

view_frames Result

Recorded at time: 1637308356.525

r4/base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1637308356.525 sec old)
Buffer length: 0.000 sec

r4/base_camera

r4/base_imu

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1637308356.525 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1637308356.525 sec old)
Buffer length: 0.000 sec

r4/base_laser