

Program Analysis - 1

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Overview

Sources:

- Principles of Program Analysis, Nielson 1999.
- Slides of Yingfei Xiong.

Contents:

- ① Introduction (**Part of**).
- ② **Data Flow Analysis.**
- ③ Constraint Based Analysis.
- ④ Abstract Interpretation.
- ⑤ Type and Effect System.

Data Flow Analysis: Preliminaries

- **Preliminaries on Partial Ordered Sets.**
- Reaching Definition Analysis.
- Live Variables Analysis.
- Theoretical Properties.

Preliminaries

Definition (Partial Order Set)

- 偏序是一个二元组 (S, \sqsubseteq) , 其中 S 是一个集合, \sqsubseteq 是一个定义在 S 上的二元关系, 并且满足如下性质:
 - 自反性: $\forall a \in S: a \sqsubseteq a$
 - 传递性: $\forall x, y, z \in S: x \sqsubseteq y \wedge y \sqsubseteq z \Rightarrow x \sqsubseteq z$
 - 非对称性: $x \sqsubseteq y \wedge y \sqsubseteq x \Rightarrow x = y$

- *Upper bound*: A subset Y of S has $l \in S$ as upper bound if $\forall l' \in Y. l' \sqsubseteq l$.
- *Greatest upper bound*: $l \in S$ is the greatest upper bound of Y iff for all upper bounds $l_0 \in S, l \sqsubseteq l_0$.
- Similar definition for lower bound and least lower bound.

We use $\sqcap Y$ and $\sqcup Y$ to represent the greatest lower bound (meet) and least lower bound (join) of Y .

$$l_1 \sqcap l_2, l_1 \sqcup l_2.$$

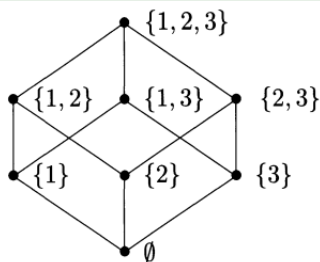
Complete Lattice

Definition (Complete Lattice)

A *complete lattice* $L = (L, \subseteq) = (L, \subseteq, \sqcup, \sqcap, \top, \perp)$.

Example

A complete lattice defined on the superset of $\{1, 2, 3\}$ where the partial order is \subseteq .



Monotone Function

Definition (Monotone Function)

A *monotone function* is a function $f : L_1 \rightarrow L_2$ between partially ordered sets (L_1, \sqsubseteq_1) and (L_2, \sqsubseteq_2) s.t.

$$\forall l, l' \in L_1. (l \sqsubseteq_1 l' \implies f(l) \sqsubseteq_2 f(l'))$$

Example

The monotone (increasing) function from (\mathbb{R}, \leq) to (\mathbb{R}, \leq) .

Fixed Points

Given a complete lattice $(L, \sqsubseteq, \sqcup, \sqcap, \top, \perp)$,

$$Red(f) = \{l \mid f(l) \sqsubseteq l\}$$

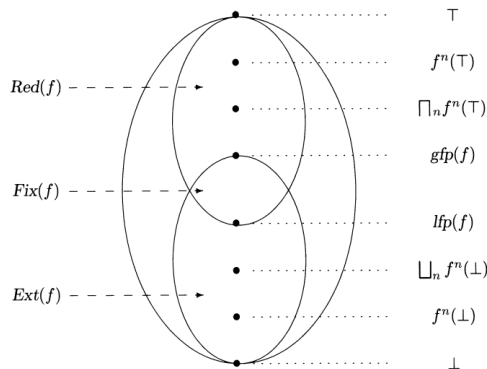
$$Ext(f) = \{l \mid f(l) \sqsupseteq l\}$$

$$Fix(f) = \{l \mid f(l) = l\}$$

Least fix-point and greatest fix-point:

$$gfp(f) = \bigsqcup Fix(f)$$

$$lfp(f) = \bigsqcap Fix(f)$$



Tarski Fixed Point Theorem

Proposition A.10

Let $L = (L, \sqsubseteq, \sqcup, \sqcap, \perp, \top)$ be a complete lattice. If $f : L \rightarrow L$ is a monotone function then $lfp(f)$ and $gfp(f)$ satisfy:

$$lfp(f) = \sqcap Red(f) \in Fix(f)$$

$$gfp(f) = \sqcup Ext(f) \in Fix(f)$$

Proof.

$$f(l_0) \sqsubseteq f(l) \sqsubseteq l \text{ for all } l \in Red(f)$$

Data Flow Analysis

- Preliminaries on Partial Ordered Sets.
- **Reaching Definition Analysis.**
- Live Variables Analysis.
- Theoretical Properties.

