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// A. Sheaff 3/15/2019 - wwv driver
// Framework code for creating a kernel driver
// that creates the digital data from WWV station
// Pass in time/date data through ioctl.
#include <linux/module.h>
#include <linux/kernel.h>
#include <linux/device.h>
#include <linux/err.h>
#include <linux/fs.h>
#include <linux/spinlock.h>
#include <linux/delay.h>
#include <linux/list.h>
#include <linux/io.h>
#include <linux/ioctl.h>
#include <linux/uaccess.h>
#include <linux/irq.h>
#include <linux/interrupt.h>
#include <linux/slab.h>
#include <linux/gpio.h>
#include <linux/of_gpio.h>
#include <linux/platform_device.h>
#include <linux/pinctrl/consumer.h>
#include <linux/gpio/consumer.h>
#include <linux/jiffies.h>

#include "wwv.h"

// Data to be "passed" around to various functions
struct wwv_data_t {
    struct gpio_desc *gpio_wwv;      // Enable pin
    struct gpio_desc *gpio_unused17; // Clock pin
    struct gpio_desc *gpio_unused18; // Bit 0 pin
    struct gpio_desc *gpio_unused22; // Bit 1 pin
    struct gpio_desc *gpio_shutdown; // Shutdown input
    int major;                       // Device major number
    struct class *wwv_class;         // Class for auto /dev population
    struct device *wwv_dev;          // Device for auto /dev population
    // ADD YOUR LOCKING VARIABLE BELOW THIS LINE
    struct mutex lock;
};

// ADD ANY WWV DEFINE BELOW THIS LINE

// WWV data structure access between functions
static struct wwv_data_t *wwv_data_fops;

//*****
// WWV Data format
//
//      0      1      2      3      4      5      6      7
//      8      9
// +---+---+---+---+---+---+---+---+
// |P0 |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
// |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
// +---+---+---+---+---+---+---+---+
// |   |Blank|Zero |DST |Leap|Sec|Warn|1's Year|2's Year|4's Year|8's Year|
// ar |Zero |POS |ID |   |   |   |   |   |   |   |   |   |   |   |   |
// +---+---+---+---+---+---+---+---+
//      10      11      12      13      14      15      16
//      17      18      19
// +---+---+---+---+---+---+---+---+
// |P1 |   |Minute|Units|Value|BCD|LSb|First|   |   |   |   |   |   |   |
// ue |BCD|LSb|First|   |   |   |   |   |   |   |   |   |   |   |   |
// +---+---+---+---+---+---+---+---+
//      20      21      22      23      24      25      26      27      28      29
```

```
// | 1's Minute | 2's Minute | 4's Minute | 8's Minute | Zero | 10's Minute | 20's Minute
// | 40's Minute | Zero | POS ID |
// +-----+-----+-----+-----+-----+-----+-----+
// | 20 | 21 | 22 | 23 | 24 | 25 | 26 |
// | 27 | 28 | 29 |
// +-----+-----+-----+-----+-----+-----+
// | P2 | Hour Units Value BCD LSb First | Hour Tens Value
// | BCD LSb First |
// +-----+-----+-----+-----+-----+-----+
// | 1's Hour | 2's Hour | 4's Hour | 8's Hour | Zero | 10's Hour | 20's Hour
// | 40's Hour | Zero | POS ID |
// +-----+-----+-----+-----+-----+-----+
// | 30 | 31 | 32 | 33 |
// | 34 | 35 | 36 | 37 | 38 | 39 |
// +-----+-----+-----+-----+-----+-----+
// +-----+-----+-----+-----+-----+-----+
// | P3 | Day of Year Units Value BCD LSb First |
// | Day of Year Tens Value BCD LSb First |
// +-----+-----+-----+-----+-----+-----+
// +-----+-----+-----+-----+-----+-----+
// | 1's Day of Year | 2's Day of Year | 4's Day of Year | 8's Day of Year | Zero
// | 10's Day of Year | 20's Day of Year | 40's Day of Year | 80's Day of Year | POS ID
// +-----+-----+-----+-----+-----+-----+
// +-----+-----+-----+-----+-----+-----+
// | 40 | 41 | 42 | 43 | 44 | 45 |
// | 46 | 47 | 48 | 49 |
// +-----+-----+-----+-----+-----+-----+
// | P4 | Day of Year Hundreds Value BCD LSb First |
// | | | | |
// +-----+-----+-----+-----+-----+-----+
// | 100's Day of Year | 200's Day of Year | Zero | Zero | Zero | Blank | Blank
// | Blank | Blank | Blank | Blank |
// +-----+-----+-----+-----+-----+-----+
// | 50 | 51 | 52 | 53 | 54 | 55 | 56 | 57 | 58 | 59 |
// +-----+-----+-----+-----+-----+-----+
// | P5 | Blank | Blank | Blank | Blank | Blank | Blank | Blank | Blank | Blank | Blank |
// +-----+-----+-----+-----+-----+-----+

