

A Local Shape Analysis based on Separation Logic

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Introduction

A **Local Shape Analysis** based on **Separation Logic**

- ▶ What is **Shape Analysis**?
- ▶ What is **Separation Logic**?
- ▶ How the analysis works?
- ▶ What does **Local** means?

Shape Analysis

- ▶ Questions in heap content: NULL-pointers, May-Alias, Must-Alias, Reachability, Disjointness, **Shape**.
- ▶ **Shapes** characterize data structures: singly linked list, linked list with cycle, doubly linked list, a binary tree...
- ▶ According to ¹, shape analysis computes for each point in the program:
A finite, conservative representation of the heap-allocated data structures that could arise when a path to this program point executed.

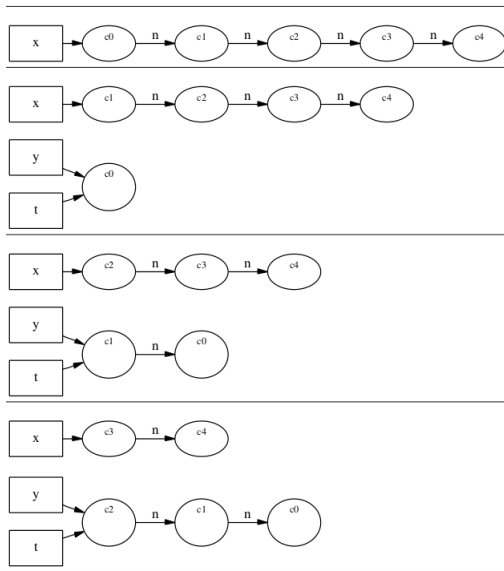
¹Reinhard Wilhelm et al. Shape Analysis. CC 2000.

Shape Analysis: Example

Example

```
1  List reverse(List x){
2      List y, t;
3      y = NULL;
4      while(x != NULL){
5          t = y;
6          y = x;
7          x = x->n;
8          y->n = NULL;
9          y->n = t;
10     }
11     return y;
12 }
```

Execution state: cells, connectivity and values of pointer variables.



Idea of the Paper

- ▶ Problem of classic shape analysis: updating of a abstract location may affect properties for other cells.
- ▶ Separation logic formula is also capable to express the configuration of memory.
- ▶ Utilize existing symbolic execution method for separation logic².

²Josh Berdine, Cristiano Calcagno and Peter W. O'Hearn. Symbolic execution with separation logic. 

Program Considered

Syntax:

$$b ::= E=E \mid E \neq E$$
$$p ::= x:= E \mid x:= [E] \mid [E]:= F \mid \mathbf{new}(x) \mid \mathbf{dispose}(E)$$
$$c ::= p \mid c ; c \mid \mathbf{while} \ b \ \mathbf{do} \ c \mid \mathbf{if} \ b \ \mathbf{then} \ c \ \mathbf{else} \ c$$

Example

```
while( $c \neq 0$ )do{  
   $t := c$ ;  
   $c := c \rightarrow tl$ ;  
  dispose( $t$ );  
}
```

Concrete State Semantic

$$\text{Values} = \text{Locations} \cup \{\text{nil}\}$$

$$\text{Heaps} = \text{Locations} \rightarrow_f \text{Values}$$

$$\text{Stacks} = (\text{Vars} \cup \text{Vars}') \rightarrow \text{Values}$$

$$\text{States} = \text{Stacks} \times \text{Heaps}$$

Graphically speaking,

We use S to denote the set States.

Concrete Execution Semantic

Primitive commands: $x := E, x := [E], [E] := F, \mathbf{new}(x), \mathbf{dispose}(E)$.

Assume the locations and values are all non-negative integers.

$$(s, h), p \Longrightarrow (s', h')$$

```
1  int main() {  
2  
3      x = 1;  
4  
5      new(y);  
6  
7  
8      [y] := x;  
9  
10  
11     dispose(y);  
12  
13 }
```

```
1  int main() {  
2  
3      new(x)  
4  
5      if (x = y) {  
6  
7          z := a;  
8  
9      } else {  
10         z := b;  
11     }  
12     dispose(x);  
13 }
```

$$\mathcal{C}[[c]] : \mathcal{P}(S) \rightarrow \mathcal{P}(S)$$

Separation Logic: Symbolic Heap

Pure

Spatial

$$\Pi \mid \Sigma$$

$$\exists x'_1 x'_2 \dots x'_n. \left(\bigwedge_{P \in \Pi} P \right) \wedge \left(\star_{Q \in \Sigma} Q \right)$$

\mathcal{SH}

Separation Logic: Semantic of Symbolic Heaps

Example

- ▶ $s, h \models E \mapsto F$:
 $s_0(x) = 1, s_0(y) = 10$ and $h_0(1) = 10$.
Then $s_0, h_0 \models x \mapsto y$.
- ▶ $s, h \models \text{ls}(E, F)$: intuitively, this means we have a path from E to F .
 - ▶ $s_0(x) = 1, s_0(y) = 10$ and $h_0(1) = 10$. Then $s_0, h_0 \models \text{ls}(x, y)$
 - ▶ $s_1(x) = 1, s_1(y) = 2, s_1(z) = 3, s_1(w) = 4$ and $h_1(1) = 2, h_1(2) = 3, h_1(3) = 4$.
Then $s_1, h_1 \models \text{ls}(x, w)$. Or $s_1, h_1 \models x \mapsto y * \text{ls}(y, w)$.
- ▶ $s, h \models \text{junk}$ iff $h \neq \emptyset$

Symbolic Execution Semantic

Primitive commands: $x := E, x := [E], [E] := F, \mathbf{new}(x), \mathbf{dispose}(E)$.

