Calibration results
====================
Camera-system parameters:
cam0 (/usb_cam/image_raw):
    type: <class 'aslam_cv.libaslam_cv_python.EquidistantDistortedPinholeCameraGeometry'>
    distortion: [-0.18299879 0.01125116 0.00548213 -0.00250442] +- [0.00763714 0.02058183 0.02161859 0.00767897]
    projection: [269.04029494 269.10702032 331.09116622 242.48451633] +- [0.48047582 0.50059396 0.16639415 0.26100448]
    reprojection error: [0.000008, -0.000001] +- [0.167539, 0.158880]

Target configuration
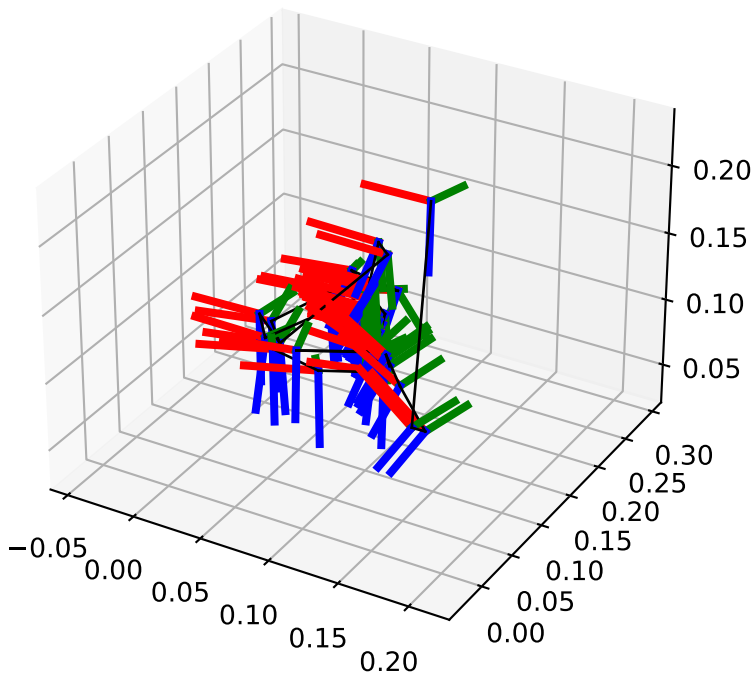====================
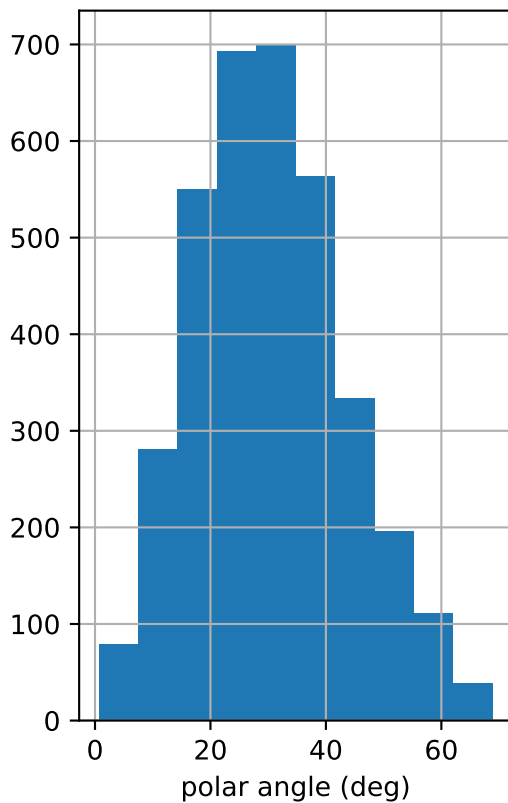
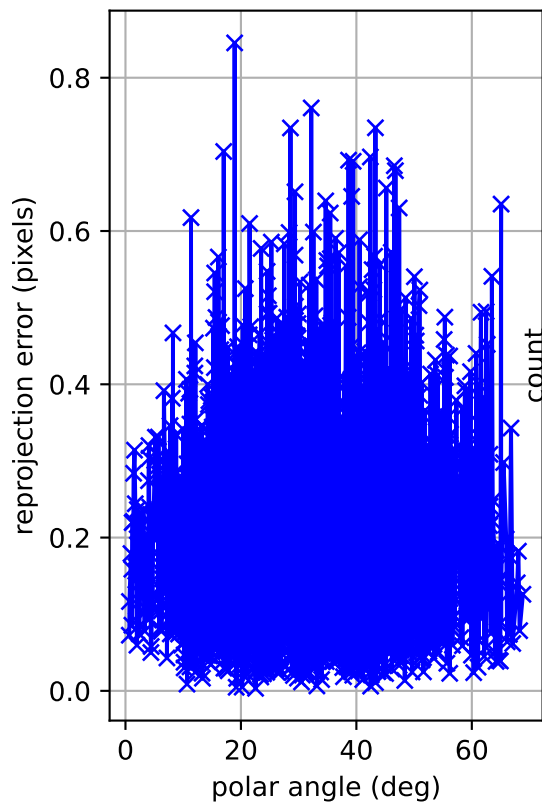 Type: aprilgrid
  Tags:
    Rows: 6
    Cols: 6
    Size: 0.022 [m]
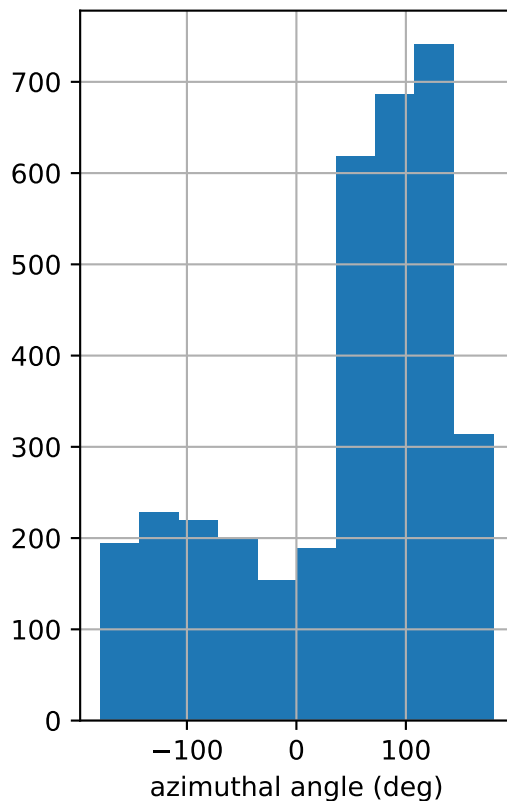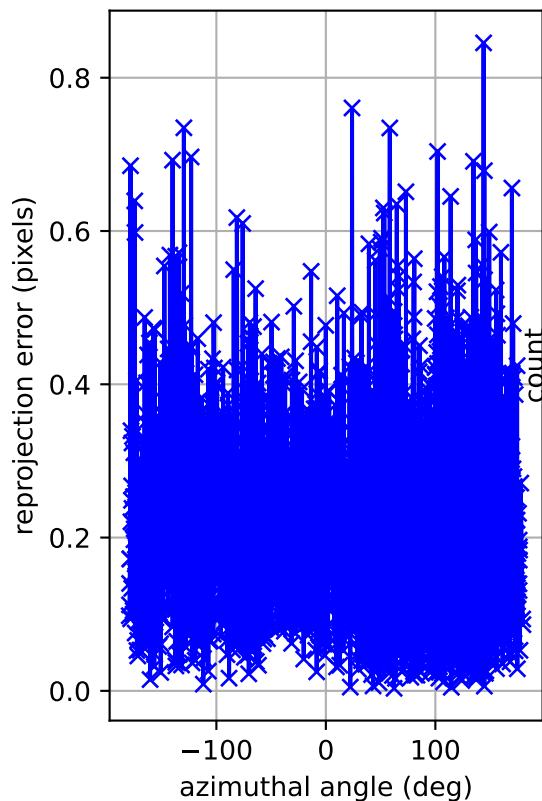   Spacing 0.006599999999999999 [m]
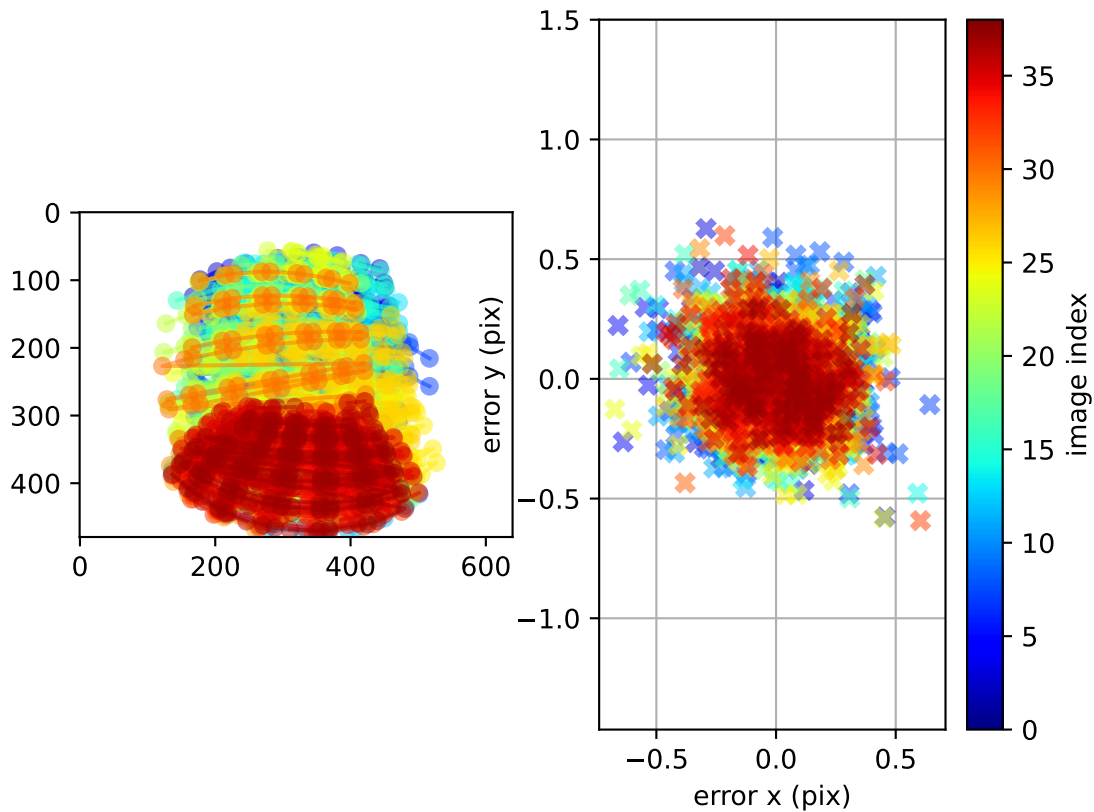
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0