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// ADD YOUR WWV ENCODING/TRANSMITTING/MANAGEMENT FUNCTIONS BELOW THIS LINE
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```
static int encodebit(int width, struct wwv_data_t *wwv_dat)
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```
{
    int i;                // Iterator

    // 100Hz signal for width ms
    for(i = 0; i < width/10; i++) {
        gpiod_set_value(wwv_dat->gpio_wwv, 1);
        usleep_range(5000, 5010);
        gpiod_set_value(wwv_dat->gpio_wwv, 0);
        usleep_range(5000, 5010);

        // Extra time for accuracy
        if(i == (width/10 - 1)) {
            gpiod_set_value(wwv_dat->gpio_wwv, 1);
            usleep_range(5000, 5010);
        }
    }
}
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    // zero for rest of second
    gpiod_set_value(wwv_dat->gpio_wwv,0);
    usleep_range((1000-width)*1000,(1000-width)*1000 + 10);
    return 0;
}

// Gets data and time and encodes it for wwv
static int encodedatetime(int *data, struct wwv_data_t *wwv_dat)
{
    int i;                // Iterator
    int ret;              // Return Value
    int *array;           // Holds widths for wwv
    int yearones;         // Date and Time variables
    int minones;
    int mintens;
    int hourones;
    int hourtens;
    int doycles;
    int doytens;
    int doyhundreds;

    // Initializes to size of 60 ints
    array = (int *)kcalloc(61,sizeof(int),GFP_ATOMIC);
    if (array == NULL) {
        printk(KERN_INFO "Memory allocation failed!\n");
        ret = -ENOMEM;
        goto fail;
    }

    // Gets ones, tens and hundreds place for date and time
    yearones = (data[0] + 1900) % 10;
    minones = (data[3]) % 10;
    mintens = ((data[3]) % 100) / 10;
    hourones = (data[2]) % 10;
    hourtens = ((data[2]) % 100) / 10;
    doycles = (data[1]) % 10;
    doytens = ((data[1]) % 100) / 10;
    doyhundreds = ((data[1]) % 1000) / 100;

    // Places 1s, 2s, 4s, and 8s bit in wwv array
    for (i = 4; i < 8; i++) {
        array[i] = ((yearones & (0x01 << (i - 4))) ? 470 : 170);
        array[i + 6] = ((minones & (0x01 << (i - 4))) ? 470 : 170);
        array[i + 16] = ((hourones & (0x01 << (i - 4))) ? 470 : 170);
        array[i + 26] = ((doyones & (0x01 << (i - 4))) ? 470 : 170);
        array[i + 31] = ((doytens & (0x01 << (i - 4))) ? 470 : 170);
    }

    // Places 1s, 2s, and 4s bit in wwv array
    for (i = 15; i < 18; i++) {
        array[i] = ((mintens & (0x01 << (i - 15))) ? 470 : 170);
        array[i + 10] = ((hourtens & (0x01 << (i - 15))) ? 470 : 170);
    }

    // Places 1s, and 2s bit in wwv array
    for (i = 40; i < 42; i++) {
        array[i] = ((doyhundreds & (0x01 << (i - 40))) ? 470 : 170);
    }

    // Places P indentifiers in wwv array
    for (i = 1; i < 5; i++) {
        array[i * 10 - 1] = 770;
    }

    // Places zero bits in wwv array
    for (i = 0; i < 3; i++) {
        array[i + 1] = 170;
    }
}

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    array[i + 42] = 170;
    array[i * 10 + 8] = 170;
    array[i * 10 + 14] = 170;
}

// Encodes each element
for(i = 0; i < 60; i++)
{
    encodebit(array[i], wwv_dat);
}

// Clean Up
kfree(array);
array = NULL;

return 0;

fail:

    return ret;
}

// Does checking that is described in comments above ioctl function
static int encodemanagement(struct file * filp, struct wwv_data_t *wwv_dat, unsigned long a
rg)
{
    int ret = 0;    // Return value
    int *kdata;    // Memory for data transfer
    int size = 16; // Size of data transfer

    // Checks if another process is using pins and if it is opened with O_NONBLOCK return
    if ((mutex_is_locked(&(wwv_dat->lock))) && (filp->f_flags & O_NONBLOCK)) {
        printk(KERN_INFO "Lock taken and Nonblock!\n");
        kdata = NULL;
        ret = -EACCES;
        goto fail;
    }