Basic Notations

$a \in \mathbf{AExp}$	arithmetic expressions	$x, y \in \mathbf{Var}$	variables
$b \in \mathbf{BExp}$	boolean expressions	$n \in \mathbf{Num}$	numerals
$S \in \mathbf{Stmt}$	statements	$\ell \in \mathbf{Lab}$	labels
$op_a \in \mathbf{Op}_a$	arithmetic operators		
$op_b \in \mathbf{Op}_b$	boolean operators		
$op_r \in \mathbf{Op}_r$	relational operators		

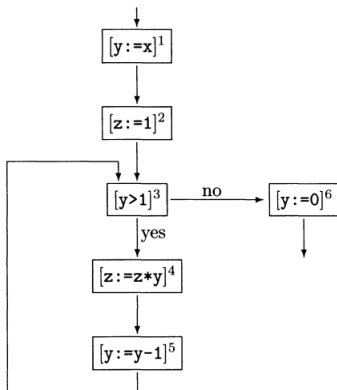
The syntax of the language is given by the following *abstract syntax*:

$$\begin{aligned} a &::= x \mid n \mid a_1 \ op_a \ a_2 \\ b &::= \mathbf{true} \mid \mathbf{false} \mid \mathbf{not} \ b \mid b_1 \ op_b \ b_2 \mid a_1 \ op_r \ a_2 \\ S &::= [x := a]^\ell \mid [\mathbf{skip}]^\ell \mid S_1; S_2 \mid \\ &\quad \mathbf{if} \ [b]^\ell \ \mathbf{then} \ S_1 \ \mathbf{else} \ S_2 \mid \mathbf{while} \ [b]^\ell \ \mathbf{do} \ S \end{aligned}$$

Example of Program

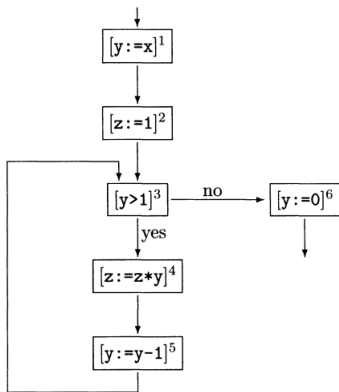
Example 1.1 An example of a program written in this language is the following which computes the factorial of the number stored in x and leaves the result in z :

$[y:=x]^1$; $[z:=1]^2$; while $[y>1]^3$ do ($[z:=z*y]^4$; $[y:=y-1]^5$); $[y:=0]^6$ ■



Other Notations

init, final, blocks, labels, flow, flow^R



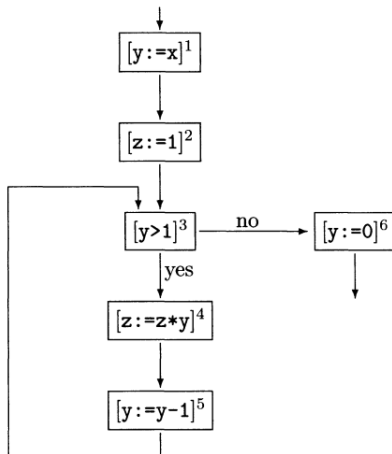
Reaching Definition Analysis

Reaching definition: An assignment of the form $[x := a]^l$ *may reach* a certain program point if there is an execution of the program where x was last assigned at value at l when the program point is reached.

Program points: exits and entries of elementary blocks.

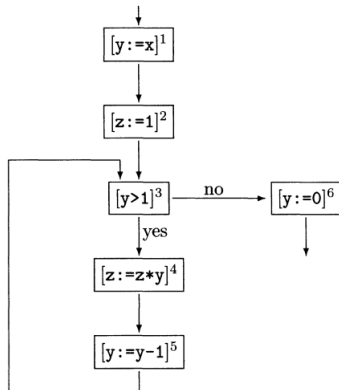
Problem: For each program points, find a set of pairs like (x, l) to represent the assignment that may reach the program points.

