



DAYANANDA SAGAR UNIVERSITY

SCHOOL OF ENGINEERING

D O P  $\angle$  C  $\nearrow$  M  $\circ$   $\nearrow$   $\square$  //  
C  $\square$  M P —  $\nearrow$   $\circ$   $\circ$  S  $\square$  =  $\circ$   $\phi$   $\square$   $\circ$   
 $\angle$   $\phi$   $\cap$  E  $\phi$   $\cap$  =  $\phi$   $\circ$   $\circ$   $\circ$  =  $\phi$   $\cap$

S P  $\circ$   $\square$  =  $\angle$  L T  $\square$  P =  $\square$   
R O L =  $\circ$   $\vee$  1

# DROWSINESS DETECTION SYSTEM

Presented By:  $\circ$   $\square$  // .  
Sinchara M (ENG22CS0170)  
Sneha Ilager (ENG22CS0174)  
Sneha M P (ENG22CS0175)  
Spandana K R (ENG22CS0182)

0 L O O L = O V

- A ⊥ (S) ↗ ↗ (O) < □ ↗ ↗
- P (O) □ ⊥ (L) (O) (M)  
S ↗ ↗ < ↗ ↗ (O) (M) (O) ∅ ↗ ↗
- I ∅ ↗ ↗ (O) □ ∩ — □ ↗ ↗ = □ ∅
- S □ □ = < (L) / E ∅ ⊥ = (O) □ ∅ (M) (O) ∅  
↗ ↗ < (L) I (M) (P) < □ ↗ ↗ (I //  
< (P) (P) (L) = □ < ⊥ (L) (O))
- S ↗ ↗ < ↗ ↗ (O) □ // ↗ ↗ ↗ ↗ (O) A (O) ↗ ↗  
✓ □ (O) ∩  
(L = ↗ ↗ (O) (O) < ↗ ↗ — (O) (O)  
(S — (O) ⊥ (O) —> )
- F — ∅ □ ↗ ↗ = □ ∅ < (L)  
R (O) ‡ — = (O) (O) (M) (O) ∅ ↗ ↗ (S)
- \* N □ ∅ — F — ∅ □ ↗ ↗ = □ ∅ < (L)  
R (O) ‡ — = (O) (O) (M) (O) ∅ ↗ ↗ (S)

A  $\perp$  (S)  $\nearrow \nearrow$  (O)  $\angle$   $\square$   $\nearrow \nearrow$

- A  $\cap$  (O)  $\square \vee$  (S)  $\equiv \emptyset$  (O) (S) (S)  
 $\cap$  (O)  $\nearrow \nearrow$  (O)  $\square \nearrow \nearrow \equiv \square \emptyset$  (S)  $\rightarrow$  (S)  $\nearrow \nearrow$  (O) (M)  
 $\equiv \emptyset$  P  $\rightarrow$   $\nearrow \nearrow \nearrow \square \emptyset$   $\square \angle \emptyset$   $\perp$  (O)  
 $\angle \perp$  (S)  $\nearrow \nearrow$  (O)  $\angle \square \nearrow \nearrow$  (O)  $\cap$   $\equiv \emptyset \nearrow \nearrow \square$   
 $// \equiv \perp$  (O)  $\cap$  (O)  $\rightarrow$  (S)  $\nearrow \nearrow$  (O) (P) (S).
- F  $\equiv$  (O) (S)  $\nearrow \nearrow$ ,  $\equiv \nearrow \nearrow \equiv \emptyset \perp \square$  (L)  $\perp$  (O) (S)  
 $\square \angle$  (P)  $\nearrow \nearrow$   $\rightarrow$  (O)  $\equiv \emptyset \nearrow \nearrow \angle$  (L)  $\equiv \perp$  (O)  
 $\perp \equiv \cap$  (O)  $\square$  (S)  $\nearrow \nearrow$  (O)  $\angle$  (M)  $\square //$   $\nearrow \nearrow \nearrow$  (O)  
 $\cap$  (O)  $\equiv \perp$  (O) (O) (S)  $// \angle \square$  (O)  $\rightarrow$  (S)  $\equiv \emptyset \nearrow \nearrow \angle$   
 $\vee$  (O)  $\perp \square \angle$  (M).
- S (O)  $\square \square \emptyset \cap$ ,  $// \angle \square \equiv \angle$  (L)  
 $(L) \angle \emptyset \cap$  (M)  $\angle$  (O)  $\cap$  (S)  $\angle$  (O) (O)  
 $\cap$  (O)  $\nearrow \nearrow$  (O)  $\square \nearrow \nearrow$  (O)  $\cap$   $\rightarrow$  (S)  $\equiv \emptyset \nearrow \nearrow$   
 $\square \square$  (M) (P)  $\rightarrow$   $\nearrow \nearrow$  (O) (O)  $\perp \equiv$  (S)  $\equiv \square \emptyset$   
 $\nearrow \nearrow$  (O)  $\square \nearrow \emptyset \equiv \perp \rightarrow$  (O) (S) (L)  $\equiv \cap$  (O)  
 $\cap$  (L)  $\equiv \perp$   $\square$  (O) (O) (P) (O)  $\vee$ .



