Homework1: Boolean functions

A perceptron with a single output neuron can be used to determine whether an n-dimensional Boolean function is linearly separable. In this task, you implement a computer program that determines whether a Boolean function is linearly separable or not, using a perceptron with activation function $g(b) = \operatorname{sgn}(b)$, where $b = \sum_{i=1}^{n} w_i x_i - \theta$ [See Eq. (5.9) in the course book for the case n=2]. Using this program, sample an n-

dimensional Boolean function randomly and determine whether it is linearly separable. Do this 10^4 times for n=2,3,4 and 5 dimensions, and save the number of linearly separable Boolean functions found. Be sure to not count the same Boolean function twice. This can, for example, be done by adding every sampled Boolean function to a list and excluding the function if it comes up a second time.

The learning rules for the weights w_i and threshold θ are

$$\delta w_i^{(\mu)} = \eta (t^{(\mu)} - O^{(\mu)}) x_i^{(\mu)}$$

and

$$\delta\theta^{(\mu)} = -\eta (t^{(\mu)} - O^{(\mu)})$$

See also Eq. (5.18) in the course book. For each Boolean function, train the perceptron for 20 training epochs (one epoch amounts to updating the parameters once for every input-output pair) using a learning rate η =0.05. Initialize the weights from a normal distribution with mean zero and variance 1/n, and initialize the thresholds to zero.

Task description

for trail = $1:10^4$

- Sample Boolean
- Train percepton
- Check accuracy
- if 100% correct, counter+=1
- else, pass

shape of weights

$$w = \begin{bmatrix} w_1 \\ w_2 \\ \dots \\ w_n \end{bmatrix}$$

number of Boolean functions

$$2^{2^N}$$

number of outputs

Setup boolean inputs and used bool list

```
boolean_inputs_2 = ff2n(2)';
boolean_inputs_3 = ff2n(3)';
boolean_inputs_4 = ff2n(4)';
boolean_inputs_5 = ff2n(5)';
```

```
n = 2;
boolean_inputs = boolean_inputs_2;
separable_counter_2D = learning_iter(n, nTrials, nEpoches, eta, boolean_inputs);
disp(separable_counter_2D)
```

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```
n = 3;
boolean_inputs = boolean_inputs_3;
separable_counter_3D = learning_iter(n, nTrials, nEpoches, eta, boolean_inputs);
disp(separable_counter_3D)
```

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```
n = 4;
boolean_inputs = boolean_inputs_4;
separable_counter_4D = learning_iter(n, nTrials, nEpoches, eta, boolean_inputs);
disp(separable_counter_4D)
```

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```
n = 5;
boolean_inputs = boolean_inputs_5;
separable_counter_5D = learning_iter(n, nTrials, nEpoches, eta, boolean_inputs);
disp(separable_counter_5D)
```

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```
function separable_counter = learning_iter(n, nTrials, nEpoches, eta, boolean_inputs)
```

```
used_bool=[];
    separable_counter = 0;
    for trail = 1:nTrials
        boolean_outputs = 2 * randi([0, 1], 2^n, 1) - 1;
        if isempty(used_bool) || ~ismember(boolean_outputs',used_bool','rows')
            w = normrnd(0, 1/n, [n,1]);
                                              % initialize weight with normal distribution
                                            % initialize theta with 0
            theta = 0;
            for epoch = 1:nEpoches
                total_error = 0;
                                            % 1 epoch is updating the parameters once for every
                for mu = 1:2^n
                    Out = sign(dot(w,boolean_inputs(:,mu))-theta);
                    if Out == 0
                        Out = 1;
                    end
                    err = boolean_outputs(mu) - Out;
                    % delta_w, delta_theta calculation
                    delta_w = cal_delta_w(n, eta, err, boolean_inputs(:,mu));
                    delta_theta = -eta * err;
                    % update w and theta
                    w = w + delta_w;
                    theta = theta + delta_theta;
                    total_error = total_error + abs(err);
                end
                if total error == 0
                    separable_counter = separable_counter + 1;  % find one linear sepration for
                    break
                end
            end
            used_bool(:,end+1) = boolean_outputs;
        end
    end
end
function delta_w = cal_delta_w(n, eta, err, input)
    delta_w = zeros([n,1]);
    for j=1:n
        delta_w(j) = eta * err * input(j);
    end
end
```