```
clear all;
% Spencer Goulette
% 02/04/20
```

## **Problem 6**

```
R a = 3.9;
                                             % resistance
L_a = .665e-3; % inductance
K_p = 3.17125; % control parameters
K 1 = 34473.6;
% Simulink
out = sim('ECE414HW2_6',...
                               'StartTime', '-.1e-6',...
                              'StopTime', '2e-3',...
                               'MaxStep', '1e-9');
open_system('ECE414HW2_6');
% Get Simulink data for input, plant input, and output
data = out.get('simout');
t = data.Time;
r = data.Data;
data1 = out.get('simout1');
t1 = data1.Time;
r1 = data1.Data;
data2 = out.get('simout2');
t2 = data2.Time;
r2 = data2.Data;
% Plot All Simulink Data
figure(1);
plot(t/1e-3,r,t1/1e-3,r1,t2/1e-3,r2);
grid on;
title("HW02, Problem 6");
xlabel("Time, msec");
ylabel("Response");
legend("Step input", "Plant input", "Step response");
% Plot step response and horizontal specs
figure(2);
plot(t2/1e-3,r2,[-0.5,2],[1.05,1.05], '-.r',[-0.5,2],[1.01,1.01], '--.r',[-0.5,2],[1.01,1.01], '--.r',[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2],[-0.5,2]
g',[-0.5,2],[0.99,0.99], '--g');
grid on;
ylim([0.9 1.1]);
title("HW02, Problem 6 Spec1");
xlabel("Time, msec");
ylabel("Step Response Specs");
legend("Step response", "Overshoot spec", "Settling Time spec")
```

```
% Plot step response and vertical specs
figure(3);
plot(t2/1e-3,r2,[-0.5,2],[0.1,0.1], '--q',[-0.5,2],[0.9,0.9], '--b',
[.0219,.0219],[0,1.5], '--g',[.262,.262],[0,1.5], '--b');
grid on;
xlim([0 0.5]);
title("HW02, Problem 6 Spec2");
xlabel("Time, msec");
ylabel("Step Response Specs");
legend("Step response","10% rise time","90% rise time")
Warning: Block diagram '<a href="matlab:open system"
('ECE414HW2_6')">ECE414HW2_6</a>' contains 1 algebraic loop(s). To see
details about the loops use the command <a
href="matlab:Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);">Simulink.BlockDiagram.getAlgebraicLoops(bdroot);</s>
href="matlab:open_system ('ECE414HW2_6')">ECE414HW2_6</a>') </a> or
  the command
line Simulink debugger by typing <a
  href="matlab:sldebug(bdroot);">sldebug('<a</pre>
href="matlab:open_system ('ECE414HW2_6')">ECE414HW2_6</a>') </a> in
  the MATLAB
command window. To eliminate this message, set <sldiag
  objui="configset"
objparam="AlgebraicLoopMsg">Algebraic loop</sldiag> to "none".
Found algebraic loop containing:
'<a href="matlab:open_and_hilite_hyperlink ('ECE414HW2_6/Varying
  Transfer Function1/Sum1', 'error')">ECE414HW2 6/Varying Transfer
  Function1/Sum1</a>'
'<a href="matlab:open_and_hilite_hyperlink ('ECE414HW2_6/</pre>
Subtract','error')">ECE414HW2_6/Subtract</a>'
'<a href="matlab:open_and_hilite_hyperlink ('ECE414HW2_6/Varying</pre>
  Transfer Function/Product1', 'error')">ECE414HW2 6/Varying Transfer
  Function/Product1</a>'
 '<a href="matlab:open_and_hilite_hyperlink ('ECE414HW2_6/Varying</pre>
  Transfer Function/Sum1', 'error')" > ECE414HW2 6/Varying Transfer
  Function/Sum1</a>'
 '<a href="matlab:open_and_hilite_hyperlink ('ECE414HW2_6/Varying</pre>
  Transfer Function1/Product1','error')">ECE414HW2_6/Varying Transfer
  Function1/Product1</a>' (algebraic variable)
```

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