

Optimising SKA1-Mid Scale-Dependent Sensitivity

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Abstract

In this report we study the scale dependent sensitivity of the SKA1-Mid baseline design. We also propose changes to the baseline design that enhance the sensitivity at smaller angular scales (e.g. 0.4-1 arcsec at 650MHz) without compromising the performance at larger scales. The changes we propose are guided by the SKA1-Mid level-zero science requirements [2], which suggest that very long baselines (> 150km) are not necessary to achieve the SKA1-Mid science objectives. The layouts we propose could be transformational for other potential science cases which are possible with such an instrument, such as cosmology with weak lensing, at no significant cost to any of the key science cases. In particular, a layout which has a maximum baseline of 120km (SKA1X9-12A72B120) has more than twice the survey speed of the “second generation” baseline layout at angular resolutions of around 0.4-1 arcsec (over 650-1100MHz). Furthermore, such a layout spans significantly less space which could potentially reduce trenching and data transport costs.

1 Introduction

The Square Kilometre Array (SKA) project is meant to be an international facility that will provide as much science as possible during its lifetime. The large emphasis on key science projects is outlined in several SKA memos, as the baseline design has emerged. It should however be noted that changes which do not compromise the key science cases are possible and such changes could be transformational for other science cases. In this short report, we compare the scale-dependent sensitivity of the SKA1-Mid baseline design to 4 alternative designs. The alternative layouts we propose are guided by the SKA1-Mid general science requirements outlined in the SKA1 Level-zero requirements document [2], and the possibility of having better imaging quality with SKA-Mid. Essentially, looking that at the SKA1-Mid science requirements [2], it is clear that baselines longer than about 100km are not a necessity. We therefore seek a layout with the shortest possible maximum baseline that does at least as well as the “second generation” baseline design in the resolution range 0.4-1 arcsec over 650, 800 and 1100MHz¹ while not significantly compromising the performance at the larger angular scales. Moreover, having a layout which performs just as well as (or better) than the baseline layout but which covers significantly less space translates to less trenching, which may present the opportunity to re-invest the funds somewhere else, therefore we consider the conservative addition of 12 dishes. However, we note that improvements on the scales of interest are still possible without these 12 additional dishes. In the next section we present 4 alternative layouts with maximum baselines of 90, 100, 120 and 133 km. The scale dependent sensitivity of these layouts is compared to the baseline layout in section 2, and our conclusions are presented in section 3.

1.1 Background on Layouts

The following SKA1-Mid layouts are under consideration here:

REF2A100B173 : This is the Second-generation layout (254 dishes) produced by Robert Braun (September 2013)². The spiral arms of this layout stretch out to 100km, and the maximum baseline is 173km. In this report, we also refer to this layout as REF2.

$Xi-jAkBl$: This is the REF2 layout with the core (within a 400m radial distance from the the centre) “puffed up” by 10%, i dishes moved from the outer core (between a radial distance of 0.4 and 4km from the centre) to the spiral arms and j extra dishes added to the spiral arms. The spacing in the arms is then optimised to get more sensitivity on the longer (> 50km) baselines (See baseline distribution histograms in Figure 2). Each spiral arm stretches out to k kilometres and the maximum baseline length is about l kilometres.

¹This well covers the highest resolution requirements in the level-zero science requirements

²We assume this to be the baseline layout.

The layouts are shown in Figure 1, while Figure 2 shows the baseline distribution histogram for the different layouts. Figure 3 shows the uv-coverage for the different layouts at 1.1GHz at declination -30 degrees for 8hr tracks. At this point some optimisations have been done on the antenna distributions but we emphasise that further improvements can be and should be made.

