Processes OPS Lecture 3, G53OPS/G52OSC

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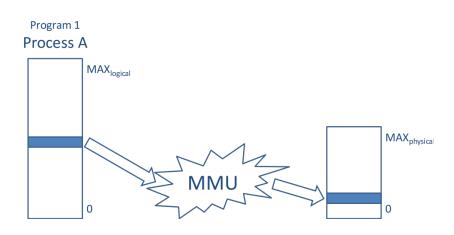
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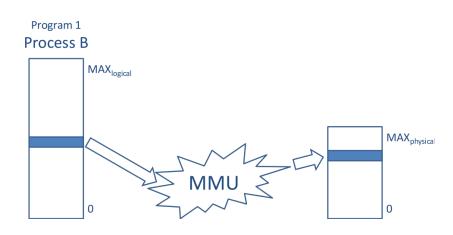
Recap Last Lecture

- The hardware and the operating system interract closely
- The operating system must have in depth knowledge of the hardware
- Examples of interrupts and address translation

Recap Last Lecture



Recap Last Lecture



Goals for Today Overview

- Introduction to processes and their implementation
- Process states and state transitions
- System calls for process management

Processes Definition

- The simplified definition: "a process is a running instance of a program"
 - A program is passive and "sits" on a disk
 - A process has control structures associated with it, may be active, and may have resources assigned to it (e.g. I/O devices, memory, processor)
- A process is registered with the OS using its "control structures": i.e. an entry in the OS's process table to a process control blocks (PCB)
- The process control block contains all information necessary to administer the process and is essential for context switching in multiprogrammed systems

Processes

Memory Image of Processes

- A process' memory image contains:
 - The program code (could be shared between multiple processes running the same code)
 - A data segment, stack and heap
- Every process has its own logical address space, in which the stack and heap are placed at opposite sides to allow them to grow

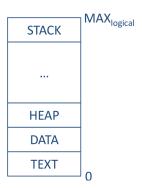
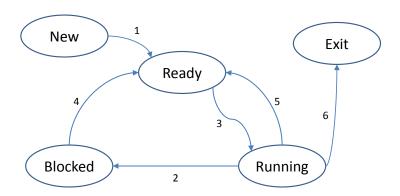


Figure: Representation of a process in memory

Process States and Transitions Diagram



Process States and Transitions

- A new process has just been created (has a PCB) and is waiting to be admitted (it may not yet be in memory)
- A ready process is waiting for CPU to become available (e.g. unblocked or timer interrupt)
- A running process "owns" the CPU
- A blocked process cannot continue, e.g. is waiting for I/O
- A terminated process is no longer executable (the data structures PCB may be temporarily preserved

Process States and Transitions

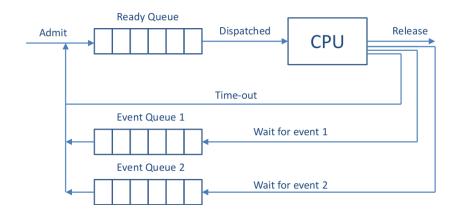
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- A suspended process is swapped out (not discussed further)

Process States and Transitions

Transitions

- State transitions include:
 - **1** New \rightarrow ready: admit the process and commit to execution
 - Running → blocked: e.g. process is waiting for input or carried out a system call
 - Ready → running: the process is selected by the process scheduler
 - Blocked
 → ready: event happens, e.g. I/O operation has finished
 - Sunning → ready: the process is preempted, e.g., by a timer interrupt or by pause
 - Running → exit: process has finished, e.g. program ended or exception encountered
- The interrupts/traps/system calls lie on the basis of the transitions

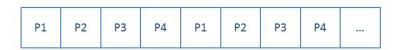
Process States and Transitions OS Queues



