# Termination Analysis for Multi-Path Linear Loops

Hui Jin et. al from Tianjin Uni.

July 14, 2020

# History of Research

Joint research with Xiaofei Xie of NTU.

- Xiaofei Xie, Bihuan Chen, Liang Zou, Shang-Wei Lin, Yang Liu, and Xiaohong Li. "Loopster: static loop termination analysis." In Proceedings of the 2017 11th Joint Meeting on Foundations of Software Engineering, pp. 84-94. ACM, ESEC/FSE 2017
- Xiaofei Xie, Bihuan Chen, Liang Zou, Yang Liu, Wei Le, and Xiaohong Li. X. Xie, B. Chen, L. Zou, Y. Liu, W. Le and X. Li, "Automatic Loop Summarization via Path Dependency Analysis." In IEEE Transactions on Software Engineering, vol. 45, no. 6, pp. 537-557, TSE 2019

#### Contribution

- Extend the path dependency automaton(PDA) to analyze the linear loop and extract paths in CFG as states in the PDA to obtain the dependecy relationship between paths.
- ► Make a simple classification of cycles in PDA, and proposed methods to determie the termination of the cycle.
- ► Implement algorithm proposed by Tiwari to determine the termination of linear loops.

## Loop Path of CFG

#### Definition (Control Flow Graph(CFG))

A control flow graph of a loop is a tuple  $\mathcal{G}=(V,E,v_s,V_h,V_e,\mathbf{1})$ , where  $V_h,V_e$  are the set of header blocks and exit blocks respectively.  $\mathbf{1}(e)$  is the branch conditio nof the edge  $e\in E$ .

#### Definition

Given a CFG  $\mathcal{G}=(V,E,v_s,V_h,V_e,{\scriptscriptstyle 1})$ , the loop path  $\sigma$  is a finite sequence  $v_0,v_1,\ldots,v_k$  of basic blocks where  $v_0\in V_h$  and  $v_k\in V_h\cup V_e$  are the head and tail of  $\sigma$ . We call a path iterable path if  $head(\sigma)=tail(\sigma)$ .

- Path condition:  $\theta_{\sigma}$  is the conjunction of the branch condition of each edge in the path.
- ▶ Value change of vars:  $\mathcal{V}_{\sigma}$ .  $\theta(\sigma_i, \mathcal{V}_{\sigma_j}^n) \to \{true, false\}$ .
- $ightharpoonup pre(\mathcal{G})$ : precondition of loop represent the possible valuation of vars.

# Exmaple

```
int x=*;
                                                    int y=*;
int x = *;
int y = *;
                                                            b
while (2x+y>0) {
                                                2x+y>0 -
                                                        -2x+y \le 0
      if(y>0) {
                                        c
            x = -x-y;
            y = -3y;
                                         y>0 ____ y<=0 ___
       }else{
            x = -2x + y;
                                   x = -x-y;
                                                  x = -2x-y;
                                   y = -3y;
                                      e
```

Loop paths:  $\sigma_1 = (b, c, e, b), \sigma_2 = (b, c, f, b), \sigma_3 = (b, d)$ 

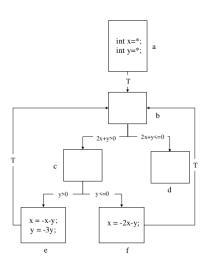
# Path Dependency Automaton

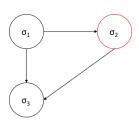
## Definition (Path Dependency Automaton(PDA))

Given a loop with CFG  $\mathcal{G}$ , the path dependency automaton of this loop is  $\mathcal{A} = (S, T, init, accept)$  where

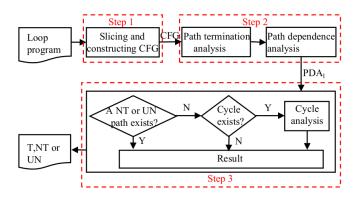
- ▶ S is the set of states. Each  $\sigma \in S$  corresponds to a path in the loop.
- ►  $T \subseteq S \times S$  is a set of transistions.  $(\sigma_i, \sigma_j) \in T$  means that  $\exists n > 0$  s.t.  $\theta(\sigma_j, \mathcal{V}_{\sigma_i}^n) = true \wedge tail(\sigma_i) = head(\sigma_j)$ .
- init, accept are the set of initial states and accepting states respectively.

# Example





#### Overview of MLTERM



The main part of termination analysis is step 3, where we first check if there is NT or UN path reachable. If not, do cycle analysis.

# Path Termination Analysis

If the path is not iterative, it is terminating.

Otherwise the path represents a loop.

$$while(Bx > 0)\{x = Ax\}$$

Do termination analysis on this loop and output T if it is terminating.

The method for the terminating analysis is from [Tiwari].

