

Parthan Manisekaran

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Jülicher Straße 41, 52070, Aachen, Germany

About me:

from datetime import date

(Robotics Graduate (Student(2023 - date.today().year)) && Jack of (Many)^{date.today().year-2016} Tech && (Avid Maker and Startup Enthusiast)

#A Maker with a drive to develop and convert cutting edge tech into a useful applications for the world

WORK EXPERIENCE

02/2022 - CURRENT - Aachen, Germany

UNIVERSITY RESEARCH ASSISTANT (HIWI) – INSTITUTE OF MECHANISM THEORY, MACHINE DYNAMICS AND ROBOTICS, RWTH AACHEN UNIVERSITY

- Working on Project Lysis, a modular application to control ANY ROS based Robots and deploy software models with ease
- Developed a basic Progressive Web App which can read and write ROS topics through MQTT and control Robot Manipulators
- Currently extending the app to other Robotic Manipulators and Mobile Robots and developing Computer Vision Features allowing Robotic manipulators to "see" through the app itself

08/2019 - 09/2021 - Bengaluru, India

UNIVERSITY RESEARCH ASSOCIATE – PES CENTRE FOR ROBOTICS, AUTOMATION AND INTELLIGENT SYSTEMS

- Lead the Project Quadbionics, a unique use of Supernumerary Robotic Limbs (SRL) to aid
 Disaster Relief Operatives to help them manage debris after calamities.
- Designed and analyzed the SRL required to manage debris.
- Implemented Vision and Autonomous Capabilities in Project Quadbionics
- Developed the Path planning workflow for the manipulator (Perceive, Process Vision based data for debris coordinates and push the debris) using ROS, Movelt and OpenCV

01/2020 - 05/2020 - Bengaluru, India

TEACHING ASSISTANT - PES CENTRE FOR INNOVATION AND ENTREPRENEURSHIP

- Assisted in setting up the Intel OpenVINO framework as a curriculum for sophomore students of PES Department of Electronics and Communication.
- Guided students to finish their capstone projects by taking up demo classes and presentations.
- Evaluated students' capstone project and collected insights from the students to enhance the course experience for the next batch.

EDUCATION AND TRAINING

10/2021 - CURRENT - Aachen, Germany

M.SC. ROBOTIC SYSTEMS ENGINEERING - RWTH Aachen University

Subjects Include: Advanced Robot Kinematics and Dynamics, Machine Learning, Computer Vision and Robotic Systems

https://www.academy.rwth-aachen.de/en/

08/2016 - 08/2020 - Bengaluru, India

BACHELOR OF TECHNOLOGY IN MECHANICAL ENGINEERING - PES University

Subjects Include: Hydraulics and Pneumatics, Aerospace Propulsion, Drone Computing, CFD

Thesis: Supernumerary Robotic Limbs for the Visually Impaired

8.43/10 | https://pes.edu

LANGUAGE SKILLS

Mother tongue(s): TAMIL | KANNADA

Other language(s):

	UNDERSTANDING		SPEAKING		WRITING
	Listening	Reading	Spoken production	Spoken interaction	
ENGLISH	C2	C2	C2	C2	C2
GERMAN	A2	A2	A1	A1	A2

Levels: A1 and A2: Basic user; B1 and B2: Independent user; C1 and C2: Proficient user

DIGITAL SKILLS

My Digital Skills

Python (NumPy, Pandas, Scikit-learn, TensorFlow, Spacy) | ROS (Movelt, Gazebo, RVIZ) | Git | C+ + | Autodesk Fusion 360 | Computer Vision (OpenCV) | Unity -Vuforia Augmented Reality | Unity Virtual Reality | Linux | Good command of Arduino, Raspberry Pi platforms

PUBLICATIONS

ARMER: Modular and Semi-Autonomous Supernumerary Robotic Limbs for Disaster Relief

https://dlnext.acm.org/doi/abs/10.1145/3478586.3480649 - 2021

Supernumerary Robotic Limbs for the Blind

https://ieeexplore.ieee.org/abstract/document/9342553 - 2020

HONOURS AND AWARDS

22/05/2022

Runners-up at #hackingforfuture - Fraunhofer IPT

- The Hackathon was related to Time Series Classification with Transformers. The data given to us was the Ford Engine Time series dataset.
- We had to implement a transformer algorithm for classification of time series dataset and compare the results with the LSTM network
- We achieved a result of 90.9% Accuracy with Voting between two transformer models as compared to 75% accuracy with LSTM. Link to the presentation below:

shorturl.at/DMU38

05/11/2021

Runners-up - i-Days by EIT Health

- A Three-day ideathon event to develop novel healthcare solutions to avoid a pandemic in the future. We ideated a "MedTalk" a Social Network for Doctors which focuses on transparency and secure communication so that "information spreads faster than the pandemic"
- Won the Runners-up and the best pitch award which was a total prize worth 250 Euros and a startup workshop at the Gateway Exzellenz Start-up Center in Cologne.
- Link to be presentation below:

shorturl.at/eFKN2

2018

Runners-up - Microsoft Hashcode

Won Runners up amongst 20 teams across the State. Also secured a seed fund of \$ 26,000 for starting an Augmented Reality based startup

2018

Request for Innovation in Connected Cars - Xinova

Received a price money of \$500 Dollars for presenting a solution on Inter-vehicle communication through Emoji

Dr CNR Rao Academic Scholarship - PES University

Received a scholarship of \$320 USD