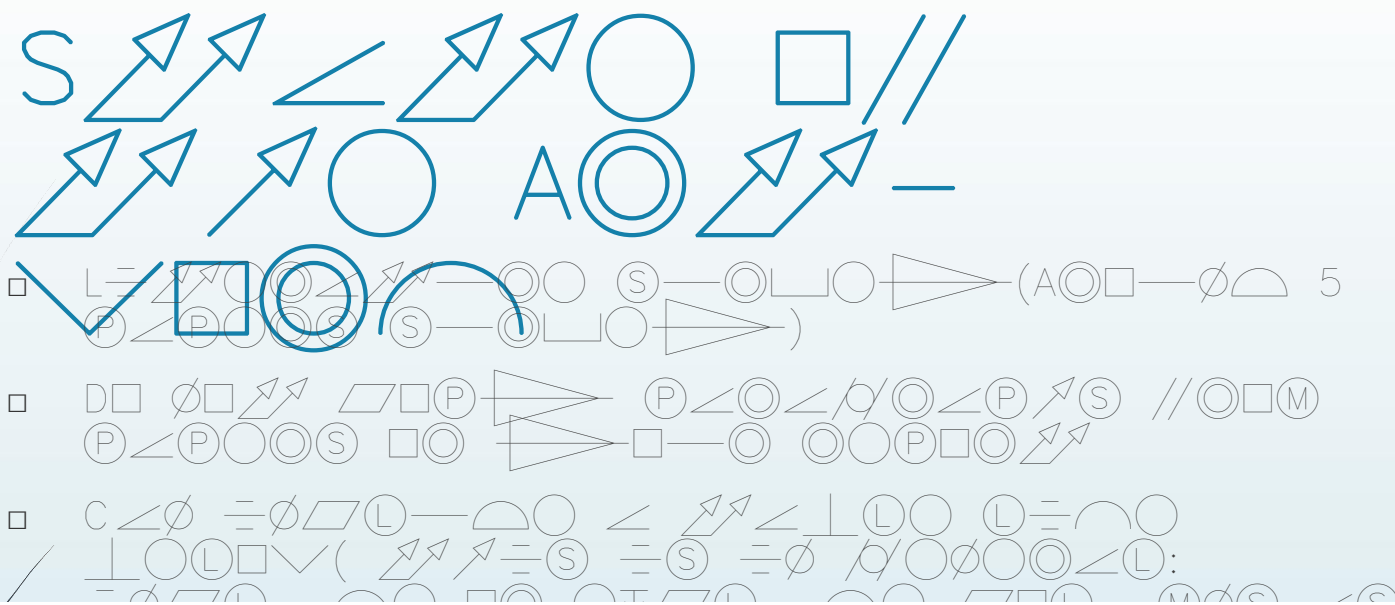
-



- A complex sequence of geometric symbols including circles, squares, triangles, and lines, some with internal markings like slashes or dots. Some symbols are highlighted with blue outlines.

- Another complex sequence of geometric symbols, similar to the first one, featuring various shapes and their combinations.





