Lecture 11: DBScan

Sophie Rober

Introduction

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Hyperparameters

Advantages

Lecture 11: DBScan

Introduction to Machine Learning

Sophie Robert

L3 MIASHS — Semestre 2

2022-2023

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Introduction

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Hyperparameters

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Advantages and limits

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- 3 Algorithm
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- 5 Advantages and limits

Question

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Do you remember what the goal of clustering is ? Do you remember what algorithms we studied ?

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Density-based spatial clustering of applications with noise (DBSCAN) is a **density-based clustering non-parametric algorithm**.

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DBScan

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Given a set of points in some space:

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DBScan

Density-based spatial clustering of applications with noise (DBSCAN) is a **density-based clustering non-parametric algorithm**.

Given a set of points in some space:

 group together points that are closely packed together (many nearby neighbors)

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DBScan

Density-based spatial clustering of applications with noise (DBSCAN) is a **density-based clustering non-parametric algorithm**.

Given a set of points in some space:

- group together points that are closely packed together (many nearby neighbors)
- mark as outliers point that lie alone in low-density regions (nearest neighbors are far away)

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Advantage

Given a radius ϵ , a distance d and threshold number of points n_{points} , each individual in the dataset can be labelled as:

■ Core points: at least n_{points} are within distance ϵ

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Advantages

- Core points: at least n_{points} are within distance ϵ
- Directly reachable: q is directly reachable if p is within distance ϵ of q

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Advantages

- Core points: at least n_{points} are within distance ϵ
- Directly reachable: q is directly reachable if p is within distance ϵ of q
- Reachable: q is reachable from p if there is a path p_0, p_1, \ldots, p_n, q where each p_i is directly reachable from p_{i-1} .

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Advantages

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- Reachable: q is reachable from p if there is a path p_0, p_1, \ldots, p_n, q where each p_i is directly reachable from p_{i-1} .
- Outlier: All points not reachable from any other points.

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Advantages and limits Once each point has been properly labelled:

- A cluster is the all the points (core or non-core) reachable from a core point.
- Non-reachable points are not clusterized.

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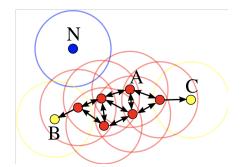
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All red points are *core* points, *yellow* points are reachable and *N* is an outlier.



Algorithm

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Advantage and limits

- For every point in the dataset, find its ϵ nearest neighbors and identify the core points with more than n_{points}
- Find all the connected core points
- Assign each non-core point to a nearby cluster if the cluster is within ϵ else assign it to noise.

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Can you list the hyperparameters ?

- Min points for individuals to be defined as core points
- lacksquare neighborhood radius
- Distance between individuals

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Advantages

Does not require to choose the number of clusters

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Advantages

- Does not require to choose the number of clusters
- Arbitrarily shaped clusters

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Advantages

- Does not require to choose the number of clusters
- Arbitrarily shaped clusters
- Notion of noise and robust to outliers

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Advantages

- Does not require to choose the number of clusters
- Arbitrarily shaped clusters
- Notion of noise and robust to outliers
- Only three hyperparameters that can be set by domain experts.

Limits

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Advantages

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Limits

 Does not behave well for data with differing density across the parametric space

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Advantages

- Does not require to choose the number of clusters
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Limits

- Does not behave well for data with differing density across the parametric space
- Hyperparameter selection

Questions

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 ${\sf Questions}\ ?$