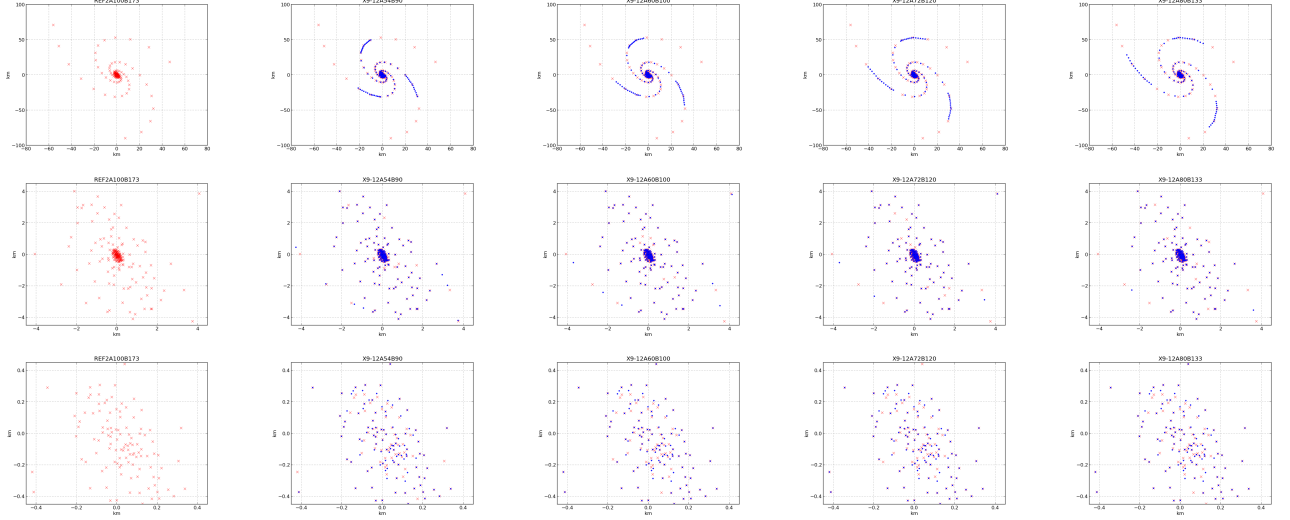


Figure 1: Antenna layouts, REF2 plotted as a reference (red crosses)

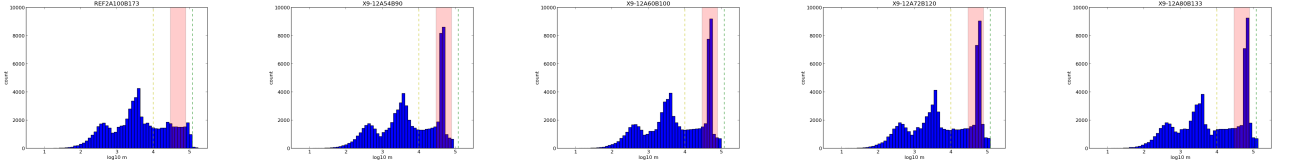


Figure 2: Baseline distribution with the uv-distance in \log_{10} km . Yellow and green dashed lines mark 10 and 120 kilometres respectively, and the pink strip represents baselines from 30-80km.

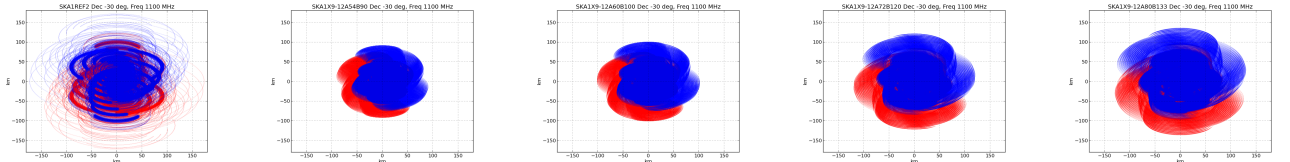


Figure 3: UV-Coverage for 8-hr tracks at 1.1 GHz (50MHz bandwidth) at declinations -50,-30,-10 for the different layouts. Blue indicates uv-points, red indicates conjugate uv-points.