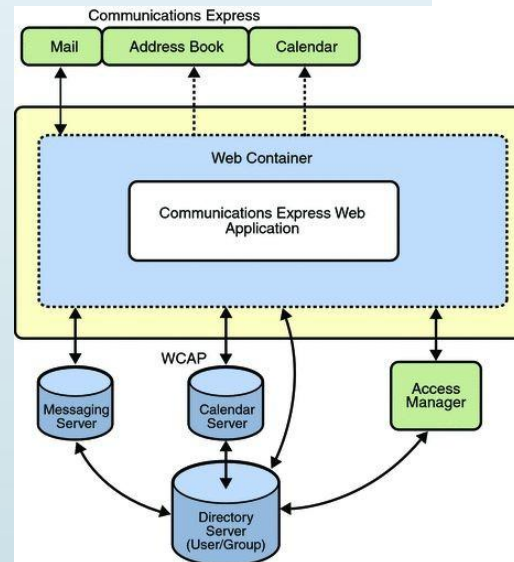
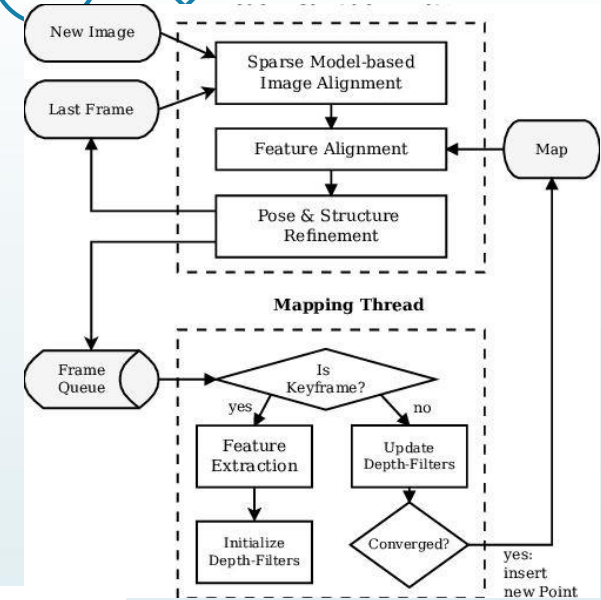
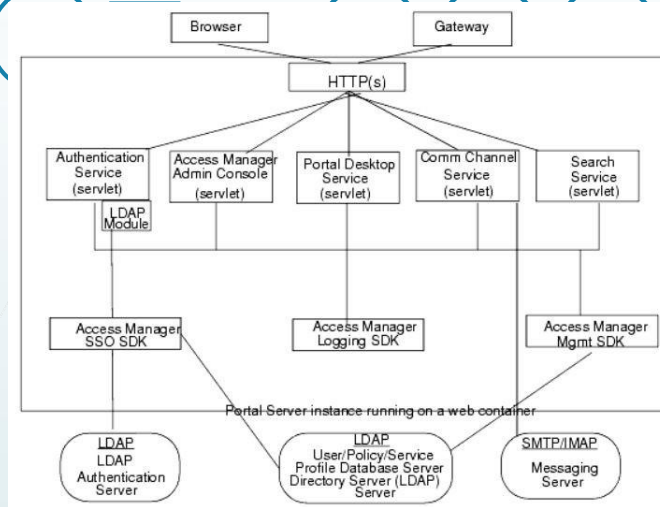
Author's Name/ Paper Title	Conference/ Journal Name and year	Technology/ Design	Results shared by author	What you infer
Jiang Hongyu et al. "Genre-based Emoji Usage Analysis and Prediction in	IEEE International Symposium on Dependable , Autonomic and	Gated Recurrent Unit(GRU) Neural Networks.	To predict an emojis category and position in the video comments.	Categorize the emojis to achieve the high accuracy and recommend