    // Checks if another process is using pins. If so wait and if receive a signal handles
    error.
    if(mutex_lock_interruptible(&(wwv_dat->lock))) {
        printk(KERN_INFO "Error getting lock!\n");
        kdata = NULL;
        ret = -EACCES;
        goto fail;
    }

    // Allocates memory for data
    kdata = (int *)kmalloc(size+1,GFP_ATOMIC);
    if (kdata == NULL) {
        printk(KERN_INFO "Memory allocation failed!\n");
        mutex_unlock(&(wwv_dat->lock));
        ret = -ENOMEM;
        goto fail;
    }

    // Gets datetime from userspace
    if(copy_from_user(kdata, (const void __user *)arg, size) != 0) {
        printk(KERN_INFO "Copying from userspace failed!\n");
        mutex_unlock(&(wwv_dat->lock));
        kfree(kdata);
        kdata = NULL;
        ret = -EFAULT;
        goto fail;
    }

    // Encodes data
    ret = encodedatetime(kdata, wwv_dat);
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    if(ret != 0) {
        printk(KERN_INFO "Encoding Error!\n");
        mutex_unlock(&(wwv_dat->lock));
        kfree(kdata);
        kdata = NULL;
        goto fail;
    }

    // Unlocks and cleans up
    mutex_unlock(&(wwv_dat->lock));
    printk(KERN_INFO "Cleaning up!\n");
    kfree(kdata);
    kdata = NULL;

    return 0;

fail:

    return ret;
}
// ioctl system call
// If another process is using the pins and the device was opened O_NONBLOCK
// then return with the appropriate error
// Otherwise
// If another process is using the pins
// then block/wait for the pin to be free. Clean up and return an error if a signal is
// received.
// Otherwise
// Copy the user space data using copy_from_user() to a local kernel space buffer that
// you allocate
// Encode to the copied data using your encoding system from homework 5 (your "wwv" cod
// e) to another kernel buffer that you allocate
// Toggle pins as in homework 04 gpio code. While delaying, do not consume CPU resourc
// es. *** SEE TIMERS-HOWTO.TXT IN THE KERNEL DOCUMENTATION ***
// Use a variable for the clock high and low pulse widths that is shared with the ioc
// tl class. The
// CLEAN UP (free all allocated memory and any other resouces you allocated) AND RETURN AP
// PROPRAITE VALUE

// You will need to choose the type of locking yourself. It may be atmonic variables, spin
// locks, mutex, or semaphore.
static long wwv_ioctl(struct file * filp, unsigned int cmd, unsigned long arg)
{
    long ret = 0; // Return value
    struct wwv_data_t *wwv_dat; // Driver data - has gpio pins

    // Get our driver data
    wwv_dat=(struct wwv_data_t *)filp->private_data;

    // IOCTL cmds
    switch (cmd) {
        case WWV_TRANSMIT:
            // PLACE A CALL TO YOUR FUNCTION AFTER THIS LINE
            ret = encodemangement(filp, wwv_dat, arg);
            break;
        default:
            ret = -EINVAL;
            break;
    }

    // Clean up
    gpiod_set_value(wwv_dat->gpio_wwv, 0);
    goto fail;

fail:

    return ret;
}

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// Write system call
// Just return 0
static ssize_t wwv_write(struct file *filp, const char __user * buf, size_t count, loff_t *
    offp)
{
    return 0;
}

// Open system call
// Open only if the file access flags (NOT permissions) are appropriate as discussed in clas
s
// Return an appropriate error otherwise
static int wwv_open(struct inode *inode, struct file *filp)
{
    // SUCESSFULLY THE FILE IF AND ONLY IF THE FILE FLAGS FOR ACCESS ARE APPROPRIATE
    // RETURN WITH APPROPRIATE ERROR OTHERWISE
    if ((filp->f_flags&O_ACCMODE)==O_RDONLY) return -EOPNOTSUPP;
    if ((filp->f_flags&O_ACCMODE)==O_RDWR) return -EOPNOTSUPP;

    filp->private_data=wwv_data_fops; // My driver data (afsk_dat)

    return 0;
}

// Close system call
// What is there to do?
static int wwv_release(struct inode *inode, struct file *filp)
{
    return 0;
}

