- Most use quadrature encoding
 - Grey code for those of you in EE M16
- Magnetic use Hall Effect sensor
- Optical use IR sensors



B _____

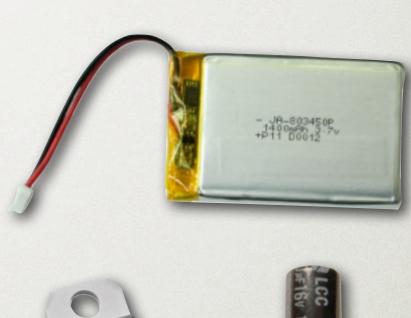
B leads A (forward)

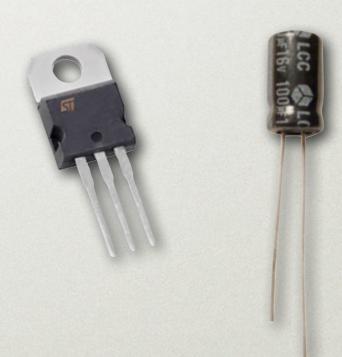
A leads B (backward)



BASIC COMPONENTS

- Battery
- Voltage regulators
- Filtering capacitors





POWER DISTRIBUTION

- Power-hungry parts
 - Motor system: ~500mA per motor
 - IR Sensors: ~40mA per sensor
- Low-power parts
 - MCU: ~30mA
 - Other sensors
 - Gyro and encoders: <10mA total

VOLTAGE REGULATORS

Different voltages for different components



- 3.3v and 5v
- Very inefficient, but easy to configure
 - Suitable for our purposes

FILTERING CAPACITORS

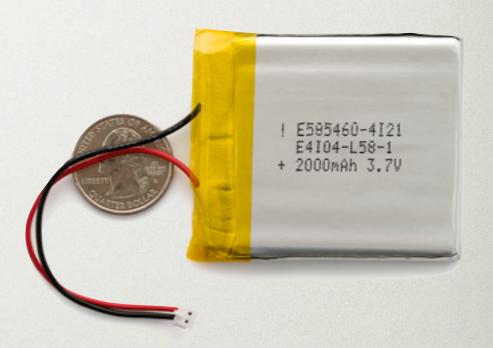
- Especially useful for sensors
- Connect between power and ground
- Smooth voltage ripple
 - Give ground path for high frequency noise
- Lower capacitance = Higher cutoff frequency
 - Values around 10uF and 0.1uF work well

RECOMMENDED BATTERIES

- Li-Po's are the best!
 - Small
 - High power density
- Or maybe not



Don't stab them!!!



SOME RECOMMENDED CHOICES

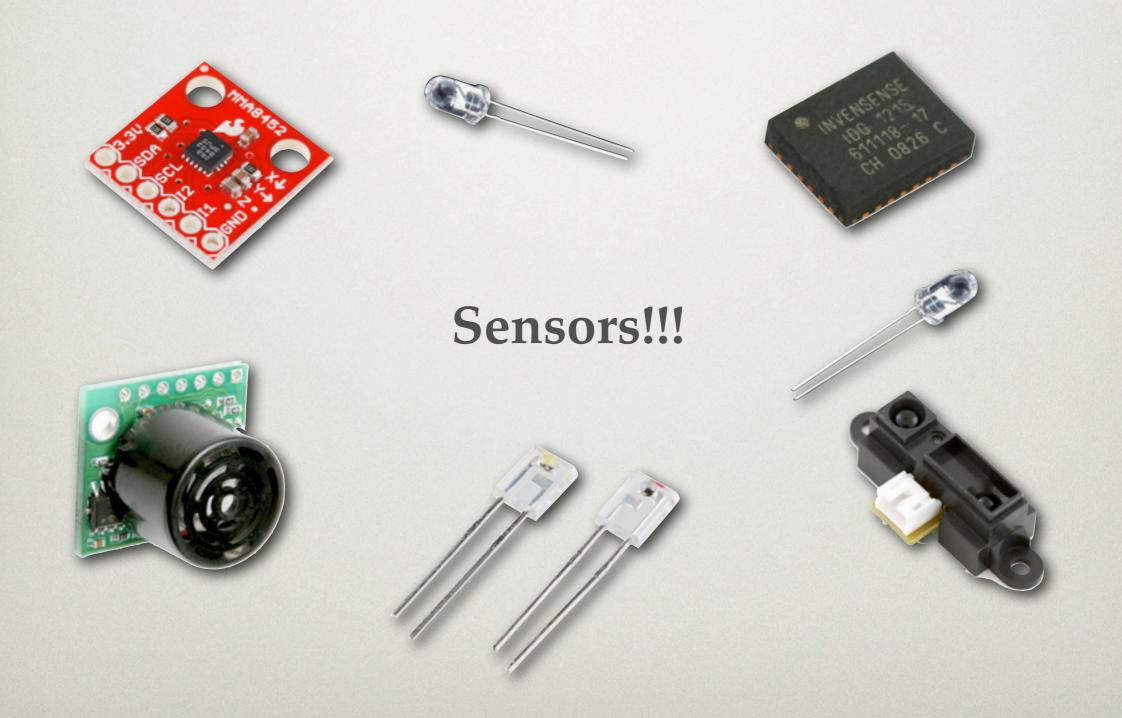
MOTORS AND ENCODERS

- GM9 Motors from Pololu
 - Matched with Wheel Watcher Kit
- Pololu motor and encoder kit
 - Metal gearbox
- Faulhaber Motors
 - Super high performance
 - Only for high budget

CHOOSING PARTS

- Create spreadsheet from our template
 - Share with us
 - Add microcontroller and motor choices
 - Including vendor, part no., and other information
 - This will be how you order parts

NEXT MEETING'S AGENDA



DEPOSITS

- We'll call you up by team
- Make checks out to UCLA IEEE
- If you don't have it now, drop it off in the IEEE Lab before next Thursday!