 $[{\sf Tiwari}] \ {\sf Termination} \ {\sf of} \ {\sf Linear} \ {\sf Program}.$ 

#### **Algorithm 1** PathTermAnalysis( $\sigma$ ,pre( $\sigma$ ))

```
Input: \sigma, pre(\sigma): the precondition of \sigma Output: \{T, NT, UN\}
```

```
1: for all \sigma \in S do

2: if head(\sigma) \neq tail(\sigma) then

3: return T

4: end if
```

5: Construct while Bx > b do x = Ax + c to analysis termination of  $\sigma$  denote as term

```
if term = T then
            return T
 7.
8:
        else
            if pre(\sigma) = true then
Q.
                return NT
10:
            end if
11:
            if pre(\sigma) always satisfiable in \sigma then
12:
                \sigma.condition.append(pre(\sigma))
13.
                return PathTermAnalysis(\sigma,true)
14:
            end if
15:
            return UN
16:
        end if
17.
18: end for
```

## **Examples**

(b) NT with witness x=2,y=1. (c)  $pre(\mathcal{G})$  is not always satisfied.

# Path Dependece Analysis

Target of path dependence analysis is to determine whether a loop path can transit to another.

There are two kinds of transitions:

- $\sigma_i$  is terminating and its outdegree is 1.
- ► Check whether the formula  $\exists n.\theta(\sigma_i, \mathcal{V}_{\sigma_i}^n)$  is true.

```
\label{eq:algorithm 2} \begin{tabular}{ll} \hline \textbf{Algorithm 2} & \textbf{ComputeTran}(\mathcal{G}) \\ \hline \textbf{Input:} & \mathcal{G}: CFG \\ \hline \end{tabular}
1: & \textbf{for all } \left(\sigma_i,\sigma_j\right) \in \left\{ (\sigma_m,\sigma_n) | \sigma_m \in S \land \sigma_n \in S \land tail(\sigma_m) \\ & = head(\sigma_n) \land m \neq n \right\} \\ \textbf{do} \\ 2: & \textbf{if } \sigma_i \text{is termination } \land \sigma_i.outdegree = 1 \textbf{ then} \\ 3: & T = T \cup ((\sigma_i,\sigma_j)) \\ 4: & \textbf{else} \\ \hline 5: & \textbf{if } \theta(\sigma_j,\mathcal{V}^n_{\sigma_i}) == true \textbf{ then} \\ 6: & T = T \cup ((\sigma_i,\sigma_j)) \\ 7: & \textbf{end if} \\ 8: & \textbf{end if} \\ 9: & \textbf{end for} \\ \hline \end{tabular}
```

# Cycle Analysis

### Definition (Cycle in PDA)

Let  $C = \{\sigma_1, \sigma_2, \dots, \sigma_\}$ . C is a cycle of PDA if

- $ightharpoonup \mathcal{C} \subset S$
- $ightharpoonup \sigma_1, \sigma_2, \ldots, \sigma_n$  constitues an SCC in PDA.

Classify cycles into 2 categories:

- ▶ Type 1 cycle: All path in C are one-time paths.
- Type 2 cycle: Otherwise.

# Cycle Analysis for Type 1

Idea: Since all paths are simple, we can simply merge them into a new path and do path termination analysis on the new path.

```
1: if \forall \sigma_i \in \mathcal{C} \land \sigma_i.iterable = false then
```

- 2:  $\sigma = \text{merge}(C)$
- 3: **return** PathTermAnalysis $(\sigma, pre(\sigma_1))$
- 4: end if

# Cycle Analysis for Type 2

```
assume \mathcal{C}_{II} is a set that all iterable path in \mathcal{C}
 5: for all \sigma \in \mathcal{C} do
          if head(\sigma) == tail(\sigma) then
               \mathcal{C}_{II}.append(\sigma)
          end if
 9: end for
10: for all \sigma \in \mathcal{C}_{II} do
     We use \Theta_{\sigma} to denote the conditional of \sigma
11:
          if \exists \theta_i \in \Theta_{\sigma} only change in \sigma then
               \mathcal{C}.del(\sigma)
12:
13:
               \mathcal{C}_{II}.\operatorname{del}(\sigma)
          end if
14:
15: end for
16: if C is not a cycle then
17.
          return T
18: end if
19: if C_{II}.empty() then
          return CycleAnalysis(C)
20:
21: end if
22: return UN
```

# **Experimental Results**

TABLE I EXPERIMENTAL RESULTS

	MLTerm	Ultimate	CPAchecker	2LS
CR	67	72	61	61
CUN	10	5	14	16
COT	0	0	2	0
TT	149.1	668.6	6147.9	1582.6

Benchmark: SV-COMP 2020

CR: num of right result. CUN: num of unknown. COT: num of timeout.

TT: total time.

# **Experimental Results**

