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**LINEAR SYSTEMS CONTROL**
**Solutions to Problems**


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**Problem 2.9**

- a. Using the volume conservation law:

$$\left. \begin{aligned} A_1 \dot{x}_1 &= ku_1 - q_1 \\ A_2 \dot{x}_2 &= q_1 - q_0 + q_2 \\ A_3 \dot{x}_3 &= -q_2 + ku_2 \end{aligned} \right\} \quad (1)$$

The corresponding flow equations are:

$$\left. \begin{aligned} q_1 &= c_1 \sqrt{x_1 - x_2} \\ q_2 &= c_2 \sqrt{x_3 - x_2} \\ q_0 &= c_0 \sqrt{x_2} \end{aligned} \right\} \quad (2)$$

Inserting equation (2) into (1):

$$\begin{aligned} \dot{x}_1 &= \frac{1}{A_1}(-c_1 \sqrt{x_1 - x_2} + ku_1) = f_1(x, u) \\ \dot{x}_2 &= \frac{1}{A_2}(c_1 \sqrt{x_1 - x_2} + c_2 \sqrt{x_3 - x_2} - c_0 \sqrt{x_2}) = f_2(x, u) \\ \dot{x}_3 &= \frac{1}{A_3}(ku_2 - c_2 \sqrt{x_3 - x_2}) = f_3(x, u) \end{aligned}$$

$$y = q_0 = c_0 \sqrt{x_2} = g(x, u)$$

- b. The stationary states are found by setting:

$$\dot{x}_1 = 0, \quad \dot{x}_2 = 0, \quad \dot{x}_3 = 0.$$

$$ku_{10} = c_1 \sqrt{x_{10} - x_{20}} \quad (3)$$

$$c_1 \sqrt{x_{10} - x_{20}} + c_2 \sqrt{x_{30} - x_{20}} = c_0 \sqrt{x_{20}} \quad (4)$$

$$ku_{20} = c_2 \sqrt{x_{30} - x_{20}} \quad (5)$$

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When equations (3) and (5) are inserted into (4):

$$ku_{10} + ku_{20} = c_0 \sqrt{x_{20}}$$

$$\Rightarrow x_{20} = \left( \frac{k}{c_0} (u_{10} + u_{20}) \right)^2$$

From (3) and (5) the following result is obtained:

$$x_{10} = \left( \frac{k}{c_1} u_{10} \right)^2 + x_{20}$$

$$x_{30} = \left( \frac{k}{c_2} u_{20} \right)^2 + x_{20}$$

with the output:

$$y_0 = c_0 \sqrt{x_{20}}$$

Now define the following incremental variables:

$$\begin{aligned} x_1 &= x_{10} + \Delta x_1 & u_1 &= u_{10} + \Delta u_1 \\ x_2 &= x_{20} + \Delta x_2 & u_2 &= u_{20} + \Delta u_2 \\ x_3 &= x_{30} + \Delta x_3 & y &= y_0 + \Delta y \end{aligned}$$

$$\mathbf{A} = \left\{ \frac{\partial f_i}{\partial x_j} \right\}_0$$

$$= \begin{bmatrix} \frac{-c_1}{2A_1 \sqrt{x_{10} - x_{20}}} & \frac{c_1}{2A_1 \sqrt{x_{10} - x_{20}}} & 0 \\ \frac{c_1}{2A_2 \sqrt{x_{10} - x_{20}}} - \frac{c_1}{2A_2 \sqrt{x_{10} - x_{20}}} - \frac{c_0}{2A_2 \sqrt{x_{20}}} - \frac{c_2}{2A_2 \sqrt{x_{30} - x_{20}}} & \frac{c_2}{2A_2 \sqrt{x_{30} - x_{20}}} \\ 0 & \frac{c_2}{2A_3 \sqrt{x_{30} - x_{20}}} & -\frac{c_2}{2A_3 \sqrt{x_{30} - x_{20}}} \end{bmatrix}$$

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$$\mathbf{B} = \left\{ \frac{\partial f_i}{\partial u_j} \right\}_0 = \begin{bmatrix} \frac{k}{A_1} & 0 \\ 0 & 0 \\ 0 & \frac{k}{A_3} \end{bmatrix}$$

$$\mathbf{C} = \left\{ \frac{\partial g_i}{\partial x_j} \right\}_0 = \left\{ 0 \quad \frac{c_0}{2\sqrt{x_{20}}} \quad 0 \right\}$$

$$\mathbf{D} = \left\{ \frac{\partial g_i}{\partial u_j} \right\}_0 = 0$$

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