// File operations for the wwv device
static const struct file_operations wwv_fops = {
    .owner = THIS_MODULE, // Us
    .open = wwv_open, // Open
    .release = wwv_release, // Close
    .write = wwv_write, // Write
    .unlocked_ioctl=wwv_ioctl, // ioctl
};

static struct gpio_desc *wwv_dt_obtain_pin(struct device *dev, struct device_node *parent,
char *name, int init_val)
{
    struct device_node *dn_child=NULL; // DT child
    struct gpio_desc *gpiod_pin=NULL; // GPIO Descriptor for setting value
    int ret=-1; // Return value
    int pin=-1; // Pin number
    char *label=NULL; // DT Pin label

    // Find the child - release with of_node_put()
    dn_child=of_get_child_by_name(parent,name);
    if (dn_child==NULL) {
        printk(KERN_INFO "No child %s\n",name);
        gpiod_pin=NULL;
        goto fail;
    }

    // Get the child pin number - does not appear to need to be released
    pin=of_get_named_gpio(dn_child,"gpios",0);
    if (pin<0) {
        printk(KERN_INFO "no %s GPIOs\n",name);
        gpiod_pin=NULL;
        goto fail;
    }
    // Verify pin is OK
    if (!gpio_is_valid(pin)) {
        gpiod_pin=NULL;
    }
}

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        goto fail;
    }
    printk(KERN_INFO "Found %s pin %d\n",name,pin);

    // Get the of string tied to pin - Does not appear to need to be released
    ret=of_property_read_string(dn_child,"label",(const char *)&label);
    if (ret<0) {
        printk(KERN_INFO "Cannot find label\n");
        gpiod_pin=NULL;
        goto fail;
    }
    // Request the pin - release with devm_gpio_free() by pin number
    if (init_val>=0) {
        ret=devm_gpio_request_one(dev,pin,GPIOF_OUT_INIT_LOW,label);
        if (ret<0) {
            dev_err(dev,"Cannot get %s gpio pin\n",name);
            gpiod_pin=NULL;
            goto fail;
        }
    } else {
        ret=devm_gpio_request_one(dev,pin,GPIOF_IN,label);
        if (ret<0) {
            dev_err(dev,"Cannot get %s gpio pin\n",name);
            gpiod_pin=NULL;
            goto fail;
        }
    }

    // Get the gpiod pin struct
    gpiod_pin=gpio_to_desc(pin);
    if (gpiod_pin==NULL) {
        printk(KERN_INFO "Failed to acquire wwv gpio\n");
        gpiod_pin=NULL;
        goto fail;
    }

    // Make sure the pin is set correctly
    if (init_val>=0) gpiod_set_value(gpiod_pin,init_val);

    // Release the device node
    of_node_put(dn_child);

    return gpiod_pin;

fail:
    if (pin>=0) devm_gpio_free(dev,pin);
    if (dn_child) of_node_put(dn_child);

    return gpiod_pin;
}

// Sets device node permission on the /dev device special file
static char *wwv_devnode(struct device *dev, umode_t *mode)
{
    if (mode) *mode = 0666;
    return NULL;
}

// My data is going to go in either platform_data or driver_data
// within &pdev->dev. (dev_set/get_drvdata)
// Called when the device is "found" - for us
// This is called on module load based on ".of_match_table" member
static int wwv_probe(struct platform_device *pdev)
{
    struct device *dev = &pdev->dev;    // Device associated with platform

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struct wwv_data_t *wwv_dat;          // Data to be passed around the calls
struct device_node *dn=NULL;

int ret=-1; // Return value

// Allocate device driver data and save
wwv_dat=kmalloc(sizeof(struct wwv_data_t),GFP_ATOMIC);
if (wwv_dat==NULL) {
    printk(KERN_INFO "Memory allocation failed\n");
    return -ENOMEM;
}

memset(wwv_dat,0,sizeof(struct wwv_data_t));

dev_set_drvdata(dev,wwv_dat);

// Find my device node
dn=of_find_node_by_name(NULL,"wwv");
if (dn==NULL) {
    printk(KERN_INFO "Cannot find device\n");
    ret=-ENODEV;
    goto fail;
}
wwv_dat->gpio_wwv=wwv_dt_obtain_pin(dev,dn,"WWV",0);
if (wwv_dat->gpio_wwv==NULL) goto fail;
wwv_dat->gpio_unused17=wwv_dt_obtain_pin(dev,dn,"Unused17",0);
if (wwv_dat->gpio_unused17==NULL) goto fail;
wwv_dat->gpio_unused18=wwv_dt_obtain_pin(dev,dn,"Unused18",0);
if (wwv_dat->gpio_unused18==NULL) goto fail;
wwv_dat->gpio_unused22=wwv_dt_obtain_pin(dev,dn,"Unused22",0);
if (wwv_dat->gpio_unused22==NULL) goto fail;
wwv_dat->gpio_shutdown=wwv_dt_obtain_pin(dev,dn,"Shutdown",-1);
if (wwv_dat->gpio_shutdown==NULL) goto fail;