Context Switching

Multi-programming

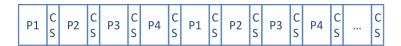
- Modern computers are multi-programming systems:
- Assuming a single processor system, the instructions of individual processes are executed sequentially
 - Multi-programming goes back to the "MULTICS" age
 - Multi-programming is achieved by alternating processes and context switching
 - True parallelism requires multiple processors



TIME

Context Switching Multi-programming (Cont'ed)

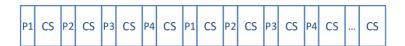
- When a context switch takes place, the system saves the state of the old process and loads the state of the new process (creates overhead)
 - Saved ⇒ the process control block is updated
 - (Re-)started ⇒ the process control block read
- A trade-off exists between "responsiveness" and "overhead"
- The OS uses process control blocks and a process table to manage processes and maintain their information



TIME

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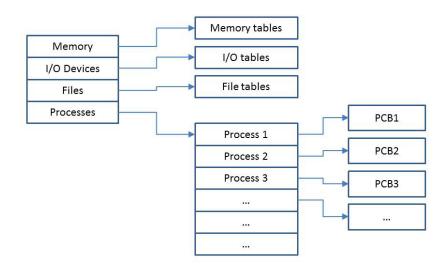
TIME

Context Switching Multi-programming (Cont'ed)

- A process control block contains three types of attributes:
 - Process identification (PID, UID, Parent PID)
 - Process state information (user registers, program counter, stack pointer, program status word, memory management information, files, etc.)
 - Process control information (process state, scheduling information, etc.)
- Process control blocks are kernel data structures, i.e. they are protected and only accessible in kernel mode!
 - Allowing user applications to access them directly could compromise their integrity
 - The operating system manages them on the user's behalf through system calls

Process Implementation

Tables and Control Blocks



Process Implementation

Tables and Control Blocks

- An operating system maintains information about the status of "resources" in tables
 - Process tables (process control blocks)
 - Memory tables (memory allocation, memory protection, virtual memory)
 - I/O tables (availability, status, transfer information)
 - File tables (location, status)
- The process table holds a process control block for each process, allocated upon process creation
- Tables are maintained by the kernel and are usually cross referenced

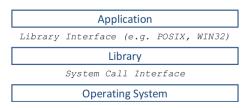
Context Switching

Switching Processes

- 1. Save process state (program counter, registers)
- 2. Update PCB (running -> ready)
- 3. Move PCB to appropriate queue (ready/blocked)
- 4. Run scheduler, select new process
- 5. Update to running state in PCB
- 6. Update memory structures
- 7. Restore process

System Calls Process Creation

- The true system calls are "wrapped" in the OS libraries (e.g. libc) following a well defined interface (e.g. POSIX, WIN32 API)
- System calls for process creation:
 - Unix: fork() generates and exact copy of parent ⇒ exec()
 - Windows: NTCreateProcess()
 - Linux: Clone()



System Calls Process Termination

- System calls are necessary to notify the OS that the process has terminated
 - Resources must be de-allocated
 - Output must be flushed
 - · Process admin may have to be carried out
- A system calls for process termination:
 - UNIX/Linux: exit(), kill()
 - Windows: TerminateProcess()

Processes

Process Creation in Linux

```
while (TRUE) {
                                                  /* repeat forever /*/
     type_prompt();
                                                  /* display prompt on the screen */
                                                  /* read input line from keyboard */
     read_command(command, params);
                                                  /* fork off a child process */
     pid = fork();
     if (pid < 0) {
                                                  /* error condition */
           printf("Unable to fork0);
           continue:
                                                  /* repeat the loop */
     if (pid! = 0) {
                                                  /* parent waits for child */
           waitpid (-1, \&status, 0);
     } else {
                                                  /* child does the work */
           execve(command, params, 0);
```

Figure: Use of the fork() and exec() system calls (Tanenbaum)

Recap Take-Home Message

- **Definition of a process** and their **implementation** in operating systems
- States, state transitions of processes
- Kernel structures for processes and process management
- System calls for process management

Next Lecture Content

• Next Lecture: Process Scheduling