

Computing Linear Arithmetic Representation of Reachability Relation of One-counter Automata

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Overview

- Introduction to One-counter Automata(OCA) and its Reachability Relation.

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- Computing the Reachability Relation of OCA.
- Tool OCAREACH and Experimental Results.

What is One-counter Automata(OCA)

- DFA with a **counter** c where c is a **non-negative** integer.

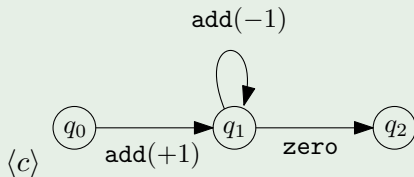
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- Transitions: $q \xrightarrow{0p} q'$ where $0p \in \{\text{add}(+1), \text{add}(-1), \text{zero}\}$

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Example (OCA)



Semantic of OCA

Semantic of OCA: A transition system.

- Configuration: (q, c) .
- Transitions of configurations corresponds to the transitions in the OCA.

$$(q_1, c_1) \rightarrow_{\mathcal{A}} (q_2, c_2)$$

if $q_1 \xrightarrow{\text{add}(+1)} q_2$ in the OCA and $c_1 + 1 = c_2$ and $\text{add}(-1)$ vice versa, or
if $q_1 \xrightarrow{\text{zero}} q_2$ and $c_1 = c_2 = 0$.
 $c_1, c_2 \geq 0$

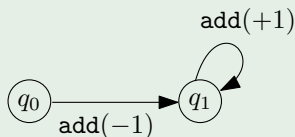
Reachability Problem

Reachability Problem of OCA: whether $(q_s, c_s) \rightarrow_{\mathcal{A}}^* (q_t, c_t)$

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Example



Due to the non-negative requirement,
 $(q_1, 1)$ is not reachable from $(q_0, 0)$

Reachability Relation

Reachability Problem of OCA: whether $(q_s, c_s) \rightarrow_{\mathcal{A}}^* (q_t, c_t)$

Instead of using concrete values c_s and c_t , we use variables x_s and x_t for the reachability relation.

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Definition (Reachability Relation of OCA)

A reachability relation of an OCA \mathcal{A} from state q_s to q_t is a set $R_{\mathcal{A}, q_s, q_t} \subseteq \mathbb{N} \times \mathbb{N}$.

$$\forall (c_s, c_t) \in R_{\mathcal{A}, q_s, q_t}. (q_s, c_s) \rightarrow_{\mathcal{A}}^* (q_t, c_t)$$

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Goal: use a Presburger Arithmetic (PA) formula $\phi(x_s, x_t)_{\mathcal{A}, q_s, q_t}$ to represent this relation.

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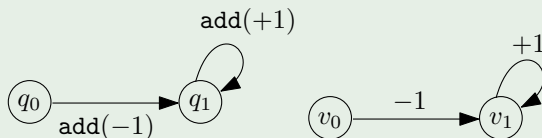
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- **Flow**: a function $f : E \rightarrow \mathbb{N}$.

Example



- path: $v_0 \cdot v_1 \cdot v_1 \cdot v_1$
- drop: -1

Path Flow and Support

- Support: edge-induced subgraph of flow.
- s - t **path flow**: the flow corresponds to a path.
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 - Connectivity of the support.

$$\phi_{G_{\mathcal{A}},s,t}^{pf}(x_s, x_t)_{f \in E} := \text{weight}(f) = x_t - x_s \wedge$$

if $(s = t)$ **then foreach** $v \in V : \text{num}(\text{in-flows})_v = \text{num}(\text{out-flows})_v$

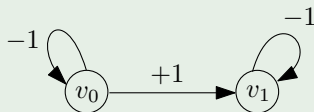
else foreach $v \in V - \{s, t\} : (\text{num}(\text{in-flows})_v = \text{num}(\text{out-flows})_v \wedge$

$$\text{num}(\text{in-flows})_s = \text{num}(\text{out-flows})_s - 1 \wedge$$

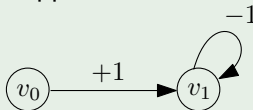
$$\text{num}(\text{in-flows})_t = \text{num}(\text{out-flows})_t + 1)$$

Example of Path Flow

Example



- Support:



- Path: $v_0 \cdot v_1 \cdot v_1 \cdot v_1$
- Pathflow: $f(v_0, v_0) = 0$
 $f(v_0, v_1) = 1$
 $f(v_1, v_1) = 2$
- Weight: $weight(f) = \sum_{e \in E} f(e) \cdot \eta(e)$

The Difficulty of Computing the Reachability Relation

NON-NEGATIVE

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If we do not require the non-negative of counter.

