1.

```
#!/usr/bin/python
import numpy
from matplotlib import pyplot as plt
from datetime import datetime
# Opens the data file with the formatted data, time, and wind speeds
    f = open("/home/pi/ECE331/HW/HW04/data.txt",'r')
   print "Couldn't open file"
   pass
# Loads the data from the text file then close file
data = numpy.loadtxt(f,dtype=int)
f.close()
# Creates datetimes and puts in array (year, month, day, hour, minute, second)
time = []
for i in range(len(data[:,1])):
    dates = datetime(data[i][0],data[i][1],data[i][2],data[i][3],data[i][4],data[i][5])
    time.append(dates)
# Plot the wind speeds
plt.plot(time, data[:, 6], time, data[:, 7])
plt.title("Top of Mount Katahdin Wind Speeds")
plt.xlabel("Dates")
plt.ylabel("Wind Speeds in mph")
plt.legend("Min Wind Speeds", "Max Wind Speeds")
plt.show()
2.
************ main.c *************
#include "gpio.h"
#include <stdlib.h>
#include <stdio.h>
#include <stdint.h>
#include <unistd.h>
// Run tests on gpio.c functions
int main(int argc, char *argv[])
{
    // test case for gpio 4
    uint32_t num4 = 4;
    uint32_t iter;
    // turn on and off gpio output five times to blink LED
    GPIO_export (num4);
    GPIO_setdir(num4,"out");
    for (iter = 0; iter < 5; iter++) {</pre>
       GPIO_setval(num4,0);
        usleep(500000);
        GPIO_setval(num4,1);
        usleep(500000);
    GPIO_unexport (num4);
    return 0;
}
******************* qpio.h *****************
```

```
#ifndef GPIO_H
#define GPIO_H
// includes to be used
#include <stdio.h>
#include <stdlib.h>
#include <stdint.h>
#include <string.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <unistd.h>
// gpio function prototypes
uint32_t GPIO_export(uint32_t gpio);
uint32_t GPIO_unexport(uint32_t gpio);
uint32_t GPIO_setval(uint32_t gpio, uint32_t val);
uint32_t GPIO_setdir(uint32_t gpio, char dir[]);
#endif
#include "gpio.h"
// Export gpio
uint32_t GPIO_export(uint32_t gpio)
    int32_t f; // file
                       // write
   char string[10];
    sprintf(string,"%u",gpio); // change gpio from int to string
    // open export file
    f = open("/sys/class/gpio/export",O_WRONLY);
    if (f < 0) {
       printf("Could not open export\n");
       return 1;
    }
    // export gpio
    if (write(f, string, strlen(string)) < 0) {</pre>
       printf("Could not export\n");
       return 2;
    }
    // close and wait
   close(f);
   usleep(50000);
   return 0;
}
// Unexport gpio
uint32_t GPIO_unexport(uint32_t gpio)
    int32_t f; // file
   char string[10];
                     // write
    sprintf(string,"%u",gpio); // change gpio from int to string
    // open unexport file
    f = open("/sys/class/gpio/unexport",O_WRONLY);
    if (f < 0) {
       printf("Could not open unexport\n");
       return 1;
    // unexport gpio
```

```
if(write(f, string, strlen(string)) < 0) {</pre>
        printf("Could not unexport\n");
        return 2;
    }
    // close and wait
    close(f);
    usleep(50000);
    return 0;
}
// Set value for gpio
uint32_t GPIO_setval(uint32_t gpio, uint32_t val)
    int32_t f; // file
                       // write
    char string[50];
                       // value
    char string1[10];
    sprintf(string,"/sys/class/gpio/gpio%u/value",gpio); // change gpio from int to stri
na
    sprintf(string1,"%u",val); // change val from int to string
    // open value file
    f = open(string,O_WRONLY);
    if (f < 0) {
        printf("Could not open value\n");
        return 1;
    }
    // write value
    if(write(f, string1, strlen(string1)) < 0) {</pre>
        printf("Could not set value\n");
        return 2;
    }
    // close and wait
    close(f);
    usleep(500);
    return 0;
}
// Set direction for gpio
uint32_t GPIO_setdir(uint32_t gpio, char dir[])
{
    int32_t f; // file
    char string[50];
                        // write
    sprintf(string, "/sys/class/gpio/gpio%u/direction", gpio); // change gpio from int to
string
    // open direction file
    f = open(string,O_WRONLY);
    if (f < 0) {
        printf("Could not open direction\n");
        return 1;
    }
    // write value
    if (write(f,dir,strlen(dir)) < 0) {</pre>
        printf("Could not set direction\n");
        return 2;
    // close and wait
    close(f);
    usleep(500);
    return 0;
```

```
hw04.txt 20/02/20 11:38:48
                                                             Spencer Goulette
# Makefile for HW04
# Creates main.o, gpio.o, and the executable gpio
TARGET=gpio
OBJS=main.o gpio.o
CFLAGS=-Wall -g -O2
all: $(TARGET)
$(TARGET): $(OBJS)
   $(CC) -o $(TARGET) $(OBJS)
clean:
   rm -f $(TARGET) $(OBJS) core*
********************
3. sudo ln -s /var/lib/systimer/logs/abc /usr/arm/opt/bin/foobar
4. egrep "^[0-9]+$" [0-9][0-9]
5. enscript -T 4 --header='$n %E %* | $% | Spencer Goulette' hw04.txt -o - | ps2pdf - output.pd
```