Reproducing the paper: Stochastic Gradient Hamiltonian Monte Carlo by Tianqi Chen, Emily B. Fox and Carlos Guestrin

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Abstract

We reproduce the experiments contained in 'Stochastic Gradient Hamiltonian Monte Carlo' [CFG14] by Chen, Fox and Guestrin.

FiXme: Give more details in abstract

List of Corrections

Give more details in abstract	 1
Define H	 2

1 Introduction

- Overview of paper and its context.
- Which experiments replicated, and rationale for this choice.
- Target questions of paper.
- · Experimental methodology.
- Implementation details.
 - Integration with Pyro.
 - Which parts are new, and which are from publicly available code?
 - Details about how key aspects were implemented.
- · Link to repository.
- New aspects?

2 Background

Hamiltonian Monte Carlo (HMC) ([Dua+87; Nea11]) is a Markov Chain Monte Carlo (MCMC) sampling algorithm. Given a target probability distribution — in our case the posterior distribution of a set of variables θ given independent observations $x \in \mathcal{D}$ — it produces samples by carrying out a random walk over the parameter space using Hamiltonian dynamics.

To begin with prior distribution $p(\theta)$ and likelihood $p(x \mid \theta)$. Using these we define the *potential energy* function U:

$$U := -\sum_{x \in \mathcal{D}} \log p(x \mid \theta) - \log p(\theta)$$

Note that, using Bayes' rule, we have that the posterior $p(\theta \mid \mathscr{D}) \propto \exp(-U)$. Hamiltonian dynamics introduces an auxiliary set of momentum variables r. These dynamics have a physical interpretation in which an object moves about a landscape determined by U. We let this object have mass matrix M. Then U represents the potential energy of the object, and its kinetic energy is given by $\frac{1}{2}r^{\mathsf{T}}M^{-1}r$. The development of the system is governed by the following equations.

$$d\theta = M^{-1}r dt$$
$$dr = -\nabla U(\theta) dt$$

To simulate these continuous dynamics in practice, we must use a discretised version of these equations. To correct for the inaccuracies introduced by doing so, it is necessary to make a *Metropolis-Hastings correction*. A simple algorithm is given in Algorithm 1.

FiXme: Define *H*

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Algorithm 1 A simple HMC algorithm
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for t = 1, 2, ... do
     r \sim \mathcal{N}(0,1)
                                                                                  ▶ Resample momentum
    (\theta_0, r_0) = (\theta, r)
    for i = 1 to m do
         \theta \leftarrow \theta + \epsilon M^{-1}r
         r \leftarrow r - \epsilon \nabla U(\theta)
     end for
    u \sim \text{Uniform}[0, 1]
     \rho = \exp(H(\theta, r) - H(\theta_0, r_0))
                                                                                ▶ Acceptance probability
    if u > \min(1, \rho) then
                                                      \triangleright Only accept new state with probability \rho
          \theta = \theta_0
     end if
end for
```

3 Implementation Details

· Describe choice made and how we implemented the algorithms

4 Experiments

• Describe experiments and compare with results in the paper.

4.1 Simulated examples

4.2 Bayesian Neural Networks for Classification

5 Conclusion

- · Analysis and discussion of findings.
- Suggest what could have been done with more time.

References

- [CFG14] Tianqi Chen, Emily Fox and Carlos Guestrin. 'Stochastic Gradient Hamiltonian Monte Carlo'. In: *Proceedings of the 31st International Conference on Machine Learning*. Ed. by Eric P. Xing and Tony Jebara. Vol. 32. Proceedings of Machine Learning Research 2. Bejing, China: PMLR, June 2014, pp. 1683–1691. URL: https://proceedings.mlr.press/v32/cheni14.html.
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