LINEAR SYSTEMS CONTROL

Solutions to Problems

Problem 6.11

a. The spectral density matrix is found by Fourier transforming the covariance function

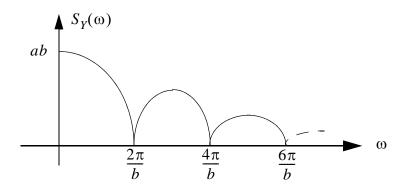
$$R_{\gamma}(\tau) = \begin{bmatrix} a \left(1 - b \frac{|\tau|}{b} \right) & |\tau| < b \\ 0 & \text{otherwise} \end{bmatrix}$$

$$\begin{split} S_{Y}(\omega) &= \int_{-\infty}^{\infty} a \left(1 - \frac{|\tau|}{b} \right) e^{-j\omega\tau} d\omega \\ &= \int_{-b}^{b} a e^{-j\omega} d\tau + \frac{a}{b} \left[\int_{-b}^{0} \tau e^{-j\omega\tau} d\tau + \int_{b}^{0} \tau e^{-j\omega\tau} d\tau \right] \\ &= \frac{a}{j\omega} (e^{j\omega b} - e^{-j\omega b}) + \frac{a}{b} \left[\frac{2}{\omega^{2}} - \frac{b}{j\omega} e^{j\omega b} - \frac{1}{\omega^{2}} e^{j\omega b} + \frac{b}{j\omega} e^{-j\omega b} - \frac{1}{\omega^{2}} e^{-j\omega b} \right] \\ &= \frac{2a \sin \omega b}{\omega} + \frac{2a}{\omega^{2} b} (1 - \cos \omega b) - \frac{2a \sin \omega b}{\omega} = \frac{2a}{\omega^{2} b} (1 - \cos \omega b) \end{split}$$

As $\int \tau e^{-j\omega\tau} d\tau = -\frac{\tau}{j\omega} e^{-j\omega\tau} + \frac{1}{\omega^2} e^{-j\omega\tau}$, which is found by partial integration.

The D.C. value of the spectrum is found from

$$S_{Y}(0) = \lim_{\omega \to 0} \frac{2a}{\omega^{2}b} (1 - \cos \omega b) = \lim_{\omega \to 0} \frac{2a}{\omega^{2}b} (1 - 1 + \frac{1}{2}\omega^{2}b^{2}) = ab$$



LINEAR SYSTEM CONTROL

Solutions to Problems

Problem 6.11

b. No because $S_{\gamma}(\omega)$ has infinitely many zeroes.

c.

$$H(s) = \frac{p}{s+q}, \quad V = 1$$

$$S_Y(\omega) = H(j\omega) \ V \ H^T(-j\omega) = \frac{p}{q+j\omega} \cdot \frac{p}{q-j\omega} = \frac{p^2}{q^2+\omega^2}$$

For the power in *Y* one finds:

$$P_Y = \int_{-\infty}^{\infty} S_Y(\omega) df = \frac{p^2}{2\pi q^2} \int_{-\infty}^{\infty} \frac{1}{1 + \left(\frac{\omega}{q}\right)^2} d\omega$$
$$= \frac{p^2}{2\pi q} \int_{-\infty}^{\infty} \frac{1}{1 + x^2} dx = \frac{p^2}{2\pi q} [\arctan x] \Big|_{-\infty}^{\infty} = \frac{p^2}{2q}, \quad (x = \frac{\omega}{q})$$

The D.C. power is

$$P_{\gamma} = R_{Y}(0) = a$$

It is required that:

$$(1) P_{\gamma} = P_{Y} \quad \Leftrightarrow \quad \frac{p^{2}}{2q} = a$$

$$(2) S_{\gamma}(0) = S_{\gamma}(0) \quad \Leftrightarrow \quad \frac{p^2}{q^2} = ab$$

which must be solved for p and q.

$$\frac{p^2}{q^2} = ab = \frac{p^2}{2q} b \Leftrightarrow q = \frac{2}{b}$$

LINEAR SYSTEMS CONTROL

Solutions to Problems

Problem 6.11

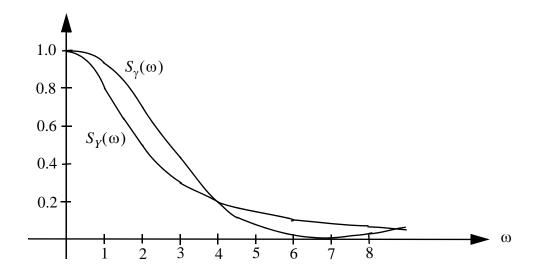
$$\frac{p^2}{q^2} = ab \iff p = q\sqrt{ab} = 2\sqrt{\frac{a}{b}}$$

$$H(s) = \frac{2\sqrt{\frac{a}{b}}}{s + \frac{2}{b}}$$

d.

$$a = 1, b = 1,$$

$$\begin{cases} S_{\gamma}(\omega) = \frac{2}{\omega^{2}} (1 - \cos \omega) \\ S_{\gamma}(\omega) = \frac{4}{\omega^{2} + 4} \end{cases}$$



The power bandwidth for *Y* can be found from:

$$P_Y^{\omega_0} = \int_{-\frac{\omega_0}{2\pi}}^{\frac{\omega_0}{2\pi}} S_Y(\omega) df = \frac{p^2}{\pi q} \left[a \tan \frac{\omega}{q} \right]$$

LINEAR SYSTEM CONTROL

Solutions to Problems

Problem 6.11

 $\boldsymbol{\omega}_0$ must be found so that

$$P_Y^{\omega_0} = \frac{1}{2}P_Y \quad \Leftrightarrow \quad \tan\frac{\omega_0}{q} = \frac{\pi}{4}$$

$$\Leftrightarrow \omega_0 = \frac{2}{b}$$

which is the power bandwidth for Y.