$$D \bigcirc (S) \equiv \cancel{p} / \phi$$

- A  $\nearrow \equiv \cancel{p} \nearrow - (L \bigcirc L \bigcirc L) \bigcirc (S) \equiv \cancel{p} / \phi$   
 $(M) \angle \triangle \equiv \phi \square L - \bigcirc \bigcirc \bigcirc \angle \nearrow \nearrow \angle$   
 $// (L \square \vee S), // (L \square \vee \square \nearrow \angle \bigcirc \nearrow \nearrow S),$   
 $\bigcirc \angle \nearrow \nearrow \angle (S) \nearrow \nearrow \bigcirc - \square \nearrow \nearrow - \bigcirc \bigcirc (S):$
- S  $\triangle (S) \nearrow \nearrow \bigcirc (M)$   
 $\angle \bigcirc \square \nearrow \equiv \nearrow \nearrow \bigcirc \square \nearrow - \bigcirc \bigcirc$
- D  $\angle \nearrow \angle \perp \angle (S) \bigcirc \bigcirc (S) \equiv \cancel{p} / \phi$
- B  $\bigcirc \equiv \bigcirc // (M) \bigcirc \phi \nearrow \nearrow \equiv \square \phi \square // \angle (L) (L)$   
 $\nearrow \nearrow \bigcirc (P) L \angle \nearrow \nearrow // \square \bigcirc (M) S,$   
 $(S) \triangle (S) \nearrow \nearrow \bigcirc (M) S, (S) \bigcirc \bigcirc L \equiv \square \bigcirc (S),$   
 $\angle \phi \bigcirc (P) \bigcirc \square \square \bigcirc (S) S \bigcirc (S) \nearrow \nearrow \bigcirc$   
 $(P) \bigcirc \square \bigcirc - \square \nearrow \nearrow \vee \square - (L) \bigcirc \bigcirc (P) \bigcirc \phi \bigcirc$   
 $\square \phi$
- $B \bigcirc \equiv \bigcirc // \bigcirc \bigcirc (S) \square \bigcirc \equiv (P) \nearrow \nearrow \equiv \square \phi \square //$   
 $\bigcirc \bigcirc (L) \angle \nearrow \nearrow \equiv \square \phi (S) \nearrow \nearrow \equiv \bigcirc (S) \perp \bigcirc \nearrow \vee \bigcirc \bigcirc \phi$   
 $\nearrow \nearrow \bigcirc (M) \square \bigcirc - (L) \bigcirc (S) \angle \phi \bigcirc$   
 $(S) \triangle (S) \nearrow \nearrow \bigcirc (M) // \bigcirc \angle \nearrow \nearrow - \bigcirc \bigcirc (S)$

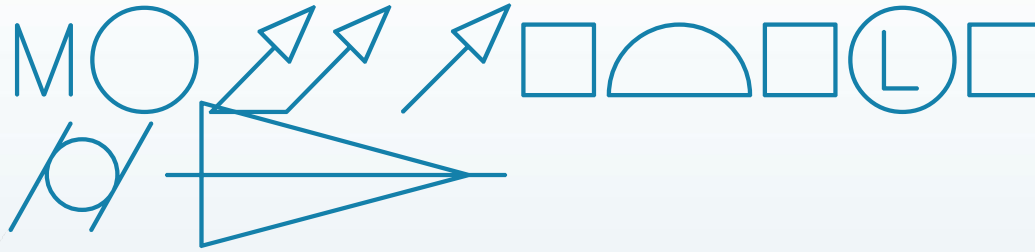


$\text{DOS} = \text{DoS} - \text{DoS}$





$D \circ S = \emptyset -$   
 $S \square \odot \circ \circ \emptyset$   
 $\frown \circ S = \emptyset -$



- what work you did and how you carried out the work
- **Describe your methods of data collection**
- How you prepared the data before analyzing it (e.g. checking for missing data, removing outliers, transforming variables)

RO//○○○∅/○S

- L≡S ↗ ↗ □// ∠LL ↗ ↗ ↗ ○ P∠P○○S  
↗ ↗ ↗ ↗ ↗ √○○○ ○○//○○○○ ∠ ≡∅  
IEEE //□○M∠ ↗ ↗.
- F≡∅ ∠ S∠MPL○ ○○//○○○∅/○S

[1] G. Z ↗ ∠□, Z. L≡—, Y. C ↗ ∠□  
∠∅ ∠ X. Q ≡ ∠∅, "CAPER:  
C □ ∅ ↗ ↗ ○ ↘ ↗ ↗ — A √ ∠ ○  
P○○S □ ∅ ∠ L ≡ ∠ ∠ ∠ E M □ ⊕ ≡  
R○/□M M○∅ ∠ ↗ ↗ ≡ □ ∅," ≡ ∅ IEEE  
T ○ ∠ ∅ S ∠ □ ↗ ↗ ≡ □ ∅ S □ ∅  
K ∅ □ √ L ○ ∠ ∅ ∅ ∅ ∠ ∅ ∠ D ∠ ↗ ∠  
E ∅ ∅ ≡ ∅ ○ ○ ○ ≡ ∅ ∅, □ □ L. 33, ∅ □. 9,  
P(P). 3160–3172, 1 S○P ↗. 2021, ∠ □ ≡:  
10.1109/TKDE.2020.2966971.

[2] J≡\* ∠ ∅ ∅, H □ ∅ ∅ ∅ — □, A □ 12 of 12  
M ∠, J ≡ ∠ ∅ ↗ — ∠. (2020). G ○ ∅ ○ ○ —  
L ∠ S ○ ○ E M □ ⊕ ≡ — S ∠ ∅ ○



# THANK YOU