2 The Experiment

Our aim is to investigate the scale-dependent sensitivity of the layouts described in the previous section. We use the **makems** tool to make simulated measurement sets of 8hr tracks with a 60s integration time at declination -30° at frequencies of $\{650, 800, 1100\}$ MHz with a single channel. The expected rms noise per real and imaginary part for each visibility is calculated as $\sigma_{\text{vis}} = \text{SEFD} / \sqrt{2\Delta t \Delta \nu}$. We use the baseline design's system equivalent flux density (SEFD) value of 400 corresponding to the 15m dishes. We then fill the measurement set with random Gaussian noise using the computed value of the noise for a given integration and bandwidth. We then use the (CASA-derived) **lwimager** tool to make maps of the point spread function (PSF) as well as dirty maps of the noise. The following metrics were generated:

Note: These metrics are generated at different angular scales. This is done by tapering out³ visibilities that do not fall within a given uv-distance range, i.e., we only consider uv-points that correspond to a given resolution.

³The weights for the taper are generated using a Butterworth function

- PSF full width at half maximum (FWHM) size (mean of the FWHM dimensions). This was measured by making high-resolution images of the PSF (0.05 arcsec resolution), and fitting a Gaussian to the PSF. Note that for the highly non-Gaussian PSFs corresponding to natural and (some) robust weighting schemes, the fit is very poor, so the size parameter becomes somewhat ill-defined (Table 1).
- PSF symmetry (PSF size parameters are obtained as explained above). As a measure of PSF symmetry, we define $\text{PSF}_{\text{sym}} = 1 - \text{FWHM}_{\text{min}}/\text{FWHM}_{\text{maj}}$, then $\text{PSF}_{\text{sym}} = 0$ is perfect symmetry, and the symmetry degenerates as $\text{PSF}_{\text{sym}} \rightarrow 1$ (Table 2).
- RMS pixel noise at different angular scales for a 166MHz wide band (Table 3).
- SNR for a $10\mu\text{Jy}$ source at 1100MHz with a spectral index of -0.7 after 8hrs for a 166MHz band (Table 4).
- Average SNR over frequencies 650, 800 and 1100MHz (166MHz band) after 8 hours, for a $10\mu\text{Jy}$ source at 1100MHz with a spectral index of -0.7 (Table 5). $\overline{\text{SNR}}_{10} = \sqrt{\text{SNR}_{650}^2 + \text{SNR}_{800}^2 + \text{SNR}_{1100}^2}$.
- Hours required to reach a mean SNR of 10 (Table 6).

3 Conclusions

The metrics we have used suggest that the science goals (at least those listed in the SRD in addition to cosmology with weak lensing and HI surveys) can be met by a layout which covers significantly less space compared to the baseline layout. Some of these “smaller” layouts perform significantly better than the baseline layout at smaller scales, up to a 50% improvement in terms of the noise properties, without compromising the larger scales. This obviously presents an opportunity to reduce trenching and data transport costs. Moreover, bringing in the dishes from the longer baselines translates to a greater sensitivity on the relevant (to the science goals of SKA1-Mid) smaller scales, as can be seen in Tables 3-6. Even more encouraging is the fact that this doesn’t compromise the size or the symmetry of the PSF as seen in Tables 1 and 2. **Our preferred solution which allows for weak lensing, HI and continuum source morphology characterisation for galaxy evolution studies is the SKA1X9-12A72B120 configuration.** Although we note that we have not optimised around this solution and such a configuration also needs to be analysed by SKA science working groups, in particular the HI science working group.