Assume the locations and values are all non-negative integers.

$$\Pi \mid \Sigma, p \Longrightarrow \Pi' \mid \Sigma'$$

```
1  int main(){
2      // true | emp
3      x = 1;
4
5
6      new(y);
7
8
9      [y] := x;
10
11
12     dispose(y);
13
14
15 }
```

```
1  int main(){
2
3      new(x)
4
5      if(x = y){
6
7          z := a;
8
9      } else {
10         z := b;
11     }
12     dispose(x);
13 }
```

$$\mathcal{I}[[c]] : \mathcal{P}(\mathcal{SH}) \rightarrow \mathcal{P}(\mathcal{SH})$$

Concretization

The link between concrete semantic and symbolic semantic:

$$\gamma : \mathcal{P}(\mathcal{SH}) \rightarrow \mathcal{P}(\text{States})$$

Theorem

The symbolic semantics is a sound overapproximation of the concrete semantics:

$$\forall X \in \mathcal{P}(\mathcal{SH}). \mathcal{C}[[c]](\gamma(X)) \subseteq \gamma(\mathcal{I}[[c]]X)$$

General Semantic Setting

Working with complete lattice: D .

D is constructed from $\mathcal{P}(S')$, where $S' = S \cup \{\top\}$. \top is a special element corresponds to memory fault.

semantic of a command $\llbracket c \rrbracket : D \rightarrow D$.

Semantic for key commands:

$$\begin{aligned}\llbracket c ; c' \rrbracket &= \llbracket c \rrbracket ; \llbracket c' \rrbracket & \llbracket \text{if } b \text{ then } c \text{ else } c' \rrbracket &= (\text{filter}(b) ; \llbracket c \rrbracket) \sqcup (\text{filter}(\neg b) ; \llbracket c' \rrbracket) \\ \llbracket \text{while } b \text{ do } c \rrbracket &= \lambda d. \text{filter}(\neg b) \left(\text{fix } \lambda d'. d \sqcup (\text{filter}(b) ; \llbracket c \rrbracket)(d') \right)\end{aligned}$$

where $\text{filter}(b) : D \rightarrow D$.

Execution semantic:

$$p \Longrightarrow \subseteq S \times (S \cup \{\top\})$$

The execution semantic on the powerset of S' is a function $\bar{p} : \mathcal{P}(S') \rightarrow \mathcal{P}(S')$:

$$\bar{p}X = \{\sigma' \mid \exists \sigma \in X. (\sigma, p \Longrightarrow \sigma') \vee (\sigma = \sigma' = \top)\}$$

Problem Encountered

\mathcal{SH} is an infinite set.

Define an abstract domain for the fix-point convergence and abstraction rules for the conversion.

- ▶ Expression replacement for primed variables.
- ▶ Garbage collection rules.
- ▶ List abstraction rules.

The conversion is given by \rightsquigarrow . The abstract domain after the abstraction is \mathcal{CSH} and corresponding abstract semantic function $\mathcal{A}[[c]] : \mathcal{P}(\mathcal{CSH}) \rightarrow \mathcal{P}(\mathcal{CSH})$.

The Analysis

Theorem

\mathcal{CSH} is finite.

Theorem

The abstract semantic is a sound overapproximation of the concrete semantic.

$$\forall X \in \mathcal{P}(\mathcal{SH}). \mathcal{C}[[c]](\gamma(X)) \subseteq \gamma(\mathcal{A}[[c]]X)$$

The Analysis

Example

A program to dispose a list.

Program: **while** ($c \neq 0$) **do** ($t := c; c := c \rightarrow tl; \text{dispose}(t)$)

Pre: $\{\} \mid \{\text{ls}(c, 0)\}$

Post: $\{c = 0\} \mid \{\}$

Inv: $\{c = 0\} \mid \{\} \vee \{\} \mid \{\text{ls}(c, 0)\}$

Locality

Theorem (Frame Rule)

For all $X, Y \in \mathcal{P}(\mathcal{CSH})$, if $\text{Vars}(Y) \cap \text{Mod}(X) = \emptyset$ then
$$\gamma(\mathcal{A}[[c]](X * Y)) \subseteq \gamma(\mathcal{A}[[c]]X) * Y$$

Conclusion

- ▶ Concrete semantic.
- ▶ Symbolic semantic. (Symbolic heap)
- ▶ Abstract semantic. (Canonical symbolic heap)
- ▶ Locality.

What can be done with the sound over-approximation?