Notations: $(x, ?)$, (x, l)



Data Flow Analysis: Equational Approach

$$\begin{aligned}RD_{exit}(1) &= (RD_{entry}(1) \setminus \{(y, \ell) \mid \ell \in \mathbf{Lab}\}) \cup \{(y, 1)\} \\RD_{exit}(2) &= (RD_{entry}(2) \setminus \{(z, \ell) \mid \ell \in \mathbf{Lab}\}) \cup \{(z, 2)\} \\RD_{exit}(3) &= RD_{entry}(3) \\RD_{exit}(4) &= (RD_{entry}(4) \setminus \{(z, \ell) \mid \ell \in \mathbf{Lab}\}) \cup \{(z, 4)\} \\RD_{exit}(5) &= (RD_{entry}(5) \setminus \{(y, \ell) \mid \ell \in \mathbf{Lab}\}) \cup \{(y, 5)\} \\RD_{exit}(6) &= (RD_{entry}(6) \setminus \{(y, \ell) \mid \ell \in \mathbf{Lab}\}) \cup \{(y, 6)\}\end{aligned}$$



Data Flow Analysis: Equational Approach

$$RD_{entry}(2) = RD_{exit}(1)$$

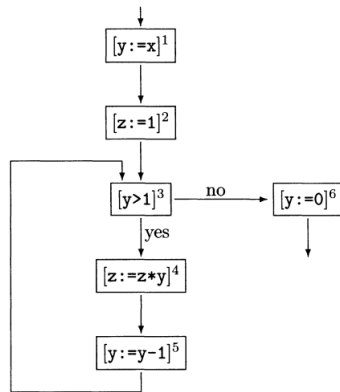
$$RD_{entry}(3) = RD_{exit}(2) \cup RD_{exit}(5)$$

$$RD_{entry}(4) = RD_{exit}(3)$$

$$RD_{entry}(5) = RD_{exit}(4)$$

$$RD_{entry}(6) = RD_{exit}(3)$$

$$RD_{entry}(1) = \{(x, ?), (y, ?), (z, ?)\}$$



How these equations generated?

Forward analysis.

<i>kill</i> and <i>gen</i> functions	
$kill_{RD}([x := a]^\ell)$	$= \{(x, ?)\} \cup \{(x, \ell') \mid B^{\ell'} \text{ is an assignment to } x \text{ in } S_\star\}$
$kill_{RD}([\text{skip}]^\ell)$	$= \emptyset$
$kill_{RD}([b]^\ell)$	$= \emptyset$
$gen_{RD}([x := a]^\ell)$	$= \{(x, \ell)\}$
$gen_{RD}([\text{skip}]^\ell)$	$= \emptyset$
$gen_{RD}([b]^\ell)$	$= \emptyset$
data flow equations: RD^\equiv	
$RD_{entry}(\ell)$	$= \begin{cases} \{(x, ?) \mid x \in FV(S_\star)\} & \text{if } \ell = init(S_\star) \\ \bigcup \{RD_{exit}(\ell') \mid (\ell', \ell) \in flow(S_\star)\} & \text{otherwise} \end{cases}$
$RD_{exit}(\ell)$	$= (RD_{entry}(\ell) \setminus kill_{RD}(B^\ell)) \cup gen_{RD}(B^\ell)$ where $B^\ell \in blocks(S_\star)$

Solve the equation system.

For the above program we obtain twelve sets at the program points:

$$\vec{RD} = (RD_{entry}(1), RD_{exit}(1), \dots, RD_{entry}(6), RD_{exit}(6))$$

We can regard one step execution of the program as a function F on \vec{RD} . i.e.

$$\begin{aligned}\overline{RD} &= F(\vec{RD}) \\ F(\vec{RD}) &= (F_{entry}(1)(\vec{RD}), F_{exit}(1)(\vec{RD}), \dots, F_{entry}(6)(\vec{RD}), F_{exit}(6)(\vec{RD}))\end{aligned}$$

where e.g.:

$$F_{entry}(3)(\dots, RD_{exit}(2), \dots, RD_{exit}(5), \dots) = RD_{exit}(2) \cup RD_{exit}(5)$$

Solve the equation system.