References

- [1] http://www.skatelescope.org/wp-content/uploads/2013/05/SKA-TEL-SK0-DD-001-1_BaselineDesign1.pdf
- [2] https://www.skatelescope.org/wp-content/uploads/2014/03/SKA-TEL_SCI-SK0-SRQ-001-1_Level_0_Requirements-1.pdf

Table 1: FWHM PSF sizes (in arcseconds) for the different layouts at different angular scales. These values are generated at 650, 800 and 1100MHz, for angular scales {0.4-1, 1-2, 2-3, 3-4, 600-3600} arcsec and are labeled *resbin* {1, 2, 3, 4, 5} respectively. This is done for natural weighting at declination -30 degrees. For each column, the intensity of the color increases with the value.

(a) DEC=-30, natural weighting

resbin	650MHz					800MHz					1100MHz				
	1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
SKA1REF2	0.65	1.34	2.35	3.37	797.29	0.60	1.33	2.35	3.34	790.58	0.59	1.33	2.35	3.35	759.20
SKA1X9-12A54B90	0.86	1.20	2.36	3.32	788.95	0.80	1.19	2.34	3.33	790.72	0.64	1.31	2.35	3.34	761.78
SKA1X9-12A60B100	0.84	1.18	2.35	3.36	789.63	0.75	1.26	2.34	3.34	788.41	0.60	1.34	2.36	3.37	760.33
SKA1X9-12A72B120	0.76	1.26	2.35	3.36	786.89	0.66	1.31	2.34	3.33	787.70	0.52	1.34	2.36	3.36	761.09
SKA1X9-12A80B133	0.71	1.29	2.35	3.34	788.81	0.61	1.33	2.37	3.36	789.88	0.50	1.32	2.34	3.33	763.30

Table 2: PSF symmetry (see section 2) for the different layouts at different angular scales. These values are generated at 650, 800 and 1100MHz, for angular scales $\{0.4-1, 1-2, 2-3, 3-4, 600-3600\}$ arcsec and are labeled *resbin* $\{1, 2, 3, 4, 5\}$ respectively. This is done for natural weighting at declination -30 degrees. For each column, the intensity of the color increases with the value.

(a) DEC=-30, natural weighting

	650MHz					800MHz					1100MHz				
resbin	1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
SKA1REF2	0.13	0.07	0.08	0.06	0.02	0.09	0.08	0.06	0.08	0.03	0.06	0.08	0.06	0.05	0.07
SKA1X9-12A54B90	0.20	0.08	0.06	0.05	0.03	0.17	0.05	0.08	0.05	0.03	0.11	0.05	0.08	0.06	0.04
SKA1X9-12A60B100	0.19	0.02	0.04	0.08	0.03	0.14	0.09	0.07	0.09	0.02	0.11	0.06	0.05	0.06	0.03
SKA1X9-12A72B120	0.15	0.10	0.04	0.08	0.03	0.12	0.01	0.07	0.09	0.02	0.11	0.06	0.05	0.06	0.03
SKA1X9-12A80B133	0.13	0.03	0.06	0.04	0.04	0.11	0.05	0.06	0.06	0.02	0.06	0.06	0.09	0.02	0.03

Table 3: Noise (in μ Jy) for a 166MHz band after an 8hr synthesis with a 60s integration for the different layouts at different angular scales. These values are generated at 650, 800 and 1100 MHz, at angular scales $\{0.4-1, 1-2, 2-3, 3-4, 600-3600\}$ arcsec and are labeled *resbin* $\{1, 2, 3, 4, 5\}$ respectively. This is done for natural at declination -30 degrees. For each column, the intensity of the color increases with the value.

