

Section 2.6 Shape Analysis

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Syntax of Pointer Language

Selectors: a set of selector names are given (What can be selectors?)

$$sel \in \mathbf{Sel}$$

A set of pointer expressions.

$$p \in \mathbf{PExp}$$

where $p ::= x \mid x.sel$ The extended WHILE-language:

Arithmetic a is extended to pointer expressions, but not pointer arithmetic.
 op_r allows equality test for pointers.

Example

Example

Example

Structural Operational Semantics Basic Definitions

- An infinite set of locations **Loc**: $\xi \in \mathbf{Loc}$.
- A set of states **State**: $\sigma \in \mathbf{State} = \mathbf{Var}_* \rightarrow (\mathbf{Z} + \mathbf{Loc} + \{\diamond\})$
- A set of heaps **Heap**: $\mathcal{H} \in \mathbf{Heap} = (\mathbf{Loc} \times \mathbf{Sel}) \rightarrow_{fin} (\mathbf{Z} + \mathbf{Loc} + \{\diamond\})$

where the partial means not all selector fields need to be defined.

The semantic of pointer arithmetic is given by:

Example

- oval nodes: heap cells
- $\xi_i s'$: locations
- labelled edges: heap
- unlabelled edges: state

Semantics of Expressions

Extend the old semantic to store and heap:

Semantics of Statements

- $\langle [x := a]^\ell, \sigma, \mathcal{H} \rangle$
- $\langle [x.sel := a]^\ell, \sigma, \mathcal{H} \rangle$
- malloc: allocation for pointers.

Semantic of Statements

For malloc: a limited reused strategy is used.

- x can be reused: $[\text{malloc } x]^1; [x := \text{nil}]^2; [\text{malloc } x]^3$
- x cannot be reused although unreachable:
 $[\text{malloc } x]^1; [x.\text{cdr} := \text{nil}]^2; [x := \text{nil}]^3; [\text{malloc } x]^4$

Shape Graphs: Abstraction of the Memory Configurations

Definition

Shape Graph A shape graph is a triplet (S, H, is) , where

- Abstract state S is a map from variables to *abstract locations*:

$$S \in \mathbf{AState} = \mathcal{P}(\mathbf{Var}_* \times \mathbf{ALoc})$$

- Abstract heap H is set specifies the links between abstract locations :

$$H \in \mathbf{AHeap} = \mathcal{P}(\mathbf{ALoc} \times \mathbf{Sel} \times \mathbf{ALoc})$$

- A set of abstract locations that are shared:

$$is \in \mathbf{IsShared} = \mathcal{P}(\mathbf{ALoc})$$

Abstract Locations

The abstract locations have the form n_X where X is a subset of the variables of \mathbf{Var}_* :

$$\mathbf{ALoc} = \{n_X \mid X \subseteq \mathbf{Var}_*\}$$

Finiteness: the set \mathbf{Var}_* is finite.

- Intuitively, n_X is the abstraction of the location $\sigma(x)$ of pointer variables $x \in X$
- We shall enforce:
Invariant 1: If n_X and n_Y occur in the same shape graph, then either $X = Y$ or $X \cap Y = \emptyset$.
- We use *abstract summary location* n_\emptyset to represent all locations that cannot be reached directly from the state without using the heap.

Example of Abstract Locations

Abstract States and Heaps

- Abstract state: Abstract state S is a map from variables to *abstract locations*:

$$S \in \mathbf{AState} = \mathcal{P}(\mathbf{Var}_* \times \mathbf{ALoc})$$

Invariant 2. If x is mapped to n_X by the abstract state then $x \in X$.

Define the set $ALoc(S) = \{n_X \mid \exists x : (x, n_X) \in S\}$ to be the abstract locations occurring in S .

- Abstract heap: heap H is set specifies the links between abstract locations :

$$H \in \mathbf{AHeap} = \mathcal{P}(\mathbf{ALoc} \times \mathbf{Sel} \times \mathbf{ALoc})$$

Intuitively, if $\mathcal{H}(\xi_1, sel) = \xi_2$ and ξ_1, ξ_2 are represented by n_V, n_W resp., then $(n_V, sel, n_W) \in H$.

Invariant 3. Whenever (n_V, sel, n_W) and $(n_V, sel, n_{W'})$ are in the abstract heap, then either $V = \emptyset$ or $W = W'$.

Both abstract state and abstract heap are changing along the execution.

Example of Abstract States and Heaps

Sharing Information

A set of abstract locations that are shared due to pointers in the *heap*:

$$is \in \mathbf{IsShared} = \mathcal{P}(\mathbf{ALoc})$$

Sharing Information

With above observations we have following invariant:

And the connection of i is to the abstract heap H :

Sharing information clearly gives extra information: n_\emptyset

Use of Shape Graph

The Complete Lattice of Shape Graph

$$S \in \mathbf{AState} = \mathcal{P}(\mathbf{Var}_* \times \mathbf{ALoc})$$

$$H \in \mathbf{AHeap} = \mathcal{P}(\mathbf{ALoc} \times \mathbf{Sel} \times \mathbf{ALoc})$$

$$is \in \mathbf{IsShared} = \mathcal{P}(\mathbf{ALoc})$$

$$\mathbf{ALoc} = \{n_Z \mid Z \subseteq \mathbf{Var}_*\}.$$

A shape graph (S, H, is) is compatible if it satisfies **Invariant 1.- 5.**, the set of compatible shape graphs is denoted:

$$\mathbf{SG} = \{(S, H, is) \mid S, H, is \text{ is compatible}\}$$

The analysis will operate over on $\mathcal{P}(\mathbf{SG})$. Since it is a power set, it is trivially a complete lattice over union and subset relation. Due to the finiteness of \mathbf{Var}_* is finite.

The Analysis: Basic Framework

An instance of monotone framework: let $\mathcal{P}(\mathbf{SG})$ be the complete lattice of properties. For label consistent program S_* , we obtain a set of equations by

In the following, the transfer functions over different statements will be developed. The transfer function associate with label l : $f_l^{\text{SA}} : \mathcal{P}(\mathbf{SG}) \rightarrow \mathcal{P}(\mathbf{SG})$.

$$f_l^{\text{SA}}(SG) = \bigcup \{ \phi_l^{\text{SA}}((S, H, is)) \mid (S, H, is) \in SG \}$$

$$\phi_l^{\text{SA}} : \mathbf{SG} \rightarrow \mathcal{P}(\mathbf{SG}).$$

Transfer Functions

- For $[b]^\ell$ and $[\text{skip}]^\ell$: $\phi_\ell^{\text{SA}}((S, H, \text{is})) = \{(S, H, \text{is})\}$
- For $[x := a]^\ell$ where a is of the form $n, a_1 \text{ op}_a a_2$ or nil :
 - Renaming of abstract locations to exclude x : $k_x(n_Z) = n_Z \setminus \{x\}$
 - Function ϕ_ℓ^{SA} is given by

Example

Transfer Functions

- For $[x := y]^\ell$: - $x = y$. - $x \neq y$
- Based on previous (S', H', is') :

Here (y', n_Y) means n_Y must can be visit by a pointer variable by state.

Example

Transfer Functions

- For $[x := y.sel]^\ell$, we can regard it as an equivalent sequence:

$$[t := y.sel]^{l_1}; [x := t]^{l_2}; [t := nil]^{l_3}$$

and

$$f_\ell^{\text{SA}} = f_{\ell_3}^{\text{SA} \cdot f_{\ell_2}^{\text{SA} \cdot f_{\ell_3}^{\text{SA}}}}$$