Definition of the function F :

$$F : (\mathcal{P}(\mathbf{Var}_* \times \mathbf{Lab}_*))^{12} \rightarrow (\mathcal{P}(\mathbf{Var}_* \times \mathbf{Lab}_*))^{12}$$

Partial order for the complete lattice:

$$\overrightarrow{RD} \sqsubseteq \overrightarrow{RD}' \quad \text{iff} \quad \forall i : RD_i \subseteq RD'_i$$

F is a monotone function:

$$\overrightarrow{RD} \sqsubseteq \overrightarrow{RD}' \quad \text{implies} \quad F(\overrightarrow{RD}) \sqsubseteq F(\overrightarrow{RD}')$$

Fix-point of F is the least solution to the equation system.

$$F^{n+1}(\vec{\emptyset}) = F^n(\vec{\emptyset})$$

Data Flow Analysis: Live Variable Analysis

- Reaching Definition Analysis.
- Preliminaries on Partial Ordered Sets.
- **Live Variables Analysis.**
- Theoretical Properties.

Live Variable Analysis

Live variable: $\text{varDef} \longrightarrow \text{varUsed}$

Along the path, there is no redefinition to the variable.

Then we call it live at the exit of the program.

Problem: for each program point, which variable *may* be live at the exit from the point.

Example

```
int main(){  
    int x = 10;  
    int y = 11;  
    int z = x + 1;  
    return z;  
}
```

Live variable analysis is useful in dead code elimination.

Live Variable Analysis

Backward analysis. Smallest solution.

<i>kill</i> and <i>gen</i> functions	
$kill_{LV}([x := a]^\ell)$	$= \{x\}$
$kill_{LV}([\mathbf{skip}]^\ell)$	$= \emptyset$
$kill_{LV}([b]^\ell)$	$= \emptyset$
$gen_{LV}([x := a]^\ell)$	$= FV(a)$
$gen_{LV}([\mathbf{skip}]^\ell)$	$= \emptyset$
$gen_{LV}([b]^\ell)$	$= FV(b)$
data flow equations: $LV^=$	
$LV_{exit}(\ell)$	$= \begin{cases} \emptyset & \text{if } \ell \in final(S_\star) \\ \bigcup \{LV_{entry}(\ell') \mid (\ell', \ell) \in flow^R(S_\star)\} & \text{otherwise} \end{cases}$
$LV_{entry}(\ell)$	$= (LV_{exit}(\ell) \setminus kill_{LV}(B^\ell)) \cup gen_{LV}(B^\ell)$ where $B^\ell \in blocks(S_\star)$

Table 2.4: Live Variables Analysis.

The Difference between May and Must

$(\text{while } [x > 1]^\ell \text{ do } [\text{skip}]^{\ell'}); [x := x + 1]^{\ell''}$

$$LV_{\text{entry}}(\ell) = LV_{\text{exit}}(\ell) \cup \{x\}$$

$$LV_{\text{entry}}(\ell') = LV_{\text{exit}}(\ell')$$

$$LV_{\text{entry}}(\ell'') = \{x\}$$

$$LV_{\text{exit}}(\ell) = LV_{\text{entry}}(\ell') \cup LV_{\text{entry}}(\ell'')$$

$$LV_{\text{exit}}(\ell') = LV_{\text{entry}}(\ell)$$

$$LV_{\text{exit}}(\ell'') = \emptyset$$

After some calculations:

$$LV_{\text{exit}}(\ell) = LV_{\text{exit}}(\ell) \cup \{x\}$$

The Difference between May and Must



数据流分析单调框架

- 一个控制流图(V, E)
- 一个有限高度的半格(S, \sqcap)
- 一个entry的初值 I
- 一组结点转换函数, 对任意 $v \in V - \text{entry}$ 存在一个结点转换函数 f_v
- 注意: 对于逆向分析, 变换控制流图方向再应用单调框架即可



数据流分析实现算法

```
DATAentry = I
 $\forall v \in (V - \text{entry}): \text{DATA}_v \leftarrow \top$ 
ToVisit  $\leftarrow V - \text{entry}$ 
While (ToVisit.size > 0) {
     $v \leftarrow \text{ToVisit}$  中任意结点
    ToVisit -= v
     $\text{MEET}_v \leftarrow \bigcap_{w \in \text{pred}(v)} \text{DATA}_w$ 
    If ( $\text{DATA}_v \neq f_v(\text{MEET}_v)$ ) ToVisit  $\cup = \text{succ}(v)$ 
     $\text{DATA}_v \leftarrow f_v(\text{MEET}_v)$ 
}
```

Data Flow Analysis: Live Variable Analysis

- Reaching Definition Analysis.
- Preliminaries on Partial Ordered Sets.
- Live Variables Analysis.
- **Theoretical Properties.**

Theoretical Properties