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$$\phi_{G_{\mathcal{A}},s,t}(x_s, x_t)_{f_{e \in E}}$$

Non-negative implies the constraint: everywhere along the path, the counter need to be non-negative.

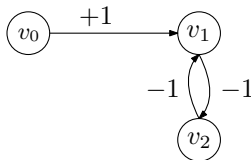
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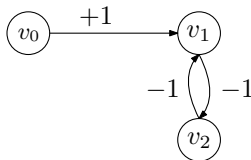
- Type-1 Certificate:
 - Flow is a path flow.
 - No positive cycle.
 - Path flow has edge decompositions (which implies **non-negative**).



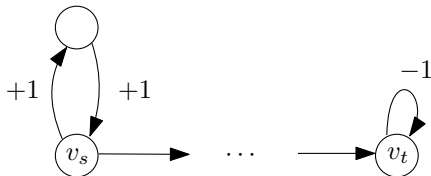
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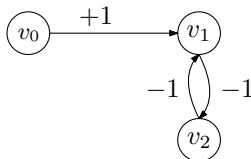
- Type-3 Certificate:



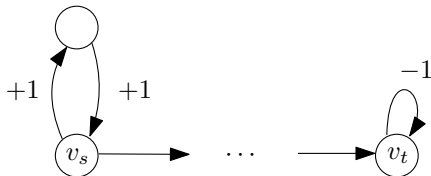
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- Type-3 Certificate:



- Type-2 Certificate: Dual of type-1 certificate at the end.

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- $weight(f_i) + weight(e_i) \geq 0$ for all i .

This definition implies the non-negative requirement of Type-1 certificate.



Decidability of Reachability of OCA

Theorem (Haase)

The reachability problem of OCA can be solved iff we can find a certificate that is of the form

$$(Type-1)^{n_1} (Type-3)^{n_3} (Type-2)^{n_2}$$

where $n_i \in \{0, 1\}$

Use PA Formula to Represent Type-3 Reachability Relation

$$\phi_{G_{\mathcal{A}},s,t}(x_s, x_t) = \exists (f_e)_{e \in E}. \phi^{T1RC} \vee \phi^{T2RC} \vee \phi^{T3RC} \vee \dots$$

Type-3 certificate:

$$\phi_{G_{\mathcal{A}},s,t}^{T3RC}(x_s, x_t)_{(f_e)_{e \in E}}$$

- Positive Cycle at q_s .
- Existence of a q_s - q_t path flow.
- Negative Cycle at q_t .

Use PA Formula to Represent Type-1 Reachability Relation

$$\phi_{G_{\mathcal{A}},s,t}^{T1RC}(x_s, x_t)_{(f_{e,1})_{e \in E}} := \exists (idx_e, sum_e)_{e \in E}$$

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$$\phi^{EDC}((f_e, idx_e, sum_e)_{e \in E}, (f_{e,e'})_{e,e' \in E})$$

OCAREACH: Experimental Evaluation

Implemented in Java and utilizing Z3 solver for formula manipulation.

INPUT: file describing the OCA.

OUTPUT: a PA formula ϕ representing reachability relation.

- Experiment on handcrafted cases.

state num.	2	2	2	2	3	3	4	4	4
transition num.	1	2	2	5	2	3	3	3	6
zero-test num.	0	1	1	0	0	1	1	1	1
time (s)	0.066	0.062	0.078	0.076	0.066	0.072	0.061	0.079	0.093
size (kB)	0.302	0.404	0.697	0.302	0.133	0.929	0.348	0.325	2.592
state num.	5	6	6	6	7	8	10	10	
transition num.	6	6	7	8	9	7	11	11	
zero-test num.	1	2	2	2	2	2	2	3	
time (s)	0.087	0.078	0.106	0.091	0.106	0.090	0.116	0.117	
size (kB)	2.057	2.469	7.457	3.078	6.427	4.807	8.443	7.515	

- On random cases.

Contributions and Future Work

Contributions:

- Some work to make computation of reachability relation possible.
- We built the gap between the theory and implementation by the tool OCAREACH.

Future work:

- Optimize our tool to improve the efficiency.
- More and larger cases and find benchmarks for experiment.
- Other topics about one-counter automata.

Thanks! & Questions?