(a) DEC=-30, natural weighting

	650MHz					800MHz					1100MHz				
resbin	1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
SKA1REF2	1.50	1.60	2.10	2.60	5.60	1.40	1.60	2.20	2.60	7.10	1.40	1.60	2.20	2.60	10.00
SKA1X9-12A54B90	1.40	0.98	2.20	2.80	5.90	1.00	1.30	2.20	2.90	7.50	0.91	1.70	2.30	2.70	11.00
SKA1X9-12A60B100	1.20	1.10	2.30	2.70	5.90	0.96	1.50	2.30	2.70	7.50	0.90	1.70	2.40	2.80	11.00
SKA1X9-12A72B120	0.95	1.50	2.40	2.80	5.90	0.93	1.70	2.40	2.70	7.50	0.88	1.80	2.40	2.90	11.00
SKA1X9-12A80B133	0.91	1.50	2.20	3.00	5.90	0.89	1.70	2.40	3.00	7.50	0.92	1.70	2.30	3.00	11.00

Table 4: SNR after 8 hours relative to a 10μ Jy source at 1100Hz (166 MHz band) with a spectral index of -0.7 for the different layouts. These values are generated at 650, 800 and 1100 MHz, at angular scales $\{0.4-1, 1-2, 2-3, 3-4, 600-3600\}$ arcsec and are labeled *resbin* $\{1, 2, 3, 4, 5\}$ respectively. This is done for natural weighting at declination -30 degrees. For each column, the intensity of the color increases with the value.

(a) DEC=-30, natural weighting

	650MHz					800MHz					1100MHz				
resbin	1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
SKA1REF2	9.52	8.85	6.74	5.51	2.57	8.86	7.65	5.60	4.79	1.76	7.14	6.11	4.53	3.86	1.00
SKA1X9-12A54B90	10.04	14.82	6.59	5.15	2.47	12.30	9.94	5.71	4.30	1.66	11.02	6.00	4.32	3.73	0.92
SKA1X9-12A60B100	12.35	13.26	6.28	5.29	2.44	12.99	8.46	5.37	4.56	1.67	11.13	5.87	4.14	3.62	0.94
SKA1X9-12A72B120	15.18	9.96	6.10	5.18	2.46	13.47	7.42	5.22	4.57	1.66	11.40	5.70	4.14	3.49	0.94
SKA1X9-12A80B133	15.83	9.43	6.44	4.85	2.45	14.02	7.32	5.30	4.22	1.67	10.82	5.72	4.28	3.28	0.92

Table 5: SNR after 8 hours relative to a 10μ Jy source at 1100Hz (166 MHz band) with a spectral index of -0.7 averaged over 650,800 and 1100MHz, for the different layouts at different angular scales. These values are generated for angular scales $\{0.4-1, 1-2, 2-3, 3-4, 600-3600\}$ arcsec and are labeled *resbin* $\{1, 2, 3, 4, 5\}$ respectively. This is done for natural weighting at declination -30 degrees. For each column, the intensity of the color increases with the value.

(a) DEC=-30, natural weighting

resbin	1	2	3	4	5
SKA1REF2	14.83	13.20	9.86	8.26	3.27
SKA1X9-12A54B90	19.33	18.82	9.73	7.67	3.11
SKA1X9-12A60B100	21.10	16.79	9.24	7.87	3.10
SKA1X9-12A72B120	23.27	13.67	9.03	7.74	3.11
SKA1X9-12A80B133	23.76	13.24	9.37	7.22	3.11

Table 6: The hours required to reach a mean SNR of 10 (average over 650,800 and 1100MHz), assuming a 10μ Jy source at 1100MHz with a spectral index of -0.7 for the different layouts at different angular scales. These values are generated for angular scales $\{0.4-1, 1-2, 2-3, 3-4, 600-3600\}$ arcsec and are labeled *resbin* $\{1, 2, 3, 4, 5\}$ respectively. This is done for natural weighting at declinations -30 degrees. For each column, the intensity of the color increases with the value.

(a) DEC=-30, natural weighting

resbin	1	2	3	4	5
SKA1REF2	3.64	4.59	8.22	11.73	74.76
SKA1X9-12A54B90	2.14	2.26	8.45	13.59	82.71
SKA1X9-12A60B100	1.80	2.84	9.37	12.93	83.22
SKA1X9-12A72B120	1.48	4.28	9.80	13.37	82.66
SKA1X9-12A80B133	1.42	4.56	9.11	15.35	82.82