// Create the device - automagically assign a major number
wwv_dat->major=register_chrdev(0,"wwv",&wwv_fops);
if (wwv_dat->major<0) {
    printk(KERN_INFO "Failed to register character device\n");
    ret=wwv_dat->major;
    goto fail;
}

// Create a class instance
wwv_dat->wwv_class=class_create(THIS_MODULE, "wwv_class");
if (IS_ERR(wwv_dat->wwv_class)) {
    printk(KERN_INFO "Failed to create class\n");
    ret=PTR_ERR(wwv_dat->wwv_class);
    goto fail;
}

// Setup the device so the device special file is created with 0666 perms
wwv_dat->wwv_class->devnode=wwv_devnode;
wwv_dat->wwv_dev=device_create(wwv_dat->wwv_class,NULL,MKDEV(wwv_dat->major,0),(void *)
wwv_dat,"wwv");
if (IS_ERR(wwv_dat->wwv_dev)) {
    printk(KERN_INFO "Failed to create device file\n");
    ret=PTR_ERR(wwv_dat->wwv_dev);
    goto fail;
}

wwv_data_fops=wwv_dat;

mutex_init(&(wwv_dat->lock));

printk(KERN_INFO "Registered\n");
dev_info(dev, "Initialized");
```



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    return 0;

fail:
    // Device cleanup
    if (wwv_dat->wwv_dev) device_destroy(wwv_dat->wwv_class, MKDEV(wwv_dat->major, 0));
    // Class cleanup
    if (wwv_dat->wwv_class) class_destroy(wwv_dat->wwv_class);
    // char dev clean up
    if (wwv_dat->major) unregister_chrdev(wwv_dat->major, "wwv");

    if (wwv_dat->gpio_shutdown) devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_shutdown));
    if (wwv_dat->gpio_unused22) devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_unused22));
    if (wwv_dat->gpio_unused18) devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_unused18));
    if (wwv_dat->gpio_unused17) devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_unused17));
    if (wwv_dat->gpio_wwv) devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_wwv));

    dev_set_drvdata(dev, NULL);
    kfree(wwv_dat);
    printk(KERN_INFO "WWV Failed\n");
    return ret;
}

// Called when the device is removed or the module is removed
static int wwv_remove(struct platform_device *pdev)
{
    struct device *dev = &pdev->dev;
    struct wwv_data_t *wwv_dat; // Data to be passed around the calls

    // Obtain the device driver data
    wwv_dat = dev_get_drvdata(dev);

    // Device cleanup
    device_destroy(wwv_dat->wwv_class, MKDEV(wwv_dat->major, 0));
    // Class cleanup
    class_destroy(wwv_dat->wwv_class);
    // Remove char dev
    unregister_chrdev(wwv_dat->major, "wwv");

    // Free the gpio pins with devm_gpio_free() & gpiod_put()
    devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_shutdown));
    devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_unused22));
    devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_unused18));
    devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_unused17));
    devm_gpio_free(dev, desc_to_gpio(wwv_dat->gpio_wwv));
    #if 0
    // not clear if these are allocated and need to be freed
    gpiod_put(wwv_dat->gpio_shutdown);
    gpiod_put(wwv_dat->gpio_unused22);
    gpiod_put(wwv_dat->gpio_unused18);
    gpiod_put(wwv_dat->gpio_unused17);
    gpiod_put(wwv_dat->gpio_wwv);
    #endif

    // Free the device driver data
    dev_set_drvdata(dev, NULL);
    kfree(wwv_dat);

    printk(KERN_INFO "Removed\n");
    dev_info(dev, "GPIO mem driver removed - OK");

    return 0;
}

static const struct of_device_id wwv_of_match[] = {
    { .compatible = "brcm,bcm2835-wwv", },
    { /* sentinel */ },
};

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```
MODULE_DEVICE_TABLE(of, wwv_of_match);

static struct platform_driver wwv_driver = {
    .probe = wwv_probe,
    .remove = wwv_remove,
    .driver = {
        .name = "bcm2835-wwv",
        .owner = THIS_MODULE,
        .of_match_table = wwv_of_match,
    },
};

module_platform_driver(wwv_driver);

MODULE_DESCRIPTION("WWV pin modulator");
MODULE_LICENSE("GPL");
MODULE_DESCRIPTION("WWV");
//MODULE_ALIAS("platform:wwv-bcm2835");
```